Московский государственный технический университет им. Н.Э. Баумана Факультет «Информатика и системы управления» Кафедра «Системы обработки информации и управления»



Отчет Лабораторная работа № 8 По курсу «Проектирование интеллектуальных систем»

Вариант 9

ИСПОЛНИТЕЛЬ: Попов Илья Андреевич Группа ИУ5-23М	
""	2022 г.
ПРЕП	ГОДАВАТЕЛЬ: Канев А.И.
"_"	2022 г.

Задание

Необходимо выполнить машинный перевод тектового корпуса для формирования набора данных. Обучить на сформированном наборе данных модель трасформер.

Выполнить предсказание с помощью обученной модели. Проанализировать метрику BLEU

Выполнение

/usr/local/lib/python3.7/dist-packages/transformers/models/marian/tokenization warnings.warn("Recommended: pip install sacremoses.")
Модель переводчик с en на ru загружена!

Пакетный перевод для каждой части выборки

```
def translate_batch(text_batch):
        with torch.no_grad():
            # токенизируем список с предложениями
            batch = tokenizer(text_batch, return_tensors="pt", padding=True)
            # помещаем батч на GPU
            batch = {k:v.to(device) for k,v in batch.items()}
            # переводим
            gen = model.generate(**batch)
            # декодируем из токенов полученные предложения
            return tokenizer.batch decode(gen, skip special tokens=True)
    batch_size = 128
    for part in ['train', 'val', 'test2016']:
        text_batch = []
        output_corpus = []
        with open('%s.%s'%(part, src), 'r') as f:
            for line in tqdm(f):
                sample text = line.strip()
                if len(sample_text) == 0: continue
                text_batch.append(sample_text)
                if len(text_batch) > batch_size - 1 :
                    output_corpus.extend(translate_batch(text_batch))
                    text batch = []
        if len(text_batch):
            output corpus.extend(translate batch(text batch))
        with open('%s.%s'%(part, trg), 'w') as f:
            f.write('\n'.join(output_corpus))
C→
        29001/? [11:59<00:00, 40.70it/s]
        1015/? [00:22<00:00, 40.41it/s]
```

Загружаем модель переводчика

```
[ ] spacy_de = spacy.load('de_core_news_sm')
    spacy_en = spacy.load('en_core_web_sm')

[ ] from_razdel import_tokenize
```

```
[ ] from razdel import tokenize
  import re

def tokenize_de(text):
    """
    Tokenizes German text from a string into a list of strings
    """
    return [tok.text for tok in spacy_de.tokenizer(text)]

def tokenize_en(text):
    """
    Tokenizes English text from a string into a list of strings
    """
    return [tok.text for tok in spacy_en.tokenizer(text)]

def tokenize_ru(text):
    return [tok.text for tok in tokenize(text)]

def tokenize_regex(text):
    return re.findall("[A-Z]{2,}(?![a-Z])|[A-Z][a-Z]+(?=[A-Z])|[\'\w\-]+",text)

tokenize_regex('Простое предложение для токенизации')
```

['Простое', 'предложение', 'для', 'токенизации']

