

## ↳ Euler's Formula for Connected Planar Graphs

- **Theorem 6.14:** Let  $G$  be a **connected planar graph** with  $n$  vertices,  $m$  edges, and  $r$  faces. Then,  **$n-m+r=2$** .
- **Proof:** (by induction on  $m$ ).
  - **Base case:** When  $m=0$ ,  $G$  is a trivial graph and  $n-0+r=2$  holds.
  - **Inductive Hypothesis:** Assume the formula holds for all graphs with  $m=k$  edges, i.e.,  $n-k+r=2$ .
  - **Inductive step:** We now prove it for  $m=k+1$  by considering two cases:
    - ① If  $G$  contains **no cycle**, then  $G$  must have a vertex  $v$  of degree 1. By deleting  $v$  and its incident edge, we get a new graph  $G'$ , which is connected, has  $n-1$  vertices,  $k$  edges, and  $r$  faces. By the inductive hypothesis,  $(n-1)-k+r=2$ , so  $n-(k+1)+r=2$ , which proves the conclusion for  $m=k+1$ .
    - ② If  $G$  contains a **cycle**, we can delete one edge from the cycle, resulting in a new graph  $G'$  with  $n$  vertices,  $k$  edges, and  $r-1$  faces. Again, by the inductive hypothesis,  $n-k+(r-1)=2$ , so  $n-(k+1)+r=2$ , proving the conclusion for  $m=k+1$ .
- Thus, by induction, the **theorem holds**.

## ↳ Corollary: Euler's Formula for Disconnected Planar Graphs

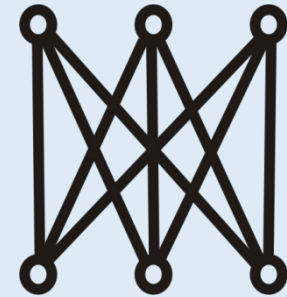
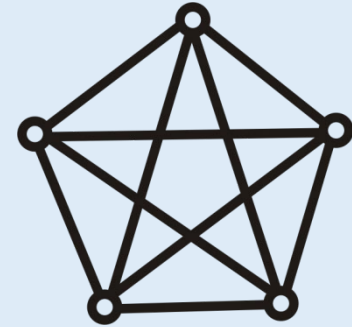
- **Corollary:** Let  $G$  be a planar graph with  $p$  connected components ( $p \geq 2$ ). Then,  $n - m + r = p + 1$  where  $n$ ,  $m$ , and  $r$  are the number of vertices, edges, and faces of  $G$ , respectively.
- **Proof:** Let the  $i$ -th connected component have  $n_i$  vertices,  $m_i$  edges, and  $r_i$  faces.
  - By Euler's formula for each connected component, we have:  $n_i - m_i + r_i = 2$ ,  $i = 1, 2, \dots, p$ .
  - Summing these equations gives:  $(n_1 + n_2 + \dots + n_p) - (m_1 + m_2 + \dots + m_p) + (r_1 + r_2 + \dots + r_p) = 2p$ .
  - Note that the total number of faces  $r = r_1 + \dots + r_p - p + 1$ , so we obtain:  $n - m + r = p + 1$ .
- Thus, the *corollary is proven*.

## ↳ Edge Bound for Connected Planar Graphs

- **Theorem 6.15:** Let  $G$  be a **connected planar graph** with  $n$  vertices and  $m$  edges, where the degree of each face is at least  $l$  ( $l \geq 3$ ), Then
$$m \leq \frac{l}{l-2}(n-2).$$
- **Proof:** In the planar graph  $G$ , the sum of the degrees of all faces is  $2m$ . Let the number of faces be  $r$ .
  - Since the degree of each face is at least  $l$ , we have  $r \cdot l \leq 2m$ , By Euler's formula,  $n - m + r = 2$ , thus  $r = 2 + m - n$ , Substituting this into the inequality:  $2m \geq l(2 + m - n)$ ,  $2m - lm \geq 2l - ln$ ,  $m(2 - l) \geq 2l - ln$ .
  - Since  $l \geq 3$ ,  $2 - l < 0$ , thus dividing by  $2 - l$  reverses the inequality:
$$m \leq \frac{l}{l-2}(n-2).$$
- Thus, the inequality is proven.

