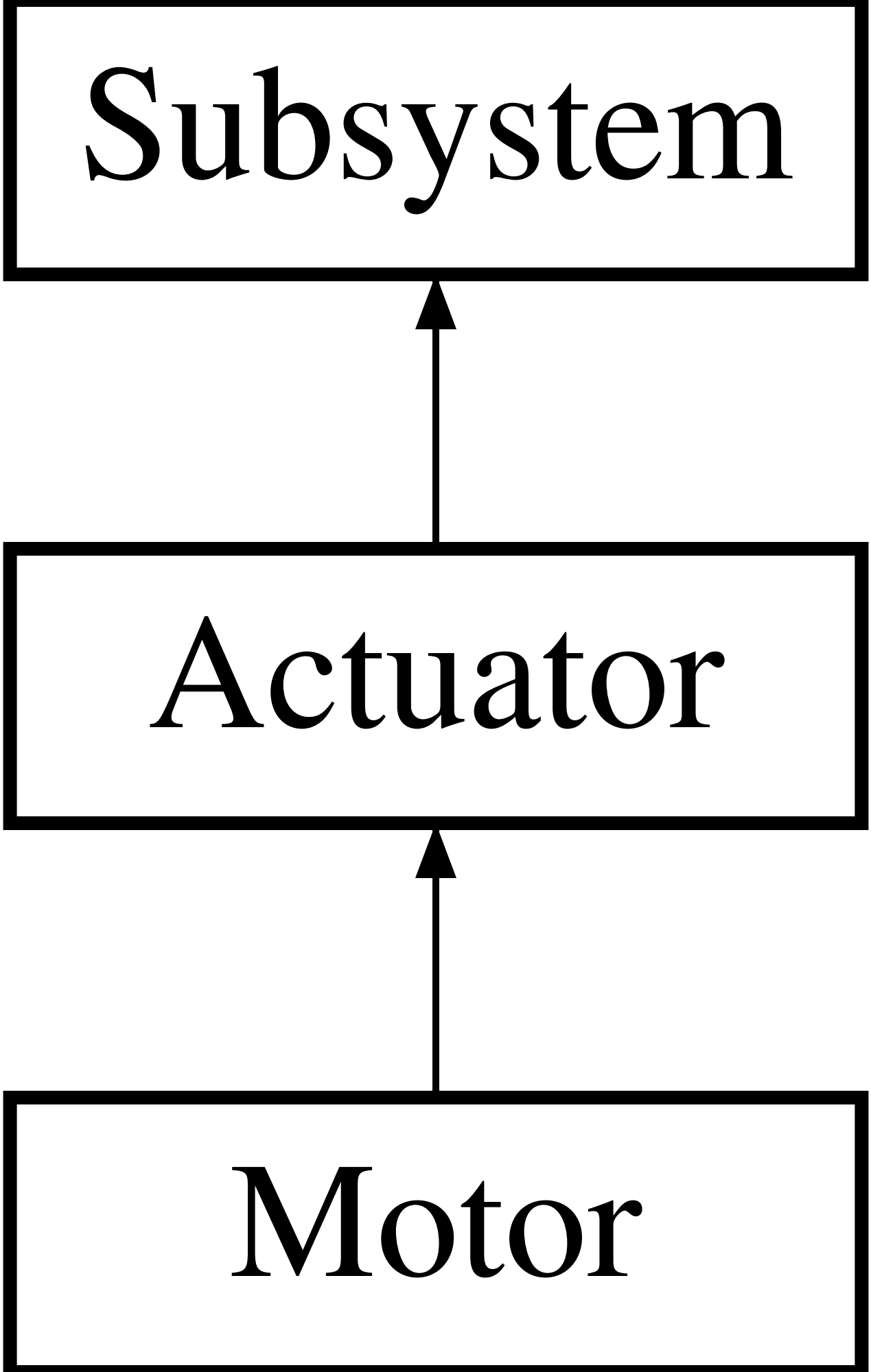


Subsystem



```
graph BT; Motor[Motor] --> Actuator[Actuator]; Actuator --> Subsystem[Subsystem]
```

Actuator

Motor