EE 332: Devices and Circuits II

Lecture 2: MOS Devices (Part 2)

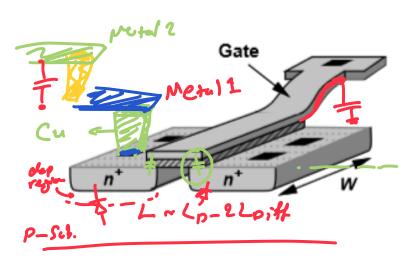
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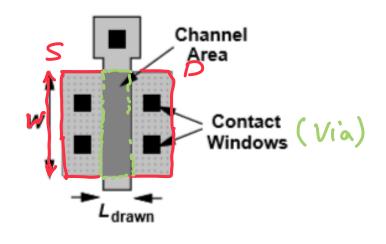
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Autumn 2022

Gale

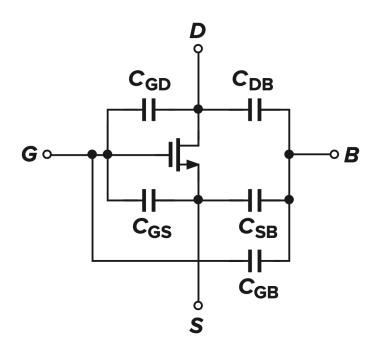
MOS Device Layout





- The gate polysilicon and the source and drain terminals must be tied to metal (aluminum) wires that serve as interconnects with low resistance and capacitance.
- This is accomplished with "contact windows" which are filled with metal and connected to the upper metal wires.
- To minimize the capacitance of the source and drain, the total area of each junction must be minimized.

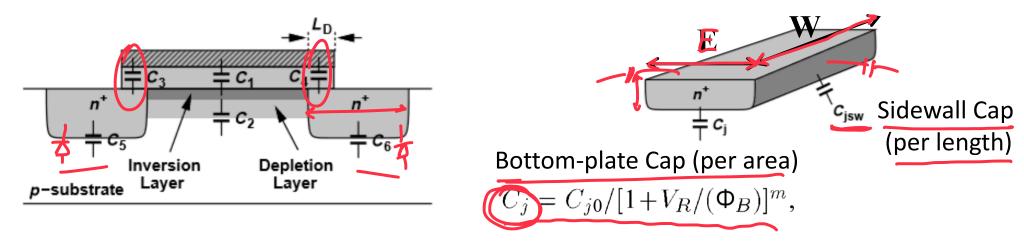
MOS Device Capacitances



- To better predict high-frequency behavior, it is necessary to consider device capacitances.
- Capacitance exists between every two of the four terminals, and their values depend on the bias conditions of the transistor.

MOS Device Capacitances





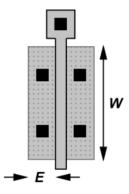
$$C_1 = WLC_{ox}$$
 $C_2 = WL\sqrt{q\epsilon_{si}N_{sub}/(4\Phi_F)}$

- Capacitances include
 - Oxide capacitance between the gate and the channel C₁.
 - Depletion capacitance between the channel and the substrate C₂.
 - Overlap capacitance between the gate & source/drain (C₃ and C₄).
 - Junction capacitance between the source/drain areas and the substrate C₅ and C₆.

MOS Device Capacitances (C_{DB}, C_{SB})

One "Finger"

Source Terminal



• For example calculating the source and drain junction capacitance of the topology on the left,

$$C_{DB} = C_{SB} = WEC_j + 2(W + E)C_{jsw}.$$

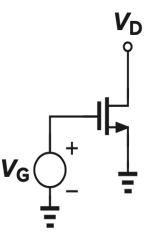
- We assumed the total source/drain perimeter 2(W+E) is multiplied by $C_{\rm isw}$.
- Calculating the source and drain junction capacitance of the second topology on the left,

