

# Integration and Integration

K

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# Introduction

One problem of the Riemann integral is that some functions are not Riemann integratable.

**Example 0.0.1** (Dirichlet function). For  $[a, b] \subset \mathbb{R}$ , define the Dirichlet function as

$$g : [a, b] \rightarrow \mathbb{R}, x \mapsto g(x) := \begin{cases} 1 & \text{for } x \in \mathbb{Q}, \\ 0 & \text{for } x \in \mathbb{R} \setminus \mathbb{Q}. \end{cases} \quad (1)$$

What are the properties a generalized concept of volumina should have?

1. positive valued
2. null empty set
3. monotonous
4. translationinvariance
5. normalization

**Definition 0.1.** Let  $\mu : \mathcal{P}(\mathbb{R}^n) \rightarrow \overline{\mathbb{R}}_0^+$ .

- $\mu$  is monotonous.
- $\mu$  is translationinvariant.
- $\mu$  is  $\sigma$ -additive.

**Theorem 0.1.1** (Vitali's Theorem).



## Part I

# $\sigma$ -algebra and measures

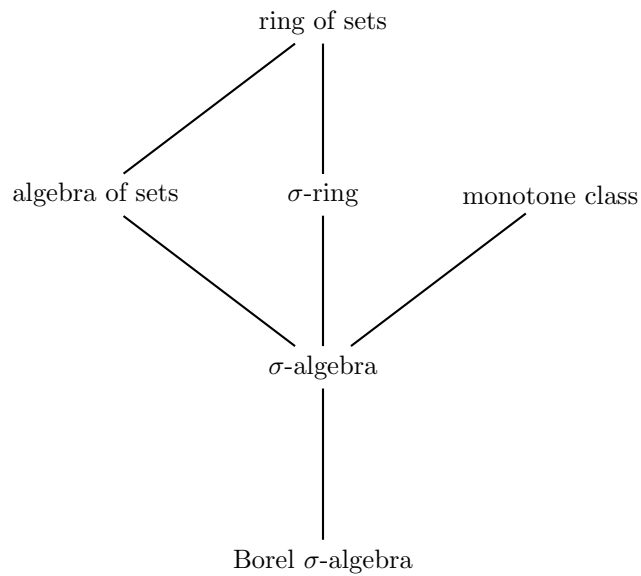




# Chapter 1

## Family of Sets

We have the following tree of inclusion.



### 1.1 Symmetric Difference

**Definition 1.1** (Symmetric difference).

**Theorem 1.1.1** (Rules for symmetric difference).

### 1.2 Ring of Sets

**Definition 1.2** (Ring of sets). There are two equivalent definitions. Let  $\Omega$  be a set and  $\mathcal{R} \subset \mathcal{P}(\Omega)$  a system of subsets. Then  $\mathcal{R}$  is a ring of sets over  $\Omega$ , if

1. the following axioms are met.
  - (a)  $\mathcal{R} \neq \emptyset$  ( $\mathcal{R}$  is nonempty.)
  - (b)  $A, B \in \mathcal{R} \Rightarrow A \setminus B \in \mathcal{R}$  ( $\mathcal{R}$  is closed under relative complement.)
  - (c)  $A, B \in \mathcal{R} \Rightarrow A \cup B \in \mathcal{R}$  ( $\mathcal{R}$  is closed under finite unions.)
2.  $(\mathcal{R}, \Delta, \cap)$  is a ring in the algebraic sense, with  $\Delta$  as addition and  $\cap$  as multiplication.

**Remark.** In the above definition, the condition that  $\mathcal{R}$  is closed under the relative complement, i.e.

$$A, B \in \mathcal{R} \Rightarrow A \setminus B \in \mathcal{R} \quad (1.1)$$

can be replaced with closure under finite intersection, therefore

$$A, B \in \mathcal{R} \Rightarrow A \cap B \in \mathcal{R} \quad (1.2)$$

because  $A \cap B = A \setminus (A \setminus B)$ .

