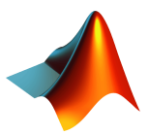


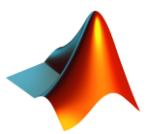
MATLAB 프로그래밍 및 실습

12강. 기초 수치해석 1

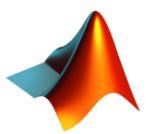


오늘 배울 내용

- Polynomial
- Curve fitting
- Interpolation
- 다음주
 - 방정식의 해
 - 함수 최소값 및 최적화
 - 수치미분, 수치적분
 - 미분방정식
 - 몬테카를로 시뮬레이션



polynomial



polynomial

- Definition (n-th order polynomial)

$$p(x) = a_n x^n + a_{n-1} x^{n-1} + \dots + a_1 x + a_0$$

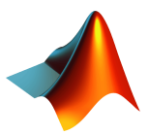
where $a_n, a_{n-1}, \dots, a_1, a_0$ are constants and n is nonnegative integer.

- 대수학의 기본정리

$$p(x) = \sum_{i=0}^n a_i x^i = a_n x^n + a_{n-1} x^{n-1} + \dots + a_0 (a_n \neq 0, n \geq 1) \text{에 대해 복소수 } \alpha \text{가 존재하여 } p(\alpha) = 0 \text{이다.}$$

- 따름 정리

$$\begin{aligned} p(x) &= a_n x^n + a_{n-1} x^{n-1} + \dots + a_1 x + a_0 \\ &= a_n (x - r_1)(x - r_2) \dots (x - r_n) \end{aligned} \quad r_i \in \mathbb{C}$$



매트랩에서 polynomial 표현

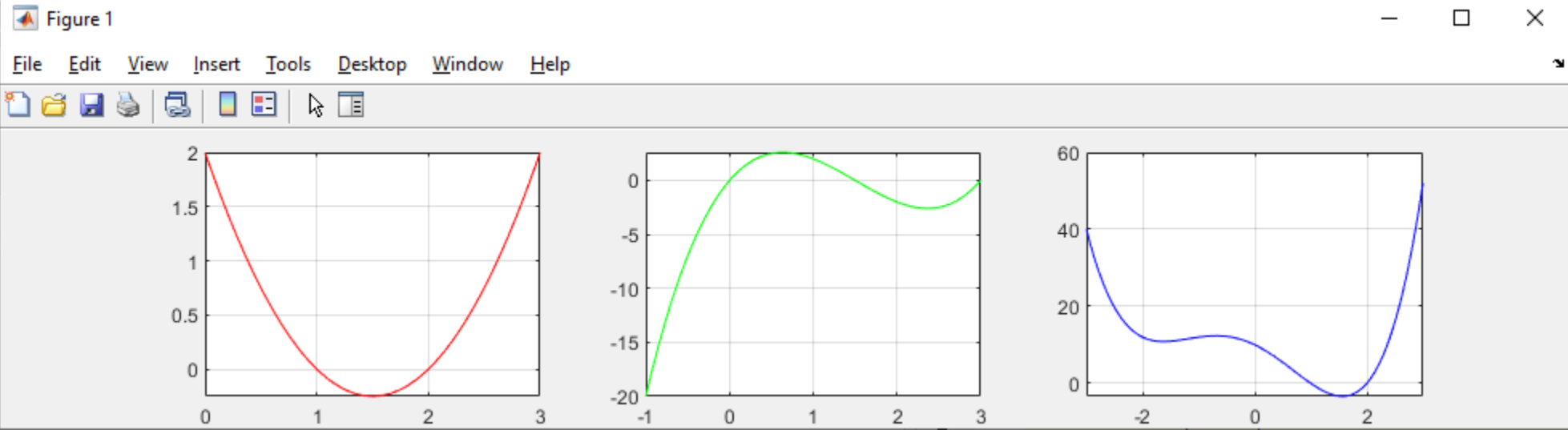
```
x = linspace(-4, 4);  
  
p1 = [1, -3, 2];  
fx1 = polyval(p1, x);
```

$$p(x) = a_n x^n + a_{n-1} x^{n-1} + \dots + a_1 x + a_0$$

※ 계수가 0인 경우에도 0으로 자리를 채움

```
p2 = [2, -9, 9, 0];  
fx2 = polyval(p2, x);  
  
p3 = [1, 1, -5, -7, 10];  
fx3 = polyval(p3, x);
```

```
figure,  
subplot(1,3,1), plot(x,fx1,'r'), grid on, xlim([0 3])  
subplot(1,3,2), plot(x,fx2,'g'), grid on, xlim([-1 3])  
subplot(1,3,3), plot(x,fx3,'b'), grid on, xlim([-3 3])
```



polyval vs anonymous function vs fplot

```
x = linspace(-4, 4);
```

```
p1 = [1, -3, 2];  
fx1 = polyval(p1,x);
```

```
p2 = [2, -9, 9, 0];  
fx2 = polyval(p2,x);
```

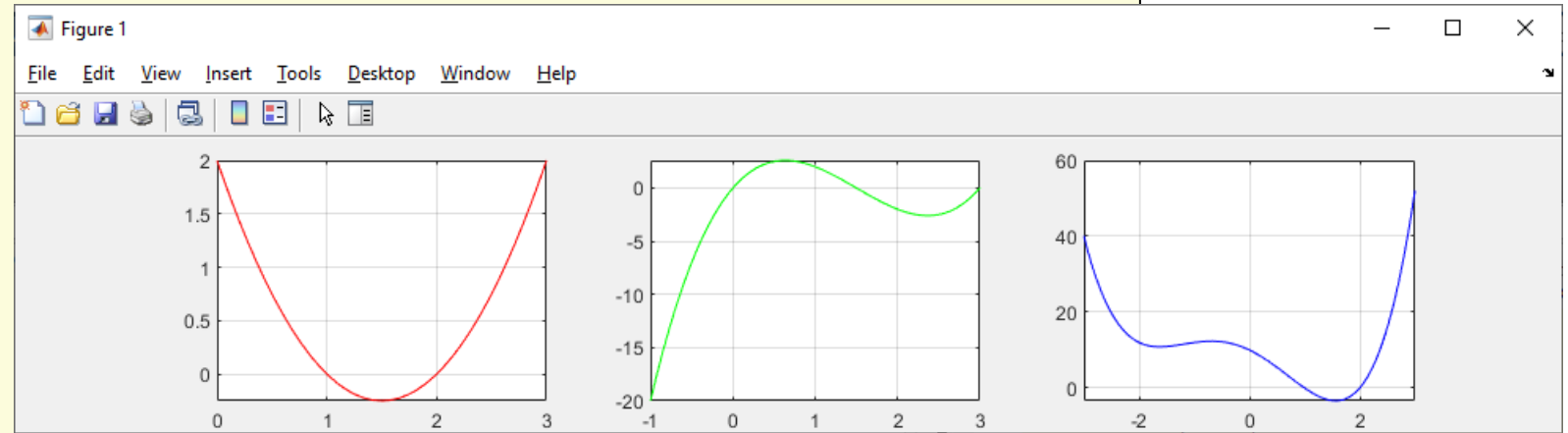
```
p3 = [1, 1, -5, -7, 10];  
fx3 = polyval(p3, x);
```

```
f1 = @(x) x.^2 - 3*x + 2;  
f2 = @(x) 2*x.^3 - 9*x.^2 + 9*x;  
f3 = @(x) x.^4 + x.^3 - 5*x.^2 - 7*x + 10;
```

```
f1m = @(x) p1(:)'*[x(:).^2 x(:) ones(numel(x),1)]';  
f2m = @(x) p2(:)'*[x(:).^3 x(:).^2 x(:) ones(numel(x),1)]';  
f3m = @(x) p3(:)'*[x(:).^4 x(:).^3 x(:).^2 x(:) ones(numel(x),1)]';
```

```
figure,  
subplot(1,3,1), fplot(@(x) polyval(p1, x), [ 0, 3], 'r'), grid on  
subplot(1,3,2), fplot(@(x) polyval(p2, x), [-1, 3], 'g'), grid on  
subplot(1,3,3), fplot(@(x) polyval(p3, x), [-3 3], 'b'), grid on
```

$$p(x) = a_n x^n + a_{n-1} x^{n-1} + \dots + a_1 x + a_0$$



다항식 곱하기, 나누기: conv, deconv

```
x = linspace(-4, 4);
```

```
p1 = [1, -3, 2];  
fx1 = polyval(p1,x);
```

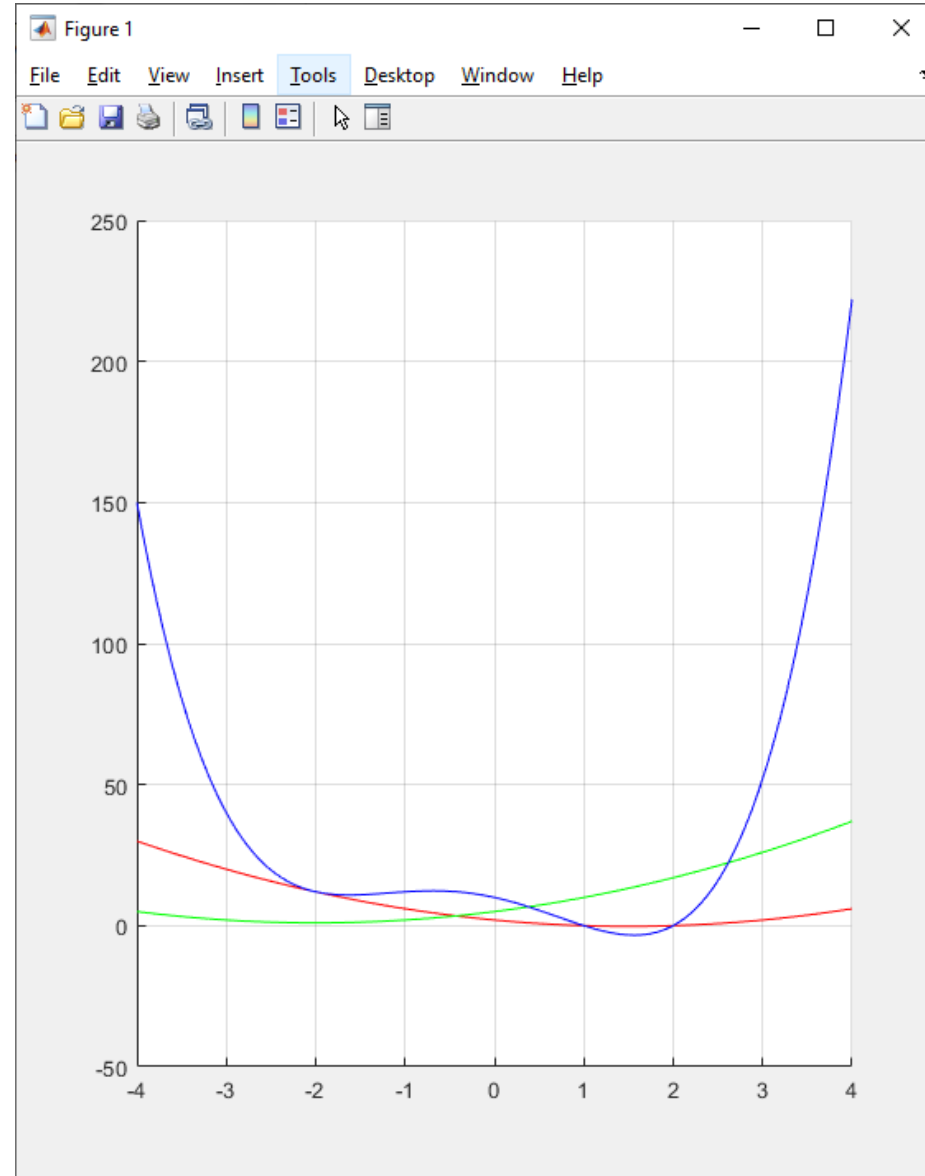
```
p2 = [1, 4, 5];  
fx2 = polyval(p2,x);
```

```
p3 = conv(p1, p2);  
fx3 = polyval(p3,x);
```

```
u = [2, 9, 7, -6];  
v = [1, 3];  
[q, r] = deconv(u, v);
```

```
u = [2, -13, 0, 75, 2, 0, -60];  
v = [1, 0, -5];  
[q, r] = deconv(u, v);
```