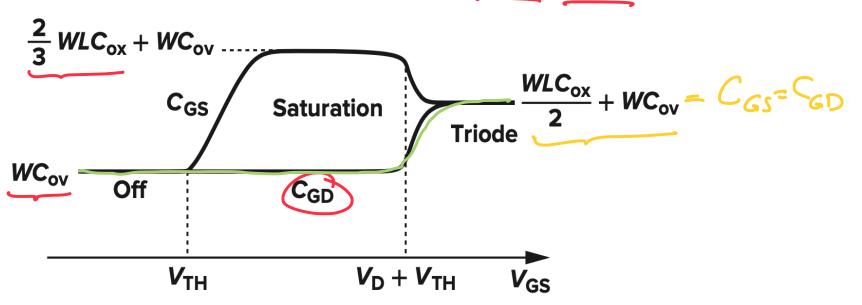
$$C_{DB} = \frac{W}{2}EC_j + 2\left(\frac{W}{2} + E\right)C_{jsw} \subset C_{DB} \text{ one fige}$$

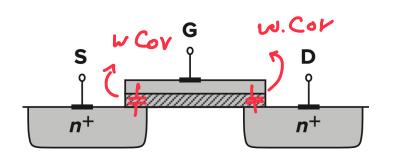
$$C_{SB} = 2\left[\frac{W}{2}EC_j + 2\left(\frac{W}{2} + E\right)C_{jsw}\right]$$

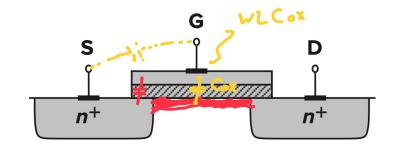
$$= WEC_j + 2(W + 2E)C_{jsw}. \subset SD \text{ one-fige}$$

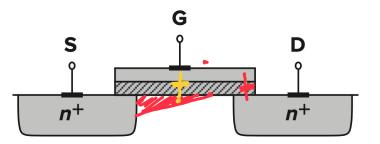
Example MOS Device Capacitances (C_{GS} , C_{GD}) $C_{GS} = 0.1$ C_{GS}











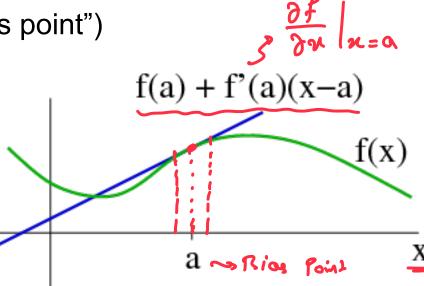






Small-signal (SS) Modeling

- Linear modeling (for AC analysis, etc.)
 - Easier to analyze circuit behavior
 - Using RLC, and voltage & current sources mapping, we can model/solve any circuit
- Linearizing a non-linear function (e.g., 1st-order Taylor series)
 - SS model depends on the operating point ("Bias point")



SS Modeling Example: Diode

$$v_{D} = V_{D} + v_{d}$$

$$v_{d} \ge r_{d}$$

$$v_{d$$

Figure 13.8 (a) Total diode terminal voltage and current. (b) Small signal model for the divide.