**Theorem 1.2.1** (Properties of ring of sets).

### 1.3 Algebra of Sets

**Definition 1.3** (Algebra of sets). There are two equivalent definitions.

1. A ring of sets  $\mathcal{A}$  is a algebra of sets if it contains  $\Omega$

### 1.4 $\sigma$ -Ring

**Definition 1.4** ( $\sigma$ -Ring). Let  $\Omega$  be set and  $\mathcal{R} \subset \mathcal{P}(\Omega)$  a system of subsets.  $\mathcal{R}$  is a  $\sigma$ -ring over  $\Omega$ , if

1.  $\mathcal{R} \neq \emptyset$ .
2.  $A, B \in \mathcal{R} \Rightarrow A \setminus B \in \mathcal{R}$
3.  $A_1, A_2, A_3, \dots \in \mathcal{R} \Rightarrow \bigcup_{k=1}^{\infty} A_k \in \mathcal{R}$

### 1.5 $\sigma$ -Algebra

**Definition 1.5** ( $\sigma$ -algebra). Let  $\Omega$  be set and  $\mathcal{A} \subset \mathcal{P}(\Omega)$  a system of subsets.  $\mathcal{A}$  is a  $\sigma$ -algebra over  $\Omega$ , if

1.  $\mathcal{A} \neq \emptyset$ .
2.  $A \in \mathcal{A} \Rightarrow A^c \in \mathcal{A}$
3.  $A_1, A_2, A_3, \dots \in \mathcal{A} \Rightarrow \bigcup_{k=1}^{\infty} A_k \in \mathcal{A}$

**Example 1.5.1.** Trivial examples for the above structures.

**Example 1.5.2.** Let

$$\mathfrak{Q}(\mathbb{R}) := \left\{ \bigcup_{i=1}^m [a_i, b_i) \mid m \in \mathbb{N}; a_i, b_i \in \mathbb{R} \right\} \quad (1.3)$$

be the set of all unions of finitely many right half open intervals on  $\mathbb{R}$ . Then,  $\mathfrak{Q}(\mathbb{R})$  is a set of rings. Similarly for the left half open sets, but not for open or closed intervals!  $\mathfrak{Q}(\mathbb{R})$  is neither  $\sigma$ -ring,  $\sigma$ -algebra nor an algebra of sets. One can generalize this to higher dimensions.

**Definition 1.6.** Let  $\mathcal{E} \subset \mathcal{P}(\Omega)$  be a system of sets. Define

$$\mathcal{F}(\mathcal{E}) := \{ \mathcal{A} \subset \mathcal{P}(\Omega) \mid \mathcal{E} \subset \mathcal{A}, \mathcal{A} \sigma\text{-Algebra} \} \quad (1.4)$$

$$\langle \mathcal{E} \rangle^\sigma := \sigma(\mathcal{E}) := \bigcap_{\mathcal{A} \in \mathcal{F}(\mathcal{E})} \mathcal{A} \quad (1.5)$$

The first is the family of all  $\sigma$ -algebras that contain  $\mathcal{E}$ . The second is the smallest  $\sigma$ -algebra that contains  $\mathcal{E}$ .

## 1.6 Monotone Class

**Definition 1.7** (Monotone class). Let  $\mathcal{M} \subset \mathcal{P}(\Omega)$  a system of sets and  $k \in \mathbb{N}^*$ . Then,  $\mathcal{M}$  is a monotone class, if

1. Let  $X_k \in \mathcal{M}$  with  $X_k \uparrow X$ , then  $X \in \mathcal{M}$ .
2. Let  $Y_k \in \mathcal{M}$  with  $Y_k \downarrow X$ , then  $X \in \mathcal{M}$ .

Intersection of arbitrary many monotonous class is again a monotonous class. Therefore, for all  $\mathcal{E} \subset \mathcal{P}(\Omega)$  with  $\mathcal{E} \neq \emptyset$  there exists the smallest monotonous class around  $\mathcal{E}$

$$\mathcal{M}_{\mathcal{E}} := \bigcap_{\mathcal{M} \text{ is monotonous class, } \mathcal{E} \subset \mathcal{M}} \mathcal{M} \quad (1.6)$$

**Remark.** All  $\sigma$ -algebras are monotone class.

**Theorem 1.7.1.** Let  $\mathcal{A} \subset \mathcal{P}(\Omega)$  an algebra of sets. Then, the following are equivalent

- $\mathcal{A}$  is a  $\sigma$ -algebra.
- For  $A_k \uparrow A$ ,  $A \in \mathcal{A}$ .

## 1.7 Product Algebra??

**Definition 1.8.** Let  $\Omega_1$  and  $\Omega_2$  be sets; let  $\mathcal{R}_1 \subset \mathcal{P}(\Omega_1)$  and  $\mathcal{R}_2 \subset \mathcal{P}(\Omega_2)$  be ring of sets, and  $\Omega := \Omega_1 \times \Omega_2$ . Define

$$\mathcal{R} := \mathcal{R}_1 \boxtimes \mathcal{R}_2 := \left\{ \bigcup_{i=1}^m A_i \times B_i \mid A_i \in \mathcal{R}_1, B_i \in \mathcal{R}_2, m \in \mathbb{N} \right\} \quad (1.7)$$

$\mathcal{R}$  is a ring of sets over  $\Omega$ .

