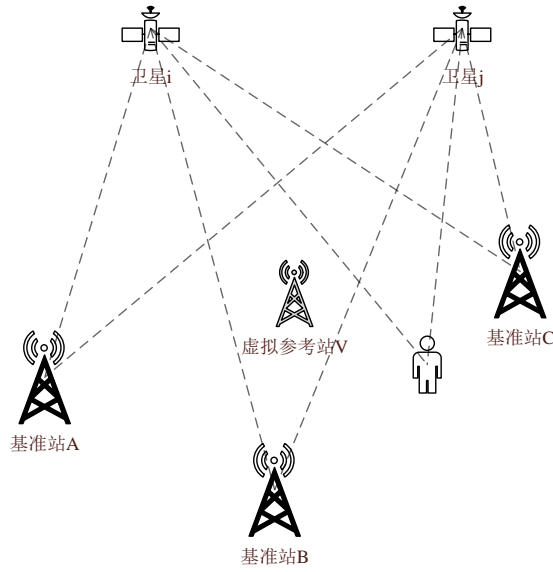


本文简要推导 VRS 虚拟参考站观测值生成的基本算法<sup>1</sup>;

假设在  $t$  时刻, 流动站  $u$  和基准站 A、B、C 几乎同时观测到  $n$  颗卫星播发的 L1 C/A 卫星信号, L1 C/A 信号波长为  $\lambda$ , 则伪距观测值为

$$\begin{aligned}\rho_u^i &= r_u^i + cdt_u - cdt^i + I_u^i + T_u^i + \epsilon_u^i \\ \rho_A^i &= r_A^i + cdt_u - cdt^i + I_A^i + T_A^i + \epsilon_A^i \\ \rho_B^i &= r_B^i + cdt_u - cdt^i + I_B^i + T_B^i + \epsilon_B^i \\ \rho_C^i &= r_C^i + cdt_u - cdt^i + I_C^i + T_C^i + \epsilon_C^i\end{aligned}$$

式中,  $i = 1, 2, \dots, n$ ;



以卫星  $j$  为参考卫星, A 为主参考站;  
假设

$$\begin{cases} I_u^i = F_I^i(r_u, r^i) \\ I_A^i = F_I^i(r_A, r^i) \\ I_B^i = F_I^i(r_B, r^i) \\ I_C^i = F_I^i(r_C, r^i) \end{cases}, \quad \begin{cases} I_u^j = F_I^j(r_u, r^j) \\ I_A^j = F_I^j(r_A, r^j) \\ I_B^j = F_I^j(r_B, r^j) \\ I_C^j = F_I^j(r_C, r^j) \end{cases}$$

$$\begin{cases} T_u^i = F_T^i(r_u, r^i) \\ T_A^i = F_T^i(r_A, r^i) \\ T_B^i = F_T^i(r_B, r^i) \\ T_C^i = F_T^i(r_C, r^i) \end{cases}, \quad \begin{cases} T_u^j = F_T^j(r_u, r^j) \\ T_A^j = F_T^j(r_A, r^j) \\ T_B^j = F_T^j(r_B, r^j) \\ T_C^j = F_T^j(r_C, r^j) \end{cases}$$

构建基准站和流动站的伪距双差观测方程为

$$\begin{aligned}\rho_{uA}^{ij} &= r_{uA}^{ij} + I_{uA}^{ij} + T_{uA}^{ij} + \epsilon_{uA}^{ij} \\ \rho_{BA}^{ij} &= r_{BA}^{ij} + I_{BA}^{ij} + T_{BA}^{ij} + \epsilon_{BA}^{ij}\end{aligned}$$

<sup>1</sup> 苏景岚

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$$\rho_{CA}^{ij} = r_{CA}^{ij} + l_{CA}^{ij} + t_{CA}^{ij} + \epsilon_{CA}^{ij}$$