## ↳ Edge Bound for Connected Planar Graphs (e.g.)

- **Example:** Prove that the complete graph  $K_5$  and the complete bipartite graph  $K_{3,3}$  are not planar graphs.
- **Proof:** We use proof by contradiction. Assume that they are planar graphs.
  - For  $K_5$  :  $n=5$ ,  $m=10$ ,  $l=3$ , Assuming the graph satisfies Theorem 6.15 ,  $m \leq \frac{l}{l-2}(n-2)$ ,  $10 \leq 9$ .
  - For  $K_{3,3}$  :  $n=6$ ,  $m=9$ ,  $l=4$  , Similarly, we get:  $9 \leq 8$ .
  - This also leads to a contradiction. Therefore, the assumption is incorrect, meaning  $K_5$  and  $K_{3,3}$  are **not planar graphs**.
- **Note:**  $K_{3,3}$  there are no simple cycles of length 1 or 2. Any closed path must pass through an even number of edges, so each face is surrounded by at least 4 boundary edges, which means the degree of each face  $l \geq 4$ .

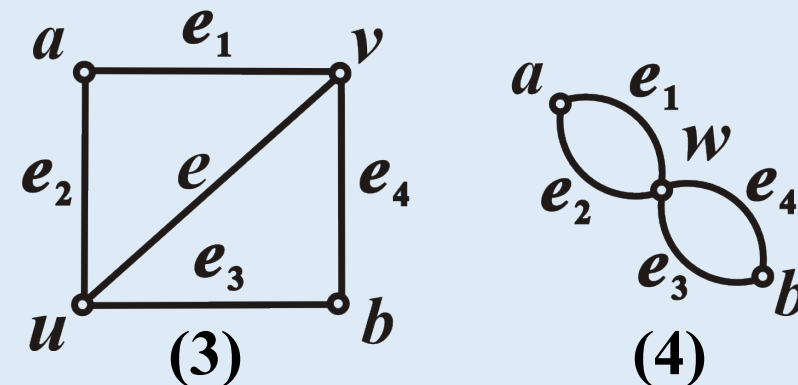
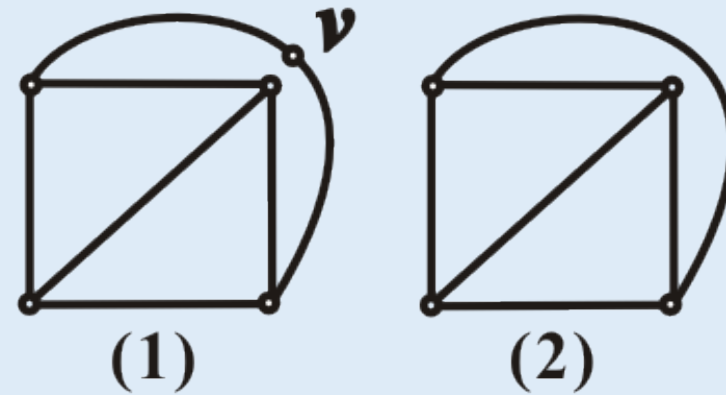


- **Homotopy**: Homotopy focuses on the isomorphism between two graphs after inserting or removing 2-degree vertices.
- Homotopy helps in understanding whether two different graphs are "**essentially the same**" and aids in recognizing the fundamental similarities or equivalences between different structures.
- **Homotopy transformations** are typically a concept in topology, and graph transformations are considered homotopy transformations in the graph's topological structure (such as inserting or removing 2-degree vertices).

### ↳ Graph Contraction and Contraction Transformations

- **Contraction**: Contraction simplifies a graph by removing an edge and replacing the two original vertices with a new vertex.
- Contraction helps reduce the complexity of a problem, making it easier to analyze and solve. It can assist in solving complex optimization problems such as finding the minimum cut, network flow, and graph coloring.
- Contraction is one of the graph **transformation operations** that simplifies a graph by merging edges while maintaining its topological structure.