**Theorem 1.8.1.** In above definition, if  $\mathcal{R}_1$  and  $\mathcal{R}_2$  are algebra of sets, then  $\mathcal{R}$  is a algebra of set.

**Theorem 1.8.2.**

$$\mathcal{Q}(\mathbb{R}^n) \quad (1.8)$$

is a ring of sets.

**Remark.** From  $\mathcal{Q}(\mathbb{R}^n)$  we can construct one very important  $\sigma$ -algebra, the Borel-Algebra of  $\mathbb{R}^n$ .

**Definition 1.9** (Products of  $\sigma$ -algebras). Let  $\mathcal{A}_1$  and  $\mathcal{A}_2$  be  $\sigma$ -algebras on  $\Omega_1, \Omega_2$ . Then, let

$$\mathcal{A}_1 \otimes \mathcal{A}_2 = \sigma(\mathcal{A}_1 \boxtimes \mathcal{A}_2) \quad (1.9)$$

**Example 1.9.1.**

$$\mathcal{B}(\mathbb{R}^{n+m}) = \mathcal{B}(\mathbb{R}^n) \otimes \mathcal{B}(\mathbb{R}^m) \quad (1.10)$$

**Definition 1.10.** Let  $(X_k)_{k \in \mathbb{N}^*}$  be a sequence of sets with  $X_1 \subset X_2 \subset X_3 \subset \dots$  and  $X := \lim_{k \rightarrow \infty} X_k := \bigcup_{k \in \mathbb{N}^*} X_k$ . Similar for monotonously decreasing.

## 1.8 Borel $\sigma$ -algebra

**Definition 1.11.** Let  $\Omega$  be a set. A collection  $\mathcal{U} \subset \mathcal{P}(\Omega)$  of subsets of  $X$  is called a topology on  $X$  if it satisfies the following axioms.

1.  $\emptyset, X \in \mathcal{U}$ .

2. If  $n \in \mathbb{N}$  and  $U_1, \dots, U_n \in \mathcal{U}$  then  $\bigcap_{i=1}^n U_i \in \mathcal{U}$ .
3. If  $I$  is any index set and  $U_i \in \mathcal{U}$  for  $i \in I$  then  $\bigcup_{i \in I} U_i \in \mathcal{U}$ .

A topological space is a pair  $(\Omega, \mathcal{U})$  consisting of a set  $\Omega$  and a topology  $\mathcal{U} \in \mathcal{P}(\Omega)$ .

**Example 1.11.1** (Standard Topology on  $\overline{\mathbb{R}}$ ). The set of open subsets  $\mathcal{T}$  of  $\overline{\mathbb{R}}$  is the standard topology on  $\overline{\mathbb{R}}$ . Concretely,  $\mathcal{T}$  contains countable union of open intervals in  $\mathbb{R}$  and sets of the form  $(a, \infty]$  or  $[-\infty, b)$  for  $a, b \in \mathbb{R}$ .

**Definition 1.12** (Borel algebra). Let  $(\Omega, \mathcal{T})$  be a topological space, then  $\mathcal{B}(\Omega) := \sigma(\mathcal{T})$  is the Borel  $\sigma$ -algebra of  $\Omega$ . The elements of  $\mathcal{B}$  are called Borel (measurable) sets. There are many ways to generate this algebra.

**Theorem 1.12.1.** Let  $(\Omega, \mathcal{T})$  be a topological space. Then the following holds.

1. Every closed subset  $F \subset \Omega$  is a Borel set.
2. Every countable union  $\bigcup_{i=1}^{\infty} F_i$  of closed subsets  $F_i \subset \Omega$  is a Borel set.
3. Every countable intersection  $\bigcap_{i=1}^{\infty} F_i$  of open subsets  $F_i \subset \Omega$  is a Borel set.

**Theorem 1.12.2.** It is

$$\mathcal{B}(\mathbb{R}^n) = \sigma(\mathfrak{Q}(\mathbb{R}^n)) \quad (1.11)$$

Moreover, define

$$\mathfrak{Q}_{\mathbb{Q}}(\mathbb{R}^n) := \left\{ \bigcup_{i=1}^m [a_{1,i}, b_{1,i}) \times \dots \times [a_{n,i}, b_{n,i}) \mid m \in \mathbb{N}; a_{\nu,i}, b_{\nu,i} \in \mathbb{Q}; \nu = 1, \dots, n \right\} \quad (1.12)$$

the ring of sets of finite unions of quadern with rational edge points. Then, we even have

$$\mathcal{R}(\mathbb{R}^n) = \sigma(\mathfrak{Q}_{\mathbb{Q}}(\mathbb{R}^n)) \quad (1.13)$$