若已知 $l_{BA}^{ij}$ 和 $l_{CA}^{ij}$ , 估计 $l_{uA}^{ij}$ :

$$l_{uA}^{ij} = l_u^i - l_A^i - (l_u^j - l_A^j) = F_1^i(r_u, r^i) - F_1^i(r_A, r^i) - (F_1^j(r_u, r^j) - F_1^j(r_A, r^j))$$

$$l_{BA}^{ij} = l_B^i - l_A^i - (l_B^j - l_A^j) = F_1^i(r_B, r^i) - F_1^i(r_A, r^i) - (F_1^j(r_B, r^j) - F_1^j(r_A, r^j))$$

$$l_{CA}^{ij} = l_C^i - l_A^i - (l_C^j - l_A^j) = F_1^i(r_C, r^i) - F_1^i(r_A, r^i) - (F_1^j(r_C, r^j) - F_1^j(r_A, r^j))$$

将 $F_1^i(r_B, r^i)$ 和 $F_1^i(r_C, r^i)$ 在 $r_A$ 处进行泰勒级数展开并忽略高阶项, 即

$$F_1^i(r_B, r^i) = F_1^i(r_A, r^i) + \frac{\partial F_1^i(r_A, r^i)}{\partial r_A^T} \cdot (r_B - r_A)$$

$$F_1^i(r_C, r^i) = F_1^i(r_A, r^i) + \frac{\partial F_1^i(r_A, r^i)}{\partial r_A^T} \cdot (r_C - r_A)$$

将 $F_1^j(r_B, r^j)$ 和 $F_1^j(r_C, r^j)$ 在 $r_A$ 处进行泰勒级数展开并忽略高阶项, 即

$$F_1^j(r_B, r^j) = F_1^j(r_A, r^j) + \frac{\partial F_1^j(r_A, r^j)}{\partial r_A^T} \cdot (r_B - r_A)$$

$$F_1^j(r_C, r^j) = F_1^j(r_A, r^j) + \frac{\partial F_1^j(r_A, r^j)}{\partial r_A^T} \cdot (r_C - r_A)$$

由此可得

$$l_{BA}^{ij} = \left( \frac{\partial F_1^i(r_A, r^i)}{\partial r_A^T} - \frac{\partial F_1^j(r_A, r^j)}{\partial r_A^T} \right) \cdot (r_B - r_A)$$

$$l_{CA}^{ij} = \left( \frac{\partial F_1^i(r_A, r^i)}{\partial r_A^T} - \frac{\partial F_1^j(r_A, r^j)}{\partial r_A^T} \right) \cdot (r_C - r_A)$$

即有

$$\begin{bmatrix} l_{BA}^{ij} \\ l_{CA}^{ij} \end{bmatrix} = \begin{bmatrix} (r_B - r_A)^T \\ (r_C - r_A)^T \end{bmatrix} \cdot \underbrace{\left( \frac{\partial F_1^i(r_A, r^i)}{\partial r_A^T} - \frac{\partial F_1^j(r_A, r^j)}{\partial r_A^T} \right)}_{\chi_1^{ij}}$$

将 $F_1^i(r_u, r^i)$ 和 $F_1^j(r_u, r^j)$ 在 $r_A$ 处进行泰勒级数展开并忽略高阶项, 即

$$F_1^i(r_u, r^i) = F_1^i(r_A, r^i) + \frac{\partial F_1^i(r_A, r^i)}{\partial r_A^T} \cdot (r_u - r_A)$$

$$F_1^j(r_u, r^j) = F_1^j(r_A, r^j) + \frac{\partial F_1^j(r_A, r^j)}{\partial r_A^T} \cdot (r_u - r_A)$$

可得

$$l_{uA}^{ij} = \left( \frac{\partial F_1^i(r_A, r^i)}{\partial r_A^T} - \frac{\partial F_1^j(r_A, r^j)}{\partial r_A^T} \right) \cdot (r_u - r_A) = (r_u - r_A)^T \cdot \chi_1^{ij}$$

