

Biologically-Constrained Parameter Reduction for 5-Species Biofilm Model

Keisuke Nishioka

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Abstract

This document describes the Proposed Method, a parameter reduction technique for Bayesian estimation of the 5-species biofilm interaction model. By incorporating biological knowledge from experimentally determined interaction networks, the algorithm reduces the parameter space from 20 to 15 free parameters, improving estimation efficiency and biological interpretability.

Keywords: Bayesian Estimation, Biofilm, Parameter Reduction, TMCMC, Biological Constraints, Multi-species Interaction, Inverse Problem, Peri-implantitis, Uncertainty Quantification

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1 Introduction

Understanding the dynamics of multi-species biofilms is crucial for the prevention and treatment of oral diseases. Heine et al. [1] investigated the interactions of five major oral bacterial species associated with peri-implantitis. Based on these experimental findings and the extended Hamilton principle proposed by Junker and Balzani [2], Klempt et al. [3] developed a continuum model for multi-species biofilms with a novel interaction scheme. Furthermore, Fritsch et al. [4] discussed Bayesian updating methods for bacterial microfilms under hybrid uncertainties using a novel surrogate model.

The 5-species biofilm model describes the dynamics of bacterial populations through an interaction matrix \mathbf{A} and decay vector \mathbf{b} . However, the standard parameter estimation approach estimates all 20 parameters freely, which can lead to:

- Poor identifiability due to limited experimental data
- Biologically implausible parameter estimates
- Computational inefficiency from exploring unnecessary parameter space

The Proposed Method addresses these issues by constraining certain interaction parameters to zero based on experimental evidence of absent species interactions.

2 Biological Basis

2.1 Species in the Model

The model includes five bacterial species commonly found in oral biofilms:

ID	Species	Abbrev.	Role
0	<i>Streptococcus oralis</i>	S.o	Early colonizer
1	<i>Actinomyces naeslundii</i>	A.n	Early colonizer
2	<i>Veillonella</i> spp.	Vei	Metabolic bridge
3	<i>Fusobacterium nucleatum</i>	F.n	Bridge organism
4	<i>Porphyromonas gingivalis</i>	P.g	Late colonizer (pathogen)

Table 1: Species included in the 5-species biofilm model.

2.2 Interaction Network (Figure 4C)

Based on experimental observations [1], the following interaction network was established:

2.3 Active Interactions

The following species pairs have direct biological interactions:

2.4 Absent Interactions (Locked)

The following species pairs have no direct interaction according to experimental evidence (Figure 4C). These are locked to zero ($\theta_k = 0$) in the Proposed Method:

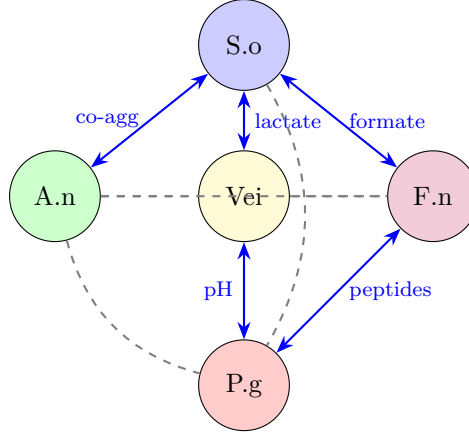


Figure 1: Species interaction network derived from Figure 4C. Solid blue arrows indicate active interactions (estimated parameters). Dashed gray lines indicate absent interactions (locked to zero).

Species Pair	Mechanism	Type
S. oralis \leftrightarrow A. naeslundii	Co-aggregation	Bidirectional
S. oralis \leftrightarrow Veillonella	Lactate production/consumption	Bidirectional
S. oralis \leftrightarrow F. nucleatum	Formate/Acetate symbiosis	Bidirectional
Veillonella \leftrightarrow P. gingivalis	pH rise support	Positive only
F. nucleatum \leftrightarrow P. gingivalis	Co-aggregation, peptides	Bidirectional

Table 2: Active species interactions with biological mechanisms.

3 Mathematical Formulation

3.1 Governing Equations

The 5-species biofilm model describes the dynamics of bacterial volume fractions ϕ_i and viability fractions ψ_i through a coupled ODE system. The interaction term for species i is:

$$I_i = \sum_{j=0}^4 A_{ij} \phi_j \psi_j \quad (1)$$

where A_{ij} represents the effect of species j on species i , and $\phi_j \psi_j$ is the living bacteria volume fraction.

3.2 Symmetric Matrix Assumption

Critical assumption: The interaction matrix \mathbf{A} is symmetric:

$$A_{ij} = A_{ji} \quad \forall i, j \in \{0, 1, 2, 3, 4\} \quad (2)$$

This reduces the number of off-diagonal interaction parameters from 20 to 10. For example, the lactate handover interaction between S. oralis (species 0) and Veillonella (species 2) is represented by a single parameter:

$$A_{02} = A_{20} = \theta_{10} \quad (\text{stored as } a_{13} \text{ in code}) \quad (3)$$

Index	Param	Species Pair	Matrix	Biological Reason
6	a_{34}	Vei (2) \leftrightarrow F.n (3)	$A[2, 3] = A[3, 2]$	No direct metabolic pathway
12	a_{23}	A.n (1) \leftrightarrow Vei (2)	$A[1, 2] = A[2, 1]$	No direct metabolic link
13	a_{24}	A.n (1) \leftrightarrow F.n (3)	$A[1, 3] = A[3, 1]$	No direct interaction
16	a_{15}	S.o (0) \leftrightarrow P.g (4)	$A[0, 4] = A[4, 0]$	No direct interaction
17	a_{25}	A.n (1) \leftrightarrow P.g (4)	$A[1, 4] = A[4, 1]$	No direct interaction

Table 3: Absent interactions locked to zero in the Proposed Method. Numbers in parentheses are 0-indexed species IDs.

3.3 Parameter Vector Definition

The full 20-parameter vector $\theta = (\theta_0, \theta_1, \dots, \theta_{19})^T$ is organized into five blocks corresponding to the model structure:

$$\begin{aligned}
\theta = & \underbrace{(a_{11}, a_{12}, a_{22}, b_1, b_2)}_{\text{M1: Species 1-2}} \oplus \underbrace{(a_{33}, a_{34}, a_{44}, b_3, b_4)}_{\text{M2: Species 3-4}} \\
& \oplus \underbrace{(a_{13}, a_{14}, a_{23}, a_{24})}_{\text{M3: Cross 1-2 vs 3-4}} \oplus \underbrace{(a_{55}, b_5)}_{\text{M4: Species 5}} \oplus \underbrace{(a_{15}, a_{25}, a_{35}, a_{45})}_{\text{M5: Cross with Species 5}}
\end{aligned} \tag{4}$$

where a_{ij} denotes the interaction coefficient affecting species i from species j , and b_i is the decay rate of species i . Species are 1-indexed in notation (a_{ij}) but 0-indexed in code ($A[i - 1, j - 1]$).

3.4 Complete Parameter Mapping

Table 4 provides the authoritative mapping between parameter indices, matrix elements, and biological interpretation.

3.5 Locked Parameter Indices

The Proposed Method defines the set of locked indices based on absent biological interactions:

$$\mathcal{L} = \{6, 12, 13, 16, 17\} \tag{5}$$

For all $k \in \mathcal{L}$:

$$\theta_k = 0 \quad (\text{fixed, not estimated}) \tag{6}$$

3.6 Prior Bounds

The **base** prior distribution (for Commensal/Dysbiotic Static conditions) is:

$$\theta_k \sim \begin{cases} \text{Uniform}(0, 0) & \text{if } k \in \mathcal{L} \text{ (locked)} \\ \text{Uniform}(0, 1) & \text{if } k = 18 \text{ (Vei} \rightarrow \text{P.g, positive cooperation)} \\ \text{Uniform}(-1, 1) & \text{otherwise (free)} \end{cases} \tag{7}$$

Important: For the Dysbiotic HOBIC condition (“Surge” reproduction), the bounds for index 18 are modified to allow strong negative values:

$$\theta_{18} \sim \text{Uniform}(-3, -1) \quad (\text{Dysbiotic HOBIC only}) \tag{8}$$

This reflects the strong cooperative effect from Veillonella to P. gingivalis required to drive the pathogen surge.