**Lemma 1.12.1.** Open subsets  $U \subset \mathbb{R}^n$  are disjoint union of countably many right half open dices with edge points in  $\mathbb{Q}^n$

## 1.9 Exercises

## Chapter 2

# Measure

**Definition 2.1.** Let  $\mathcal{R} \subset \mathcal{P}(\Omega)$  a ring of sets, and let  $\mu : \mathcal{R} \rightarrow [0, \infty]$  be an application.  $\mu$  is called a content, if

1.  $\mu(\emptyset) = 0$ .
2.  $\mu(A \dot{\cup} B) = \mu(A) + \mu(B)$

An  $\sigma$ -additive content is called premeasure.

A premeasure  $\mu : \mathcal{A} \rightarrow [0, \infty]$  on  $\sigma$ -algebra  $\mathcal{A}$  is called a measure.

$\mu$  is finite if for all  $A \in \mathcal{R} : \mu(A) < \infty$ .

$\mu$  is  $\sigma$ -finite if there exists a sequence  $(A_m)_{m \in \mathbb{N}^*}$  in  $\mathcal{R}$  with  $\mu(A_m) < \infty$  and  $\bigcup_{m \in \mathbb{N}^*} A_m = \Omega$ .

**Lemma 2.1.1.** If  $\mu(A \cap B) < \infty$ , then

$$\mu(A \cap B) = \mu(A) + \mu(B) - \mu(A \cup B) \quad (2.1)$$

**Theorem 2.1.1** (Properties of premeasure).

**Example 2.1.1** (Dirac-measure). Let  $\Omega \neq \emptyset$ . Let  $\mathcal{A} \subset \mathcal{P}(\Omega)$  a  $\sigma$ -algebra. Define for all  $x \in \Omega$  a  $\delta_x : \mathcal{A} \rightarrow \mathbb{R}_0^+$  with

$$\delta_x(A) := \begin{cases} 1, & \text{if } x \in A \\ 0, & \text{else.} \end{cases} \quad (2.2)$$

$\delta_x$  is a finite measure, called the Dirac-measure.

**Definition 2.2.** Let

$$\mathfrak{Q}(\mathbb{R}^n) := \left\{ \bigcup_{i=1}^m [a_{1,i}, b_{1,i}) \times \dots \times [a_{n,i}, b_{n,i}) \mid m \in \mathbb{N}; a_{\nu,i}, b_{\nu,i} \in \mathbb{R}; \nu = 1, \dots, n \right\} \quad (2.3)$$

define

$$\lambda^n : \mathfrak{Q}(\mathbb{R}^n) \rightarrow \mathbb{R}_0^+, A \mapsto \lambda^n(A) := \sum_{i=1}^m \prod_{\nu=1}^n (b_{\nu,i} - a_{\nu,i}) \quad (2.4)$$

is a premeasure.

**Definition 2.3.**

$$\mathcal{R}^\uparrow := \{A \in \mathcal{P}(\Omega) \mid \exists (A_k)_{k \in \mathbb{N}^*} \subset \mathcal{R} \text{ with } A_k \uparrow A\} \quad (2.5)$$

$\mathcal{R}^\uparrow$  is the set of all  $A \in \mathcal{P}(\Omega)$  that can be expressed as countably many sets from  $\mathcal{R}$ .  $\mathcal{R}^\uparrow$  is not a ring of sets.

**Definition 2.4.** Let  $\mu : \mathcal{R} \rightarrow [0, \infty]$  be a premeasure on  $\mathcal{R}$ , and  $A_k \uparrow A$ . Then,

$$\tilde{\mu} : \mathcal{R}^\uparrow \rightarrow [0, \infty], A \mapsto \tilde{\mu}(A) = \lim_{k \rightarrow \infty} \mu(A_k) \quad (2.6)$$

is an extension of  $\mu$  on  $\mathcal{R}^\uparrow$ . This is not in general a premeasure.

**Theorem 2.4.1** (Properties of the first extension).

**Definition 2.5.** Let  $\mathcal{R} \subset \mathcal{P}(\Omega)$  a set of rings,  $\mu : \mathcal{R} \rightarrow [0, \infty]$  a  $\sigma$ -finite premeasure on  $\mathcal{R}$ , and  $\tilde{\mu} : \mathcal{R}^\uparrow \rightarrow [0, \infty]$  the first extension on  $\mathcal{R}^\uparrow$ . Moreover, let  $X \subset \Omega$  a subset of  $\Omega$ . Then,

$$\mu^* : \mathcal{P}(\Omega) \rightarrow [0, \infty], X \mapsto \mu^*(X) := \inf \{ \tilde{\mu}(A) \mid A \in \mathcal{R}^\uparrow, X \subset A \} \quad (2.7)$$

is the outer measure.