对对流层延迟做同样的处理，也有

$$\begin{aligned} \begin{bmatrix} T_{BA}^{ij} \\ T_{CA}^{ij} \end{bmatrix} &= \begin{bmatrix} (r_B - r_A)^T \\ (r_C - r_A)^T \end{bmatrix} \cdot \underbrace{\left( \frac{\partial F_T^i(r_A, r^i)}{\partial r_A^T} - \frac{\partial F_T^j(r_A, r^j)}{\partial r_A^T} \right)^T}_{\chi_T^{ij}} \\ T_{uA}^{ij} &= \left( \frac{\partial F_T^i(r_A, r^i)}{\partial r_A} - \frac{\partial F_T^j(r_A, r^j)}{\partial r_A} \right) \cdot (r_u - r_A) = (r_u - r_A)^T \cdot \chi_T^{ij} \end{aligned}$$

假设在流动站附近有一个虚拟参考站 V，以基准站 A 为主参考站，则有

$$\begin{aligned} I_{VA}^{ij} &= (r_V - r_A)^T \cdot \chi_1^{ij} \\ T_{VA}^{ij} &= (r_V - r_A)^T \cdot \chi_T^{ij} \end{aligned}$$

$$\rho_{VA}^{ij} = r_{VA}^{ij} + I_{VA}^{ij} + T_{VA}^{ij} + \epsilon_{VA}^{ij}$$

$$\begin{aligned} \rho_V^i - \rho_A^i - (\rho_V^j - \rho_A^j) &= r_V^i - r_A^i - (r_V^j - r_A^j) + I_{VA}^{ij} + T_{VA}^{ij} + \epsilon_{VA}^{ij} \\ \rho_u^i - \rho_A^i - (\rho_u^j - \rho_A^j) &= r_u^i - r_A^i - (r_u^j - r_A^j) + I_{uA}^{ij} + T_{uA}^{ij} + \epsilon_{uA}^{ij} \end{aligned}$$

$$\begin{aligned} \rho_u^i - \rho_A^i - (\rho_u^j - \rho_A^j) &= r_u^i - (r_V^i + (r_A^i - r_V^i)) - (r_u^j - (r_V^j + (r_A^j - r_V^j))) + (I_{uV}^{ij} + I_{uA}^{ij} - I_{uV}^{ij}) \\ &\quad + (T_{uV}^{ij} + T_{uA}^{ij} - T_{uV}^{ij}) + \epsilon_{uV}^{ij} \\ \rho_u^i - \underbrace{(\rho_A^i + (r_V^i - r_A^i) + I_{VA}^{ij} + T_{VA}^{ij})}_{\rho_V^i} &= \left( \rho_u^j - \underbrace{(\rho_A^j + (r_V^j - r_A^j))}_{\rho_V^j} \right) \\ &= r_u^i - r_V^i - (r_u^j - r_V^j) + I_{uV}^{ij} + T_{uV}^{ij} + \epsilon_{uV}^{ij} \end{aligned}$$

由上可得，虚拟伪距观测值为

$$\begin{aligned} \rho_V^i &= \rho_A^i + (r_V^i - r_A^i) + I_{VA}^{ij} + T_{VA}^{ij} \\ \rho_V^j &= \rho_A^j + (r_V^j - r_A^j) \end{aligned}$$

假设以卫星 1 为参考卫星，则虚拟参考站的虚拟观测值为

$$\begin{bmatrix} \rho_V^1 \\ \rho_V^2 \\ \vdots \\ \rho_V^n \end{bmatrix} = \begin{bmatrix} \rho_A^1 + (r_V^1 - r_A^1) \\ \rho_A^2 + (r_V^2 - r_A^2) + I_{VA}^{21} + T_{VA}^{21} \\ \vdots \\ \rho_A^n + (r_V^n - r_A^n) + I_{VA}^{n1} + T_{VA}^{n1} \end{bmatrix}$$

