

# Topology

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## **Chapter 1**

# **Introduction**



## Chapter 2

# Topological Spaces

### 2-1

“ $\Rightarrow$ ”: Let  $f : X_1 \longrightarrow X_2$  be a homeomorphism and fix a subset (not necessarily open)  $U \in \mathcal{T}_1$ .

1. Assume  $U$  is open in  $X_1$ . Because  $f$  is continuous, the image of open subsets are again open, thus  $f(U)$  lies in  $\mathcal{T}_2$ .
2. On the other hand, if  $f(U)$  is open in  $X_2$ , then since  $f$  is bijective we have

$$f^{-1}(f(U)) = U.$$

Because  $f$  is continuous, the preimage of open subsets under  $f$  is open. We may therefore conclude  $U$  is open in  $X_1$ .

We have shown that if  $f$  is a homeomorphism, then  $f(\mathcal{T}_1) = \mathcal{T}_2$ .

“ $\Leftarrow$ ”: Let  $f : X_1 \longrightarrow X_2$  be a bijective map such that  $f(\mathcal{T}_1) = \mathcal{T}_2$ . Consider the inverse map  $f^{-1}$ . We want to show  $f^{-1}$  is continuous. Fix an open subset  $U \in \mathcal{T}_1$ . It is

$$(f^{-1})^{-1}(U) = f(U)$$

because  $f$  is bijective. Since  $f(\mathcal{T}_1) = \mathcal{T}_2$  and  $U$  is open,  $f(U)$  is open as well. Hence the preimage of  $U$  under  $f^{-1}$  is open and  $f^{-1}$  is continuous.

Now we show that  $f$  is also continuous. Again, fix an open subset  $V \in \mathcal{T}_2$ . The preimage of  $V$  under  $f$  is just the image of the inverse function. We have already shown that the inverse is continuous. Thus,  $f^{-1}(V)$  is open and  $f$  is continuous. Since  $f$  and  $f^{-1}$  exist and are continuous,  $f$  is a homeomorphism as desired.

### 2-2

#### a)

We show that  $\mathcal{T}$  is a topology by verifying the axioms of a topology.

1. Since  $\mathcal{T}$  is the collection of all unions of finite intersections of elements of  $\mathcal{B}$ , it contains the union of all elements of  $\mathcal{B}$  which is just  $X$ . The union of empty collection generates the emptyset so  $\emptyset \in \mathcal{T}$  as well.
2. Let  $\mathcal{U} \subset \mathcal{T}$  be any subset. The elements of  $\mathcal{U}$  are unions of finite intersections of elements of  $\mathcal{B}$ . Thus,  $\bigcup_{U \in \mathcal{U}} U$  is again a union of finite intersections of elements of  $\mathcal{B}$ . In other words,  $\mathcal{T}$  is closed under union.
3.  $\mathcal{T}$  is stable under finite intersections due to distributive property of sets.

b)

**2-3**

1.

The collection of subset  $\mathcal{T}_1 = \{U \subset X \mid X \setminus U \text{ is finite or is all of } X\}$  forms a topology. We show this by verifying the axioms of a topology.

1. It is  $X \setminus \emptyset = X$  and  $X \setminus X = \emptyset$  which is finite. Thus,  $X \in \mathcal{T}_1$  and  $\emptyset \in \mathcal{T}_1$ .
2. Let  $\mathcal{U} \subset \mathcal{T}$  be a subset. By De Morgan's laws we have

$$X \setminus \left( \bigcup_{U \in \mathcal{U}} U \right) = \bigcap_{U \in \mathcal{U}} (X \setminus U).$$

Since each  $U \in \mathcal{U}$  lies in  $\mathcal{T}$ , the complement  $X \setminus U$  is finite or is all of  $X$ . Therefore, the intersection of all  $X \setminus U$  is again finite or all of  $X$ , and we may conclude that  $\mathcal{T}$  is stable under arbitrary unions.

3. Use De Morgan's law again.

2.

The collection of subsets  $\mathcal{T}_2 = \{U \subset X \mid X \setminus U \text{ is infinite or is empty}\}$  is not a topology. Take  $X = \mathbb{Z}$  for example and consider  $A = \{1, 2, 3, \dots\}$  and  $B = \{-1, -2, -3, \dots\}$ .  $A$  and  $B$  are open because their complements are the non-positive and the non-negative integers respectively. If  $\mathcal{T}_2$  is a topology, it should contain their union  $A \cup B = \mathbb{Z} \setminus \{0\}$ . However,

$$\mathbb{Z} \setminus (A \cup B) = \mathbb{Z} \setminus (\mathbb{Z} \setminus \{0\}) = \{0\}$$

which is not infinite and thus doesn't lie in  $\mathcal{T}_2$ .