* 더하기: $p1 + p2$



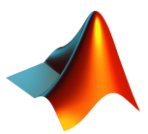
다항식의 해 -> 다항식의 계수: poly

$$p_1(x) = x^2 - 3x + 2 = (x - 1)(x - 2)$$

$$p_2(x) = 2x^3 - 9x^2 + 9x = 2x(x - 3)(2x - 3)$$

$$p_3(x) = x^4 + x^3 - 5x^2 - 7x + 10 = (x - 1)(x - 2)(x - (-2 + i))(x - (-2 - i))$$

```
x = linspace(-4, 4);  
  
p1 = poly([1, 2]); % p1 = [1, -3, 2];  
p2 = poly([0, 3, 3/2]); % p2 = [2, -9, 9, 0]/2;  
p3 = poly([1, 2, -2+1i, -2-1i]); % p3 = [1, 1, -5, -7, 10];  
  
fx1 = polyval(p1, x);  
fx2 = polyval(p2, x);  
fx3 = polyval(p3, x);
```



다항식의 계수 -> 다항식의 해: roots

* roots와 poly는 역함수

$$p_1(x) = x^2 - 3x + 2 = (x - 1)(x - 2)$$

$$p_2(x) = 2x^3 - 9x^2 + 9x = 2x(x - 3)(2x - 3)$$

$$p_3(x) = x^4 + x^3 - 5x^2 - 7x + 10 = (x - 1)(x - 2)(x - (-2 + i))(x - (-2 - i))$$

```
x = linspace(-4, 4);

p1 = [1, -3, 2];
fx1 = polyval(p1, x);
r1 = roots(p1);

p2 = [2, -9, 9, 0];
fx2 = polyval(p2, x);
r2 = roots(p2);

p3 = [1, 1, -5, -7, 10];
fx3 = polyval(p3, x);
r3 = roots(p3);
```

```
figure,
subplot(1,3,1), hold on, grid on, xlim([0 3])
plot(x,fx1,'r'), plot(r1, 0, 'ko'),

subplot(1,3,2), hold on, grid on, xlim([-1 3])
plot(x,fx2,'g'), plot(r2, 0, 'ko'),

subplot(1,3,3), hold on, grid on,
plot(x,fx3,'b'), xlim([-3 3])
for i=1:length(r3)
    if ~imag(r3(i))
        plot(r3(i), 0, 'ko')
    end
end
```

※ polynomial만 가능
※ nonlinear -> fzero

다항식의 미분과 적분

```
k = polyder(p);
```

$$k(x) = \frac{d}{dx} p(x)$$

```
k = polyder(a, b);
```

$$k(x) = \frac{d}{dx} [a(x)b(x)]$$

```
[q, d] = polyder(a, b);
```

$$\frac{q(x)}{d(x)} = \frac{d}{dx} \left[\frac{a(x)}{b(x)} \right]$$

```
q = polyint(p, C); % C 기본값은 0
```

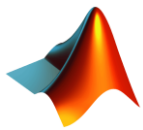
$$q(x) = \int p(x) dx$$

```
p = [4, -9, 2, -3];  
q = polyint(p);  
d1 = polyval(q, 3) - polyval(p, 1);  
d2 = diff(polyval(q, [1, 3]));
```

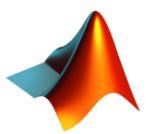
$$p(x) = 4x^3 - 9x^2 + 2x - 3$$

$$q(x) = \int p(x) dx = x^4 - 3x^3 + x^2 - 3x + C$$

$$\int_1^3 p(x) dx = q(3) - q(1) = 4$$



curve fitting



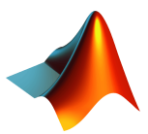
zero가 아닌 점을 지나는 polynomial은?

Q1) (1,2), (3,4)를 지나는 직선의 방정식을 구하시오.

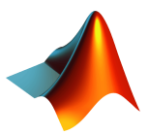
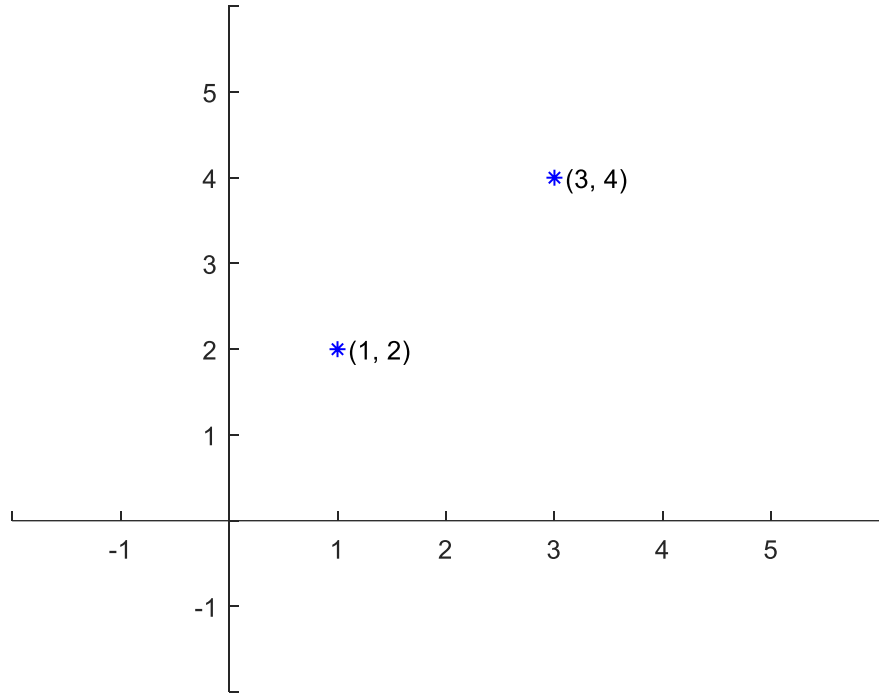
Q2) (-1, 6), (3, 2), (5, 12)를 지나는 2차 함수를 구하시오.

Q3) (1,2), (3,4), (5,5)를 "가장 가깝게" 지나는 직선의 방정식을 구하시오.

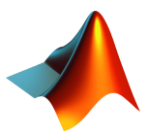
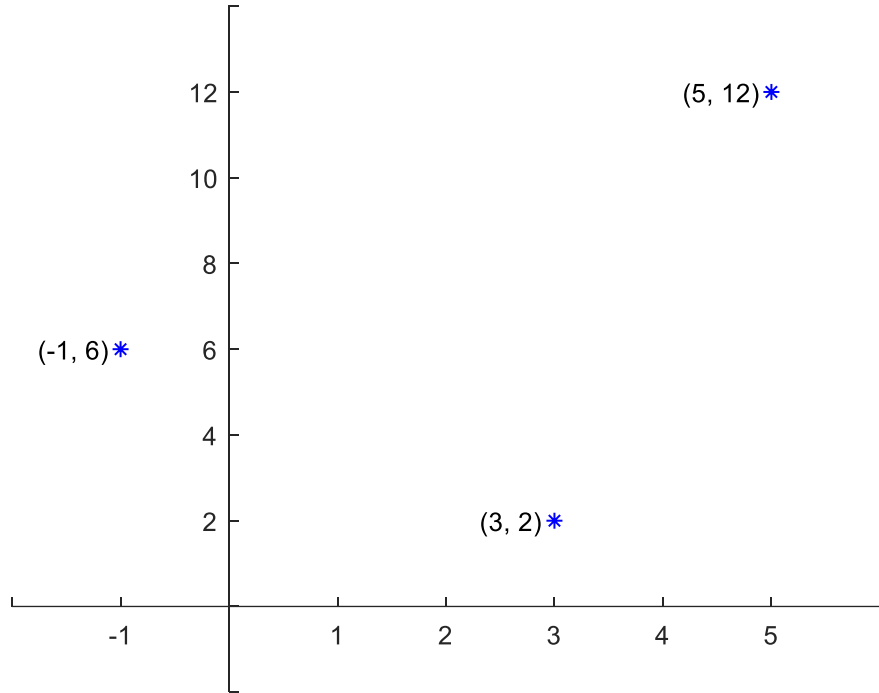
Q4) (1,5), (3,1), (5,11), (7,19)를 "가장 가깝게" 지나는 2차 함수를 구하시오.



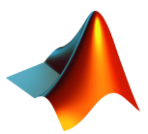
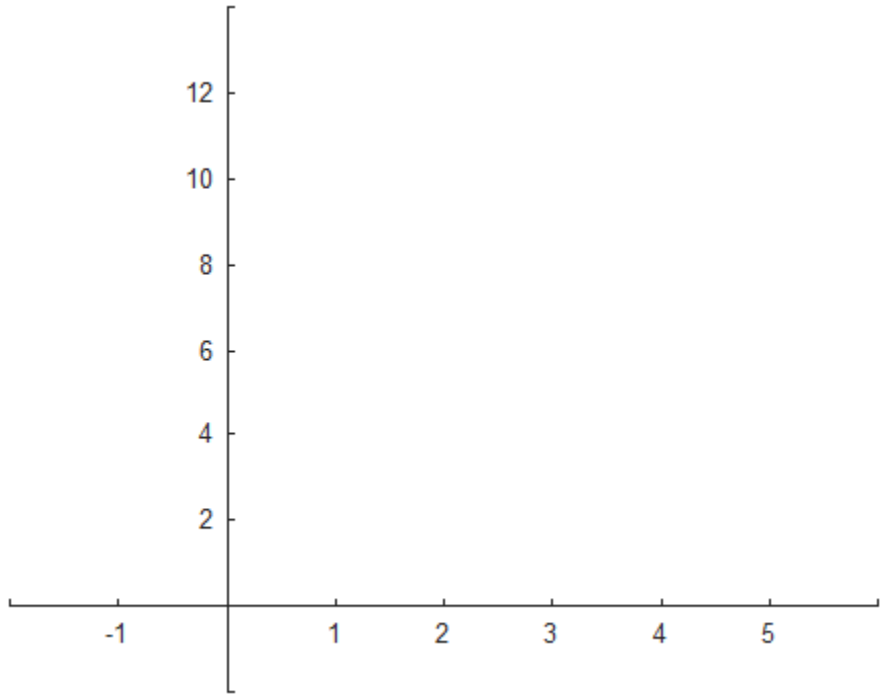
두 점을 지나는 직선의 방정식



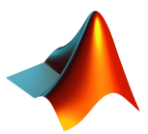
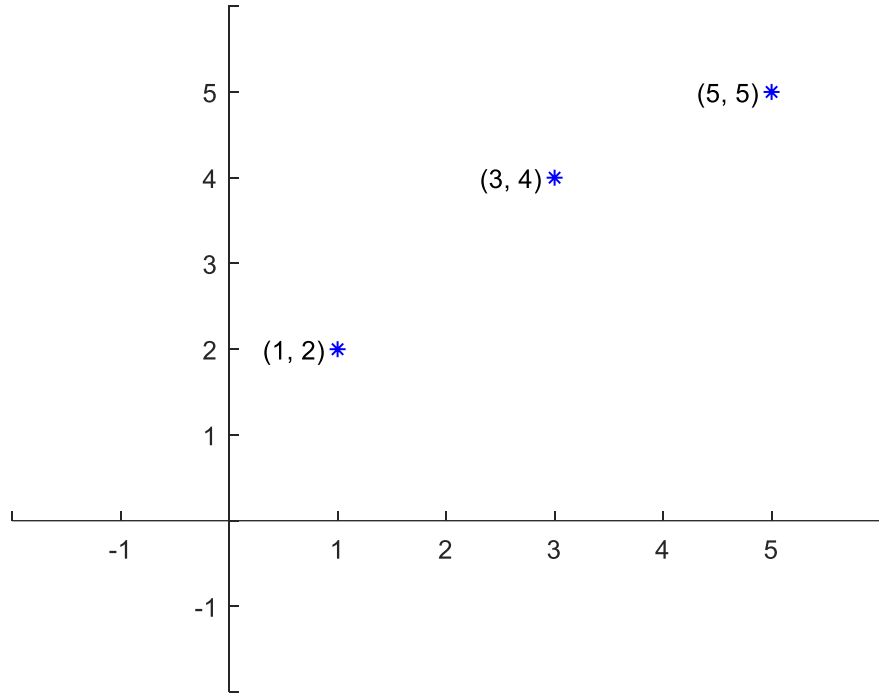
세 점을 지나는 2차 함수



