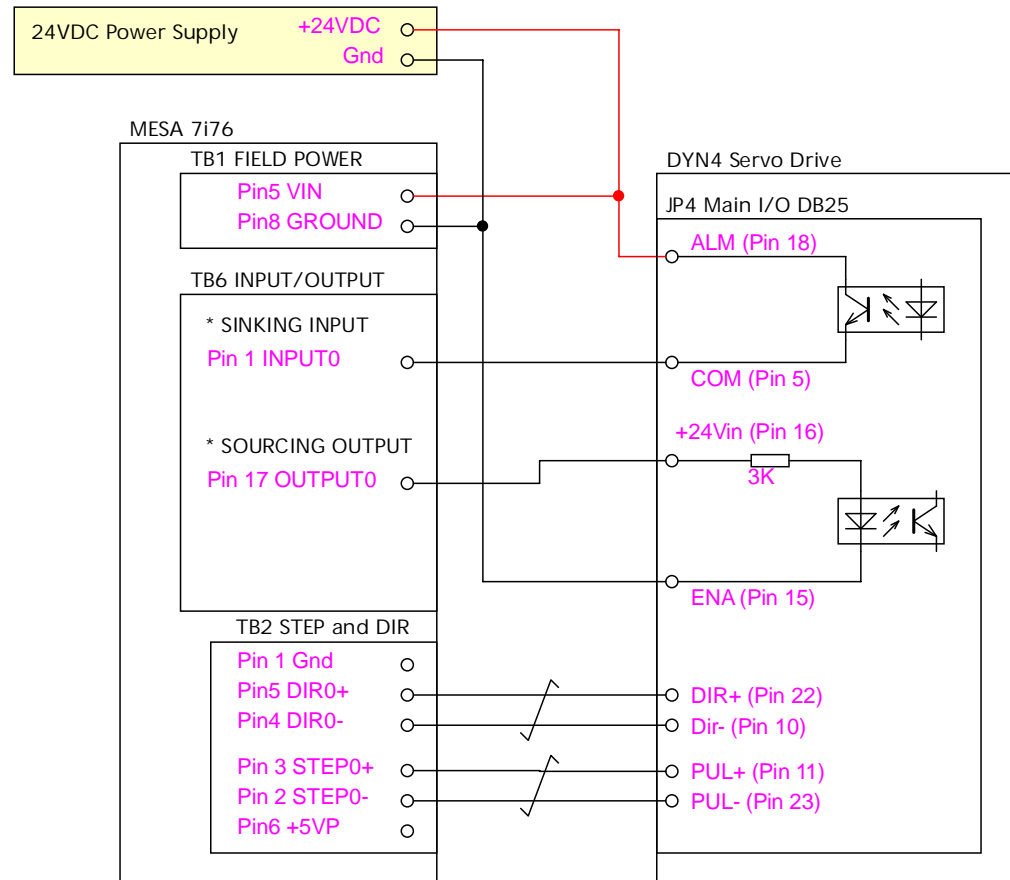Note:
- DYN4 servo drive enable logic default
is active high/enabled when high

- DYN4 servo drive alarm is active low,
output is low when servo drive fault/alarm

- Set DYN4 servo drive to PULSE/DIR
command input mode, position servo mode

24VDC Power Supply   +24VDC
                     Gnd

MESA 7i76
TB1 FIELD POWER
Pin5 VIN
Pin8 GROUND

DYN4 Servo Drive
JP4 Main I/O DB25

TB6 INPUT/OUTPUT

ALM (Pin 18)

* SINKING INPUT
Pin 1 INPUT0

COM (Pin 5)

+24Vin (Pin 16)

* SOURCING OUTPUT
Pin 17 OUTPUT0
                                3K

ENA (Pin 15)

TB2 STEP and DIR
Pin 1 Gnd
Pin5 DIR0+   DIR+ (Pin 22)
Pin4 DIR0-   Dir- (Pin 10)

Pin 3 STEP0+   PUL+ (Pin 11)
Pin 2 STEP0-   PUL- (Pin 23)
Pin6 +5VP

7i77 Reference: http://www.mesanet.com/pdf/parallel/7i76man.pdf

Responsible dep.	Technical reference	Created	Approved	
		Document type	Document status	Rev.
		Title, supplementary title		Scale
			Date of issue	Lang.	Sheet
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