假设在流动站是以卫星 2 为参考卫星，则其与虚拟参考站组成的伪距双差观测方程为

$$\begin{aligned} \rho_u^1 - (\rho_A^1 + (r_V^1 - r_A^1)) - (\rho_u^2 - (\rho_A^2 + (r_V^2 - r_A^2) + I_{VA}^{21} + T_{VA}^{21})) \\ = r_u^1 - r_V^1 - (r_u^2 - r_V^2) + I_{uV}^{12} + T_{uV}^{12} + \epsilon_{uV}^{12} \end{aligned}$$

$$\begin{aligned}
\rho_u^1 - \rho_A^1 - (\rho_u^2 - \rho_A^2) \\
&= r_u^1 - r_V^1 - (r_u^2 - r_V^2) + (r_V^1 - r_A^1) - (r_V^2 - r_A^2) + I_{uV}^{12} - I_{VA}^{21} + T_{uV}^{12} - T_{VA}^{21} + \epsilon_{uV}^{12} \\
&= r_u^1 - r_A^1 - (r_u^2 - r_A^2) + I_{uA}^{12} + T_{uA}^{12} + \epsilon_{uA}^{12}
\end{aligned}$$

$$\begin{aligned}
\rho_u^3 - (\rho_A^3 + (r_V^3 - r_A^3) + I_{VA}^{31} + T_{VA}^{31}) - (\rho_u^2 - (\rho_A^2 + (r_V^2 - r_A^2) + I_{VA}^{21} + T_{VA}^{21})) \\
&= r_u^3 - r_V^3 - (r_u^2 - r_V^2) + I_{uV}^{32} + T_{uV}^{32} + \epsilon_{uV}^{32}
\end{aligned}$$

$$\begin{aligned}
\rho_u^3 - \rho_A^3 - (\rho_u^2 - \rho_A^2) \\
&= r_u^3 - r_V^3 - (r_u^2 - r_V^2) + I_{uV}^{32} + T_{uV}^{32} + (r_V^3 - r_A^3) + I_{VA}^{31} + T_{VA}^{31} - (r_V^2 - r_A^2) - I_{VA}^{21} \\
&\quad - T_{VA}^{21} + \epsilon_{uV}^{32} \\
&= r_u^3 - r_A^3 - (r_u^2 - r_A^2) + I_{uV}^{32} + I_{VA}^{31} - I_{VA}^{21} + T_{uV}^{32} + T_{VA}^{31} - T_{VA}^{21} + \epsilon_{uV}^{32} \\
&= r_u^3 - r_A^3 - (r_u^2 - r_A^2) + I_{uA}^{32} + T_{uA}^{32}
\end{aligned}$$

$$\begin{aligned}
I_{uV}^{32} + I_{VA}^{31} - I_{VA}^{21} &= I_u^3 - I_V^3 - (I_u^2 - I_V^2) + (I_V^3 - I_A^3 - (I_V^1 - I_A^1)) - (I_V^2 - I_A^2 - (I_V^1 - I_A^1)) \\
&= I_u^3 - I_A^3 - (I_u^2 - I_A^2) = I_{uA}^{32}
\end{aligned}$$

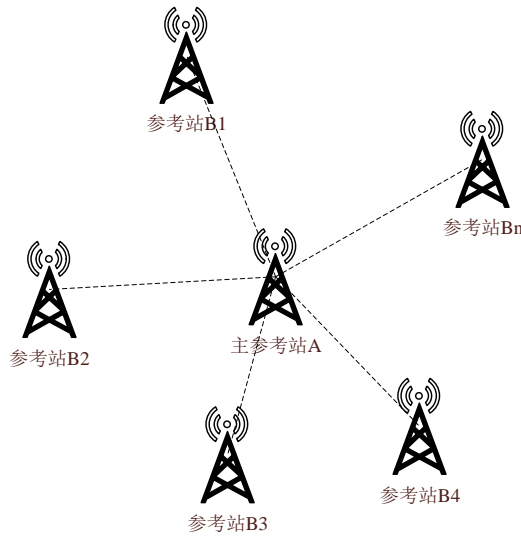
以此类推，即有

$$\begin{bmatrix} \rho_{uV}^{12} = r_{uV}^{12} + I_{uV}^{12} + T_{uV}^{12} + \epsilon_{uV}^{12} \\ \rho_{uV}^{32} = r_{uV}^{32} + I_{uV}^{32} + T_{uV}^{32} + \epsilon_{uV}^{32} \\ \vdots \\ \rho_{uV}^{n2} = r_{uV}^{n2} + I_{uV}^{n2} + T_{uV}^{n2} + \epsilon_{uV}^{n2} \end{bmatrix} \equiv \begin{bmatrix} \rho_{uA}^{21} = r_{uA}^{12} + I_{uA}^{12} + T_{uA}^{12} + \epsilon_{uA}^{12} \\ \rho_{uA}^{32} = r_{uA}^{32} + I_{uA}^{32} + T_{uA}^{32} + \epsilon_{uA}^{32} \\ \vdots \\ \rho_{uA}^{n2} = r_{uA}^{n2} + I_{uA}^{n2} + T_{uA}^{n2} + \epsilon_{uA}^{n2} \end{bmatrix}$$