- **Delete a 2-degree vertex  $v$** : As shown, from (1) to (2).
- **Insert a 2-degree vertex  $v$** : As shown, from (2) to (1).
- $G_1$  and  $G_2$  are **homotopic**:  $G_1$  and  $G_2$  are **isomorphic**, or they become isomorphic after repeatedly **inserting** or **removing 2-degree vertices**.
- **Edge contraction  $e$** : As shown, from (3) to (4)



### ↳ Necessary and Sufficient Condition for Planar Graphs

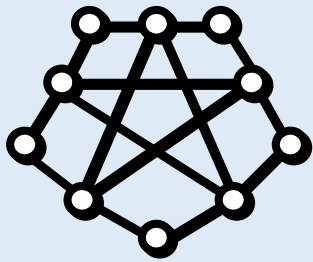
- **Theorem 6.16:** A graph is planar if and only if it contains neither a subgraph **homeomorphic to  $K_5$**  nor a subgraph **homeomorphic to  $K_{3,3}$** .
- **Theorem 6.17:** A graph is planar if and only if it contains neither a subgraph that can be **contracted to  $K_5$**  nor a subgraph that can be **contracted to  $K_{3,3}$** .
- **Note:**  $K_5$  (the complete graph with five vertices) and  $K_{3,3}$  (the complete bipartite graph with two sets of three vertices) are **typical non-planar graphs**.



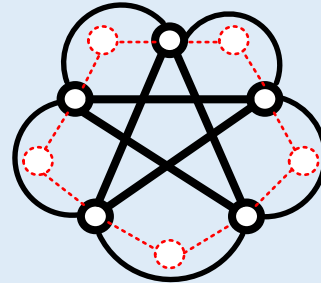
## ■ Explanation:

- ① A subgraph homeomorphic to  $K_5$  or  $K_{3,3}$  refers to a graph obtained by performing *Homotopy* transformations (adding or deleting 2-degree vertices) on  $K_5$  or  $K_{3,3}$ . These *transformations do not change the non-planarity or bipartiteness* of  $K_5$  or  $K_{3,3}$ .
- ② Theorem 6.17 emphasizes that if, after any *edge contraction* (deleting edges, merging vertices), the graph *cannot be simplified to  $K_5$  or  $K_{3,3}$* , then the graph is planar.
- ③ Homotopy focuses on *edge subdivision* (inserting a 2-degree vertex) and the removal of 2-degree vertices, while contraction focuses on *edge merging* and vertex merging. These two operations are equivalent when determining the planarity of a graph.

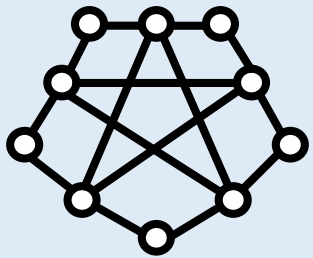
■ Example: Prove that the following graph is non-planar.



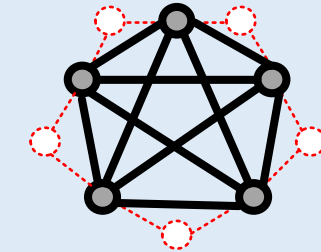
Removing five 2-degree vertices results in  $K_5$



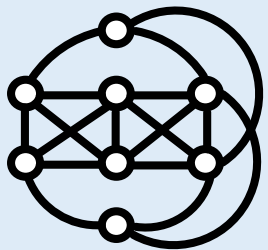
Homeomorphic to  $K_5$ , a non-planar graph.



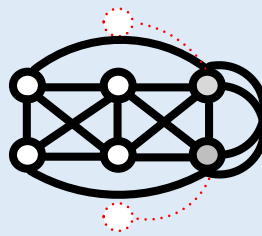
Contracting 5 edges results in  $K_5$



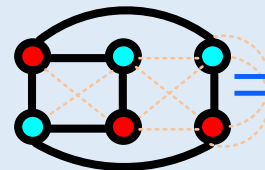
Contracting to  $K_5$ , a non-planar graph.



Contracting 2 edges



Extract  $K_{3,3}$  subgraph



A non-planar graph that is homeomorphic to  $K_{3,3}$

### ■ Definition 6.14:

Let  $G$  be a planar graph with  $n$  vertices,  $m$  edges, and  $r$  faces. The *dual graph*  $G^* = \langle V^*, E^* \rangle$  is constructed as follows:

- For each face  $R_i$  of  $G$ , choose an arbitrary point  $v_i^*$  within  $R_i$  to serve as a vertex of  $G^*$ ,  $V^* = \{ v_i^* \mid i=1, 2, \dots, r \}$ .