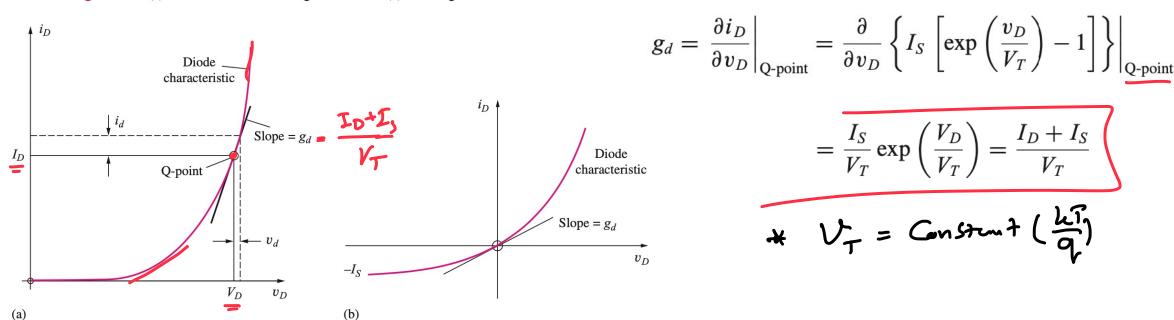


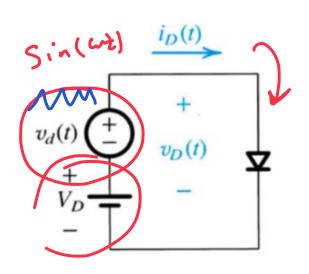
Figure 13.9 (a) The relationship between small increases in voltage and current above the diode operating point (I_D, V_D) . For small changes $i_d = g_d v_d$. (b) The diode conductance is not zero for $I_D = 0$.

ID = Is (e VO/VT-1)

 $i_c = I_s \left[\exp\left(\frac{v_{BE}}{V_T}\right) - 1 \right]$

 $i_c = g_m v_{be}$

Bias Point



$$e_{D}(t) = \frac{1}{2}$$
 Brias

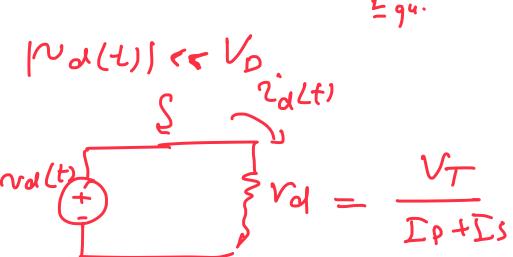
 $= \frac{1}{2} + \frac{1}{2}$ Convert.

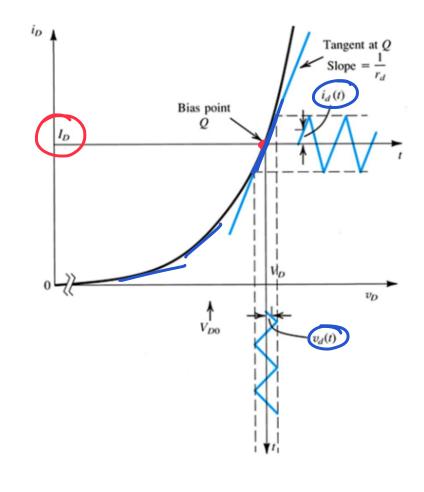
 $= \frac{1}{2} + \frac{1}{2}$ Convert.

Solve

 $= \frac{1}{2} + \frac{1}{2}$ No. (1)

 $= \frac{1}{2} + \frac{1}{2}$ No. (1)





Small-signal Modeling

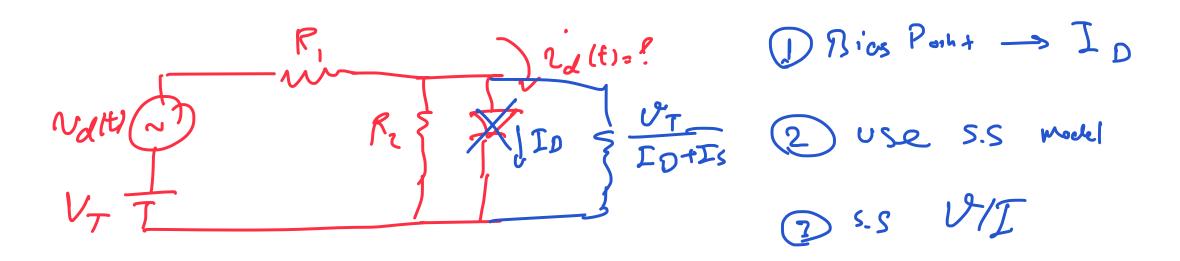
• For more complicated circuits (e.g., multiple devices), you can generate the SS model by either:

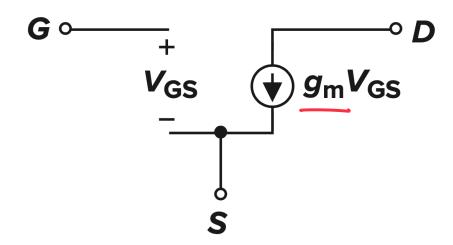
1. Calculate the overall I-V -> Linearize by taking the derivative

2. Replace each non-linear component with its SS model and then calculate the

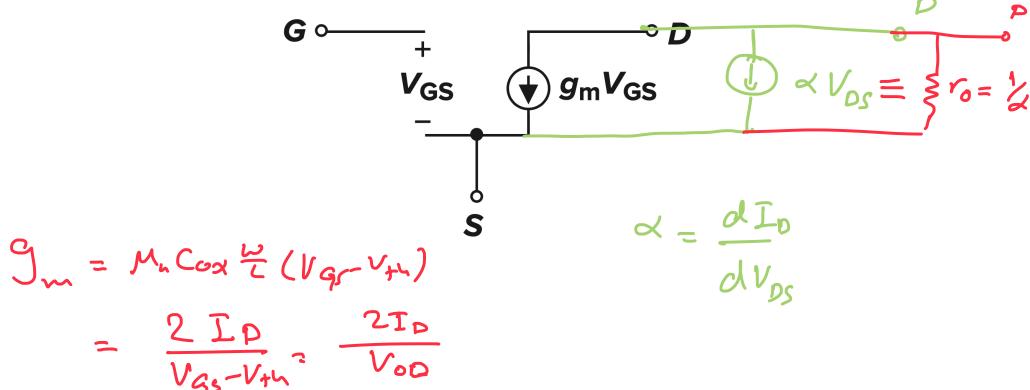
inear Mode

overall circuit model

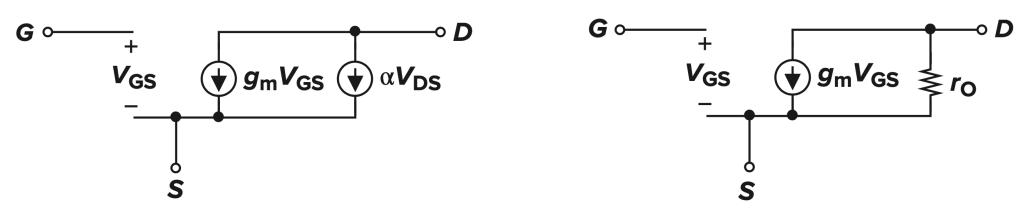




- If perturbation in bias conditions are small, a "small-signal" model can be used to simplify calculations (derived for saturation region).
- In order to derive the small-signal model, we
 - Apply certain bias voltages to the terminals of the device.
 - Increment the potential difference between two of the terminals while the other terminal voltages remain constant.
 - Measure the resulting change in all terminal currents.



- By changing the voltage between two terminals by $\Delta V = V_{GS}$ and then measuring a current change $\Delta I = g_m V_{GS}$, we can model the effect by a voltage-dependent current source.
- Above is the small-signal model of an ideal MOSFET.

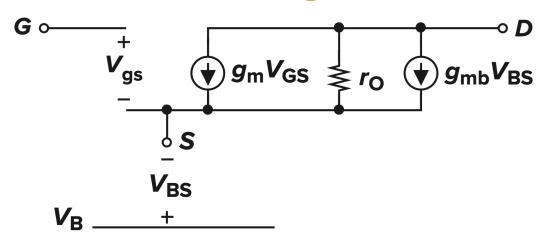


 Due to channel-length modulation, drain current also varies with V_{DS}, but a current source whose value linearly depends on the voltage across it is equivalent to a linear resistor:

$$r_{O} = \frac{\partial V_{DS}}{\partial I_{D}} = \frac{1}{\frac{\partial I_{D}}{\partial V_{DS}}} = \frac{1}{\frac{1}{2}\mu_{n}C_{ox}\frac{W}{L}(V_{GS} - V_{TH})^{2} \cdot \lambda}$$

$$\approx \frac{1 + \lambda V_{DS}}{\lambda I_{D}} \approx \frac{1}{\lambda I_{D}}$$
This account of that W_{CS} and W_{CS} and W_{CS} and W_{CS} and W_{CS} and W_{CS} are the standard form of the standard form

- It is assumed that $\lambda V_{DS} \ll 1$.
- r_o limits the maximum voltage gain of most amplifiers.