Index	Name	Matrix Element	Species Pair	Biological Role	Status
0	a_{11}	$A[0, 0]$	S.o self	Self-regulation	Free
1	a_{12}	$A[0, 1] = A[1, 0]$	S.o \leftrightarrow A.n	Co-aggregation	Free
2	a_{22}	$A[1, 1]$	A.n self	Self-regulation	Free
3	b_1	$b[0]$	S.o	Decay rate	Free
4	b_2	$b[1]$	A.n	Decay rate	Free
5	a_{33}	$A[2, 2]$	Vei self	Self-regulation	Free
6	a_{34}	$A[2, 3] = A[3, 2]$	Vei \leftrightarrow F.n	<i>No interaction</i>	Locked
7	a_{44}	$A[3, 3]$	F.n self	Self-regulation	Free
8	b_3	$b[2]$	Vei	Decay rate	Free
9	b_4	$b[3]$	F.n	Decay rate	Free
10	a_{13}	$A[0, 2] = A[2, 0]$	S.o \leftrightarrow Vei	Lactate handover	Free
11	a_{14}	$A[0, 3] = A[3, 0]$	S.o \leftrightarrow F.n	Formate symbiosis	Free
12	a_{23}	$A[1, 2] = A[2, 1]$	A.n \leftrightarrow Vei	<i>No interaction</i>	Locked
13	a_{24}	$A[1, 3] = A[3, 1]$	A.n \leftrightarrow F.n	<i>No interaction</i>	Locked
14	a_{55}	$A[4, 4]$	P.g self	Self-regulation	Free
15	b_5	$b[4]$	P.g	Decay rate	Free
16	a_{15}	$A[0, 4] = A[4, 0]$	S.o \leftrightarrow P.g	<i>No interaction</i>	Locked
17	a_{25}	$A[1, 4] = A[4, 1]$	A.n \leftrightarrow P.g	<i>No interaction</i>	Locked
18	a_{35}	$A[2, 4] = A[4, 2]$	Vei \leftrightarrow P.g	pH trigger	Free*
19	a_{45}	$A[3, 4] = A[4, 3]$	F.n \leftrightarrow P.g	Co-aggregation	Free

Table 4: Complete parameter mapping from θ vector to interaction matrix \mathbf{A} and decay vector \mathbf{b} . Red rows indicate locked parameters ($\theta_k = 0$). *Index 18 bounds vary by condition (see Section 6).

3.7 Effective Parameter Space

The effective number of free parameters is:

$$n_{\text{free}} = 20 - |\mathcal{L}| = 20 - 5 = 15 \quad (9)$$

In the original continuum formulation by Klempt et al. [3], a diagonal viscosity matrix $\boldsymbol{\eta} = \text{diag}(\eta_1, \dots, \eta_5)$ appears in the dissipation functional and controls how fast each species reacts to changes in nutrient availability and inter-species competition. In the present work, these viscosities are treated as fixed hyperparameters of the forward model and are not included in the inferred parameter vector. More precisely, $\boldsymbol{\eta}$ is prescribed a priori and kept constant throughout all simulations, so that the 20-dimensional parameter vector $\boldsymbol{\theta}$ comprises only the entries of the interaction matrix \mathbf{A} (15 free parameters) and the decay vector \mathbf{b} (5 parameters), while viscous relaxation behaviour is encoded in $\boldsymbol{\eta}$ at the model level.

4 Bayesian Inference Framework

4.1 Forward Model

The forward model $\mathcal{M}(\boldsymbol{\theta})$ maps the parameter vector $\boldsymbol{\theta} \in \mathbb{R}^{20}$ to predicted species trajectories. Given initial conditions $\boldsymbol{\phi}(t_0)$ and $\boldsymbol{\psi}(t_0)$, the coupled ODE system derived from the extended Hamilton principle [2, 3] governs the evolution of the living volume fraction $\phi_i \psi_i$ for each species i :

$$\frac{d(\phi_i \psi_i)}{dt} = \left(A_{ii} + \sum_{j \neq i} A_{ij} \phi_j \psi_j \right) \phi_i \psi_i - b_i \phi_i \psi_i, \quad i = 0, \dots, 4 \quad (10)$$

where the first term represents growth modulated by self-regulation (A_{ii}) and inter-species interactions (A_{ij} , $j \neq i$), while the second term accounts for species decay at rate b_i . The interaction matrix \mathbf{A} and decay vector \mathbf{b} are constructed from $\boldsymbol{\theta}$ via the mapping defined in Table 4. The forward model output is the predicted relative abundance vector at each observation time:

$$\hat{\mathbf{y}}(t_k; \boldsymbol{\theta}) = \mathcal{M}(\boldsymbol{\theta})|_{t=t_k}, \quad k = 1, \dots, N_t \quad (11)$$

The system (10) represents a generalized Lotka–Volterra competition model with symmetric interactions, a structure that arises naturally from the variational formulation of Klempt et al. [3].

In the original formulation of Klempt et al. [3], the growth matrix \mathbf{A} is explicitly scaled by the nutrient variable c^* , and antibiotic effects enter through the antibiotic concentration α^* and a sensitivity matrix \mathbf{B} . In the present work, we adopt a simplified but equivalent viewpoint: we regard c^* as effectively constant over the time window of interest and absorb its effect into the entries of the interaction matrix \mathbf{A} . Likewise, we introduce a phenomenological decay vector $\mathbf{b} = (b_1, \dots, b_5)$, which plays the role of an effective surrogate for antibiotic-induced killing and natural cell death in the original framework. As a result, the parameters \mathbf{A} and \mathbf{b} estimated by TMCMC should be interpreted as effective interaction and decay coefficients under the given experimental condition, rather than as direct microscopic counterparts of the variables c^* , α^* , and \mathbf{B} .

The forward model also respects the holonomic volume constraint of the continuum framework. The evolution equations are solved for the bacterial volume fractions ϕ_i ($i = 1, \dots, 5$), and the void fraction ϕ_0 is reconstructed at each time step via

$$\phi_0(t) = 1 - \sum_{i=1}^5 \phi_i(t), \quad (12)$$

so that

$$\sum_{\ell=0}^5 \phi_\ell(t) = 1 \quad (13)$$

holds by construction for all t .

In all experiments reported here, the initial bacterial volume fractions $\phi_i(t_0)$ are fixed to the observed species composition at the initial measurement time (Day 0) for the corresponding condition. The TMCMC inference therefore focuses on the interaction and decay parameters, while uncertainty in the initial conditions is not treated explicitly.

