

Non-Linear Support Vector Machine Classifiers

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Abstract—This paper examines three kernel dot products for classifying data in \mathbb{R}^2 : the linear kernel, the third order kernel, and the radial basis (square exponential) kernel. Source code to reproduce the experiments is given at the end of the paper.

Index Terms—Kernel technique, regression, vector classifier, linear kernel, third-order kernel, radial basis function

I. INTRODUCTION

A. Linear Kernel

We represent the kernel as:

$$k(\underline{\mathbf{X}}, \underline{\mathbf{Z}}) = \underline{\mathbf{X}}^T \underline{\mathbf{Z}} \quad (1)$$

B. Third Order Polynomial

We represent the kernel as:

$$k(\underline{\mathbf{X}}, \underline{\mathbf{Z}}) = \|\underline{\mathbf{X}} - \underline{\mathbf{Z}}\|^3 \quad (2)$$

C. Radial Basis

We represent the kernel as:

$$k(\underline{\mathbf{X}}, \underline{\mathbf{Z}}) = e^{-\frac{\|\underline{\mathbf{X}} - \underline{\mathbf{Z}}\|^2}{2\sigma^2}} \quad (3)$$

II. EXPERIMENTS

A. Linear Kernel

Here, we apply the linear classifier to the data that is linearly separable and we see a result that is exactly what we expect.

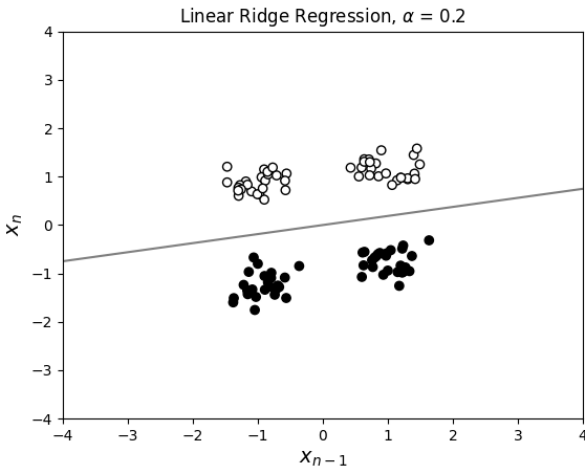


Fig. 1. Example in \mathbb{R}^2 with a linear classifier separating the two classes

While this model works well for the lower values of α , it breaks down when α increases and the data is no longer

linearly separable with zero errors. The kernel is not usable in this case.

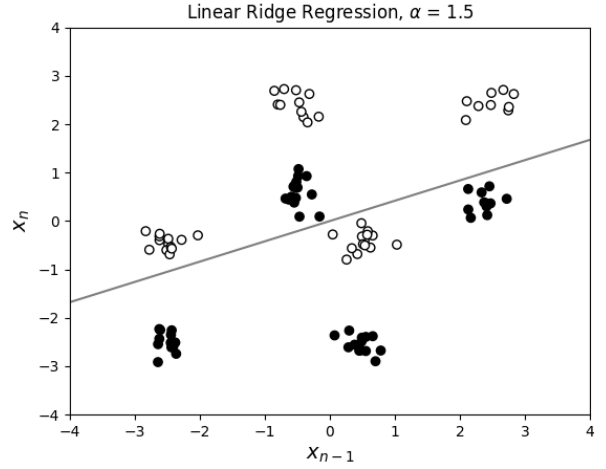


Fig. 2. Example in \mathbb{R}^2 where the data is not linearly separable with zero errors

B. Nonlinear Third-Order Polynomial

Because the linear kernel does not accurately classify the data with a larger value of α , we must find a new solution. Here, we apply the nonlinear kernel—and we see that with the first distribution, we still achieve a result similar to the linear classifier.

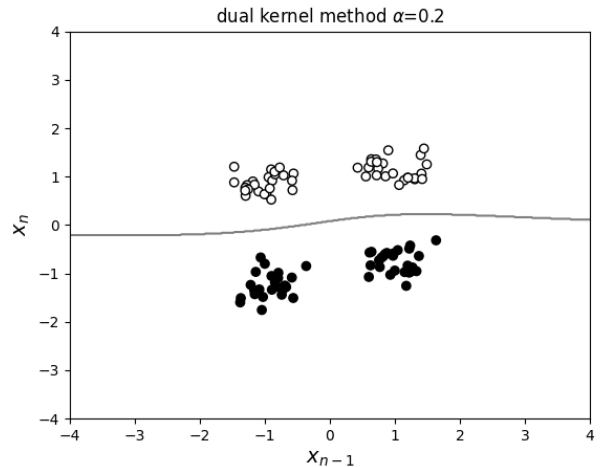


Fig. 3. Applying the nonlinear kernel to our data $\alpha = 0.2, N = 100$

Unlike the linear classifier—however—the third order polynomial can accurately separate the distribution with the larger value for α .