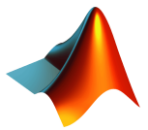
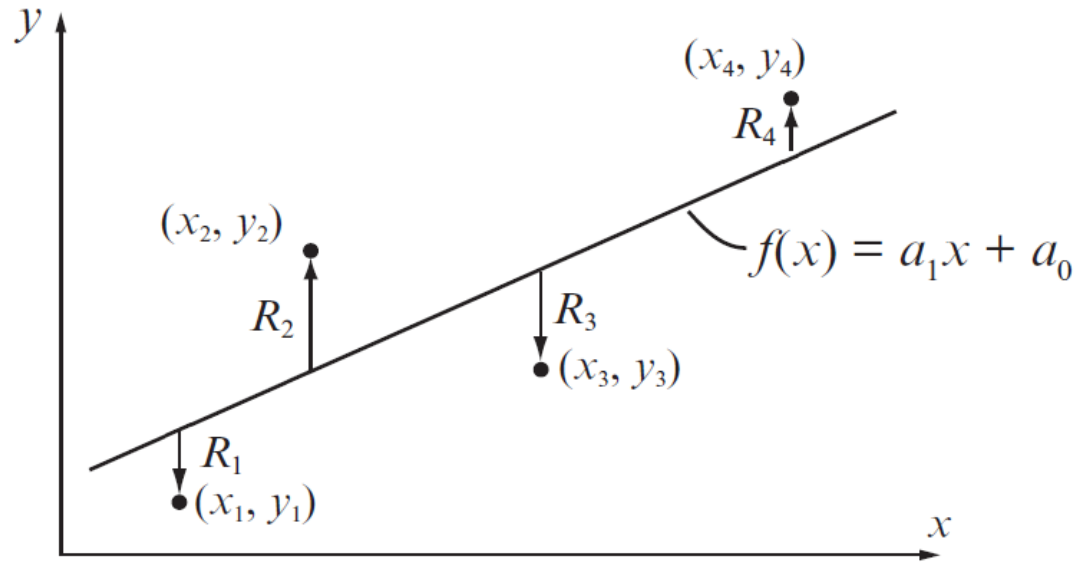
$n+1$ 개의 점을 지나는 n 차 함수



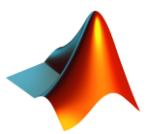
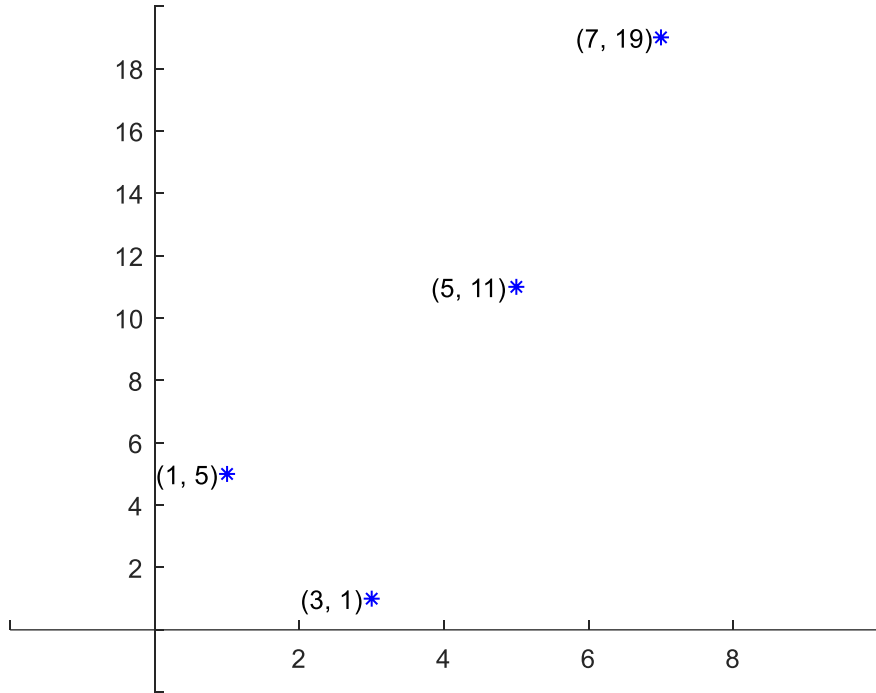
3개의 점을 "가장 가깝게" 지나는 직선?



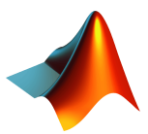
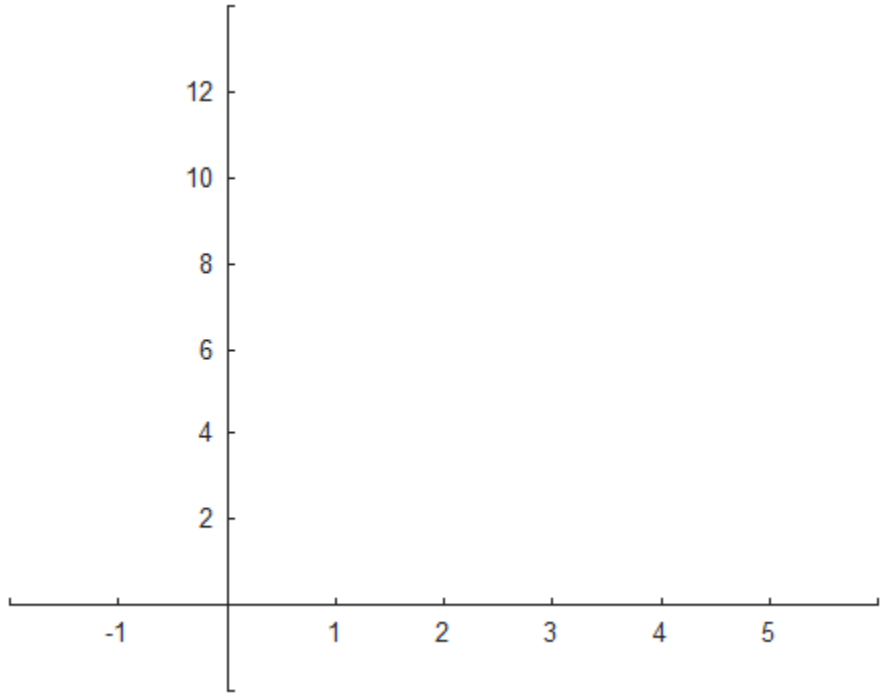
최소자승법 (least-square method)



4개의 점을 "가장 가깝게" 지나는 2차 함수



n 개의 점을 지나는 1변수 p 차 함수



polyfit

```
x = [1, 3];  
y = [2, 4];  
p = polyfit(x, y, 1);
```

```
x = [-1, 3, 5];  
y = [ 6, 2, 12];  
p = polyfit(x, y, 2);
```

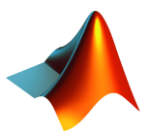
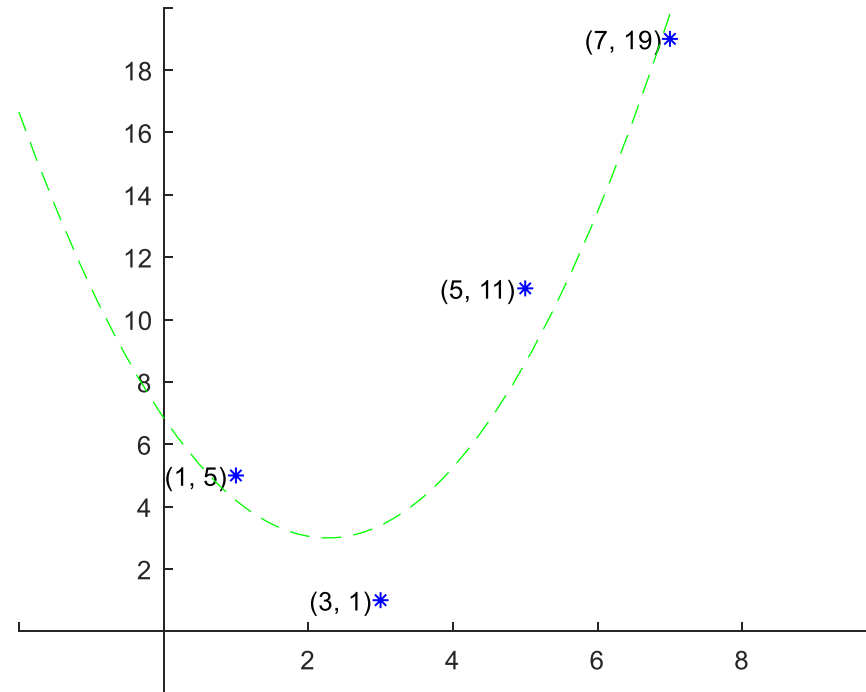
```
x = [1, 3, 5];  
y = [2, 4, 5];  
p = polyfit(x, y, 1);
```

```
x = [1, 3, 5, 7];  
y = [5, 1, 11, 19];  
p = polyfit(x, y, 2);
```

`p = polyfit(x, y, n);`

그 계수를
p에 대입해라.

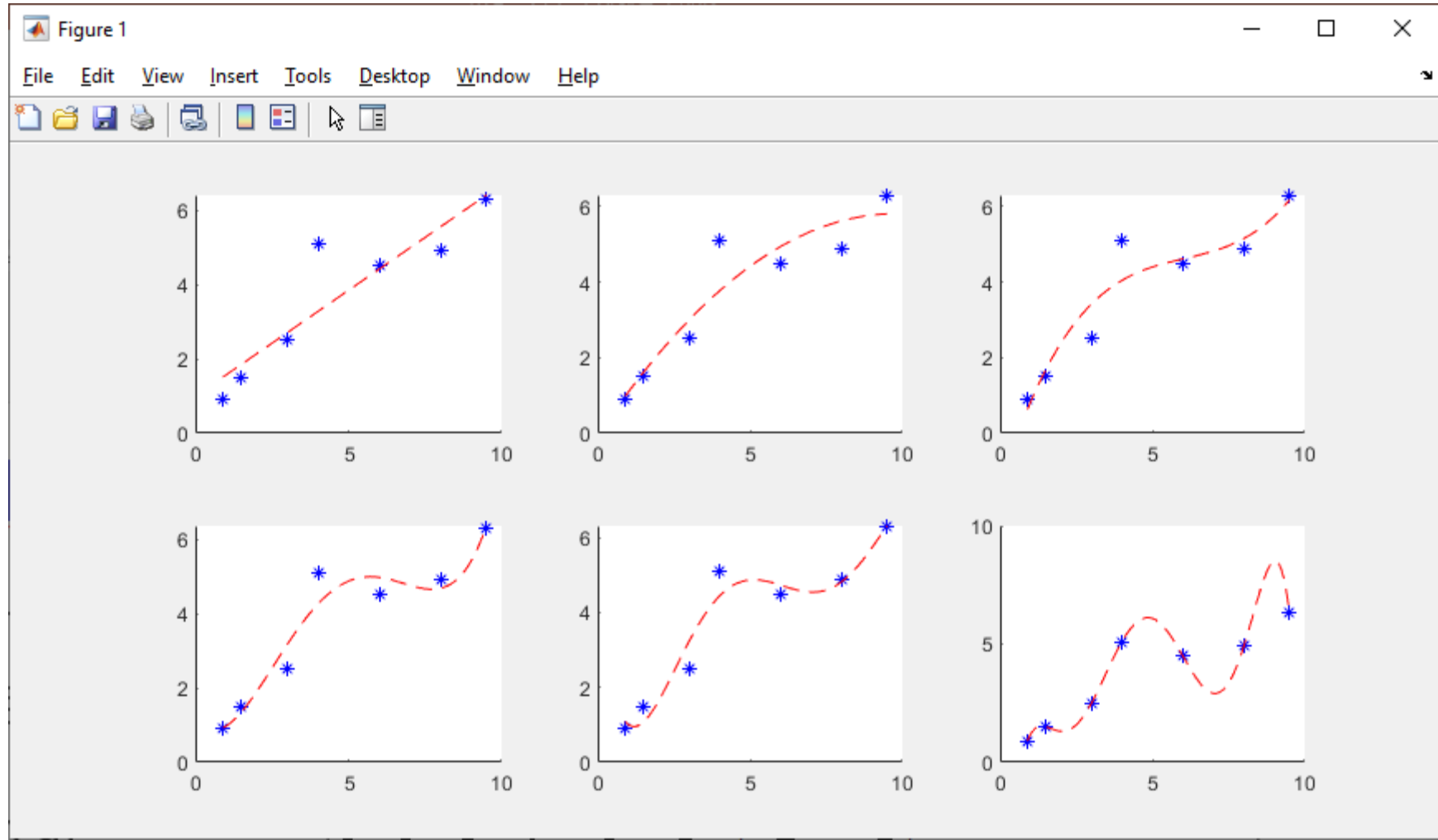
(x, y)를 지나는 n차 polynomial을
최소자승법으로 구하고



polyfit 예제

Q) 실험 측정 결과치가 아래와 같이 나왔다.
결과로부터 1차~6차 polynomial로 모델을 구하시오.

