

## Lecture # 7 10/13/2021

Last time

- Finished Ch 2 and Cuk converter example  
s.s. analysis of ideal converters

Today

- Start Ch 3  
s.s. analysis w/ non-idealities
- Read over next 1 week

Logistics

- HW 1 solution posted
- HW 2 posted today, due Wed 10/20 11:59pm PT.

- Closing Thoughts on Cuk converter example:

Take stock:

Unknowns:  $I_1, I_2, V_1, V_2$  } can do a bunch of  
# of equations = 4 } algebra to solve for  
 $I_1, I_2, V_1, V_2$

After solving, we get:

$$V_1 = \frac{V_g}{D}$$

$$V_2 = -\frac{D}{D'} V_g$$

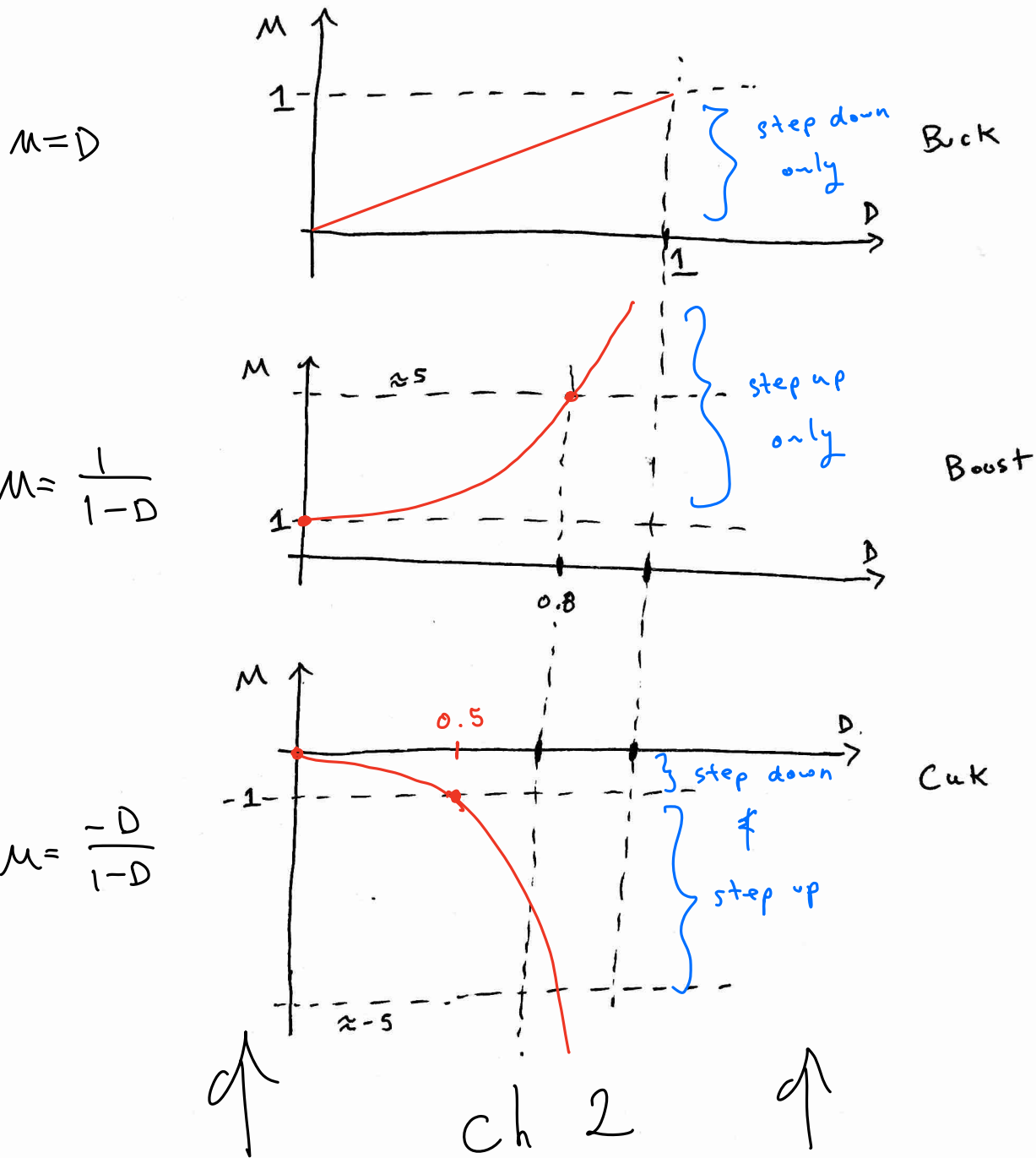