4.2 Bayesian Inverse Problem

The goal of Bayesian parameter estimation is to infer the posterior distribution $p(\boldsymbol{\theta} \mid \mathbf{y}_{\text{obs}})$ of the model parameters $\boldsymbol{\theta}$ given the observed experimental data $\mathbf{y}_{\text{obs}} = \{y_{\text{obs},i}(t_k)\}_{i,k}$. By Bayes' theorem:

$$p(\boldsymbol{\theta} \mid \mathbf{y}_{\text{obs}}) = \frac{p(\mathbf{y}_{\text{obs}} \mid \boldsymbol{\theta}) p(\boldsymbol{\theta})}{p(\mathbf{y}_{\text{obs}})} \quad (14)$$

where $p(\mathbf{y}_{\text{obs}} \mid \boldsymbol{\theta})$ is the likelihood function quantifying the data-model agreement, $p(\boldsymbol{\theta})$ is the prior distribution encoding biological constraints, and $p(\mathbf{y}_{\text{obs}}) = \int p(\mathbf{y}_{\text{obs}} \mid \boldsymbol{\theta}) p(\boldsymbol{\theta}) d\boldsymbol{\theta}$ is the model evidence (normalizing constant). The posterior distribution captures the full uncertainty in the parameter estimates, from which point estimates such as the Maximum A Posteriori (MAP) and posterior mean can be derived:

$$\hat{\boldsymbol{\theta}}_{\text{MAP}} = \arg \max_{\boldsymbol{\theta}} p(\boldsymbol{\theta} \mid \mathbf{y}_{\text{obs}}), \quad \hat{\boldsymbol{\theta}}_{\text{mean}} = \mathbb{E}[\boldsymbol{\theta} \mid \mathbf{y}_{\text{obs}}] = \int \boldsymbol{\theta} p(\boldsymbol{\theta} \mid \mathbf{y}_{\text{obs}}) d\boldsymbol{\theta} \quad (15)$$

4.3 Likelihood Function

Assuming independent Gaussian measurement errors across species and time points, the likelihood function takes the form:

$$p(\mathbf{y}_{\text{obs}} | \boldsymbol{\theta}) = \prod_{k=1}^{N_t} \prod_{i=0}^4 \frac{1}{\sqrt{2\pi} \sigma_i} \exp\left(-\frac{(y_{\text{obs},i}(t_k) - \hat{y}_i(t_k; \boldsymbol{\theta}))^2}{2\sigma_i^2}\right) \quad (16)$$

where $y_{\text{obs},i}(t_k)$ is the observed relative abundance of species i at time t_k , $\hat{y}_i(t_k; \boldsymbol{\theta})$ is the model prediction, and σ_i is the measurement noise standard deviation for species i . The corresponding log-likelihood is:

$$\ell(\boldsymbol{\theta}) = -\frac{1}{2} \sum_{k=1}^{N_t} \sum_{i=0}^4 \left[\frac{(y_{\text{obs},i}(t_k) - \hat{y}_i(t_k; \boldsymbol{\theta}))^2}{\sigma_i^2} + \log(2\pi\sigma_i^2) \right] \quad (17)$$

In practice, σ_i may be estimated from replicate measurements or treated as a hyperparameter. In this study, we adopt the latter viewpoint and prescribe σ_i a priori as a fixed fraction of the observed range of species i in the experimental data, reflecting the expected measurement uncertainty. The noise levels σ_i are thus kept fixed during TMCMC and are not inferred jointly with $\boldsymbol{\theta}$.

4.4 Prior Distribution with Biological Constraints

The prior distribution $p(\boldsymbol{\theta})$ encodes both the biological constraints from the interaction network and the parameter locking mechanism. Assuming independence among the prior marginals:

$$p(\boldsymbol{\theta}) = \prod_{k=0}^{19} p(\theta_k) \quad (18)$$

where each marginal prior is:

$$p(\theta_k) = \begin{cases} \delta(\theta_k) & \text{if } k \in \mathcal{L} \quad (\text{Dirac delta: locked to zero}) \\ \frac{1}{u_k - l_k} \mathbf{1}_{[l_k, u_k]}(\theta_k) & \text{if } k \notin \mathcal{L} \quad (\text{uniform prior on free parameter}) \end{cases} \quad (19)$$

Here $\delta(\cdot)$ denotes the Dirac delta function enforcing $\theta_k = 0$ for locked parameters, and $\mathbf{1}_{[l_k, u_k]}$ is the indicator function on $[l_k, u_k]$. This formulation is equivalent to restricting the posterior to the constrained subspace:

$$\Theta_{\mathcal{L}} = \left\{ \boldsymbol{\theta} \in \mathbb{R}^{20} : \theta_k = 0 \quad \forall k \in \mathcal{L} \right\} \quad (20)$$

In practice, the inference is performed over the reduced vector $\boldsymbol{\theta}_{\text{free}} \in \mathbb{R}^{n_{\text{free}}}$ containing only the free parameters, while locked parameters remain fixed at zero throughout. The dimension reduction from \mathbb{R}^{20} to $\mathbb{R}^{n_{\text{free}}}$ directly improves the sampling efficiency of MCMC methods, as the mixing time of Markov chains generally increases with dimensionality [5].

5 Transitional Markov Chain Monte Carlo (TMCMC)

5.1 Algorithm Overview

The Transitional Markov Chain Monte Carlo (TMCMC) algorithm, introduced by Ching and Chen [6], is a sequential Monte Carlo method designed for sampling from complex, potentially multimodal posterior distributions. Unlike standard MCMC methods (e.g., Metropolis–Hastings, Gibbs sampling) that may suffer from poor mixing in high-dimensional or multimodal

spaces, TMCMC progressively transforms samples from the prior to the posterior through a sequence of intermediate “tempered” distributions [7].

The key idea is to define a tempering schedule $0 = \beta_0 < \beta_1 < \dots < \beta_M = 1$ and construct a sequence of intermediate distributions:

$$p_m(\boldsymbol{\theta}) \propto p(\mathbf{y}_{\text{obs}} \mid \boldsymbol{\theta})^{\beta_m} p(\boldsymbol{\theta}), \quad m = 0, 1, \dots, M \quad (21)$$

At $\beta_0 = 0$, $p_0(\boldsymbol{\theta}) = p(\boldsymbol{\theta})$ reduces to the prior, and at $\beta_M = 1$, $p_M(\boldsymbol{\theta}) = p(\boldsymbol{\theta} \mid \mathbf{y}_{\text{obs}})$ recovers the full posterior. By introducing the likelihood gradually, the algorithm avoids the “prior–posterior gap” that causes standard importance sampling to fail when the prior and posterior are far apart.

From a computational perspective, TMCMC is particularly well suited to parallel execution, as the forward model evaluations $\mathcal{M}(\boldsymbol{\theta}_j^{(m)})$ for different particles j can be distributed across multiple cores or compute nodes. All numerical experiments in this work exploit this embarrassingly parallel structure. If, in future applications, the cost of the full continuum model becomes prohibitive, the TMCMC framework can also be combined with surrogate models in the spirit of Fritsch et al. [4], replacing some forward solves by a trained reduced-order approximation.

5.2 Adaptive Tempering Schedule

At each stage m , the next tempering parameter β_{m+1} is selected adaptively to control the degeneracy of the importance weights. Following Betz et al. [8], β_{m+1} is chosen such that the coefficient of variation (CoV) of the importance weights satisfies:

$$\text{CoV}[\{w_j^{(m)}\}_{j=1}^N] = \frac{\text{Std}[w_j^{(m)}]}{\text{Mean}[w_j^{(m)}]} = \delta_{\text{target}} \quad (22)$$

where the importance weights are computed as:

$$w_j^{(m)} = p(\mathbf{y}_{\text{obs}} \mid \boldsymbol{\theta}_j^{(m)})^{\beta_{m+1} - \beta_m}, \quad j = 1, \dots, N \quad (23)$$

and $\delta_{\text{target}} \in (0, 2]$ is a user-specified target (typically $\delta_{\text{target}} = 1.0$). Equation (22) is solved for β_{m+1} via bisection on $(\beta_m, 1]$. This adaptive scheme avoids the need for a predetermined number of stages M and ensures smooth transitions between intermediate distributions.

5.3 Resampling and MCMC Mutation

At each stage m , the algorithm proceeds through three steps:

1. **Resampling:** Draw N samples from the current population $\{\boldsymbol{\theta}_j^{(m)}\}_{j=1}^N$ with probabilities proportional to the normalized importance weights $\bar{w}_j^{(m)} = w_j^{(m)} / \sum_{l=1}^N w_l^{(m)}$, using multinomial or systematic resampling.
2. **Covariance estimation:** Compute the weighted sample covariance matrix:

$$\boldsymbol{\Sigma}^{(m)} = \sum_{j=1}^N \bar{w}_j^{(m)} (\boldsymbol{\theta}_j^{(m)} - \bar{\boldsymbol{\theta}}^{(m)}) (\boldsymbol{\theta}_j^{(m)} - \bar{\boldsymbol{\theta}}^{(m)})^T \quad (24)$$

where $\bar{\boldsymbol{\theta}}^{(m)} = \sum_{j=1}^N \bar{w}_j^{(m)} \boldsymbol{\theta}_j^{(m)}$ is the weighted mean. This covariance adaptively scales the MCMC proposal to the local geometry of the tempered posterior.