(0.9, 0.9)
(1.5, 1.5)
(3.0, 2.5)
(4.0, 5.1)
(6.0, 4.5)
(8.0, 4.9)
(9.5, 6.3)



polynomial이 아닌 경우는?

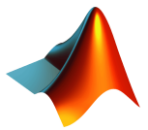
$$y = be^{mx}$$

$$y = m \ln(x) + b$$

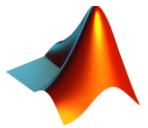
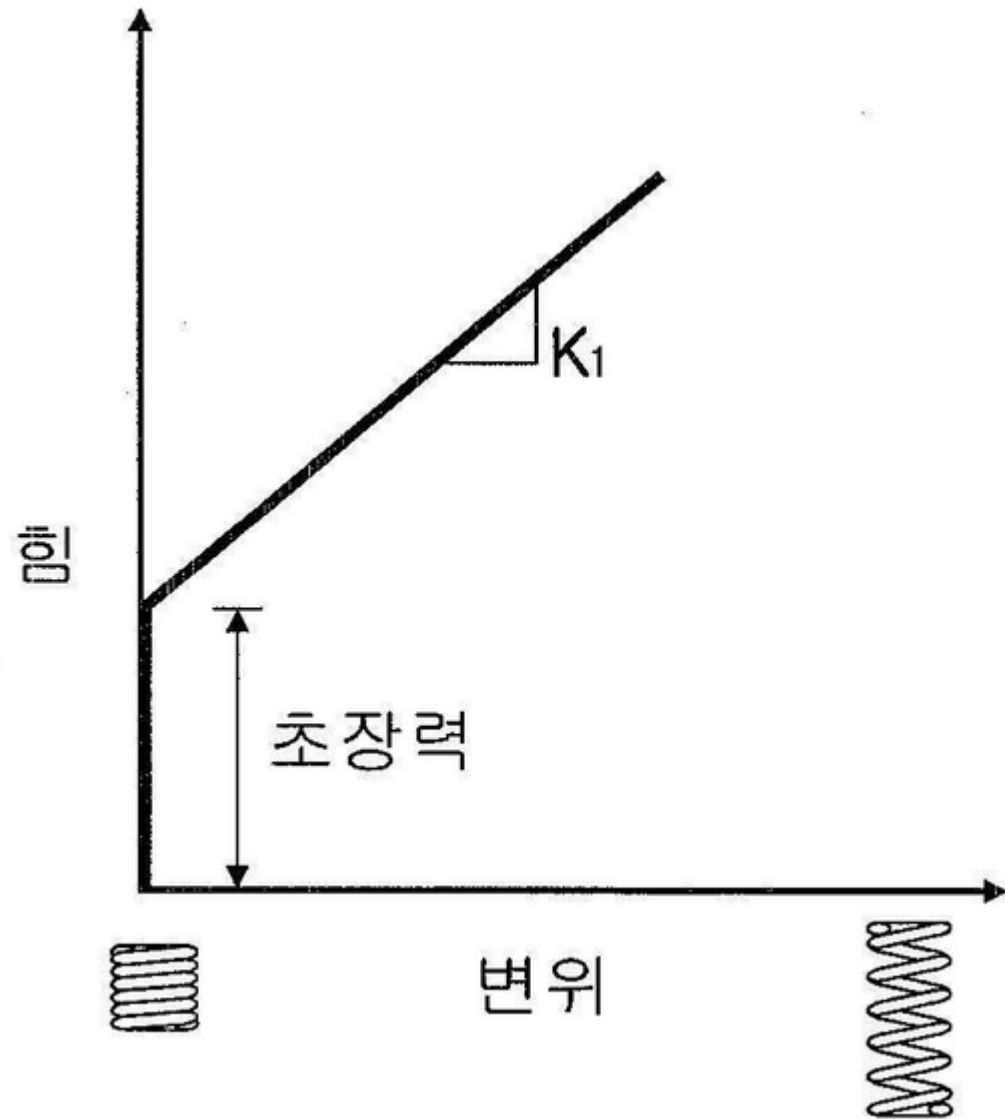
$$y = \frac{1}{mx + b}$$

$$y = \frac{nx}{mx + b}$$

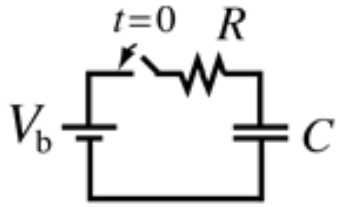
※ 모델 선정 -> polynomial fitting



예제 - 스프링 상수, 초장력



예제 - RC 회로



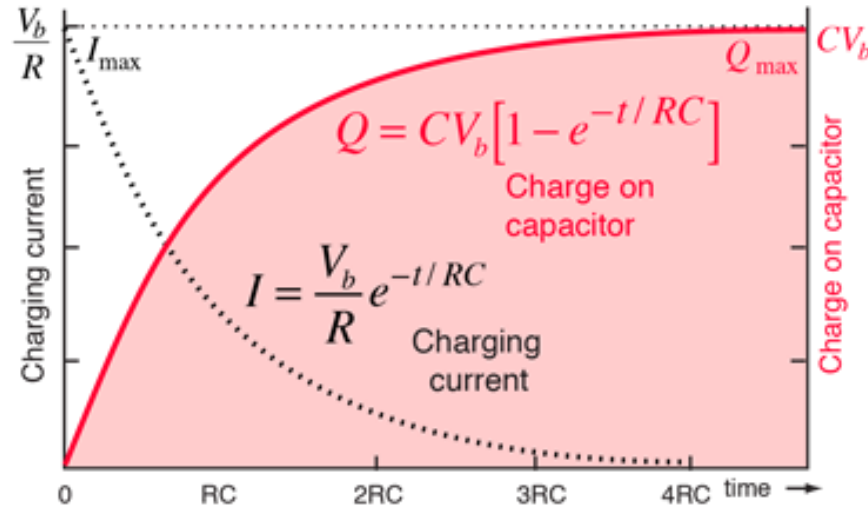
$$V_b = V_R + V_C$$

$$V_b = IR + \frac{Q}{C}$$

As charging progresses,

$$V_b = IR + \frac{Q}{C}$$

current decreases and
charge increases.



At $t = 0$

$$Q = 0$$

$$V_C = 0$$

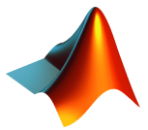
$$I = \frac{V_b}{R}$$

As $t \rightarrow \infty$

$$Q \rightarrow CV_b$$

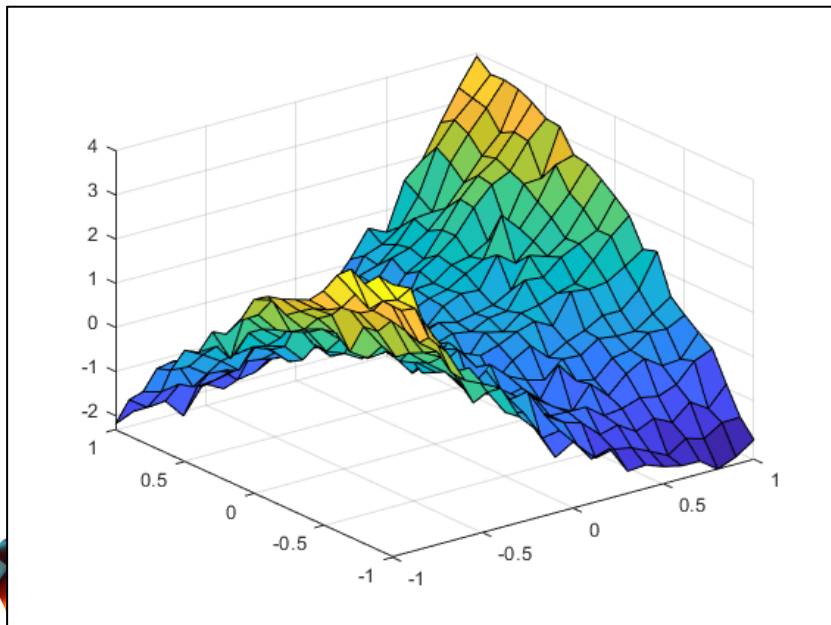
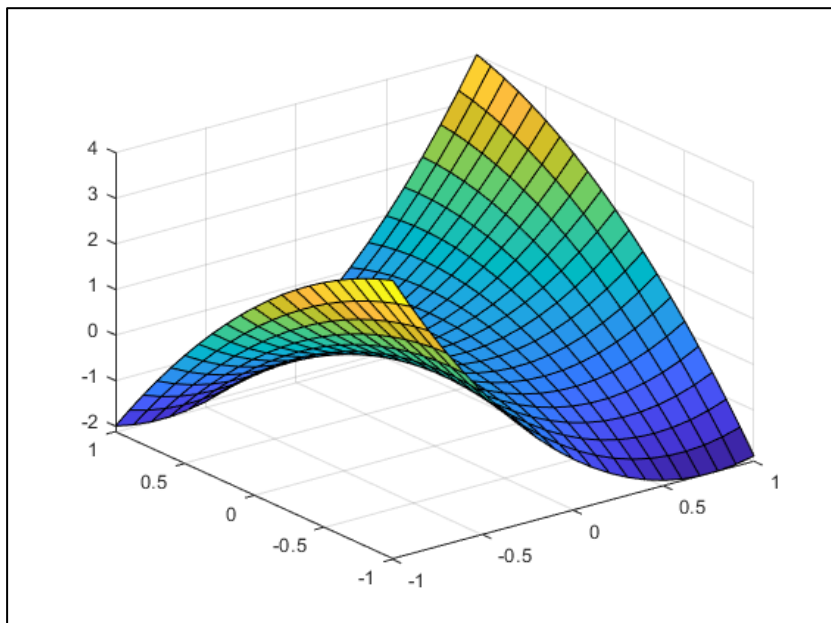
$$V_C \rightarrow V_b$$