- For each edge  $e_k$  in  $G$ :

If  $e_k$  lies *on the common boundary* of faces  $R_i$  and  $R_j$ , create an edge  $e_k^* = (v_i^*, v_j^*)$ , in  $G^*$ , such that  $e_k^*$  intersects  $e_k$ .

If  $e_k$  lies only *on the boundary of a single face*  $R_i$ , create a loop  $e_k^* = (v_i^*, v_i^*)$ .  $E^* = \{ e_k^* \mid k=1, 2, \dots, m \}$ .

### ↳ Planar Graph $\Rightarrow$ Dual Graph: Lost Information

#### ■ Details of the planar graph *lost* in the dual graph:

- **Original layout of vertices and edges:**

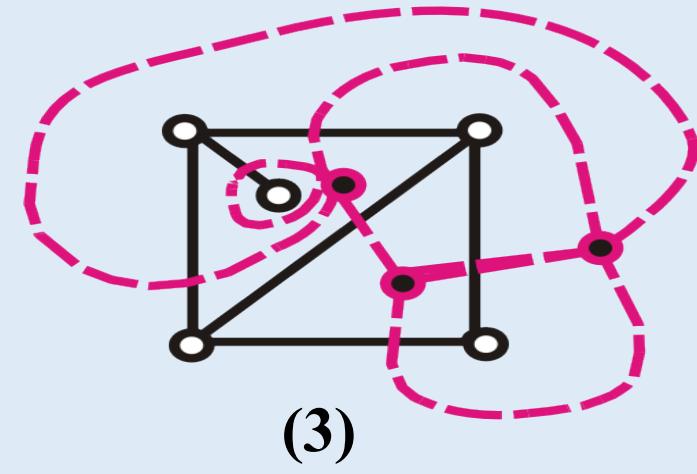
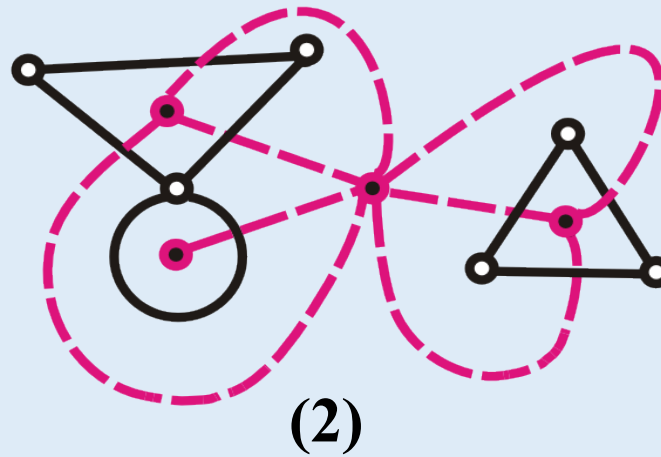
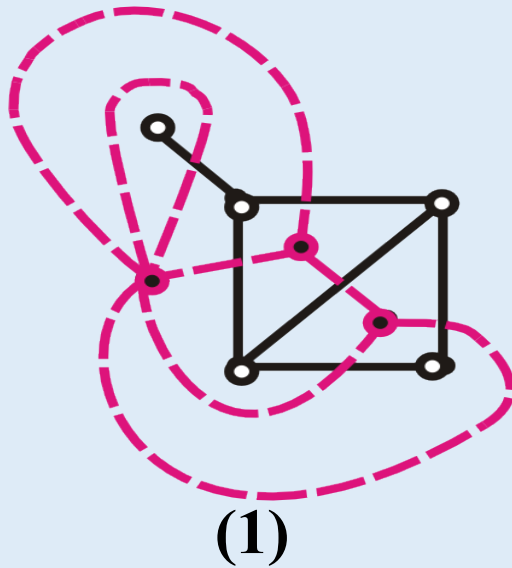
In the dual graph, faces of the original planar graph become vertices, and adjacency between faces becomes edges. However, the original layout, including the positions, placements, and relative distances of vertices and edges, is no longer directly preserved in the dual graph.