上式表明两者是等价的；

假设主参考站 A 附近有 n 个参考站：

$$B_1, B_2, B_3, \dots, B_n$$



主参考站 A 与基准站  $B_1, B_2, B_3, \dots, B_n$  分别组成基线，即有

$$AB_1, AB_2, AB_3, \dots, AB_n$$

对于双差电离层有

$$\begin{bmatrix} I_{B_1A}^{ij} \\ I_{B_2A}^{ij} \\ I_{B_3A}^{ij} \\ \vdots \\ I_{B_nA}^{ij} \end{bmatrix} = \begin{bmatrix} (r_{B_1} - r_A)^T \\ (r_{B_2} - r_A)^T \\ (r_{B_3} - r_A)^T \\ \vdots \\ (r_{B_n} - r_A)^T \end{bmatrix} \cdot \underbrace{\left( \frac{\partial F_1^i(r_A, r^i)}{\partial r_A^T} - \frac{\partial F_1^j(r_A, r^j)}{\partial r_A^T} \right)^T}_{\chi_1^{ij}}$$

将 $\chi_1^{ij}$ 表示在站心坐标系下，假设主参考站 A 由 ECEF 坐标系转换至站心坐标系的转换矩阵为 $S$ ，则有

$$\begin{aligned} \begin{bmatrix} I_{B_1A}^{ij} \\ I_{B_2A}^{ij} \\ I_{B_3A}^{ij} \\ \vdots \\ I_{B_nA}^{ij} \end{bmatrix} &= \begin{bmatrix} (r_{B_1} - r_A)^T \\ (r_{B_2} - r_A)^T \\ (r_{B_3} - r_A)^T \\ \vdots \\ (r_{B_n} - r_A)^T \end{bmatrix} \cdot \underbrace{S^T \cdot S}_I \cdot \underbrace{\left( \frac{\partial F_1^i(r_A, r^i)}{\partial r_A^T} - \frac{\partial F_1^j(r_A, r^j)}{\partial r_A^T} \right)^T}_{\chi_1^{ij}} \\ \underbrace{\begin{bmatrix} I_{B_1A}^{ij} \\ I_{B_2A}^{ij} \\ I_{B_3A}^{ij} \\ \vdots \\ I_{B_nA}^{ij} \end{bmatrix}}_{L_I^{ij}} &= \underbrace{\begin{bmatrix} (S \cdot (r_{B_1} - r_A))^T \\ (S \cdot (r_{B_2} - r_A))^T \\ (S \cdot (r_{B_3} - r_A))^T \\ \vdots \\ (S \cdot (r_{B_n} - r_A))^T \end{bmatrix}}_H \cdot \underbrace{\left( \frac{\partial F_1^i(r_A, r^i)}{\partial r_A^T} - \frac{\partial F_1^j(r_A, r^j)}{\partial r_A^T} \right)^T}_{\chi_{1,ENU}^{ij}} \end{aligned}$$

$$L_I^{ij} = H \cdot \chi_{1,ENU}^{ij}$$

$\chi_{1,ENU}^{ij}$ 表示双差电离层在 ENU 方向的梯度值；

对上式进行最小二乘估计，可得

$$\chi_{1,ENU}^{ij} = (H^T \cdot H)^{-1} \cdot H^T \cdot L_I^{ij}$$

由上式计算虚拟站 V 的双差电离层，即

$$I_{VA}^{ij} = (r_V - r_A)^T \cdot \chi_1^{ij} = \underbrace{(S \cdot (r_V - r_A))^T}_{r_{ENU}^{VA}} \cdot (H^T \cdot H)^{-1} \cdot H^T \cdot L_I^{ij} = ((H^T \cdot H)^{-1} \cdot H^T \cdot L_I^{ij})^T \cdot r_{ENU}^{VA}$$