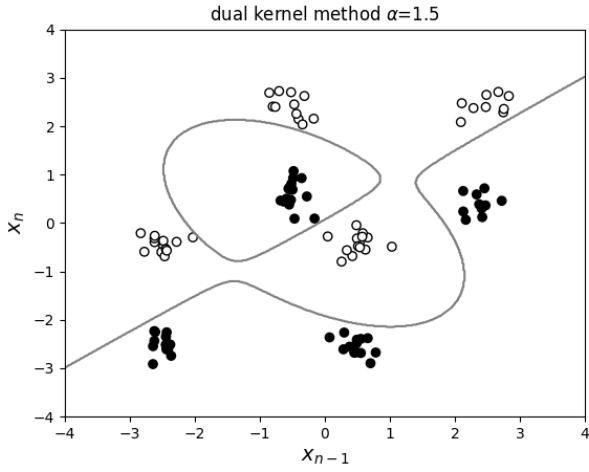


Fig. 4. Applying the nonlinear kernel to our data $\alpha = 1.5, N = 100$

C. Radial Basis Kernel

The third order polynomial can capture the distribution of our data with a reasonable degree of accuracy; however, this kernel underfits. When we apply the radial basis kernel on our first distribution with the lower value of α we see the following:

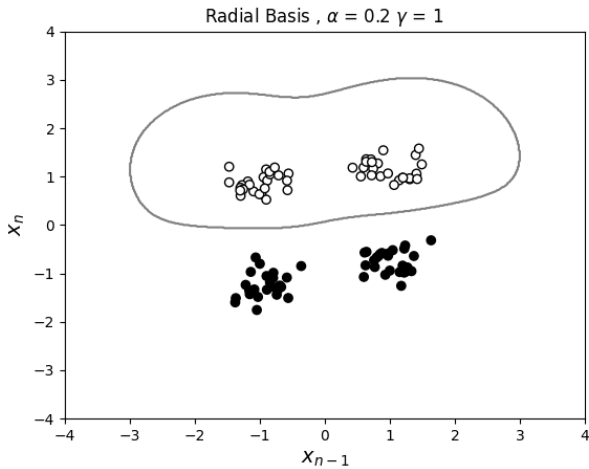


Fig. 5. Applying the radial basis kernel to our data $\alpha = 0.2, N = 100$

At first glance, this result seems less promising; however, when applied to the data that is not linearly separable with zero errors, we achieve a contour that captures the data with a higher degree of accuracy—and does not appear to underfit our distribution.

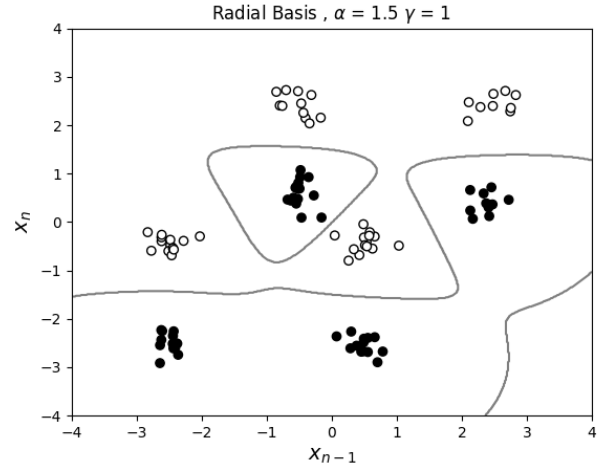


Fig. 6. Applying the radial basis kernel to our data $\alpha = 1.5, N = 100$

III. CONCLUSION

The radial basis kernel and the polynomial kernel both can accurately capture a nonlinear distribution; however, in the case of our data, the radial basis kernel appears more accurate. This is likely because the original distribution in our data function follows a gaussian—which is being approximated with the kernel we are using to generate the contour.

IV. SOURCE CODE

https://github.com/keithhboba/support_vector_machines/