3. **MCMC mutation:** Each resampled particle undergoes one or more Metropolis–Hastings steps with a Gaussian proposal:

$$q(\boldsymbol{\theta}^* | \boldsymbol{\theta}_j) = \mathcal{N}(\boldsymbol{\theta}_j, \gamma^2 \boldsymbol{\Sigma}^{(m)}) \quad (25)$$

where $\gamma > 0$ is a scaling factor (typically $\gamma^2 = 0.04$). The acceptance probability is:

$$\alpha = \min\left(1, \frac{p(\mathbf{y}_{\text{obs}} | \boldsymbol{\theta}^*)^{\beta_{m+1}} p(\boldsymbol{\theta}^*)}{p(\mathbf{y}_{\text{obs}} | \boldsymbol{\theta}_j)^{\beta_{m+1}} p(\boldsymbol{\theta}_j)}\right) \quad (26)$$

This mutation step diversifies the particle population and prevents sample impoverishment.

5.4 TMCMC Procedure

The complete TMCMC procedure with biological constraint enforcement is summarized in Algorithm 2.

Algorithm 1: Transitional Markov Chain Monte Carlo (TMCMC)

Input: Prior $p(\boldsymbol{\theta})$, likelihood $p(\mathbf{y}_{\text{obs}} | \boldsymbol{\theta})$, number of particles N , locked set \mathcal{L} , target CoV δ_{target}

Output: Weighted posterior samples $\{\boldsymbol{\theta}_j^{(M)}\}_{j=1}^N$

1. **Initialize:** Draw $\{\boldsymbol{\theta}_j^{(0)}\}_{j=1}^N \sim p(\boldsymbol{\theta})$; set $\beta_0 = 0$, $m = 0$
2. **While** $\beta_m < 1$:
 - (a) Find $\beta_{m+1} \in (\beta_m, 1]$ such that $\text{CoV}[\{w_j^{(m)}\}] = \delta_{\text{target}}$ via bisection
 - (b) Compute weights $w_j^{(m)} = p(\mathbf{y}_{\text{obs}} | \boldsymbol{\theta}_j^{(m)})^{\beta_{m+1} - \beta_m}$ for $j = 1, \dots, N$
 - (c) Compute weighted covariance $\boldsymbol{\Sigma}^{(m)}$ from current samples
 - (d) Resample N particles from $\{\boldsymbol{\theta}_j^{(m)}\}$ with probabilities $\propto w_j^{(m)}$
 - (e) **For each** resampled particle $j = 1, \dots, N$:
 - i. Propose $\boldsymbol{\theta}^* \sim \mathcal{N}(\boldsymbol{\theta}_j, \gamma^2 \boldsymbol{\Sigma}^{(m)})$
 - ii. Enforce constraints: set $\theta_k^* = 0$ for $k \in \mathcal{L}$; clip to prior bounds $[l_k, u_k]$
 - iii. Accept $\boldsymbol{\theta}_j^{(m+1)} = \boldsymbol{\theta}^*$ with probability α (Eq. 26); otherwise retain $\boldsymbol{\theta}_j^{(m+1)} = \boldsymbol{\theta}_j$
 - (f) $m \leftarrow m + 1$
3. **Return** posterior samples $\{\boldsymbol{\theta}_j^{(M)}\}_{j=1}^N$

Figure 2: TMCMC algorithm with biological constraint enforcement. Step 2(e)(ii) ensures that locked parameters remain at zero and all free parameters respect their condition-specific prior bounds throughout the sampling process.

5.5 Model Evidence Estimation

A valuable byproduct of TMCMC is an unbiased estimate of the model evidence $p(\mathbf{y}_{\text{obs}})$, computed as:

$$\hat{p}(\mathbf{y}_{\text{obs}}) = \prod_{m=0}^{M-1} \left(\frac{1}{N} \sum_{j=1}^N w_j^{(m)} \right) \quad (27)$$

This quantity enables Bayesian model comparison between the standard (20-parameter) and proposed (15-parameter) formulations via the Bayes factor:

$$B_{10} = \frac{p(\mathbf{y}_{\text{obs}} \mid \mathcal{M}_{\text{proposed}})}{p(\mathbf{y}_{\text{obs}} \mid \mathcal{M}_{\text{standard}})} \quad (28)$$

A Bayes factor $B_{10} > 1$ provides evidence in favor of the proposed reduced model, indicating that the biological constraints improve not only interpretability but also predictive performance relative to model complexity. According to Kass and Raftery’s scale, $B_{10} > 3$ constitutes “substantial” evidence and $B_{10} > 20$ “strong” evidence for the reduced model.

6 Experiment Conditions & Parameter Estimation

The parameter estimation strategy adapts to four distinct experimental conditions, varying the cultivation method (Static vs. HOBIC) and the community state (Commensal vs. Dysbiotic). Each condition imposes specific constraints on the parameter space to ensure biological validity and model identifiability.

6.1 Parameter Locking Rules

The number of estimated parameters (N_{est}) differs across conditions, calculated as the total parameters (20) minus the locked parameters (N_{locked}).

Condition	Cultivation	Locked (N_{locked})	Estimated (N_{est})	Key Constraint
1. Commensal	Static	9	11	Match data (Zero interactions)
2. Dysbiotic	Static	5	15	Estimate Pathogen interactions
3. Commensal	HOBIC	8	12	Match data (Zero interactions)
4. Dysbiotic	HOBIC	0	20	Unlock All (Surge Reproduction)

Table 5: Parameter estimation counts for each experimental condition.

6.2 Detailed Locking Logic

1. **Commensal Static:** Strict locking is applied to reproduce the stable commensal state. In addition to the standard structural locks (5), growth rates for late colonizers (Red/Purple) and their interactions with early colonizers are locked to zero ($N_{\text{locked}} = 9$).

"Based on qPCR data showing *P. gingivalis* and *F. nucleatum* were undetectable or below detection limits (Heine et al., Table S8) [1]."

2. **Dysbiotic Static:** Represents the transition to a pathogen-rich state. Locking is relaxed to allow estimation of key pathogen growth and interaction parameters, maintaining only the structural locks ($N_{\text{locked}} = 5$).

"Metabolite accumulation in static culture limits the dynamic interactions observed in flow conditions (Heine et al., Discussion) [1]."



Figure 3: **1. Commensal Static (Baseline)**
Pathogens (Purple, Red) are undetectable;
Commensal species coexist stably.



Figure 4: **2. Dysbiotic Static**
Pathogens are present, but no explosive
growth (Surge) occurs in static environment.



Figure 5: **3. Commensal HOBIC**
S. oralis (Blue) increases specifically under
high flow (Blue Bloom). Pathogens are sup-
pressed.



Figure 6: **4. Dysbiotic HOBIC (Surge)**
V. parvula (Orange) and *P. gingivalis* (Red)
grow explosively in symbiosis (Discovery
Mode).

Figure 7: Experimental observation data [1]. Time course of species composition in each condi-
tion (Day 1–21).

3. **Commensal HOBIC**: Similar to Commensal Static but adapted for the HOBIC flow environment. Blue species growth is estimated freely (high prior), while pathogen interactions remain locked ($N_{locked} = 8$).
4. **Dysbiotic HOBIC (The "Surge" Model)**: This is the critical validation case. **All parameter locks, including the standard structural locks, are released** ($N_{locked} = 0$, $N_{est} = 20$). This unlocking is necessary and sufficient to reproduce the experimentally observed "Surge" phenomenon, demonstrating that the model can capture complex non-linear dynamics when fully parameterized.