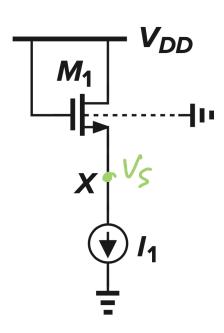


- Due to body effect, bulk potential influences V_{TH} and hence gate-source overdrive.
- With all other terminals held at a constant voltage, the bulk behaves as a second gate since the drain current is a function of the bulk voltage given by g_{mb}V_{BS}, where

$$g_{mb} = \frac{\partial I_D}{\partial V_{BS}} = \mu_n C_{ox} \frac{W}{L} (V_{GS} - V_{TH}) \left(-\frac{\partial V_{TH}}{\partial V_{BS}} \right).$$

$$\frac{\partial V_{TH}}{\partial V_{BS}} = -\frac{\partial V_{TH}}{\partial V_{SB}} = -\frac{\gamma}{2} (2\Phi_F + V_{SB})^{-1/2}.$$

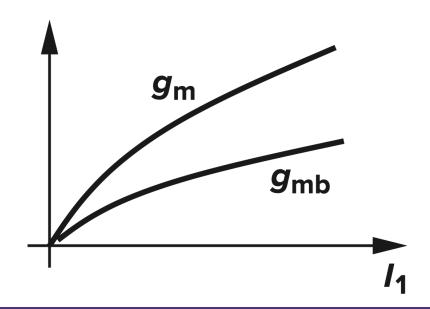
$$g_{mb} = g_m \frac{\gamma}{2\sqrt{2\Phi_F + V_{SB}}} = \eta g_m, \quad \eta = g_{mb}/g_m.$$

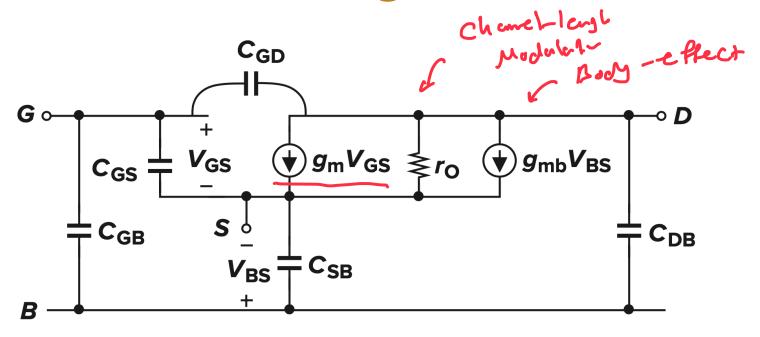


 To sketch g_m and g_{mb} of M₁ on the left as a function of bias current I₁,

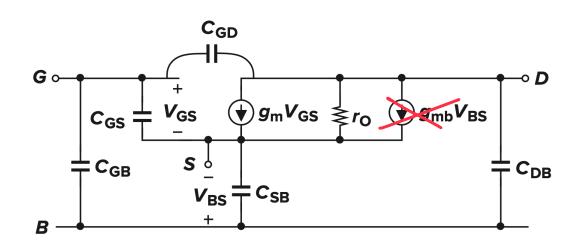
$$-g_m = \sqrt{2\mu_n C_{ox}(W/L)I_D} \implies g_m \propto \sqrt{I_1}$$

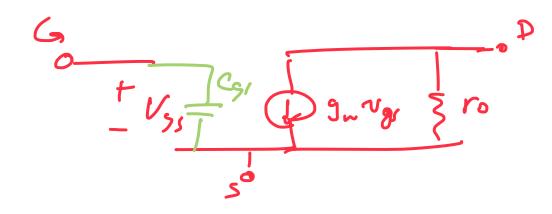
- g_{mb} dependence on I_1 is less straight forward, but as I_1 increases, V_X decreases and so does V_{SB} .