Создаём токенизаторы

```
!tar -xvzf mmt_task1_test2016.tar.gz
  /usr/local/lib/python3.7/dist-packages/gdown/cli.py:131: FutureWarning: Opt
    category=FutureWarning,
  Downloading...
  From: https://drive.google.com/uc?id=1YWbueklT5VgNhjuxoapZFnkRSwPxH r0
  To: /content/training.tar.gz
  100% 1.94M/1.94M [00:00<00:00, 157MB/s]
  /usr/local/lib/python3.7/dist-packages/gdown/cli.py:131: FutureWarning: Opt
    category=FutureWarning,
  Downloading...
   From: https://drive.google.com/uc?id=1X1aXa VMCkyAox50ABqN132AZx7Hw4uq
  To: /content/validation.tar.gz
  100% 74.6k/74.6k [00:00<00:00, 67.9MB/s]
  /usr/local/lib/python3.7/dist-packages/gdown/cli.py:131: FutureWarning: Opt
    category=FutureWarning,
  Downloading...
  From: https://drive.google.com/uc?id=1nF8ff7QniRCkP-ybDKXcAMKk8YQaHA7Q
  To: /content/mmt_task1_test2016.tar.gz
  100% 93.0k/93.0k [00:00<00:00, 67.9MB/s]
  val.de
  val.en
  val.ru
  train.de
  train.en
  train.ru
  test2016.de
  test2016.en
  test2016.fr
  test2016.ru
train_data, valid_data, test_data = Multi30k.splits(exts=('.ru', '.en'),
                                                       fields=(SRC, TRG),
                                                       path='')
SRC.build_vocab(train_data, min_freq = 2)
   TRG.build_vocab(train_data, min_freq = 2)
Загружаем текст
```

```
class Encoder(nn.Module):
        def __init__(self,
                     input dim,
                     hid_dim,
                     n_layers,
                     n_heads,
                     pf_dim,
                     dropout,
                     device,
                     max_length = 100):
            super(). init ()
            self.device = device
            self.tok_embedding = nn.Embedding(input_dim, hid_dim)
            self.pos_embedding = nn.Embedding(max_length, hid_dim)
            self.layers = nn.ModuleList([EncoderLayer(hid_dim,
                                                      n_heads,
                                                      pf_dim,
                                                      dropout,
                                                      device)
                                         for _ in range(n_layers)])
            self.dropout = nn.Dropout(dropout)
            self.scale = torch.sqrt(torch.FloatTensor([hid_dim])).to(device)
        def forward(self, src, src_mask):
            #src = [batch size, src len]
            #src_mask = [batch size, 1, 1, src len]
            batch_size = src.shape[0]
            src_len = src.shape[1]
            pos = torch.arange(0, src_len).unsqueeze(0).repeat(batch_size, 1).to(self.device)
            #pos = [batch size, src len]
```

Определяем энкодер трансформера

```
class MultiHeadAttentionLayer(nn.Module):
        def __init__(self, hid_dim, n_heads, dropout, device):
            super().__init__()
            assert hid dim % n heads == 0
            self.hid_dim = hid_dim
            self.n heads = n heads
            self.head_dim = hid_dim // n_heads
            self.fc_q = nn.Linear(hid_dim, hid_dim)
            self.fc_k = nn.Linear(hid_dim, hid_dim)
            self.fc_v = nn.Linear(hid_dim, hid_dim)
            self.fc_o = nn.Linear(hid_dim, hid_dim)
            self.dropout = nn.Dropout(dropout)
            self.scale = torch.sqrt(torch.FloatTensor([self.head_dim])).to(device)
        def forward(self, query, key, value, mask = None):
            batch_size = query.shape[0]
            #query = [batch size, query len, hid dim]
            #key = [batch size, key len, hid dim]
            #value = [batch size, value len, hid dim]
            Q = self.fc_q(query)
            K = self.fc_k(key)
            V = self.fc_v(value)
            #Q = [batch size, query len, hid dim]
            #K = [batch size, key len, hid dim]
            #V = [batch size, value len, hid dim]
            Q = Q.view(batch_size, -1, self.n_heads, self.head_dim).permute(0, 2, 1, 3)
            K = K.view(batch_size, -1, self.n_heads, self.head_dim).permute(0, 2, 1, 3)
            V = V.view(batch_size, -1, self.n_heads, self.head_dim).permute(0, 2, 1, 3)
```

Голова внимания

```
class PositionwiseFeedforwardLayer(nn.Module):
    def __init__(self, hid_dim, pf_dim, dropout):
        super().__init__()

        self.fc_1 = nn.Linear(hid_dim, pf_dim)
        self.fc_2 = nn.Linear(pf_dim, hid_dim)

        self.dropout = nn.Dropout(dropout)

def forward(self, x):

    #x = [batch size, seq len, hid dim]

    x = self.dropout(torch.relu(self.fc_1(x)))

    #x = [batch size, seq len, pf dim]

    x = self.fc_2(x)

    #x = [batch size, seq len, hid dim]

    return x
```