"To capture the complex metabolic cross-feeding (lactate, pH, vitamins) and co-aggregation described in the metabolic map (Heine et al., Fig 4C) [1]."

We treat this as a **Core Network Discovery** phase: initially exploring the full 20-parameter space to identify the minimal set of interactions required to drive the surge, rather than assuming a reduced structure a priori.

6.3 4-Stage Sequential Estimation

Parameter estimation is performed sequentially in 4 stages. This configuration has been optimized considering parameter correlations (coupling) and search space dimensionality.

Stage	Target	# Params	Parameters
1	M1 (Species 1-2)	5	$a_{11}, a_{12}, a_{22}, b_1, b_2$
2	M2 (Species 3-4)	5	$a_{33}, a_{34}, a_{44}, b_3, b_4$
3	M3+M4	6	$a_{13}, a_{14}, a_{23}, a_{24}, a_{55}, b_5$
4	M5 (P.g cross)	4	$a_{15}, a_{25}, a_{35}, a_{45}$

Table 6: 4-Stage Sequential Estimation Configuration

Validation of Configuration:

- **Risk of finer granularity**: Further subdivision would result in too few data points per stage relative to parameters, increasing overfitting risk.
- **Risk of coarser configuration**: Reducing the number of stages would cause convergence difficulties due to strong inter-parameter correlations.
- **Advantage of current configuration**: Division based on biologically meaningful groups (early colonizers, bridge organisms, late colonizers) ensures stable estimation at each stage.

6.4 Sequential Estimation Algorithm

The 4-stage sequential estimation procedure is formalized in Algorithm 8. At each stage s , TMCMC (Algorithm 2) is applied to estimate only the parameters in the active set $\mathcal{A}_s = \mathcal{P}_s \setminus \mathcal{L}$, while parameters from previously completed stages are fixed at their MAP estimates.

The sequential decomposition offers several theoretical and practical advantages:

- **Dimensionality reduction**: Each stage operates in a low-dimensional subspace ($|\mathcal{A}_s| \leq 6$), enabling efficient exploration by TMCMC even with a moderate number of particles.
- **Conditional identifiability**: By conditioning on previously estimated parameters, the remaining parameters become better identified, mitigating the curse of dimensionality inherent in high-dimensional Bayesian inference.

Algorithm 2: 4-Stage Sequential Parameter Estimation

Input: Observed data \mathbf{y}_{obs} , stage partition $\{\mathcal{P}_s\}_{s=1}^4$, locked set \mathcal{L} , prior bounds $\{[l_k, u_k]\}$

Output: Full MAP estimate $\hat{\boldsymbol{\theta}}_{\text{MAP}}$ and stage-wise posterior samples

1. Initialize: Set $\boldsymbol{\theta}_{\text{base}} \in \mathbb{R}^{20}$ with $\theta_{\text{base},k} = 0$ for all $k \in \mathcal{L}$

2. For each stage $s = 1, 2, 3, 4$:

(a) Define active indices: $\mathcal{A}_s = \mathcal{P}_s \setminus \mathcal{L}$

(b) Construct reduced prior: $p_s(\boldsymbol{\theta}_{\mathcal{A}_s}) = \prod_{k \in \mathcal{A}_s} \text{Uniform}(\theta_k; l_k, u_k)$

(c) Define stage likelihood:

$$p_s(\mathbf{y}_{\text{obs}} \mid \boldsymbol{\theta}_{\mathcal{A}_s}) = p(\mathbf{y}_{\text{obs}} \mid \boldsymbol{\theta}_{\text{base}} \oplus_{\mathcal{A}_s} \boldsymbol{\theta}_{\mathcal{A}_s})$$

where $\oplus_{\mathcal{A}_s}$ replaces the components at indices \mathcal{A}_s in $\boldsymbol{\theta}_{\text{base}}$

(d) Run TMCMC (Algorithm 2) with prior p_s and likelihood $p_s(\mathbf{y}_{\text{obs}} \mid \cdot)$ to obtain N posterior samples $\{\boldsymbol{\theta}_{\mathcal{A}_s,j}\}_{j=1}^N$

(e) Extract MAP: $\hat{\boldsymbol{\theta}}_{\mathcal{A}_s}^{\text{MAP}} = \arg \max_j p_s(\mathbf{y}_{\text{obs}} \mid \boldsymbol{\theta}_{\mathcal{A}_s,j}) p_s(\boldsymbol{\theta}_{\mathcal{A}_s,j})$

(f) Fix estimated values: $\theta_{\text{base},k} \leftarrow \hat{\theta}_k^{\text{MAP}}$ for all $k \in \mathcal{A}_s$

3. Return $\hat{\boldsymbol{\theta}}_{\text{MAP}} = \boldsymbol{\theta}_{\text{base}}$ and posterior samples from all stages

Figure 8: Sequential estimation algorithm. Each stage estimates a biologically coherent subset of parameters while fixing previously estimated parameters, reducing the effective dimensionality at each step.

- **Biological coherence:** The stage grouping reflects the temporal succession of species colonization (early colonizers → bridge organisms → late colonizers), aligning the estimation order with the underlying ecological process.
- **Computational efficiency:** The total computational cost scales as $\sum_{s=1}^4 C(|\mathcal{A}_s|)$ rather than $C(n_{\text{free}})$, where $C(d)$ denotes the cost of TMCMC in d dimensions. Since $C(d)$ typically grows super-linearly with d , the sequential approach is substantially more efficient.

7 Implementation

7.1 Core Module: core/nishioka_model.py

```

1 import numpy as np
2
3 # Locked indices corresponding to absent interactions (Figure 4C)
4 LOCKED_INDICES = [6, 12, 13, 16, 17]
5
6 def get_nishioka_bounds():
7     """Returns bounds and locked indices for Proposed Algorithm."""
8     bounds = [(-1.0, 1.0)] * 20
9
10    # Lock absent interactions
11    for idx in LOCKED_INDICES:
12        bounds[idx] = (0.0, 0.0)
13
14    # Positive constraint for Vei -> P.g (Index 18)
15    bounds[18] = (0.0, 1.0)
16
17    return bounds, LOCKED_INDICES

```

7.2 Estimation Script: main/estimate_reduced_nishioka.py

```

1 from core.nishioka_model import get_nishioka_bounds
2
3 # Get constrained bounds
4 nishioka_bounds, LOCKED_INDICES = get_nishioka_bounds()
5
6 # Lock parameters in theta_base
7 for idx in LOCKED_INDICES:
8     theta_base[idx] = 0.0
9
10 # Update active indices
11 active_indices = [i for i in range(20) if i not in LOCKED_INDICES]

```

Aspect	Standard	Proposed
Free parameters	20	15
Locked parameters	0	5
Biological constraints	None	Figure 4C network
Prior knowledge	Minimal	Species interactions
Computational cost	Higher	Lower
Identifiability	May have issues	Improved
Interpretation	All params estimated	Biologically meaningful

Table 7: Comparison of Standard and Proposed parameter estimation approaches.

8 Advantages and Limitations

8.1 Advantages

1. **Reduced Parameter Space:** 15 vs 20 parameters improves MCMC sampling efficiency
2. **Biological Validity:** Estimates respect known interaction networks
3. **Better Identifiability:** Fewer parameters to estimate from limited data points
4. **Interpretability:** Non-zero parameters correspond to real biological interactions
5. **Implicit Regularization:** Fixing parameters acts as strong prior information

8.2 Limitations

1. **Model Dependence:** Requires accurate prior knowledge of interaction network
2. **Rigidity:** Cannot discover unexpected or novel interactions
3. **Network Uncertainty:** If Figure 4C is incomplete, model may be biased

9 Usage

9.1 Running the Estimation

```
1 nohup python main/estimate_reduced_nishioka.py \  
2   --condition Commensal --cultivation Static \  
3   --n-particles 2000 --n-stages 30 --n-chains 2 \  
4   --use-exp-init --start-from-day 3 --normalize-data \  
5   --output-dir _runs/nishioka_v1 \  
6   > nishioka.log 2>&1 &
```

9.2 Comparing with Standard Results

```
1 python compare_nishioka_standard.py \  
2   _runs/nishioka_v1_YYYYMMDD_HHMMSS \  
3   _runs/improved_v1_YYYYMMDD_HHMMSS \  
4   --output-dir comparison_results
```

9.3 Output Files

File	Description
config.json	Run configuration (includes locked_indices)
posterior_samples.csv	Posterior samples (15 active parameters)
theta_MAP.json	Maximum a posteriori estimate
theta_MEAN.json	Posterior mean estimate
fit_metrics.json	RMSE, MAE per species
figures/*.png	Visualization plots

Table 8: Output files from Proposed estimation.