$$I \rightarrow 0$$

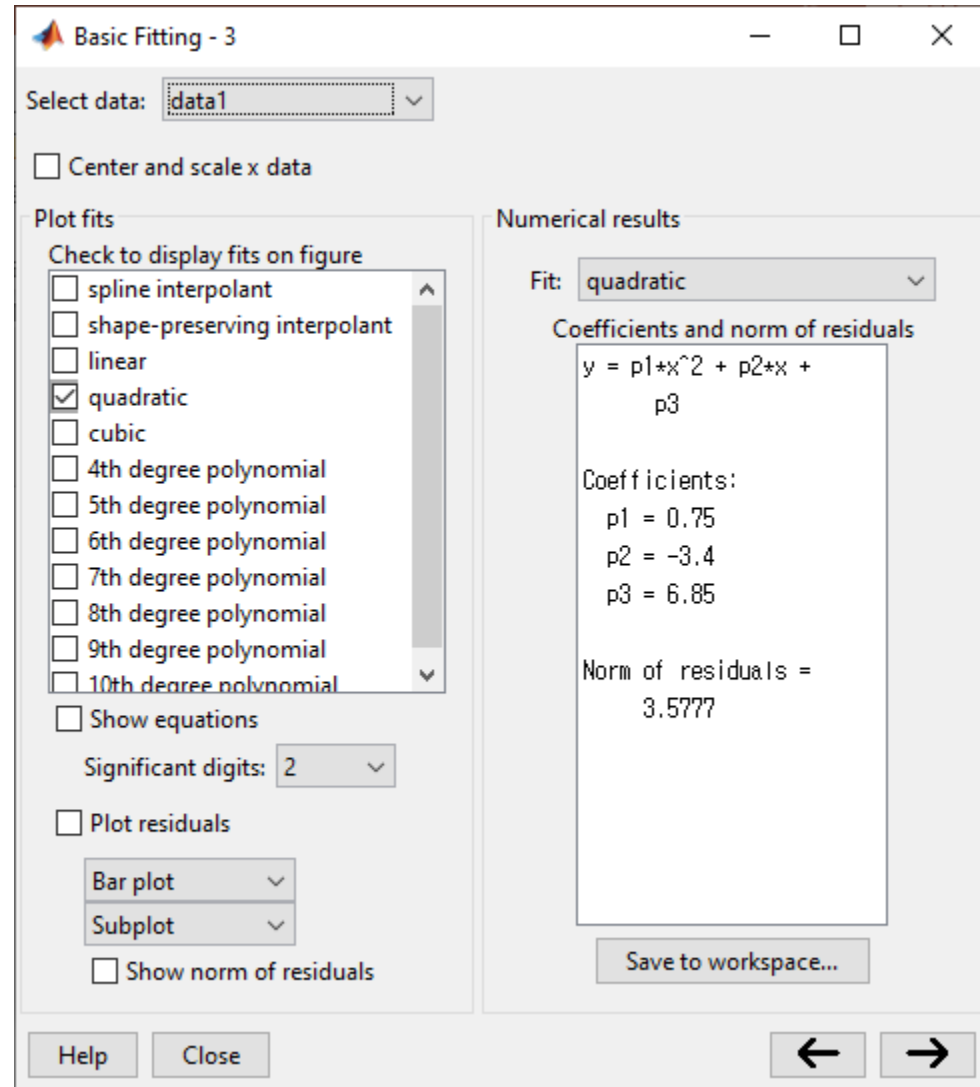
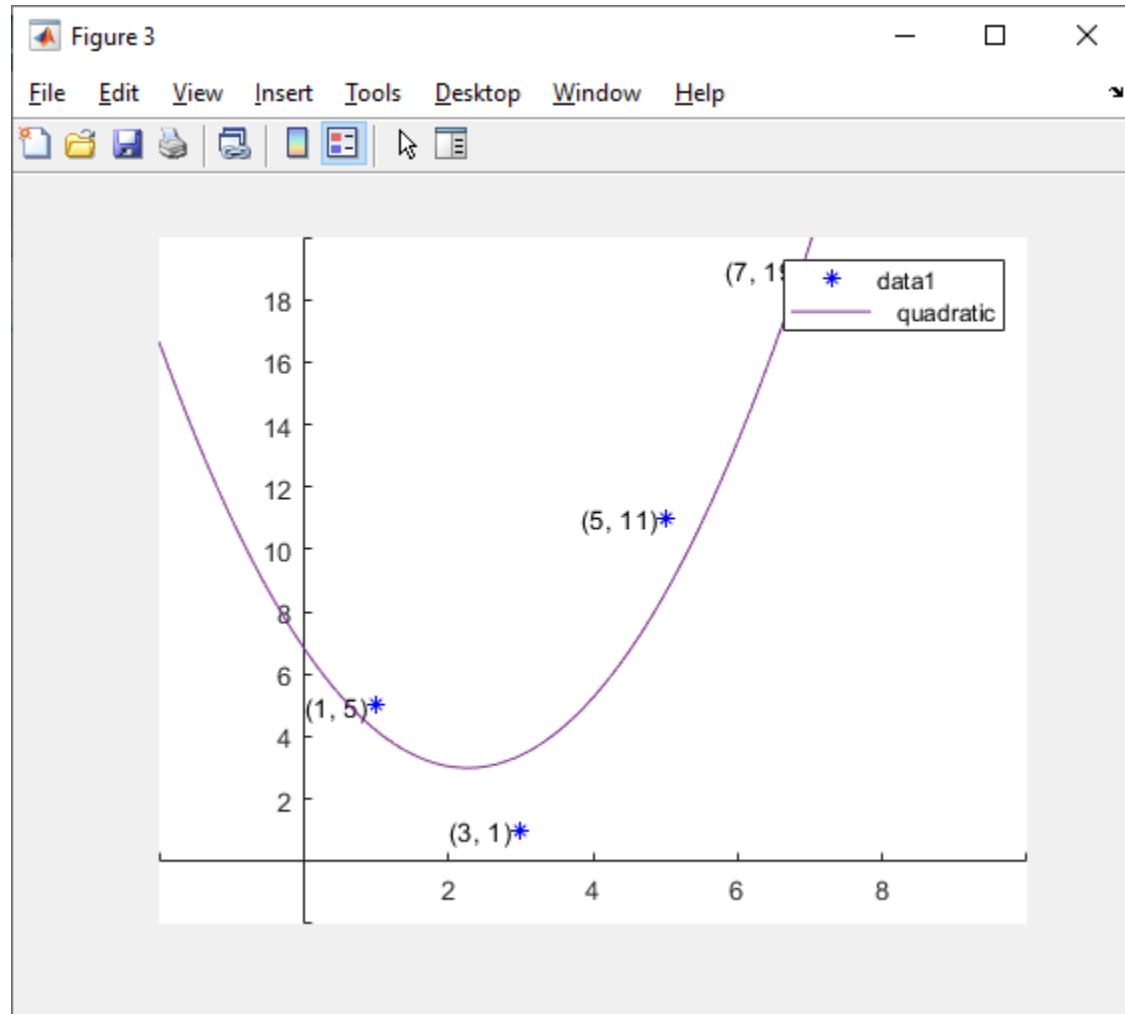


다변수 polynomial의 경우는?

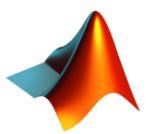
$$z = px^2 + qxy + ry^2 + s$$



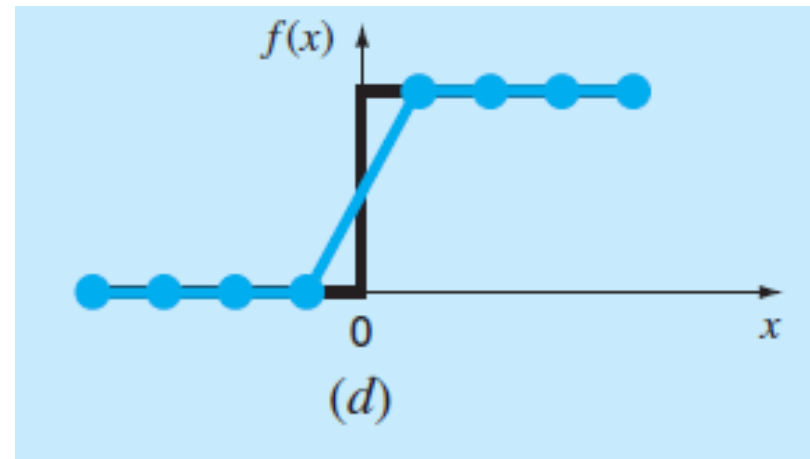
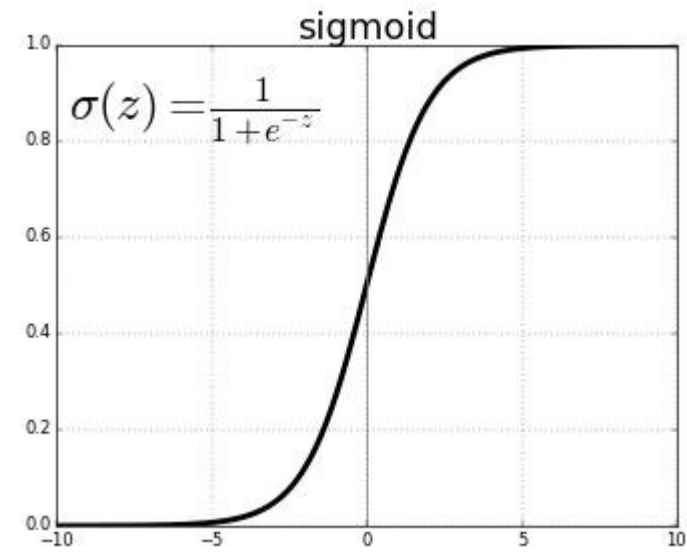
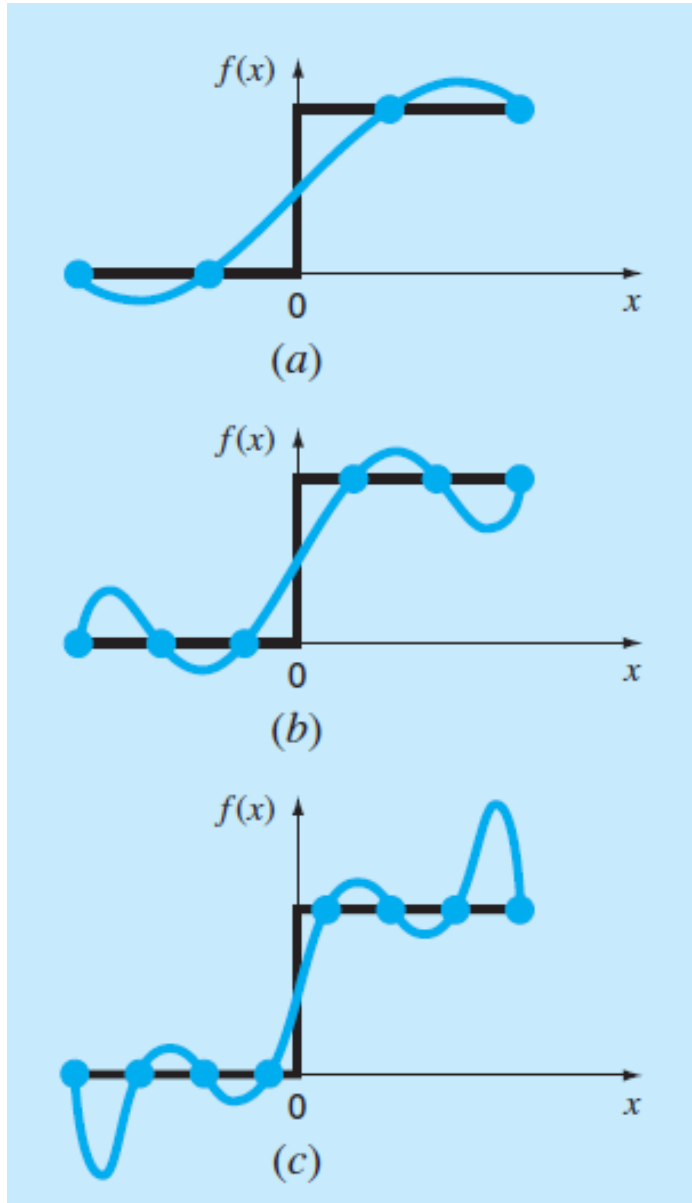
basic fitting tool



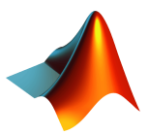
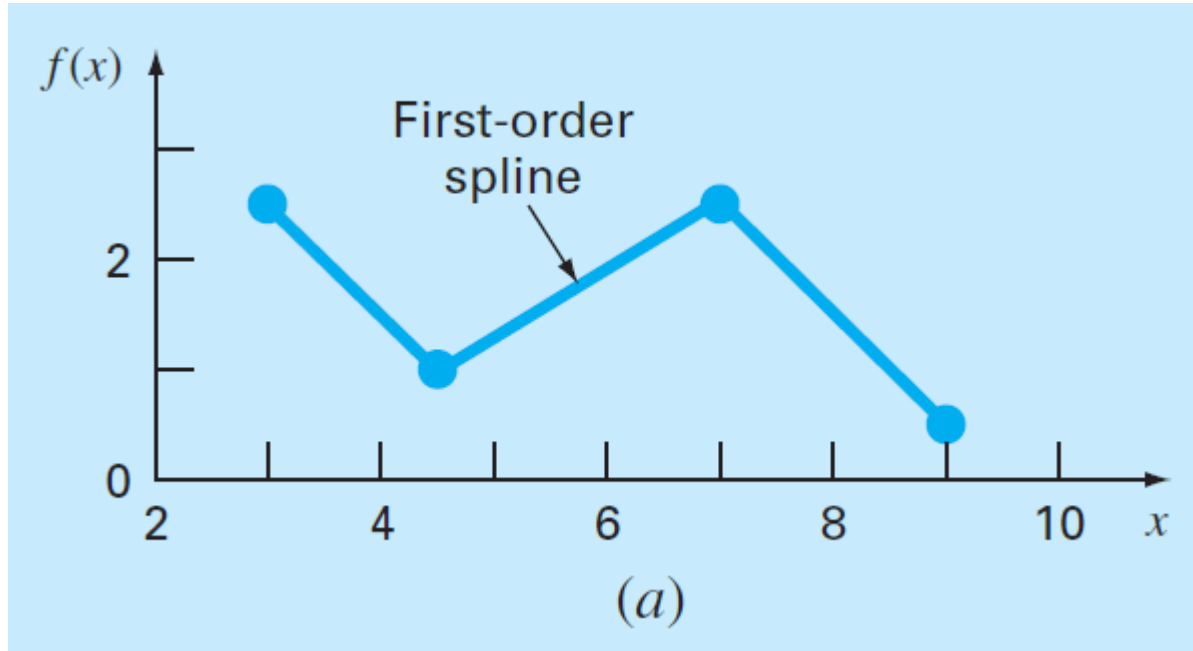
interpolation