$$I_1 = -\frac{D}{D'} ( \dots )$$

$$I_2 = \left( \frac{D}{D'} \right)^2 \frac{V_g}{R}$$

Conversion Ratio?  $\checkmark$

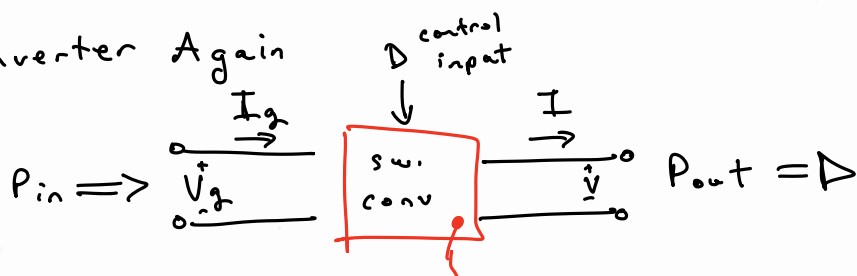
$$M(D) = \frac{V_2}{V_g} = -\frac{D}{1-D} \quad \left. \vphantom{\frac{V_2}{V_g}} \right\} \begin{array}{l} \text{similar/identical} \\ \text{buck boost} \end{array}$$

- Recap of some basic converters



↓ ch 3 ↓

- Ideal Converter Again



$$P_{in} = P_{out}$$

$$\Downarrow$$

$$V_g I_g = V I$$

}  $\Rightarrow$

efficiency

$$\eta = 1$$

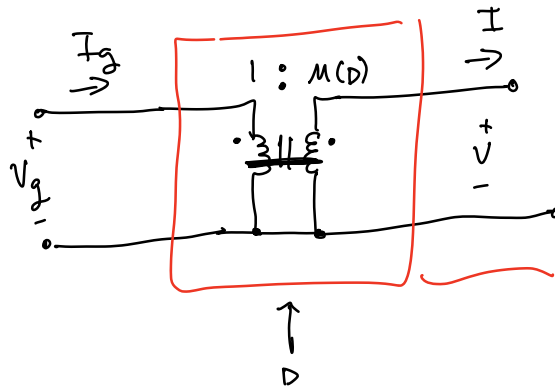
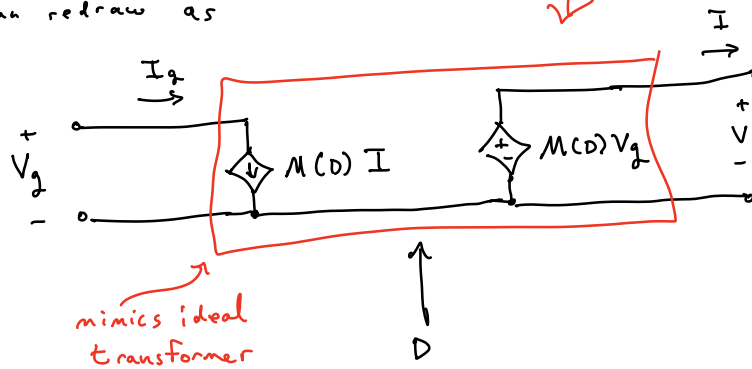
Greek symbol eta