3.

The collection of subsets  $\mathcal{T}_3 = \{U \subset X \mid X \setminus U \text{ is countable or all of } X\}$  is a topology PROBABLY.

**2-4**

Already did somewhere else.

**2-5**

1.  $\text{id}_1 : X \longrightarrow \mathbb{R}^2$  is continuous probably.
2.  $\text{id}_2 : \mathbb{R}^2 \longrightarrow X$  is not continuous probably.

**2-6**

$f$  is continuous because any preimage of a subset  $U \subset Z$  under  $f$  is open, since any subset in  $X$  is open.

For  $g$ , the only preimages to check are the emptyset  $\emptyset$  and  $Y$ . Simply,  $g^{-1}(\emptyset) = \emptyset$  and  $g^{-1}(Y) = Z$ . Both subsets are open in  $Z$ , therefore  $g$  is continuous.

If  $h$  is constant, say  $h(Y) = \{p\}$ , then  $h^{-1}(U) = Y$  if  $p \in U$  and  $h^{-1}(U) = \emptyset$  if  $p \notin U$ . In both cases the preimages are open, thus  $h$  is continuous. Assume  $h$  is continuous but not constant, i.e. there are points  $x_1, x_2 \in Y$  such that  $h(x_1) \neq h(x_2)$ .  $Z$  is Hausdorff, so there are disjoint neighbourhoods  $U$  of  $h(x_1)$  and  $V$  of  $h(x_2)$ .  $h$  was assumed to be continuous, so  $h^{-1}(U) = Y$  and  $h^{-1}(V) = Y$  which is impossible (REALLY?).



## 2-7

a)

f)

## 2-8

Firstly, any element in  $f(\mathcal{B})$  is open because  $f$  is an open map. Fix an open subset  $V$  in  $Y$  and consider its preimage  $f^{-1}(V)$  under  $f$ . Because  $f$  is continuous, the preimage is open, thus there are base elements  $B_i$  with  $i \in I$  in  $\mathcal{B}$  such that

$$f^{-1}(V) = \bigcup_{i \in I} B_i.$$

The surjectivity of  $f$  grants us  $f(f^{-1}(V)) = V$ , therefore, we have

$$f(f^{-1}(V)) = V = f\left(\bigcup_{i \in I} B_i\right) = \bigcup_{i \in I} f(B_i).$$

Thus,  $f(\mathcal{B})$  is a basis of  $Y$ .

## 2-9

## 2-10

Fix a point  $y$  in  $Y$ . Since  $f$  is surjective, there is an  $x$  in  $X$  such that  $f(x) = y$ .  $X$  is locally Euclidean, thus there is a neighbourhood  $U$  of  $x$  that is homeomorphic to  $\mathbb{R}^n$ . Moreover,  $f$  is locally homeomorphic, so there is a neighbourhood  $V$  of  $x$  such that the restriction of  $f$  under  $V$  is a homeomorphism. Then, the intersection  $U \cap V = N$  has both of these properties, i.e.  $N$  is a neighbourhood of  $x$  that is homeomorphic to  $\mathbb{R}^n$  and the restriction of  $f$  under  $V$  is a homeomorphism.  $f(N)$  is a neighbourhood of  $y$  that is homeomorphic to  $\mathbb{R}^n$ , therefore  $Y$  is locally Euclidean.

## 2-10

“ $\Rightarrow$ ”: Let  $M^0$  be a 0-manifold and consider a point  $p \in M^0$ . First, we show that  $M^0$  is discrete. Since  $M^0$  is locally Euclidean, there is a neighbourhood  $U$  of  $p$  such that  $U$  is homeomorphic to an open subset of  $\mathbb{R}^0$ . But  $\mathbb{R}^0$  contains only one element, thus the only nonempty open subset is  $\mathbb{R}^0$ . Now, a homeomorphism implies bijectivity, we have that  $U = \{p\}$ . Every singleton set in  $M^0$  is open, so  $M^0$  is a discrete space.

$M^0$  is also countable because being a manifold implies that it has a countable base and any base must contain all the singleton sets.

“ $\Leftarrow$ ”: Let  $M^0$  be a countable discrete space.  $M^0$  is second-countable because the set of singletons form a countable base. It is also  $T_2$  since each point has itself as its neighbourhood which clearly does not contain any other points. Now let  $p \in M^0$  be a point.  $\{p\}$  is a neighbourhood of  $p$  and it is homeomorphic to  $\mathbb{R}^0$  by the mapping  $p \mapsto 0$ , thus  $M^0$  is locally Euclidean.