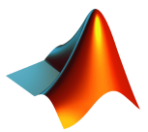
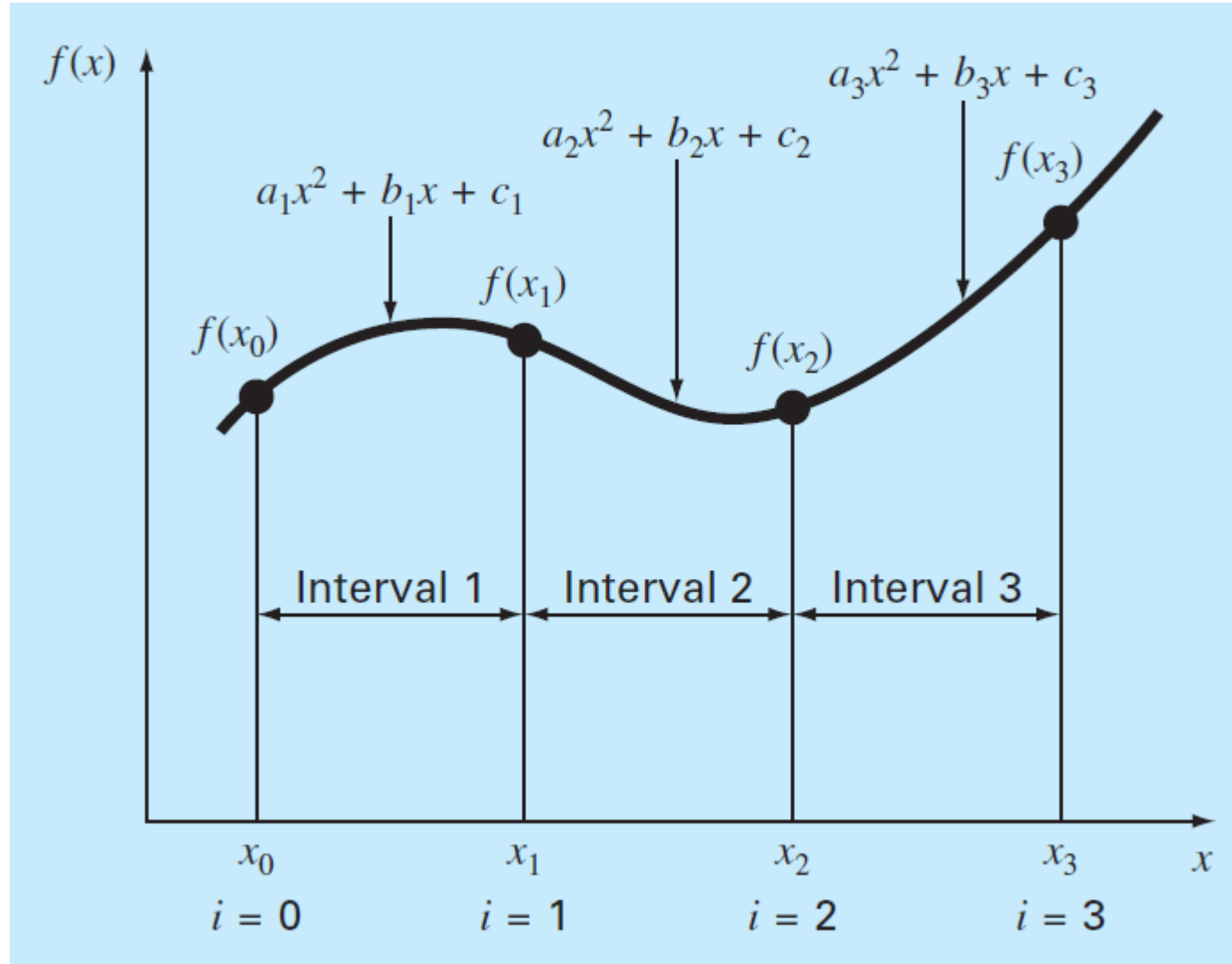
motivation



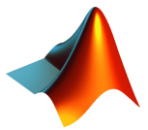
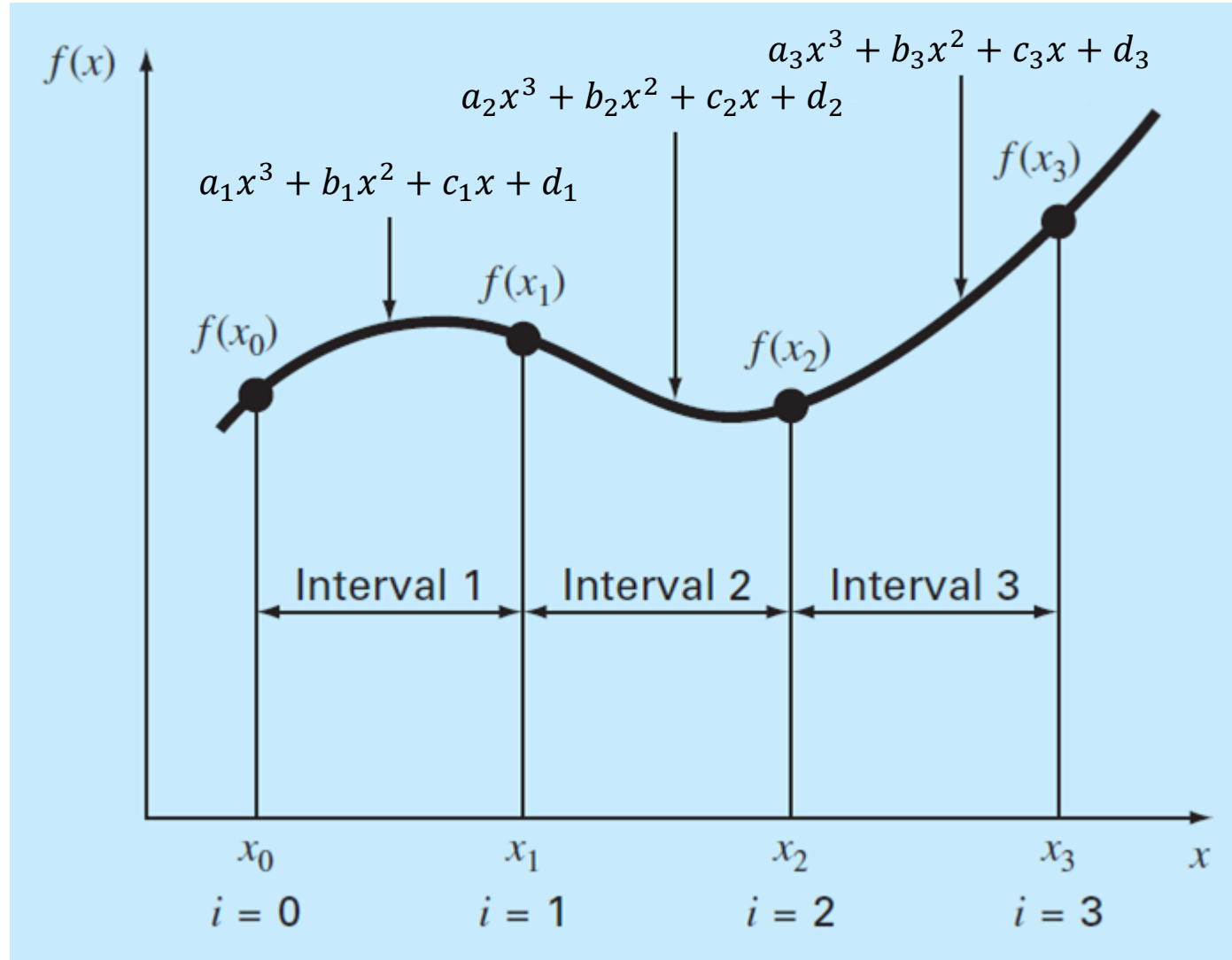
linear interpolation (linear spline)



quadratic spline



cubic spline



interp1

```
x = [-3, -2, -1, 1, 2, 3];  
y = [-1, -1, -1, 1, 1, 1];  
xx = linspace(x(1),x(end));
```

```
figure, plot(x,y,'b*'), hold on
```

```
% high order polynomial fitting
```

```
p4 = polyfit(x,y,4);
```

```
p5 = polyfit(x,y,5);
```

```
plot(xx, polyval(p4, xx), 'r')
```

```
plot(xx, polyval(p5, xx), 'm')
```

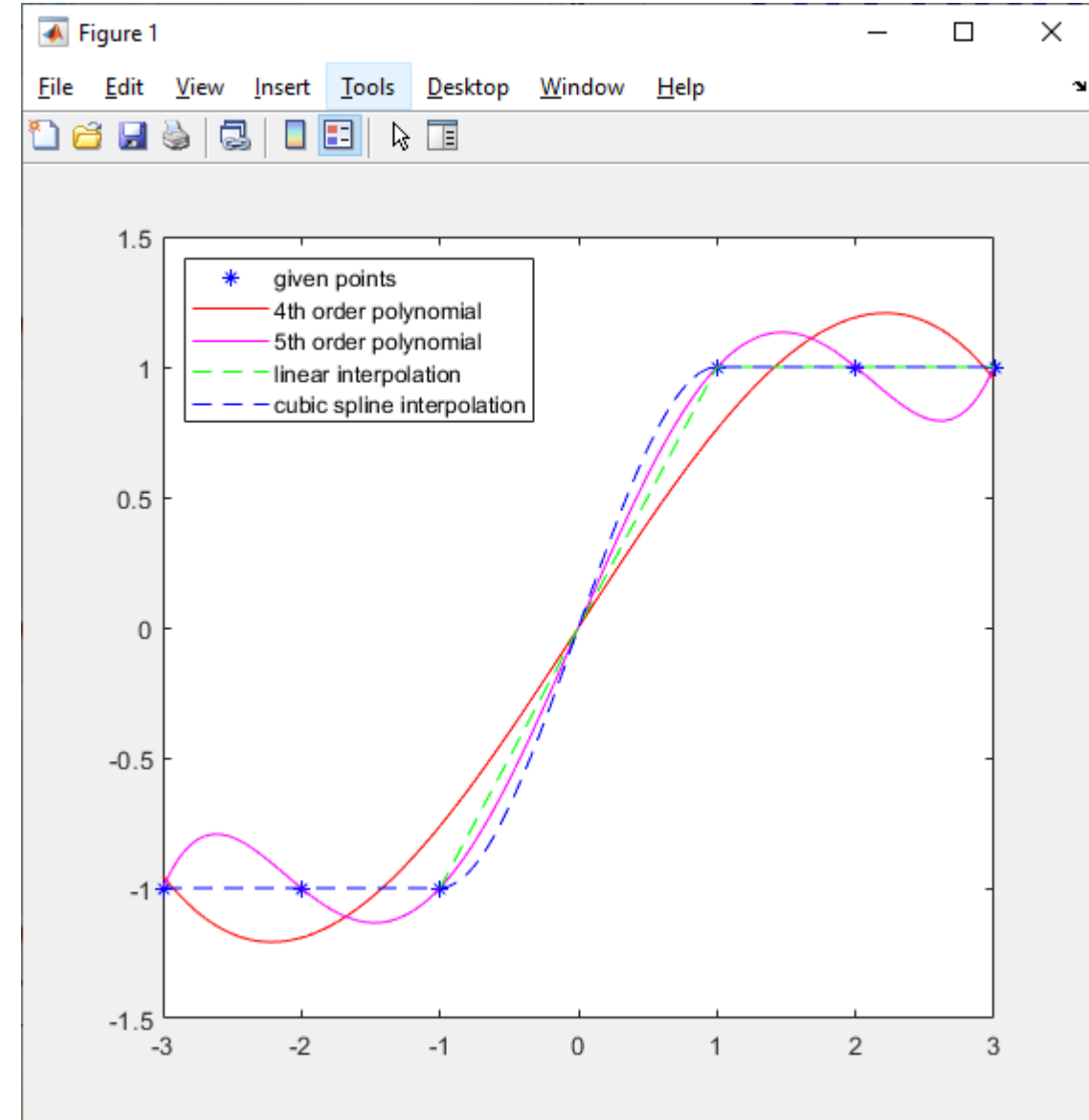
```
% interpolation
```

```
yy_lin = interp1(x,y,xx); % 'linear' is default.
```