同样地，对于双差对流层也有

$$T_{VA}^{ij} = (r_V - r_A)^T \cdot \chi_T^{ij} = ((H^T \cdot H)^{-1} \cdot H^T \cdot L_T^{ij})^T \cdot r_{ENU}^{VA}$$

下面推导 VRS 虚拟参考站载波相位观测值生成的基本算法:

载波相位观测值为

$$\begin{aligned}\varphi_u^i &= r_u^i + cdt_u - cdt^i - I_u^i + T_u^i + N_u^i + \varepsilon_u^i \\ \varphi_A^i &= r_A^i + cdt_u - cdt^i - I_A^i + T_A^i + N_A^i + \varepsilon_A^i \\ \varphi_B^i &= r_B^i + cdt_u - cdt^i - I_B^i + T_B^i + N_B^i + \varepsilon_B^i \\ \varphi_C^i &= r_C^i + cdt_u - cdt^i - I_C^i + T_C^i + N_C^i + \varepsilon_C^i\end{aligned}$$

以卫星  $j$  为参考卫星,  $A$  为主参考站, 构建基准站和流动站的伪距双差观测方程为

$$\begin{aligned}\varphi_{uA}^{ij} &= r_{uA}^{ij} - I_{uA}^{ij} + T_{uA}^{ij} + N_{uA}^{ij} + \epsilon_{uA}^{ij} \\ \varphi_{BA}^{ij} &= r_{BA}^{ij} - I_{BA}^{ij} + T_{BA}^{ij} + N_{BA}^{ij} + \epsilon_{BA}^{ij} \\ \varphi_{CA}^{ij} &= r_{CA}^{ij} - I_{CA}^{ij} + T_{CA}^{ij} + N_{CA}^{ij} + \epsilon_{CA}^{ij}\end{aligned}$$

与伪距虚拟观测值的生成同理, 载波相位虚拟观测值为

$$\begin{aligned}\varphi_V^i &= \varphi_A^i + (r_V^i - r_A^i) - I_{VA}^i + T_{VA}^i \\ \varphi_V^j &= \varphi_A^j + (r_V^j - r_A^j)\end{aligned}$$

假设以卫星 1 为参考卫星, 则虚拟参考站的载波相位虚拟观测值为

$$\begin{bmatrix} \varphi_V^1 \\ \varphi_V^2 \\ \vdots \\ \varphi_V^n \end{bmatrix} = \begin{bmatrix} \varphi_A^1 + (r_V^1 - r_A^1) \\ \varphi_A^2 + (r_V^2 - r_A^2) - I_{VA}^{21} + T_{VA}^{21} \\ \vdots \\ \varphi_A^n + (r_V^n - r_A^n) - I_{VA}^{n1} + T_{VA}^{n1} \end{bmatrix}$$