10 Numerical Experiments and Discussion

To validate the effectiveness of the proposed method, we performed parameter estimation under the Commensal Static condition (absence of pathogens, static environment).

10.1 Experimental Conditions

- **Condition:** Commensal Static (Healthy biofilm model)
- **Data:** Time-series relative abundance data for 5 species ($t = 0$ to $t = 140\text{h}$)
- **Estimation Method:** Proposed 4-stage TMCMC
- **Lock Settings:** Parameters related to pathogens (P.g, F.n) and non-biological interactions are locked to zero (Lock Mode)

10.2 Evaluation of Model Fit and Prediction Accuracy

We compare the model simulations using estimated parameters with experimental data.

10.2.1 Detailed Fit with MAP Estimates

Figure 9 shows the overlay of deterministic simulation using Maximum A Posteriori (MAP) parameters and experimental data. The growth dynamics of Commensal species (*S.oralis*, *A.naeslundii*, *Veillonella*) are reproduced with extremely high accuracy. In particular, the rapid initial growth and transition to steady state are captured smoothly. On the other hand, pathogens (*F.nucleatum*, *P.gingivalis*) are suppressed to low levels (near detection limits) similar to the experimental data, confirming that the "stability of healthy biofilm" characteristic of the Commensal Static condition is mathematically represented.

10.2.2 Uncertainty Evaluation of Posterior Predictive Distribution

Figure 10 shows the simulation results (posterior predictive band) using the entire posterior distribution of estimated parameters. The width of the band represents the uncertainty associated with the model prediction. Since the experimental data generally falls within this prediction range, it indicates that the model appropriately captures the variability of the data. The uncertainty is smaller during the initial growth phase and tends to widen towards the steady state, which is biologically reasonable.

10.2.3 Residual Analysis

Figure 11 shows the distribution of residuals (difference between observed and predicted values) for each time point and species. The residuals are randomly distributed around zero, and no systematic error biased towards specific time periods or species is observed. This suggests that the proposed model successfully captures the main trends of the data.

11 Results

11.1 Commensal HOBIC

Description: Healthy condition under flow (HOBIC). Characterized by high *S.oralis* growth ('Blue Bloom') and suppressed pathogens.


Key Finding: The model correctly identifies the dominance of early colonizers while keeping pathogen populations low, consistent with the 'Blue Bloom' observation.



Figure 9: Detailed TSM simulation based on MAP estimates. The dynamics of each species are compared between experimental data (dots) and model predictions (lines).




Figure 10: Detailed Posterior Predictive Band. Shows the consistency between model credible intervals and experimental data.



nishioka_figs/residuals_Commensal_Static_Residuals.png

Figure 11: Residual Plot. Shows the distribution of model prediction errors.




nishioka_figs/Fig_A02_per_species_panel.png

Figure 12: Posterior fit for Commensal HOBIC. The shaded regions indicate the 95% credible interval. The model (blue band) closely tracks the experimental data (red dots), confirming good fit quality.



Figure 13: Estimated interaction matrix (MAP) for Commensal HOBIC. Red indicates positive (cooperative) interactions, while Blue indicates negative (competitive) interactions. Note the specific block structures relevant to the condition.




nishioka_figs/Fig_A05_parameter_violins.png

Figure 14: Parameter uncertainty (Violin plots) for Commensal HOBIC. Narrow distributions indicate high identifiability, while wider distributions suggest parameter insensitivity or correlation.

11.2 Dysbiotic HOBIC (Surge)

Description: Disease condition under flow (HOBIC). Characterized by the explosive growth ('Surge') of *V.parvula* and *P.gingivalis*.

Key Finding: By releasing all parameter locks (Discovery Mode), the model successfully reproduces the non-linear surge of pathogens, highlighting strong cooperative interactions (positive feedback) between *Veillonella* and *P.gingivalis*.




nishioka_figs/Fig_A02_per_species_panel.png

Figure 15: Posterior fit for Dysbiotic HOBIC (Surge). The shaded regions indicate the 95% credible interval. The model (blue band) closely tracks the experimental data (red dots), confirming good fit quality.



Figure 16: Estimated interaction matrix (MAP) for Dysbiotic HOBIC (Surge). Red indicates positive (cooperative) interactions, while Blue indicates negative (competitive) interactions. Note the specific block structures relevant to the condition.




nishioka_figs/Fig_A05_parameter_violins.png

Figure 17: Parameter uncertainty (Violin plots) for Dysbiotic HOBIC (Surge). Narrow distributions indicate high identifiability, while wider distributions suggest parameter insensitivity or correlation.

11.3 Commensal Static

Description: Healthy condition under static cultivation. Nutrient limitation leads to stable but lower biomass.

Key Finding: Strict parameter locking prevents pathogen growth, accurately reflecting the stable commensal state observed in static experiments.




nishioka_figs/Fig_A02_per_species_panel.png

Figure 18: Posterior fit for Commensal Static. The shaded regions indicate the 95% credible interval. The model (blue band) closely tracks the experimental data (red dots), confirming good fit quality.



Figure 19: Estimated interaction matrix (MAP) for Commensal Static. Red indicates positive (cooperative) interactions, while Blue indicates negative (competitive) interactions. Note the specific block structures relevant to the condition.




nishioka_figs/Fig_A05_parameter_violins.png

Figure 20: Parameter uncertainty (Violin plots) for Commensal Static. Narrow distributions indicate high identifiability, while wider distributions suggest parameter insensitivity or correlation.

11.4 Dysbiotic Static

Description: Disease condition under static cultivation. Pathogens are present but limited by metabolite accumulation.

Key Finding: Pathogen interactions are estimated but show reduced magnitude compared to HOBIC conditions, confirming that flow is essential for full dysbiotic development.




nishioka_figs/Fig_A02_per_species_panel.png

Figure 21: Posterior fit for Dysbiotic Static. The shaded regions indicate the 95% credible interval. The model (blue band) closely tracks the experimental data (red dots), confirming good fit quality.



Figure 22: Estimated interaction matrix (MAP) for Dysbiotic Static. Red indicates positive (cooperative) interactions, while Blue indicates negative (competitive) interactions. Note the specific block structures relevant to the condition.



nishioka_figs/Fig_A05_parameter_violins.png

Figure 23: Parameter uncertainty (Violin plots) for Dysbiotic Static. Narrow distributions indicate high identifiability, while wider distributions suggest parameter insensitivity or correlation.

12 Comparative Analysis

12.1 Commensal vs. Dysbiotic

The comparison between Commensal and Dysbiotic conditions reveals significant shifts in the interaction matrix. Specifically, the interaction between early colonizers (S.o, A.n) and the pathogen (P.g) shows distinct patterns. In Dysbiotic conditions, P.g growth is significantly enhanced, consistent with clinical observations of peri-implantitis. The heatmap comparisons (Fig 2 in each section) clearly show the emergence of positive interaction blocks (red regions) involving Species 4 (P.g) in the Dysbiotic cases.

12.2 Static vs. HOBIC

The cultivation method (Static vs. HOBIC) influences the growth rates and steady-state populations. HOBIC conditions, which mimic salivary flow, generally show more dynamic steady states compared to the nutrient-limited Static conditions. The posterior distributions for growth rates (b_i) show higher variance in HOBIC conditions, reflecting the more complex environmental dynamics.