**Theorem 2.5.1** (Properties of the second extension).

Bla Bla bla

**Definition 2.6** (Lebesgue measure).

**Part II**

**Lebesgue Integral**





## Chapter 3

# Measurable Functions

**Definition 3.1** (Measurable Function). Let  $(X, \mathcal{A}_X)$  and  $(Y, \mathcal{A}_Y)$  be measurable spaces. A map  $f : X \rightarrow Y$  is called measurable if the pre-image of every measurable subset of  $Y$  under  $f$  is measurable subset of  $X$ , i.e.

$$B \in \mathcal{A}_Y \Rightarrow f^{-1}(B) \in \mathcal{A}_X. \quad (3.1)$$

**Definition 3.2.** Let  $(X, \mathcal{A}_X)$  be a measurable space. A function  $f : \Omega \rightarrow \overline{\mathbb{R}}$  is called measurable if it is measurable with respect to the Borel  $\sigma$ -algebra on  $\overline{\mathbb{R}}$

**Definition 3.3** (Borel Measurable Maps).

**Theorem 3.3.1.** Let  $(\Omega, \mathcal{A})$  be a measurable space, and  $\mathcal{B} = \sigma(\mathcal{E})$  for a generator  $\mathcal{E} \subset \mathcal{P}(\Omega)$ . If for all  $E \in \mathcal{E}$  it is  $f^{-1}(E) \in \mathcal{A}$ , then  $f$  is measurable.

**Example 3.3.1.** Let  $f : (\mathbb{R}, \mathcal{B}) \rightarrow (\mathbb{R}, \mathcal{B})$  defined as

$$f(x) := \begin{cases} 1 & x \in Q \\ -1 & x \notin Q \end{cases} \quad (3.2)$$

for a  $Q \notin \mathcal{B}(\mathbb{R})$ . Then,  $f^{-1}(1) = Q \notin \mathcal{B}$  and therefore,  $f$  is not measurable even though  $|f| = 1$  is measurable.



## Chapter 4

# Convergence Theorems

**Theorem 4.0.1** (Beppo Levi). Let  $(\Omega, \mathcal{A}, \mu)$  a measure space, and for  $k \in \mathbb{N}^*$ , let  $f_k : \Omega \rightarrow \mathbb{R}$  be a sequence of integrable functions such that

$$\forall x \in \Omega, \forall n \in \mathbb{N} : f_n(x) \leq f_{n+1}(x). \quad (4.1)$$

Moreover, if there exists  $M \in \mathbb{R}$  with  $\forall k : \int f_k d\mu \leq M$ , then

$$f := \lim_{k \rightarrow \infty} f_k : \Omega \rightarrow \overline{\mathbb{R}} \quad (4.2)$$

integrable with

$$\int f d\mu = \lim_{k \rightarrow \infty} \int f_k d\mu \quad (4.3)$$

**Theorem 4.0.2.** If the Riemann integral exists, it matches the Lebesgue integral.

**Theorem 4.0.3.** Let  $(\Omega, \mathcal{A}, \mu)$  a measure space, let  $g : X \rightarrow [0, \infty)$  be an integrable function, and let  $f_n : X \rightarrow \mathbb{R}$  be a sequence of integrable functions satisfying

$$|f_n(x)| \leq g(x) \text{ for all } x \in X \text{ and } n \in \mathbb{N} \quad (4.4)$$

and converging pointwise to  $f : X \rightarrow \mathbb{R}$ . Then  $f$  is integrable and, for every  $E \in \mathcal{A}$

$$\int_E f d\mu = \lim_{n \rightarrow \infty} \int_E f_n d\mu \quad (4.5)$$



# Part III

## Applications



## Chapter 5

# Cavalieri's Principle

**Definition 5.1** (Cross-section). Let  $\mathbb{R}^n = \mathbb{R}^k \times \mathbb{R}^l$  with  $n, k, l \in \mathbb{N}^*$ , and  $A \subset \mathbb{R}^n$ . Then for a  $y \in \mathbb{R}^l$

$$A_y := \{x \in \mathbb{R}^k \mid (x, y) \in A\} \quad (5.1)$$

is the  $l$ -dimensional cross-sections of  $A$ .

**Remark.** Immediately from the definition above, we have

$$A = \bigcup_{y \in \mathbb{R}^l} (A_y, y). \quad (5.2)$$

In other words,  $\{(A_y, y)\}_{y \in \mathbb{R}^l}$  is a partition of  $A$ .

