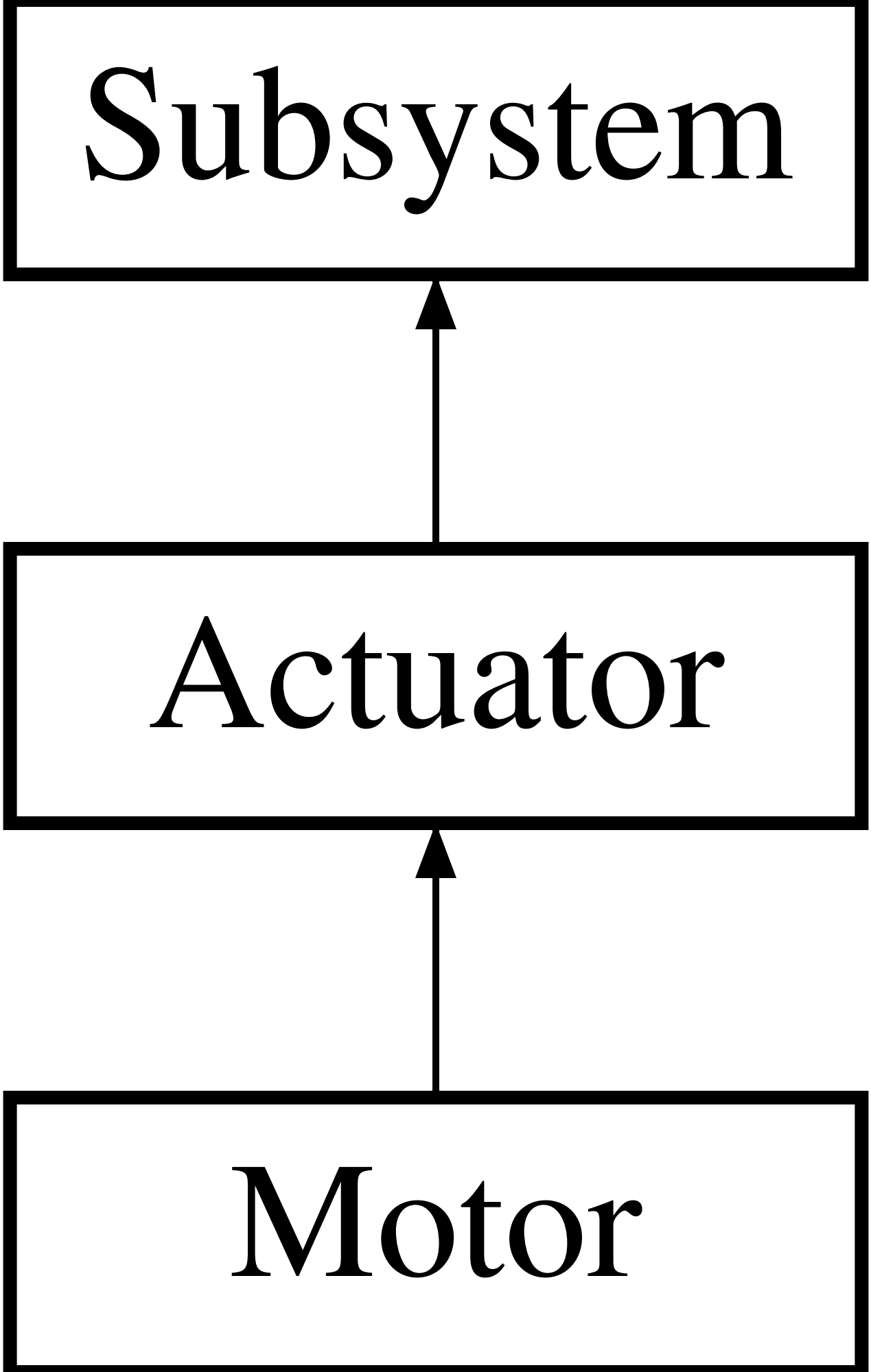


Subsystem



```
graph BT; Motor --> Actuator; Actuator --> Subsystem
```

Actuator

Motor