- **Vertex degrees and edge connections (such as edge crossings or winding patterns):**

The degree of vertices and the specific ways edges connect (e.g., crossings or how edges wrap around certain regions) are also not directly reflected in the dual graph.

- Properties of the planar graph *preserved* in the dual graph :
  - Connectivity
  - Cycles and cut sets: Cycles in the original graph correspond to cut sets in the dual graph.
  - Planarity
  - Satisfaction of the same Euler's formula as the original graph.
  - The original graph and its dual have the same number of edges

- **Example:** The black solid lines represent the original planar graph, and the red dashed lines represent its dual graph.



### ↳ Properties of the Dual Graph of a Planar Graph

- The dual graph  $G^*$  is a planar graph and a planar embedding.
- The dual graph  $G^*$  is *connected*.
- If an edge  $e$  forms a *cycle* in  $G$ , then the corresponding edge  $e^*$  in  $G^*$  is a *cut-edge* (bridge); if  $e$  is a bridge in  $G$ , then the corresponding edge  $e^*$  in  $G^*$  forms a cycle.
- The dual graphs of isomorphic planar graphs are *not necessarily isomorphic*.

For example, in the previous illustration, planar graphs (1) and (3) are isomorphic, but their dual graphs are not isomorphic.

### ↳ Relationship Between $G$ and $G^*$

■ **Theorem 6.18:** Let  $G^*$  be the dual graph of a connected planar graph  $G$ ,  $n^*$ ,  $m^*$ ,  $r^*$  and  $n$ ,  $m$ ,  $r$  denote the number of vertices, edges, and faces of  $G^*$  and  $G$ , respectively.

(1)  $n^* = r$

(2)  $m^* = m$

(3)  $r^* = n$

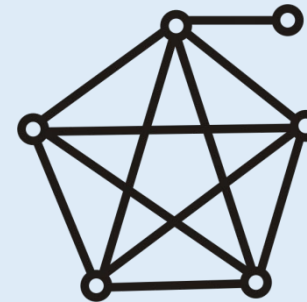
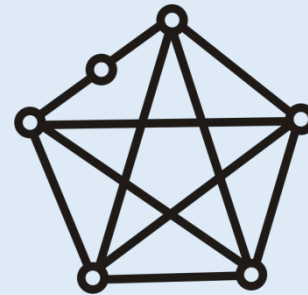
(4) If the vertex  $v_i^*$  of  $G^*$  lies in the face  $R_i$  of  $G$ , then  $d(v_i^*) = \deg(R_i)$ .



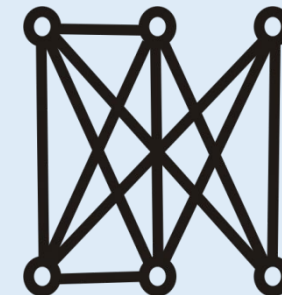
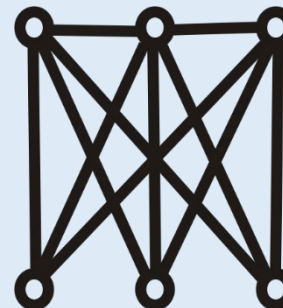
- **Example:** Draw all non-isomorphic simple connected non-planar graphs with 6 vertices and 11 edges.

- **Solution:**

(1) Add one vertex and one edge to  $K_5$  (the complete graph with 5 vertices and 10 edges).



(2) Add two edges to  $K_{3,3}$  (the complete bipartite graph with 6 vertices and 9 edges).