**Theorem 5.1.1** (Cavalieri's principle). Let  $\mathbb{R}^n = \mathbb{R}^k \times \mathbb{R}^l$  with  $n, k, l \in \mathbb{N}^*$ , let  $A \subset \mathbb{R}^k \times \mathbb{R}^l$  a Borel subset of  $\mathbb{R}^n$ , and let  $\{(A_y, y)\}_{y \in \mathbb{R}^l}$  be a partition of  $A$  via cross-sections. Then we have the following

1. For all  $y \in \mathbb{R}^l$ ,  $A_y$  is Borel subset of  $\mathbb{R}^k$ .
2. Let  $F_A : \mathbb{R}^l \rightarrow [0, \infty]$ ,  $y \mapsto F_A(y) := \text{Vol}_k(A_y) = \lambda^k(A_y)$  be the  $k$ -dimensional volume of  $A_y$ . Then  $F_A$  is Borel measurable on  $\mathbb{R}^l$ .
3.  $\text{Vol}_n(A) := \int_{\mathbb{R}^l} \text{Vol}_k(A_y)$

*Proof.* 1. Fix  $y \in \mathbb{R}^l$

**Theorem 5.1.2.** For  $K \subset \mathbb{R}^n$  compact, we have

$$\text{Vol}_n(K) = \int_{\mathbb{R}} \text{Vol}_{n-1}(K_t) \quad (5.3)$$





## Chapter 6

# Finding Volume by Rotation

**Definition 6.1.**  $F : \mathbb{R}^n \rightarrow \overline{\mathbb{R}}$  is rotationally symmetric in  $\mathbb{R}^n$  if there exists a  $f : [0, \infty) \rightarrow \overline{\mathbb{R}}$  such that for all  $x \in \mathbb{R}^n$  it is  $F(x) = f(\|x\|)$ .

**Theorem 6.1.1.** The volume of the unit sphere is

$$\tau_n = \frac{\pi^{\frac{n}{2}}}{\Gamma(\frac{n}{2} + 1)} \quad (6.1)$$

**Theorem 6.1.2.** Let  $B \subset [0, \infty)$  a Borel subset and  $A := \{x \in \mathbb{R}^n \mid \|x\| \in B\}$ . Then the Lebesgue measure of  $A$  is

$$\lambda^n(A) = n\tau_n \int_B r^{n-1} dr \quad (6.2)$$

where  $\tau_n$  is the volume of the unit sphere.

**Theorem 6.1.3.** Let  $f : [0, \infty) \rightarrow \overline{\mathbb{R}}$  is Borel measurable. Then the following are equivalent.

1.  $F : \mathbb{R}^n \rightarrow \overline{\mathbb{R}}, x \mapsto F(x) := f(\|x\|)$  is Lebesgue integrable over  $\mathbb{R}^n$ .
2.  $r^{n-1}f : [0, \infty) \rightarrow \overline{\mathbb{R}}, r \mapsto r^{n-1}f(r)$  is Lebesgue integrable over  $[0, \infty)$ .

Moreover, if one of the above is true, then we have the formula

$$\int_{\mathbb{R}^n} f(\|x\|) d^n x = n\tau_n \int_{[0, \infty)} r^{n-1} f(r) dr \quad (6.3)$$

**Example 6.1.1.** For a  $R \in \mathbb{R}^+$  and  $1 \leq i \leq n$  let

$$I_i := \int_{\|x\| \leq R} x_i^2 d^n x. \quad (6.4)$$

We immediately have  $I_i = I_j =: I$  for all  $i, j$ .

$$I = \frac{1}{n} \sum_{i=1}^n I_i \quad (6.5)$$

$$= \frac{1}{n} \sum_{i=1}^n \int_{\|x\| \leq R} x_i^2 d^n x \quad (6.6)$$

$$= \frac{1}{n} \int_{\|x\| \leq R} \sum_{i=1}^n x_i^2 d^n x \quad (6.7)$$

$$= \frac{1}{n} \int_{\|x\| \leq R} \|x\|^2 d^n x \quad (6.8)$$

$$(6.9)$$

Now with the formula above, we have

$$I = \frac{1}{n} \cdot n \cdot \tau_n \int_0^R r^{n-1} r^2 dr \quad (6.10)$$

$$= \tau_n \int_0^R r^{n+1} dr \quad (6.11)$$

$$= \tau_n \frac{R^{n+2}}{n+2} \quad (6.12)$$

**Example 6.1.2.**

$$\int_0^\infty \exp(-x^2) = \frac{\sqrt{\pi}}{2} \quad (6.13)$$

*Proof.* Define

$$I = \int_{-\infty}^\infty \exp(-x^2) dx \quad (6.14)$$

Consider

$$I^2 = \left( \int_{-\infty}^\infty \exp(-x^2) dx \right) \left( \int_{-\infty}^\infty \exp(-y^2) dy \right) \quad (6.15)$$