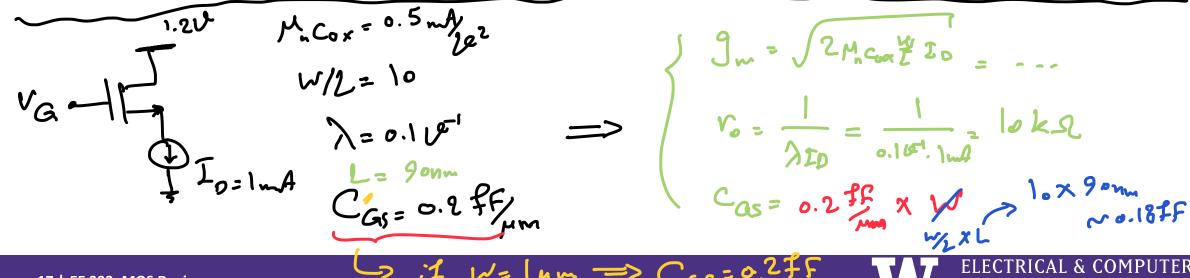


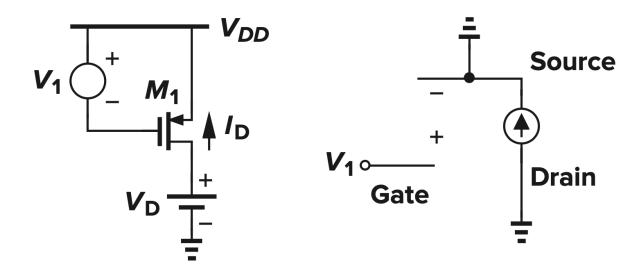


• The complete MOS small-signal model not only includes channel-length modulation and body effect, but also the capacitances between each terminal.









The derivation of the small-signal model for PMOS yields the <u>exact same model</u> as for NMOS.

• The model shows the voltage-dependent current source pointing *upward*, giving the (wrong) impression that the direction of the current in the PMOS is opposite of that in NMOS.

MOS Spice Models

Table 2.1 Level 1 SPICE models for NMOS and PMOS devices.

NMOS Model			
$\begin{aligned} LEVEL &= 1 \\ NSUB &= 9e{+}14 \\ TOX &= 9e{-}9 \\ MJ &= 0.45 \end{aligned}$	VTO = 0.7 LD = 0.08e-6 PB = 0.9 MJSW = 0.2	GAMMA = 0.45 $UO = 350$ $CJ = 0.56e-3$ $CGDO = 0.4e-9$	PHI = 0.9 LAMBDA = 0.1 CJSW = 0.35e-11 JS = 1.0e-8
PMOS Model			
LEVEL = 1 $NSUB = 5e+14$ $TOX = 9e-9$ $MJ = 0.5$	VTO = -0.8 LD = 0.09e-6 PB = 0.9 MJSW = 0.3	GAMMA = 0.4 $UO = 100$ $CJ = 0.94e-3$ $CGDO = 0.3e-9$	PHI = 0.8 $LAMBDA = 0.2$ $CJSW = 0.32e-11$ $JS = 0.5e-8$

- Simulators such as SPICE and Cadence need accurate models for each device.
- Above is the simplest MOS SPICE model, known as "Level 1," and provide typical values for each parameter corresponding to 0.5-µm technology.

NMOS versus PMOS Devices

- PMOS devices are quite inferior to NMOS in most CMOS technology.
- Lower mobility of holes $(\mu_p C_{ox} \approx 0.5 \mu_n C_{ox})$ yield lower current drive and conductance.
- NMOS exhibit higher output resistance, providing more ideal current sources and higher gain in amplifiers.
- As such is it preferred to incorporate NMOS rather than PMOS wherever possible.

Summary of Chapter 2 Topics