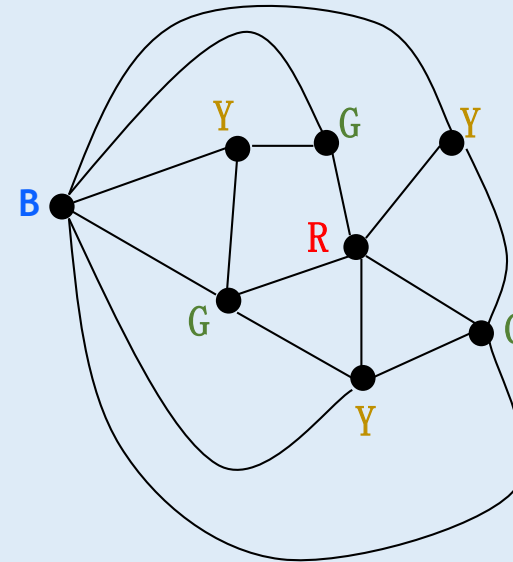
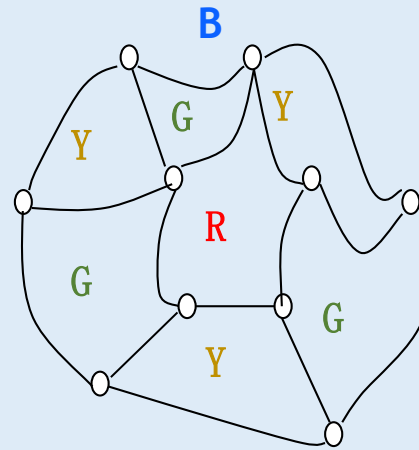
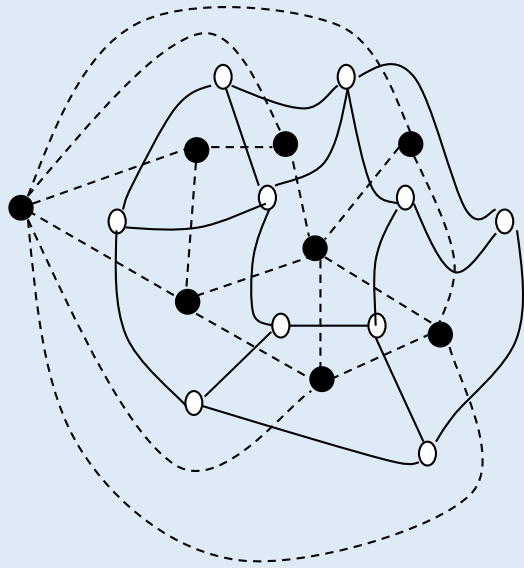


- The core objective of *graph coloring problems* is to avoid using the same color for adjacent or related elements (such as vertices, edges, or faces) under specific constraints, while using as few colors as possible.
- The *Four Color Theorem* applies to the face coloring of planar graphs, whereas vertex coloring and edge coloring follow different rules and theoretical frameworks.
- *Four Color Theorem*: For any planar graph, it is possible to color all its faces using no more than four colors, in such a way that any two faces sharing a common boundary do not have the same color (i.e., *every planar graph is 4-face-colorable*).
- The *map coloring problem* can be regarded as a specific instance of the face coloring problem for planar graph.

## ↳ Map Coloring as Vertex Coloring of Planar Graphs

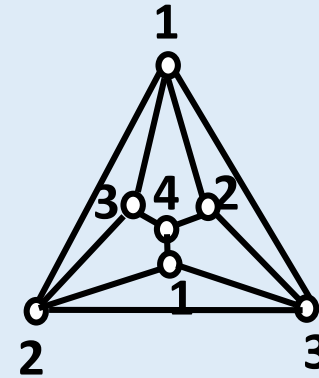
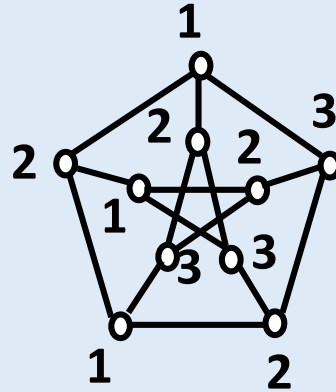
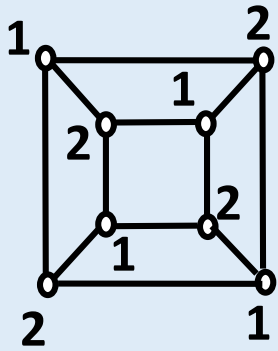
- **Map:** A planar embedding of a connected, *bridgeless planar graph*, where each face represents a country. Two countries are said to be adjacent if they share a common boundary.
- **Map coloring (face coloring):** Assign a color to each country on the map such that *adjacent countries receive different colors*.
- **Map coloring problem:** Color the map using *as few colors as possible*.
- Map coloring can be *transformed into the vertex coloring of a planar graph*. When  $G$  has no bridges, its dual graph  $G^*$  has no loops. Faces of  $G$  correspond to vertices of  $G^*$ , and two faces of  $G$  are adjacent if and only if the corresponding vertices in  $G^*$  are adjacent. Thus, *face coloring of  $G$  is equivalent to vertex coloring of  $G^*$* .