$$= \int_{-\infty}^\infty \int_{-\infty}^\infty \exp(-x^2) \exp(-y^2) dx dy \quad (6.16)$$

$$= \int_{-\infty}^\infty \int_{-\infty}^\infty \exp(-(x^2 + y^2)) dx dy \quad (6.17)$$

$$= \int_{\mathbb{R}^2} e^{-\|x\|^2} d^2 \lambda \quad (6.18)$$

$$= \int_0^\infty r e^{-r^2} dr \quad (6.19)$$

**Example 6.1.3.** Let  $B_1 := \{x \in \mathbb{R}^2 \mid \|x\| < 1\}$  be the open unit disk. Find the integral

$$\int_{B_1} \frac{1}{\sqrt{1 - \|x\|^2}} d\lambda^2(x) \quad (6.20)$$

*Proof.* Define  $f : [0, \infty) \rightarrow \overline{\mathbb{R}}$  as

$$f(x) = \frac{1}{\sqrt{1 - x^2}} \chi_{[0,1)}(x). \quad (6.21)$$

As  $[0, 1)$  is a Borel set of  $\mathbb{R}$ ,  $\chi_{[0,1)}$  is Borel measurable. On the other hand,  $\frac{1}{\sqrt{1-x^2}}$  is continuous for all  $x \in [0, 1)$ , so the composition of these two functions  $f$  is again Borel measurable.

Now consider,  $rf(r)$ . We have

$$\int |rf(r)| dr = \int_0^1 \frac{r}{\sqrt{1 - r^2}} dr \quad (6.22)$$

$$= -\sqrt{1 - r^2} \quad (6.23)$$

$$= 0 + 1 \quad (6.24)$$

$$= 1 \quad (6.25)$$

**Example 6.1.4.** Compute the following integral

$$f(\xi, \eta) := \int_{B_1} \frac{\exp(i(x\xi + y\eta))}{\sqrt{1 - x^2 - y^2}} dx dy \quad (6.26)$$

## Chapter 7

# Transformation Formula

**Theorem 7.0.1.** Suppose  $\phi : U \rightarrow V$  is a  $C^1$ -diffeomorphism between open subsets of  $\mathbb{R}^n$ . If  $f : V \rightarrow \mathbb{R}$  is Lebesgue integrable OR continuous with a compact support, then

$$\int_U (f \circ \phi) |\det(d\phi)| dm = \int_V f dm. \quad (7.1)$$

**Example 7.0.1.** (2D) From polar coordinates to cartesian coordinates.

$$\phi : \mathbb{R}_0^+ \times [0, 2\pi) \rightarrow \mathbb{R}^2, (r, \varphi) \mapsto \phi(r, \varphi) := (r \cos \varphi, r \sin \varphi) \quad (7.2)$$

$$D\phi(r, \varphi) = \begin{pmatrix} \cos \varphi & -r \sin \varphi \\ \sin \varphi & r \cos \varphi \end{pmatrix} \quad (7.3)$$

$$\det D\phi(r, \varphi) = r \quad (7.4)$$

(3D) From spherical coordinates to cartesian coordinates.

$$\phi : \mathbb{R}_0^+ \times [0, \pi] \times [0, 2\pi) \rightarrow \mathbb{R}^3 \quad (7.5)$$

$$(r, \theta, \varphi) \mapsto \phi(r, \theta, \varphi) := (r \sin \theta \cos \varphi, r \sin \theta \sin \varphi, r \cos \theta) \quad (7.6)$$

$$D\phi(r, \theta, \varphi) := \begin{pmatrix} \sin \theta \cos \varphi & r \cos \theta \cos \varphi & -r \sin \theta \sin \varphi \\ \sin \theta \sin \varphi & r \cos \theta \sin \varphi & r \sin \theta \cos \varphi \\ \cos \theta & -r \sin \theta & 0 \end{pmatrix} \quad (7.7)$$

$$\det D\phi(r, \theta, \varphi) = r^2 \sin \theta \quad (7.8)$$

(3D) From cylindrical coordinates to cartesian coordinates.