需要的话, 可将  $F_I^i(r_u, r^i)$  和  $F_I^j(r_u, r^j)$  进行泰勒级数展开至二阶, 则有

$$\begin{aligned}F_I^i(r_u, r^i) &= F_I^i(r_A, r^i) + \frac{\partial F_I^i(r_A, r^i)}{\partial r_A^T} \cdot (r_u - r_A) + (r_u - r_A)^T \cdot \frac{\partial^2 F_I^i(r_A, r^i)}{\partial r_A \partial r_A} \cdot (r_u - r_A) \\ F_I^j(r_u, r^j) &= F_I^j(r_A, r^j) + \frac{\partial F_I^j(r_A, r^j)}{\partial r_A^T} \cdot (r_u - r_A) + (r_u - r_A)^T \cdot \frac{\partial^2 F_I^j(r_A, r^j)}{\partial r_A \partial r_A} \cdot (r_u - r_A) \\ I_{uA}^{ij} &= \left( \frac{\partial F_I^i(r_A, r^i)}{\partial r_A^T} - \frac{\partial F_I^j(r_A, r^j)}{\partial r_A^T} \right) \cdot (r_u - r_A) + (r_u - r_A)^T \cdot \frac{\partial^2 F_I^i(r_A, r^i)}{\partial r_A \partial r_A} \cdot (r_u - r_A) - (r_u - r_A)^T \\ &\quad \cdot \frac{\partial^2 F_I^j(r_A, r^j)}{\partial r_A \partial r_A} \cdot (r_u - r_A) \\ &= (r_u - r_A)^T \cdot \underbrace{\left( \frac{\partial F_I^i(r_A, r^i)}{\partial r_A^T} - \frac{\partial F_I^j(r_A, r^j)}{\partial r_A^T} \right)}_{\chi_1^{ij}} + (r_u - r_A)^T \\ &\quad \cdot \underbrace{\left( \frac{\partial^2 F_I^i(r_A, r^i)}{\partial r_A \partial r_A} - \frac{\partial^2 F_I^j(r_A, r^j)}{\partial r_A \partial r_A} \right)}_{\psi_1^{ij}} \cdot (r_u - r_A)\end{aligned}$$

忽略梯度变化在方向的相关性, 则有

$$\psi_1^{ij} = \frac{\partial^2 F_I^i(r_A, r^i)}{\partial r_A \partial r_A} - \frac{\partial^2 F_I^j(r_A, r^j)}{\partial r_A \partial r_A} \approx \begin{bmatrix} a & 0 & 0 \\ 0 & b & 0 \\ 0 & 0 & c \end{bmatrix}$$

$$I_{uA}^{ij} = (r_u - r_A)^T \cdot \chi_1^{ij} + \underbrace{\left[ (r_u - r_A)_x^2 \quad (r_u - r_A)_y^2 \quad (r_u - r_A)_z^2 \right]}_{\tau_u^A} \begin{bmatrix} a \\ b \\ c \end{bmatrix}$$

主参考站 A 与基准站  $B_1, B_2, B_3, \dots, B_n$  分别组成基线，即有

$$AB_1, AB_2, AB_3, \dots, AB_n$$

对于双差电离层有

$$\underbrace{\begin{bmatrix} I_{B_1A}^{ij} \\ I_{B_2A}^{ij} \\ I_{B_3A}^{ij} \\ \vdots \\ I_{B_nA}^{ij} \end{bmatrix}}_{L_I^{ij}} = \underbrace{\begin{bmatrix} (S \cdot (r_{B_1} - r_A))^T & \tau_{B_1}^A \\ (S \cdot (r_{B_2} - r_A))^T & \tau_{B_2}^A \\ (S \cdot (r_{B_3} - r_A))^T & \tau_{B_3}^A \\ \vdots & \vdots \\ (S \cdot (r_{B_n} - r_A))^T & \tau_{B_n}^A \end{bmatrix}}_{\Phi} \cdot \begin{bmatrix} \chi_{I,ENU}^{ij} \\ a \\ b \\ c \end{bmatrix}$$

$$L_I^{ij} = \Phi \cdot \begin{bmatrix} \chi_{I,ENU}^{ij} \\ a \\ b \\ c \end{bmatrix}$$

对上式进行最小二乘估计，可得

$$\begin{bmatrix} \chi_{I,ENU}^{ij} \\ a \\ b \\ c \end{bmatrix} = (\Phi^T \cdot \Phi)^{-1} \cdot \Phi^T \cdot L_I^{ij}$$

由上式计算虚拟站 V 的双差电离层，即

$$I_{VA}^{ij} = (r_V - r_A)^T \cdot \chi_1^{ij} + (r_u - r_A)^T \cdot (r_u - r_A) \cdot \begin{bmatrix} a \\ b \\ c \end{bmatrix} = (S \cdot (r_V - r_A))^T \cdot \chi_{I,ENU}^{ij} + \tau_V^A \cdot \begin{bmatrix} a \\ b \\ c \end{bmatrix}$$

$$= \left[ (S \cdot (r_V - r_A))^T \quad \tau_V^A \right] \cdot (\Phi^T \cdot \Phi)^{-1} \cdot \Phi^T \cdot L_I^{ij}$$

对于双差对流层同理。