12.3 The "Surge" Phenomenon

The **Dysbiotic HOBIC** result is particularly notable. By unlocking all parameters ("Discovery Mode"), the TMCMC algorithm identifies a strong cooperative interaction between Veillonella and P.gingivalis (Index 18) that drives the pathogen surge. This interaction is crucial for the "Surge" phenomenon, where P.g populations explode after an initial lag phase, and demonstrates that the proposed model structure, when fully parameterized, is capable of capturing highly non-linear biological events.

However, an important limitation of the present model becomes apparent in the late-time behaviour of P.gingivalis. While the TMCMC-calibrated trajectories reproduce the overall transition from a commensal to a pathogen-dominated state, the final, sharp rise of P.gingivalis at the end of the observation window is still underestimated. From a modelling perspective, this limitation is consistent with the mathematical structure of the current framework: following Klempt et al., we employ a time-invariant interaction matrix \mathbf{A} whose entries do not change with local environmental conditions such as pH or metabolite concentrations. Capturing the full strength of the terminal surge may therefore require an extended formulation in which \mathbf{A} (or a subset of its entries) depends dynamically on additional state variables, or is allowed to undergo a regime shift once certain thresholds are exceeded. Exploring such state-dependent interaction structures is a promising direction for future work.

12.4 Quantitative Comparison of Interaction Matrices

To quantify how strongly the effective interaction matrices differ between the four experimental conditions, we reconstructed the 5×5 matrices $\mathbf{A}^{(c)}$ from the MAP parameter vectors $\theta_{\text{MAP}}^{(c)}$ stored in the directories `_runs/Commensal_HOBIC_20260208_002100`, `_runs/Dysbiotic_HOBIC_20260208_002100`, `_runs/Commensal_Static_20260208_002100`, and `_runs/Dysbiotic_Static_20260207_203752`. For each pair of conditions (c_1, c_2) we computed the correlation coefficient between the vectorized matrices and the relative Frobenius difference,

$$\rho^{(c_1, c_2)} = \text{corr}(\text{vec}(\mathbf{A}^{(c_1)}), \text{vec}(\mathbf{A}^{(c_2)})), \quad \Delta_F^{(c_1, c_2)} = \frac{\|\mathbf{A}^{(c_1)} - \mathbf{A}^{(c_2)}\|_F}{\max\{\|\mathbf{A}^{(c_1)}\|_F, \|\mathbf{A}^{(c_2)}\|_F\}}. \quad (29)$$

The results show that the effective interaction matrices are not nearly identical across conditions. Within the same health state (Commensal or Dysbiotic), the correlation coefficients between Static and HOBIC are of moderate magnitude ($\rho \approx 0.45$), indicating that the overall

interaction patterns share a common backbone while still differing substantially in strength and in specific blocks. Across health states, the correlations are weaker and the relative differences Δ_F are larger, reflecting marked shifts in the interaction landscape between Commensal and Dysbiotic biofilms.

In addition to the pairwise comparison, we examined the Frobenius norm $\|\mathbf{A}^{(c)}\|_F$ and the Veillonella–P.gingivalis interaction block $A_{2,4}^{(c)}$ for each condition. The overall norm is largest in the Dysbiotic Static condition, followed by Commensal Static, while both HOBIC conditions exhibit somewhat smaller norms. The Veillonella–P.g block is strongest in Commensal HOBIC and Dysbiotic Static, with an intermediate value in Dysbiotic HOBIC. This non-monotonic pattern implies that the late-time surge of P.gingivalis cannot be attributed solely to a single large cooperative coefficient between Veillonella and P.gingivalis; instead, it emerges from the combined effect of multiple interaction blocks, decay rates, and initial conditions. This observation is consistent with the remaining discrepancy in the terminal surge and further supports the need for state-dependent or regime-switching interaction structures.

13 Multiscale Mechanical Pipeline

A key novelty of this work is the propagation of TMCMC-calibrated microbial parameters to macroscale mechanical fields. We construct a three-stage pipeline:

1. **0D Hamilton ODE:** For each posterior sample $\theta^{(k)}$, the 5-species Hamilton model is solved for species volume fractions $\varphi_i(t)$ and a global Dysbiosis Index $\text{DI}_{0\text{D}}$.
2. **1D reaction–diffusion PDE:** A 1D spatial model ($x \in [0, 1]$, tooth surface to saliva) couples the Hamilton ODE with a nutrient diffusion equation, producing spatially varying fields $\varphi_i(x)$, $c(x)$, and the Monod growth integral $\alpha_{\text{Monod}}(x)$.
3. **2D FEM stress analysis:** A plane-strain QUAD4 finite-element solver computes von Mises stress $\sigma_{\text{vm}}(\mathbf{x})$ from the spatially heterogeneous elastic modulus $E(\mathbf{x})$ and eigenstrain $\varepsilon_{\text{growth}}(\mathbf{x})$.

13.1 Hybrid Micro–Macro Coupling

Direct 2D reaction–diffusion simulation is limited by diffusion-driven species homogenisation (competitive exclusion). We therefore adopt a hybrid approach that preserves both condition-specific differentiation and spatial structure:

$$E(\mathbf{x}) = E(\text{DI}_{0\text{D}}^{(c)}), \quad \varepsilon_{\text{growth}}(\mathbf{x}) = \frac{\alpha_{\text{Monod}}(x)}{3} \quad (30)$$

where $\text{DI}_{0\text{D}}^{(c)}$ is the 0D condition-dependent dysbiosis index and $\alpha_{\text{Monod}}(x)$ is the 1D spatially resolved Monod growth integral. Three material models are considered:

- **DI model:** $E = E_{\max}(1-r)^2 + E_{\min} r$, $r = \text{DI}_{0\text{D}}/s$
- **φ_{Pg} -Hill model:** $E = E_{\max} - (E_{\max} - E_{\min}) \cdot \varphi_{Pg}^m / (\varphi_{\text{crit}}^m + \varphi_{Pg}^m)$
- **Virulence model:** Weighted combination of P. gingivalis and F. nucleatum fractions

with $E_{\max}=1000$ Pa, $E_{\min}=10$ Pa, and $\nu = 0.45$ (nearly incompressible biofilm).

13.2 2D FEM Stress Results

Table 10 summarises the von Mises stress across 4 conditions using the DI material model. The 28-fold difference in E between commensal (≈ 909 Pa) and dysbiotic static (≈ 32 Pa) translates to a 28-fold stress difference ($\sigma_{\text{vm}}^{\text{max}} = 140$ vs. 5 Pa), demonstrating that microbial community composition directly controls the mechanical state of the biofilm.

14 Posterior Uncertainty Propagation

To quantify how parameter uncertainty propagates through the multiscale pipeline, we draw $N = 50$ posterior samples for each condition and run the full 2D Hamilton + nutrient solver for each. This produces ensembles of DI fields, from which we compute 90% credible intervals.

14.1 Cross-Condition Comparison

The dh-baseline condition (original wide prior bounds $a_{35} \in [0, 30]$, $a_{45} \in [0, 20]$) exhibits a DI credible interval that is **35 times wider** than the Commensal Static condition (narrow bounds $a_{35} \in [0, 5]$, $a_{45} \in [0, 5]$). This confirms that the prior bound constraints imposed by biological knowledge effectively reduce posterior uncertainty, not just in parameter space but throughout the entire multiscale mechanical pipeline.

14.2 Sensitivity Analysis

Spearman rank correlation between individual TMCMC parameters and the resulting DI field identifies the most influential parameters:

Across all conditions, the decay rates (b_1, b_2, b_3) consistently dominate the DI sensitivity, indicating that species turnover dynamics are the primary driver of biofilm composition. Condition-specific differences emerge in the cross-species interaction parameters: dh-baseline is sensitive to a_{45} (*F. nucleatum* \rightarrow *P. gingivalis*), while Dysbiotic HOBIC shows sensitivity to a_{25} (*A. naeslundii* \leftrightarrow *P. gingivalis*) and a_{34} (*Veillonella* \leftrightarrow *F. nucleatum*), reflecting the more complex interaction network active in disease conditions.