$$\phi : \mathbb{R} \times \mathbb{R} \times [0, 2\pi) \rightarrow \mathbb{R}^3 \quad (7.9)$$

$$x = r \cos \theta \quad (7.10)$$

$$y = r \sin \theta \quad (7.11)$$

$$z = z \quad (7.12)$$

$$D\phi(r, \theta, z) = \begin{pmatrix} \cos \theta & -r \sin \theta & 0 \\ \sin \theta & r \cos \theta & 0 \\ 0 & 0 & 1 \end{pmatrix} \quad (7.13)$$

$$\det D\phi(r, \theta, z) = r \quad (7.14)$$



**Part IV**

**More Theory**



## Chapter 8

# Lebesgue Space

**Definition 8.1** ( $L^p$ -Norm). Let  $X, \mathcal{A}, \mu$  a measure space, and  $f : X \rightarrow \overline{\mathbb{R}}$  measurable. Then for  $p \in [1, \infty)$  the  $L^p$ -norm is defined as

$$\|f\|_p := \left( \int_X |f|^p d\mu \right)^{\frac{1}{p}}. \quad (8.1)$$

**Theorem 8.1.1** (Holder Inequality). Let  $p, q \in (1, \infty)$  such that  $p^{-1} + q^{-1} = 1$ . Let  $f, g : X \rightarrow \overline{\mathbb{R}}$  measurable. Then we have

$$\|fg\|_1 \leq \|f\|_p \cdot \|g\|_q \quad (8.2)$$

**Theorem 8.1.2** (Minkowski Inequality). Let  $f, g : X \rightarrow \overline{\mathbb{R}}$  measurable and  $f + g$  well defined on  $X$ . Then

$$\forall p \in [1, \infty) : \|f + g\|_p \leq \|f\|_p + \|g\|_p \quad (8.3)$$

**Definition 8.2.** Let  $X, \mathcal{A}, \mu$  be a measure space and  $p \in [1, \infty)$ . Define

$$\mathcal{L}^p(X, \mathcal{A}, \mu) = \left\{ f : X \rightarrow \mathbb{R} \mid f \text{ is } \mathcal{A}\text{-measurable and } \|f\|_p < \infty \right\} \quad (8.4)$$





**Part V**

**Manifolds**



**Theorem 8.2.1.** If  $M \subset \mathbb{R}^n$  is a  $k$ -dimensional submanifold then the following are equivalent.

1. For all points  $a \in M$  there exists a open neighbourhood  $U \in \mathcal{U}_a(\mathbb{R})$ , and there exists a function  $f_i : U \rightarrow \mathbb{R}$  with  $1 \leq i \leq n - k$  that is  $n - k$  continuously (partially) differentiable such that

$$M \cap U = \{x \in U \mid f_1(x) = \cdots = f_{n-k}(x) = 0\} \quad (8.5)$$

and for all  $x \in U$   $Df(x) = n - k$ .

**Example 8.2.1.** The figure eight is described by  $f : \mathbb{R} \rightarrow \mathbb{R}^2$ ,  $f(t) := (\cos t, \sin 2t)$ . Define

$$M := \{x \in \mathbb{R} \mid \cos x = 0, \sin 2x = 0\} \quad (8.6)$$

then

$$D\phi(x) = \begin{pmatrix} -\sin t \\ 2 \cos 2t \end{pmatrix} \quad (8.7)$$

**Definition 8.3.** A submanifold is  $k$ -dimensional of the class  $\mathcal{C}^\alpha$  if the  $n - k$  functions that describe the submanifold is  $\alpha$  times continuously differentiable.

**Theorem 8.3.1.** Let  $M \subset \mathbb{R}^n$  a  $k$ -dimensional submanifold of the class  $\mathcal{C}^\alpha$ . Let  $i = 1, 2$   $T_i \subset \mathbb{R}^k$  open and  $\varphi_i : T_i \rightarrow V_i \subset M$  KARTEN, i.e. in parameter form of the class  $\mathcal{C}^\alpha$  with  $V := V_1 \cap V_2 \neq \emptyset$ .

### Exercise 8.1

Let  $f, g : \mathbb{R}^3 \rightarrow \mathbb{R}$  defined as

$$f(x, y, z) := x^2 + xy - y - z \quad g(x, y, z) := 2x^2 + 3xy - 2y - 3z \quad (8.8)$$

Show that

$$C := \{(x, y, z) \in \mathbb{R}^3 \mid f(x, y, z) = g(x, y, z) = 0\} \quad (8.9)$$

is a submanifold of  $\mathbb{R}^3$  and that

$$\phi : \mathbb{R} \rightarrow \mathbb{R}^3, \phi(t) := (t, t^2, t^3) \quad (8.10)$$

is a global parametrization of  $C$ .