$$\frac{V}{V_g} = M(D)$$

$$\frac{I_g}{I} = M(D)$$

ideal  
conversion  
ratios

Can redraw as

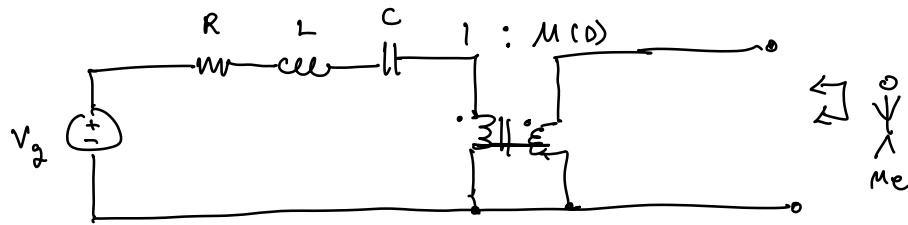


different from  
Unicorn xfmr: a real-world  
xfmr

- Adjustable
- Non-integer turns
- Passes dc power

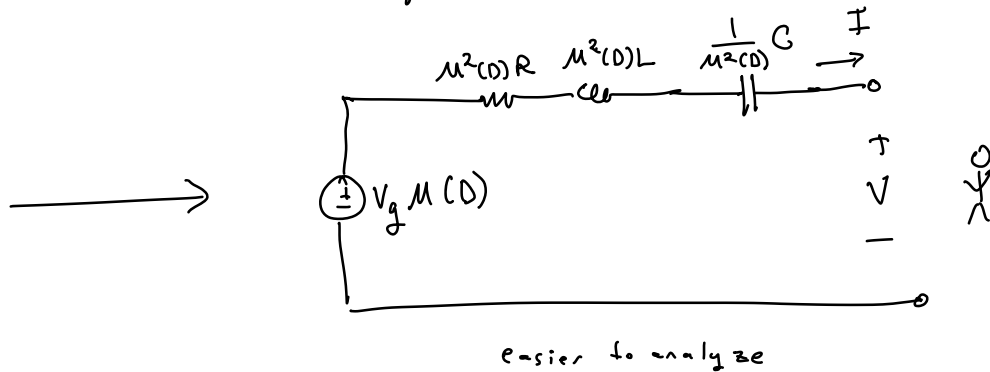
\* Ideal converter mimics an adjustable xfmr.

- Rules for "reflecting" ckt elements through a xfmr



Want equiv elements on other <sup>my</sup> side

Result after reflecting elements



→ scale by  $M(D)$



→ scale by  $M^2(D)$



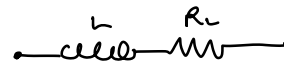
→ scale by  $\frac{1}{M^2(D)}$

# - Including Loss Mechanisms

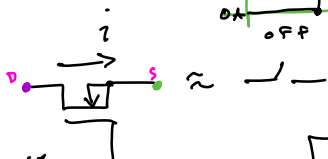
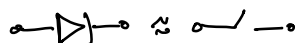
Ideal, ch2



Lossy, ch3



↑ winding resistance



n-channel symbol



↑ often dominates losses

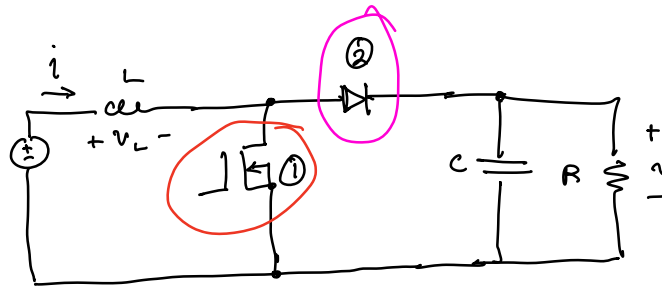
↑ forward drop

↑ often dominates losses



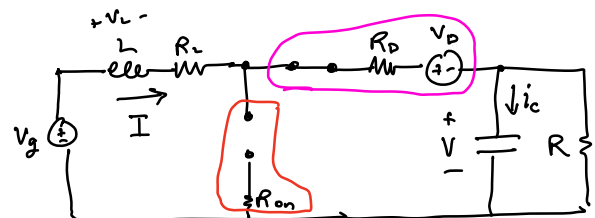
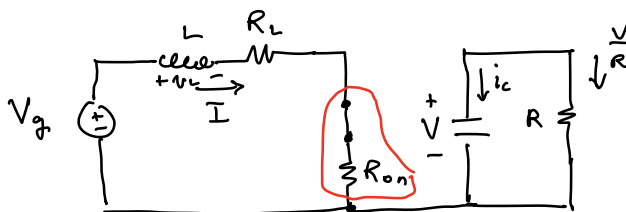
Repeat ch2 w/ lossy elements above.