### ■ Example: Map Coloring and Vertex Coloring of Planar Graphs.



## ↳ Graph coloring (e.g.)

- **Example:** Provide a coloring using as few colors as possible.



## ↳ Graph Coloring Example: Variable Register Allocation

- **Example:** A program has six variables  $x_i$  for  $i=1,2,\dots,6$ , where the following pairs of variables need to be used simultaneously:  $x_1$  with  $x_4$ ,  $x_1$  with  $x_5$ ,  $x_2$  with  $x_5$ ,  $x_2$  with  $x_6$ ,  $x_3$  with  $x_4$ ,  $x_3$  with  $x_6$ ,  $x_4$  with  $x_5$ , and  $x_5$  with  $x_6$ . Assign each variable to a register. Variables that need to be used simultaneously cannot be assigned to the same register.

**Question:** What is the minimum number of registers needed? How should the variables be assigned?

- **Solution:**

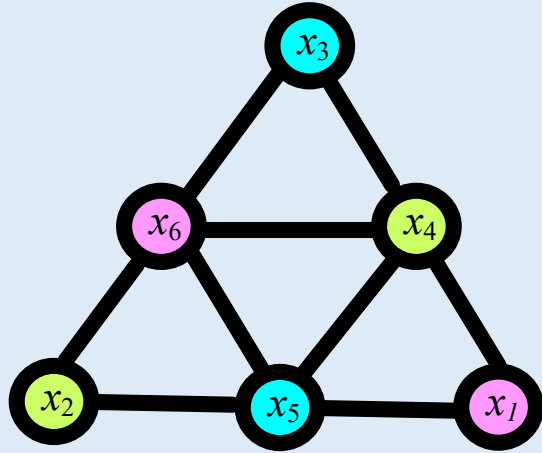
- ① The problem is *transformed into a vertex coloring problem* of a graph: each variable  $x_i$  is treated as a vertex, and the "simultaneous usage" relationship between variables indicates the presence of an edge between the corresponding vertices.

#### ■ Solution:

- ① The problem is *transformed into a vertex coloring problem* of a graph: each variable  $x_i$  is treated as a vertex, and the "simultaneous usage" relationship between variables indicates the presence of an edge between the corresponding vertices.
- ② *Construct the graph* by defining the vertex set and the edge set.
- ③ Build the graph and apply the principle of *vertex coloring* to determine the **chromatic number** (the minimum number of colors needed), ensuring that adjacent vertices are assigned different colors.
- ④ Based on the chromatic number, determine the *minimum number of registers required* and the corresponding assignment scheme.

## ↳ Graph Coloring Example: Variable Register Allocation

## ■ Result:



The register allocation scheme using three registers is as follows:

**Register 0:** Assigned to variables  $x_4$  and  $x_2$ .

**Register 1:** Assigned to variables  $x_5$  and  $x_3$ .

**Register 2:** Assigned to variables  $x_6$  and  $x_1$ .



### ↳ Four Color Theorem: Every planar graph is 4-colorable

- Four Color Conjecture (1850s)
  - Five Color Theorem (Heawood, 1890)
  - Four Color Theorem (Appel and Haken, 1976)
- Theorem (Four Color Theorem): *Every planar graph is 4-colorable.*
- The Four Color Theorem *guarantees the existence of a four-coloring scheme for any planar graph*, but finding a specific coloring usually relies on concrete algorithms and techniques.
- Common *coloring algorithms* include greedy algorithms, backtracking algorithms, and heuristic search methods such as simulated annealing and genetic algorithms.

## 6.4 Special Types of Graphs • Brief summary

**Objective :**

**Key Concepts :**