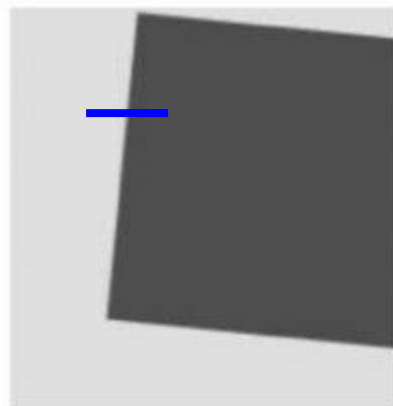
```
yy_spl = interp1(x,y,xx,'cubic');
```

```
plot(xx,yy_lin,'g--')
```

```
plot(xx,yy_spl,'b--')
```



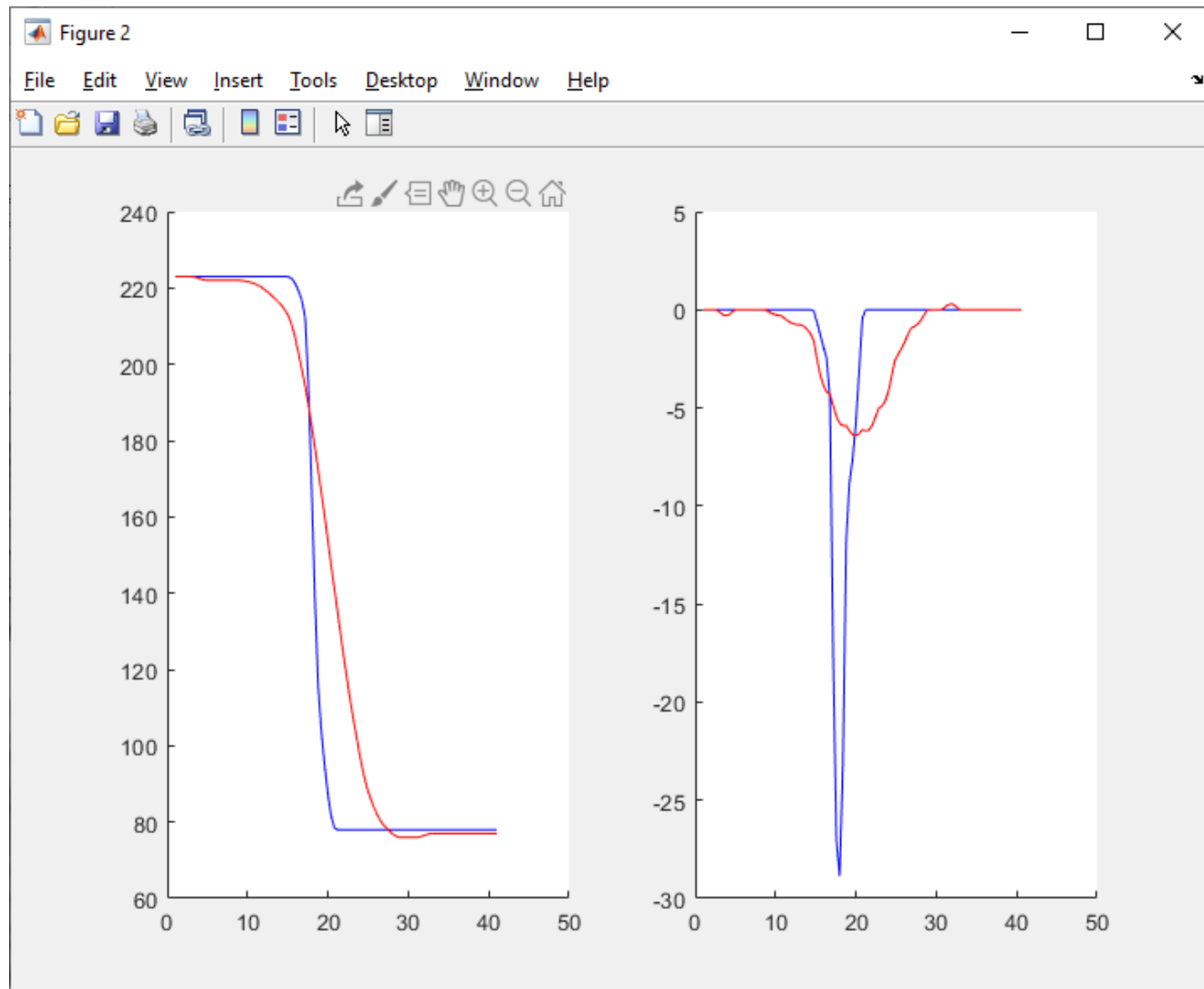
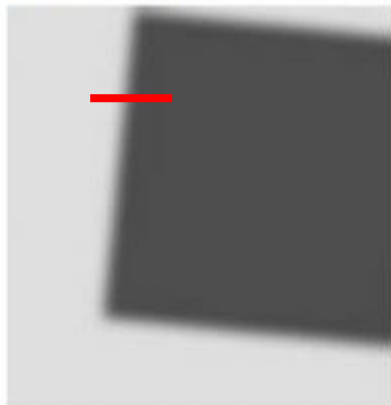
예제 - line spread function (LSF)



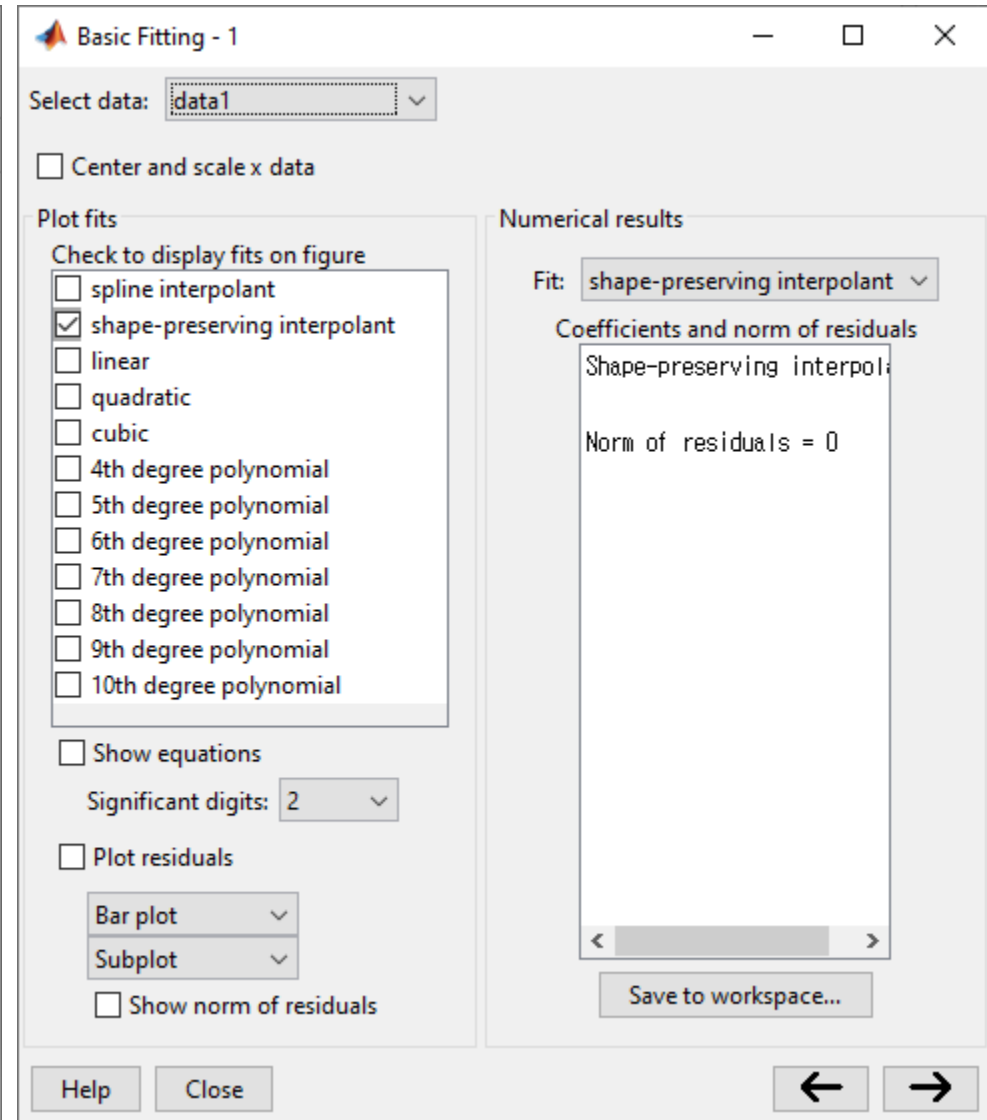
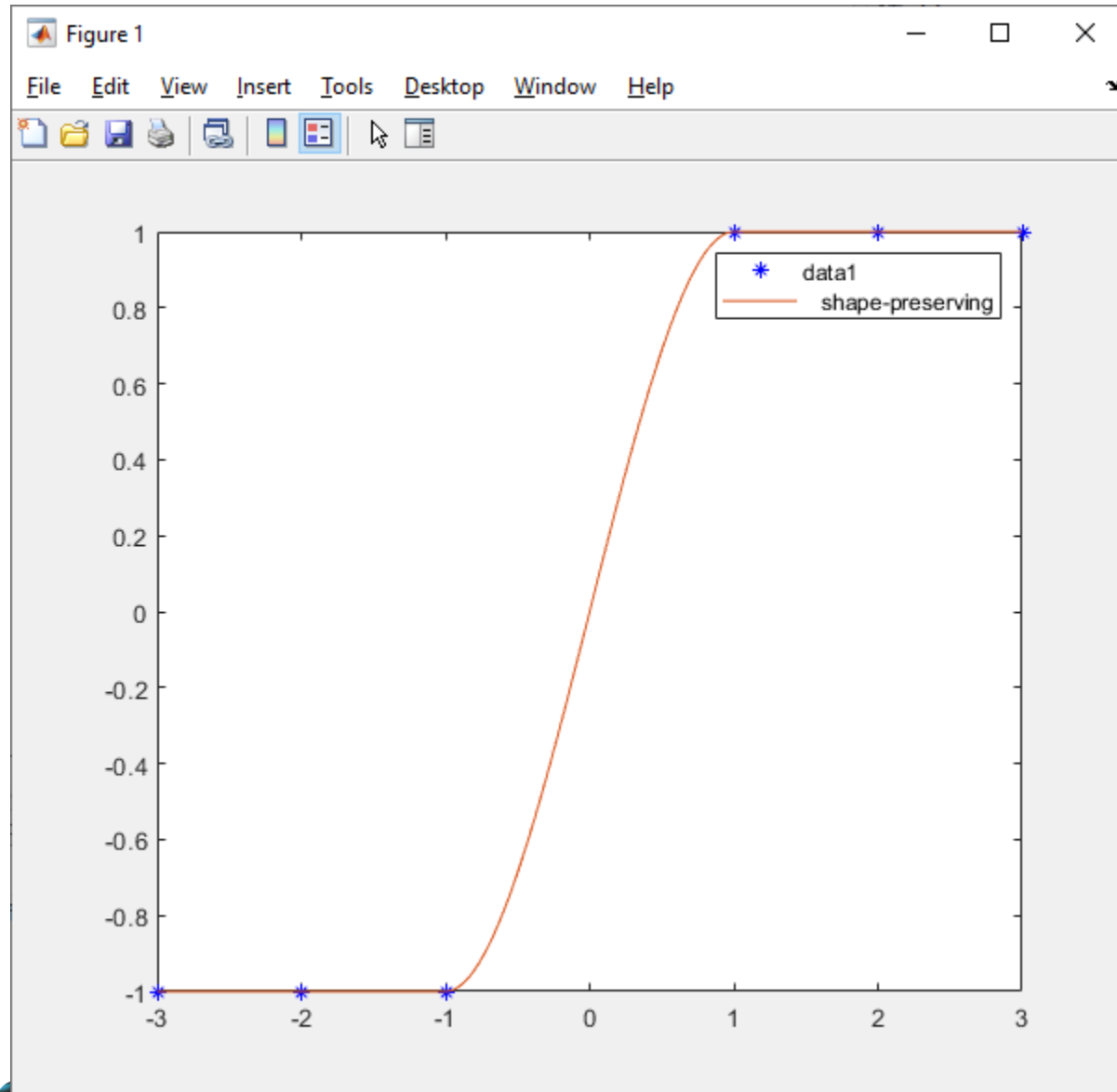
Sharp