## - Boost Convert Model w/ Losses



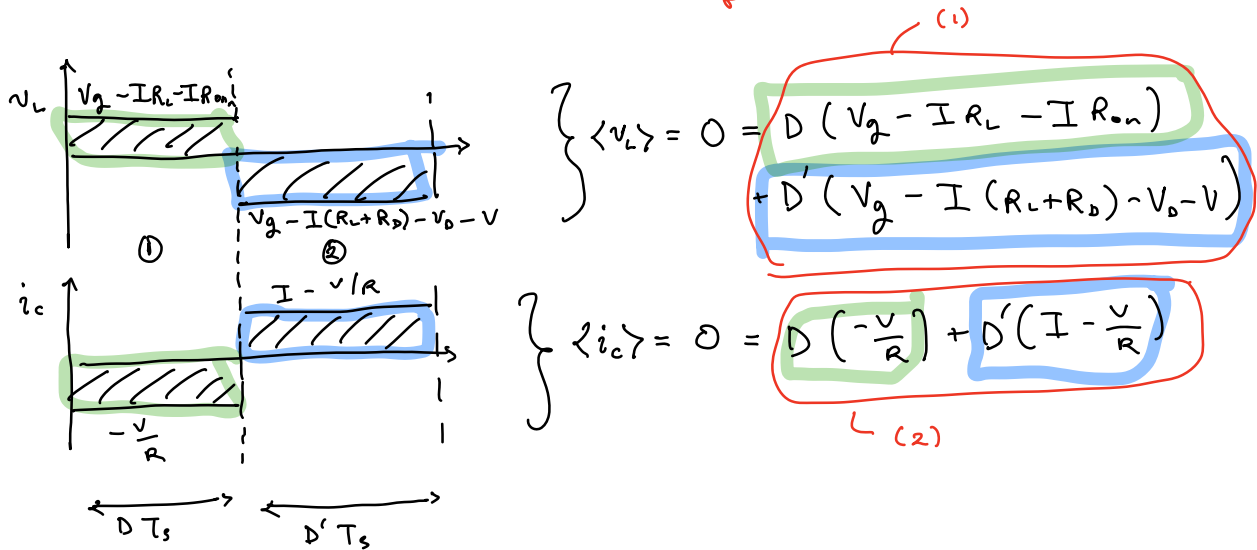
config ①

config ②



Look @ balance eqns

Goal is to compute  $V$  &  $I$ . 2 unknowns w/ 2 equations.



clean up (1)

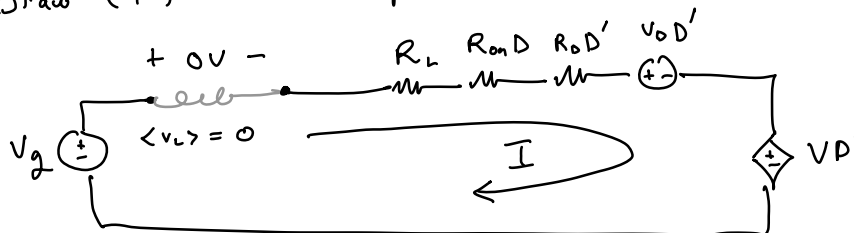
$$0 = V_g D - I R_L D - I R_{on} D + V_g - V_g D - I(R_L + R_d) + I(R_L + R_d) D - V_b + V_b D - V + V D = V_g - I R_L - I R_{on} D - I R_d D' - V_b D' - V D' = 0 \quad (1')$$

and (2)

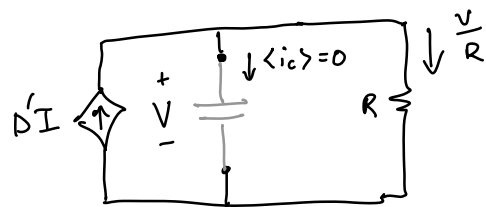
$$0 = -\frac{V}{R} D + I D' - \frac{V}{R} + \frac{V}{R} D$$

$$= I D' - \frac{V}{R} = 0 \quad (2')$$

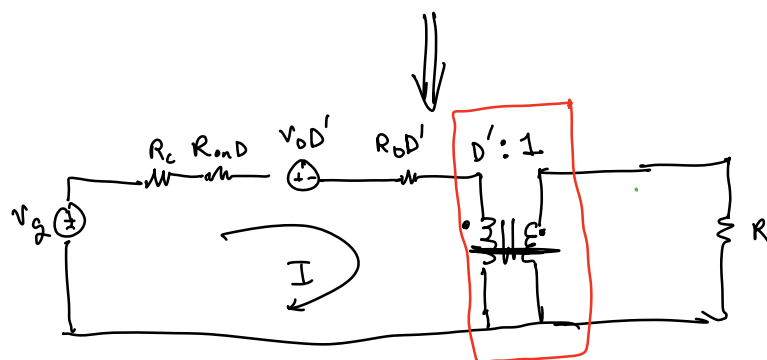
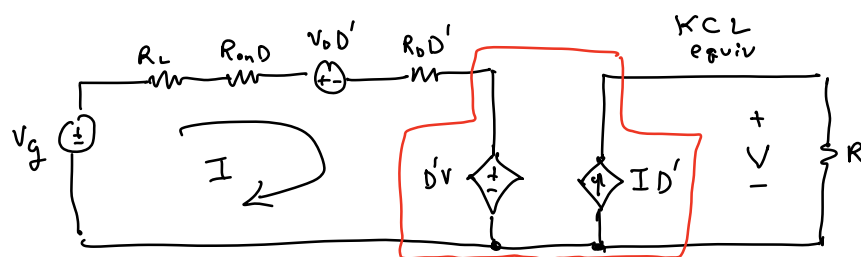
Draw (1') KVL loop



Draw (2') KCL



- Combine into 2 coupled ckt's



Next, we will  
push  $R$  to  
LHS.

can apply ckt tricks to solve this  
& get  $V, I$