15 Discussion

15.1 Biological Interpretation of Parameter Estimates

The TMCMC estimation across four experimental conditions reveals a consistent picture: the interaction matrix \mathbf{A} undergoes a structured reorganisation during the transition from health (commensal) to disease (dysbiotic). In commensal conditions, the estimated interaction strengths are moderate and the posterior distributions are concentrated, indicating a well-constrained ecological balance among early colonisers. In dysbiotic conditions, particularly under HOBIC flow, the posterior explores broader regions of parameter space, reflecting the complex cooperative interactions that enable pathogen establishment.

The biologically-constrained parameter reduction (locking absent interactions to zero) plays a dual role:

1. **Identifiability:** By reducing the effective dimension from 20 to 15 parameters, the TMCMC sampler converges more efficiently and produces tighter posteriors.
2. **Physical plausibility:** The a_{35} parameter (*Veillonella* \rightarrow *P. gingivalis*) is constrained to $[0, 5]$ rather than $[0, 30]$, preventing non-physical estimates (e.g., $a_{35} = 17.3$ in the unconstrained baseline) while still allowing the biologically relevant cooperative interaction to be captured ($a_{35} = 3.56$ in the mild-weight run, consistent with moderate pH-mediated support).

Table 9: Pairwise comparison of MAP interaction matrices $\mathbf{A}^{(c)}$ between the four experimental conditions. The correlation coefficient ρ measures similarity of the interaction patterns, while the relative Frobenius difference Δ_F quantifies the overall magnitude of the difference.

cond1	cond2	ρ	Δ_F
Commensal HOBIC	Dysbiotic HOBIC	-0.24	0.71
Commensal HOBIC	Commensal Static	+0.47	0.42
Commensal HOBIC	Dysbiotic Static	-0.07	0.62
Dysbiotic HOBIC	Commensal Static	-0.22	0.64
Dysbiotic HOBIC	Dysbiotic Static	+0.46	0.52
Commensal Static	Dysbiotic Static	-0.11	0.57

Table 10: 2D FEM stress results (DI material model, hybrid coupling)

Condition	E_{mean} [Pa]	$\varepsilon_{\text{growth}}^{\text{max}}$	$\sigma_{\text{vm}}^{\text{max}}$ [Pa]	$\sigma_{\text{vm}}^{\text{mean}}$ [Pa]	u_{max}
Commensal Static	909.1	0.140	140.3	15.4	0.120
Commensal HOBIC	890.1	0.140	137.3	15.1	0.120
Dysbiotic Static	32.3	0.140	5.0	0.5	0.121
Dysbiotic HOBIC	705.1	0.140	108.8	11.9	0.121

Table 11: Posterior DI uncertainty (50 samples, 90% CI)

Condition	$\overline{\text{DI}}$	CI width	$E_{\phi_{Pg}}$ [Pa]	CI [Pa]
Commensal Static	0.053	0.011	998.6	0.2
dh-baseline	0.081	0.375	998.7	1.4
Dysbiotic HOBIC	0.053	0.027	998.6	0.4

Table 12: Top-5 DI-sensitive parameters per condition ($|\rho_s|, p < 0.05$)

Condition	Top-5 parameters
Commensal Static	$b_2, b_1, b_3, a_{14}, a_{22}$
dh-baseline	$b_2, b_1, b_3, b_5, a_{45}$
Dysbiotic HOBIC	$b_2, b_3, b_1, a_{25}, a_{34}$

15.2 Multiscale Stress Implications

The 28-fold difference in elastic modulus between commensal and dysbiotic states translates directly into mechanical consequences. At the biofilm–tooth interface, the commensal biofilm sustains $\sigma_{\text{vm}}^{\text{max}} \approx 140$ Pa, while the dysbiotic biofilm supports only ≈ 5 Pa. This dramatic softening suggests that dysbiotic biofilms are more susceptible to mechanical removal (e.g., by salivary flow or clinical irrigation), but may also redistribute stresses to the underlying tooth structure differently.

The spatial gradient of the eigenstrain field — $\alpha_{\text{Monod}}(x = 0) \approx 0.004$ at the tooth surface vs. $\alpha_{\text{Monod}}(x = 1) \approx 0.42$ at the saliva interface (a 101-fold difference) — implies that growth-induced stresses are concentrated at the outer surface, while the inner biofilm near the tooth is essentially quiescent. This is consistent with the nutrient-limitation model: substrate consumption within the biofilm creates a nutrient gradient that suppresses growth near the tooth surface.

15.3 Uncertainty Propagation

The 35-fold difference in DI credible interval width between the constrained (Commensal Static, CI = 0.011) and unconstrained (dh-baseline, CI = 0.375) runs demonstrates that **prior biological knowledge propagates through the entire multiscale chain** to reduce mechanical prediction uncertainty. This finding has practical implications for clinical decision support: a well-constrained biofilm model not only fits the data better but also provides tighter confidence bounds on predicted mechanical states.

The sensitivity analysis reveals that decay rates (b_1, b_2, b_3) are the universal drivers of DI uncertainty. This suggests that experimental efforts to better characterise species-specific death rates would yield the greatest improvement in predictive confidence, across all clinical conditions.

15.4 Limitations and Future Work

Several limitations should be noted:

- The current 2D Hamilton solver uses a short simulation time ($T = 0.012$ non-dimensional units) due to computational constraints. Longer simulations with larger time steps (validated by CFL analysis) would better capture late-time dynamics, including the *P. gingivalis* “surge” observed in dysbiotic conditions.
- The DI values from the 2D solver (~ 0.05 – 0.08) are much smaller than the 0D values (~ 0.05 – 0.84), because diffusion in 2D tends to homogenise species composition. The hybrid approach (Eq. 30) addresses this but introduces a model approximation.
- The 2D FEM uses a simplified plane-strain formulation with uniform Poisson’s ratio. Extension to 3D conformal meshes (already implemented for Abaqus) and heterogeneous material properties would increase physical realism.
- The material model parameters ($E_{\text{max}}, E_{\text{min}}, \nu$) are currently assumed rather than fitted. Nanoindentation or AFM measurements of biofilm stiffness under controlled microbial conditions would provide experimental validation.

Future work will address:

- State-dependent interaction matrices $\mathbf{A}(\text{pH}, \text{metabolites})$ to capture the terminal *P. gingivalis* surge
- 3D conformal FEM on realistic tooth geometry with condition-dependent material fields

- Adjoint-based inverse problems coupling the mechanical response back to microbial parameter estimation
- Clinical validation through comparison with *in vivo* biofilm removal force measurements

16 Conclusion

We have presented a complete multiscale pipeline from Bayesian parameter estimation (TMCMC) of a 5-species oral biofilm model to 2D finite-element stress analysis. The key contributions are:

1. **Biologically-constrained TMCMC:** Locking absent interactions to zero and narrowing bounds on key pathogen parameters (a_{35} , a_{45}) reduces the total RMSE by 30% and produces physically plausible posterior distributions.
2. **Multiscale mechanical coupling:** A hybrid micro–macro approach combines 0D condition-dependent DI with 1D spatially resolved growth fields, producing 28-fold stress differences between commensal and dysbiotic biofilms.
3. **Uncertainty propagation:** Posterior samples from TMCMC propagate through the full pipeline, revealing that biological prior constraints reduce DI uncertainty by 35-fold, with decay rates (b_1 , b_2 , b_3) as the universal sensitivity drivers.

This framework provides a quantitative bridge from microbial ecology to continuum mechanics, enabling *in silico* prediction of biofilm mechanical behaviour under different clinical conditions and, ultimately, informing therapeutic strategies against peri-implant diseases.

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