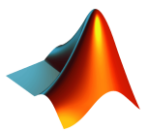
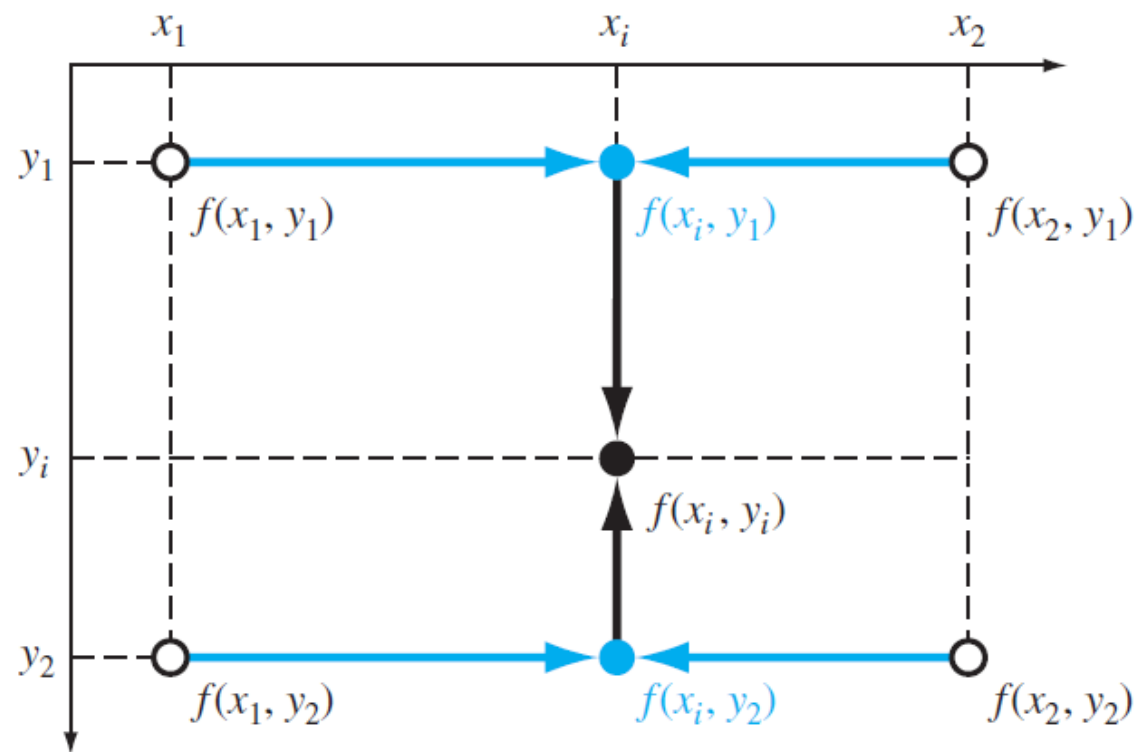
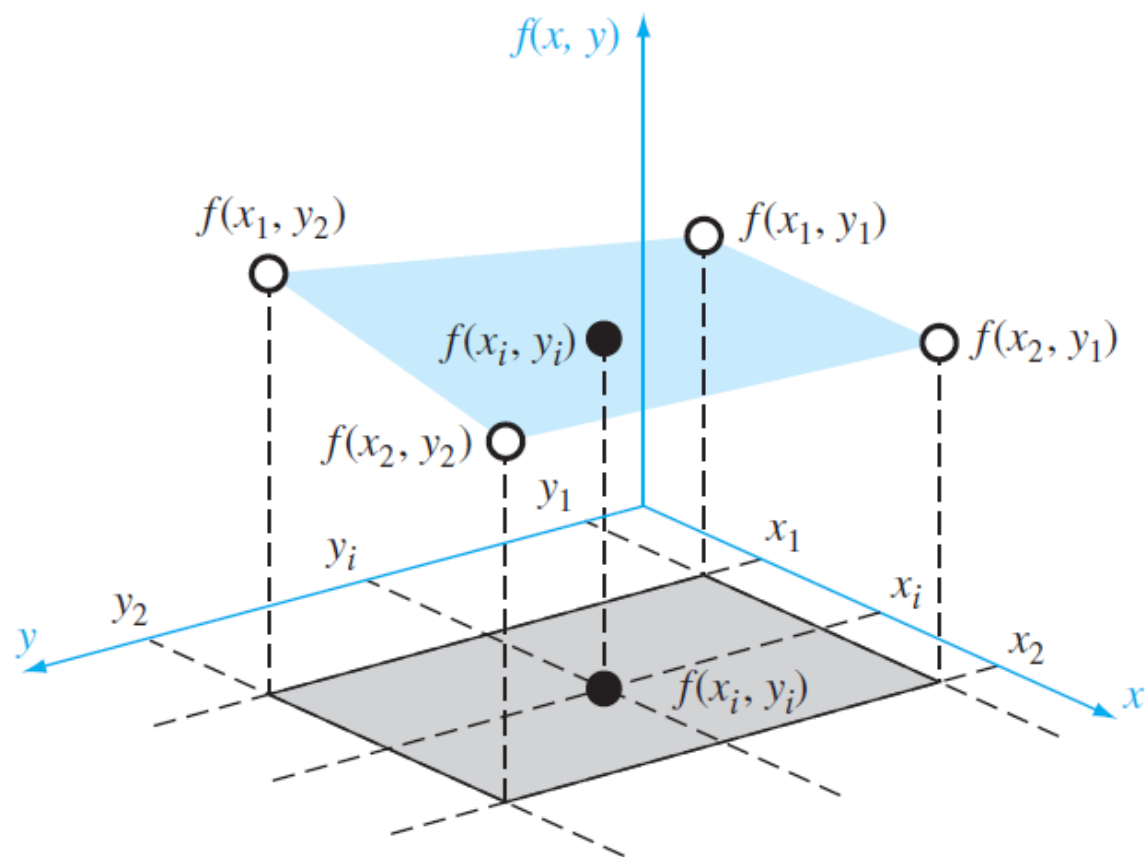
Blurred



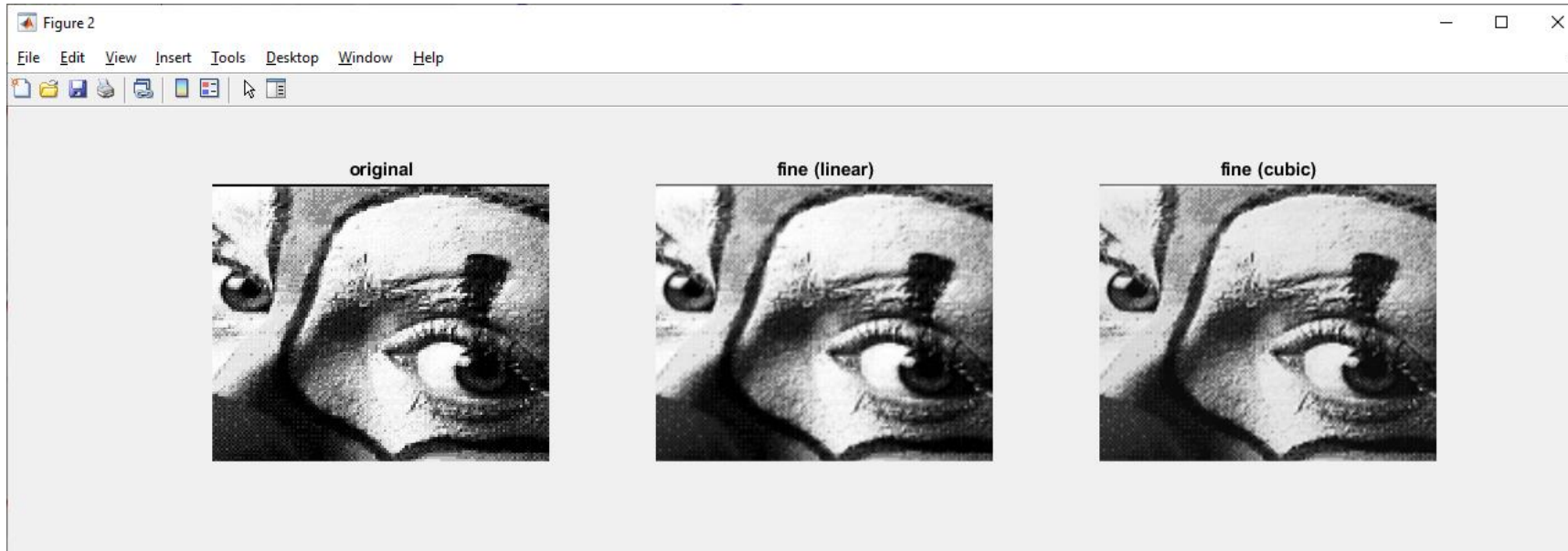
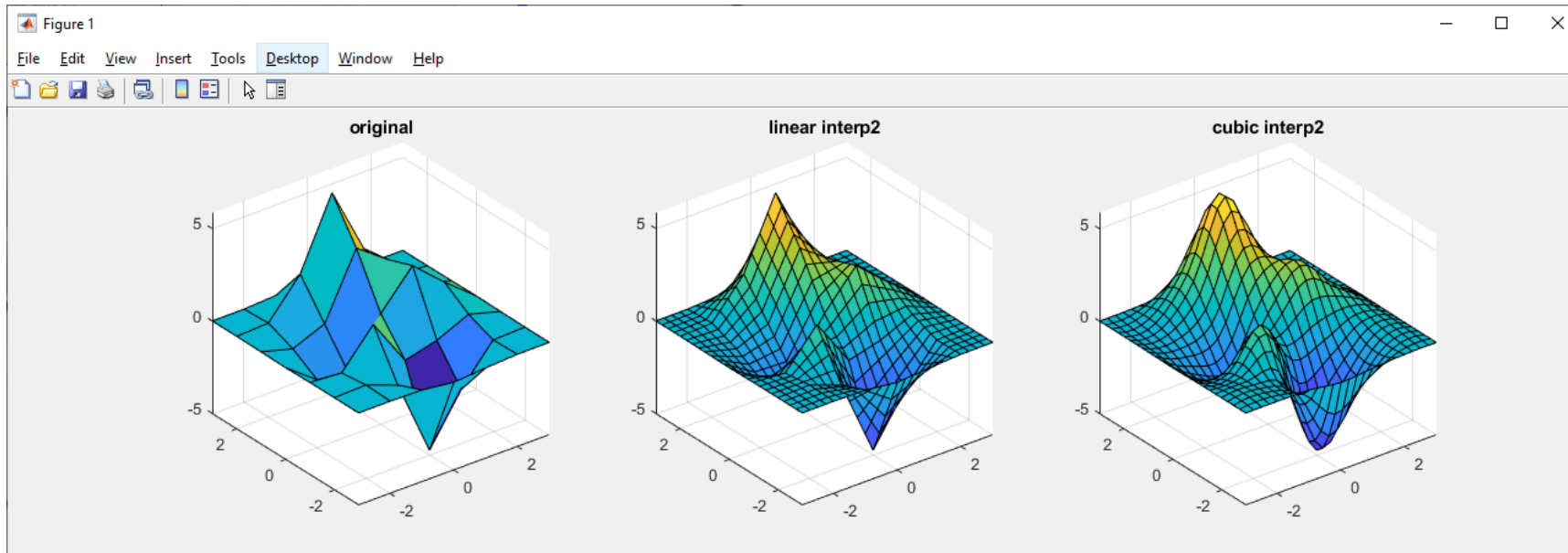
basic fitting tool



2차원 interpolation



interp2 예제



Q&A