Полносвязный слой

```
class Decoder(nn.Module):
        def __init__(self,
                     output_dim,
                     hid_dim,
                     n layers,
                     n heads,
                     pf_dim,
                     dropout,
                     device,
                     max_length = 100):
            super().__init__()
            self.device = device
            self.tok embedding = nn.Embedding(output dim, hid dim)
            self.pos_embedding = nn.Embedding(max_length, hid_dim)
            self.layers = nn.ModuleList([DecoderLayer(hid_dim,
                                                       n_heads,
                                                       pf_dim,
                                                       dropout,
                                                       device)
                                          for _ in range(n_layers)])
            self.fc_out = nn.Linear(hid_dim, output_dim)
            self.dropout = nn.Dropout(dropout)
            self.scale = torch.sqrt(torch.FloatTensor([hid_dim])).to(device)
        def forward(self, trg, enc_src, trg_mask, src_mask):
            #trg = [batch size, trg len]
            #enc_src = [batch size, src len, hid dim]
            #trg_mask = [batch size, 1, trg len, trg len]
            #src_mask = [batch size, 1, 1, src len]
            batch_size = trg.shape[0]
            trg_len = trg.shape[1]
```

Слой Декодера

```
class Seq2Seq(nn.Module):
     def __init__(self,
                  encoder,
                  decoder,
                  src_pad_idx,
                  trg_pad_idx,
                  device):
         super().__init__()
         self.encoder = encoder
         self.decoder = decoder
         self.src_pad_idx = src_pad_idx
         self.trg_pad_idx = trg_pad_idx
         self.device = device
     def make_src_mask(self, src):
         #src = [batch size, src len]
         src_mask = (src != self.src_pad_idx).unsqueeze(1).unsqueeze(2)
         #src_mask = [batch size, 1, 1, src len]
         return src_mask
     def make_trg_mask(self, trg):
         #trg = [batch size, trg len]
         trg_pad_mask = (trg != self.trg_pad_idx).unsqueeze(1).unsqueeze(2)
         #trg_pad_mask = [batch size, 1, 1, trg len]
         trg_len = trg.shape[1]
         trg_sub_mask = torch.tril(torch.ones((trg_len, trg_len), device = self.device)).bool()
         #trg_sub_mask = [trg len, trg len]
```

Формируем трансформер с помощью модели Seq2Seq

```
[ ] INPUT_DIM = len(SRC.vocab)
   OUTPUT_DIM = len(TRG.vocab)
   HID DIM = 256
   ENC_LAYERS = 3
   DEC_LAYERS = 3
   ENC_HEADS = 8
   DEC\_HEADS = 8
    ENC_PF_DIM = 512
   DEC_PF_DIM = 512
    ENC_DROPOUT = 0.15
   DEC_DROPOUT = 0.15
    enc = Encoder(INPUT_DIM,
                HID_DIM,
                ENC_LAYERS,
                ENC HEADS.
                ENC_PF_DIM,
                ENC DROPOUT,
                device)
    dec = Decoder(OUTPUT_DIM,
                HID DIM,
                DEC_LAYERS,
                DEC_HEADS,
                DEC_PF_DIM,
                DEC_DROPOUT,
                device)
 N_EPOCHS = 15
     CLIP = 1
     best_valid_loss = float('inf')
     for epoch in range(N_EPOCHS):
         start_time = time.time()
         train_loss = train(model, train_iterator, optimizer, criterion, CLIP)
         valid_loss = evaluate(model, valid_iterator, criterion)
         end time = time.time()
         epoch_mins, epoch_secs = epoch_time(start_time, end_time)
         if valid_loss < best_valid_loss:</pre>
             best_valid_loss = valid_loss
             torch.save(model.state_dict(), 'tut6-model.pt')
         print(f'Epoch: {epoch+1:02} | Time: {epoch_mins}m {epoch_secs}s')
         print(f'\tTrain Loss: {train_loss:.3f} | Train PPL: {math.exp(train_loss):7.3f}')
         print(f'\t\ Val.\ Loss:\ \{valid\_loss:.3f\}\ |\ \ Val.\ PPL:\ \{math.exp(valid\_loss):7.\beta f\}')
Epoch: 01 | Time: 0m 18s
             Train Loss: 4.337 | Train PPL: 76.452
              Val. Loss: 3.145 | Val. PPL: 23.220
     Epoch: 02 | Time: 0m 18s
             Train Loss: 2.986 | Train PPL: 19.801
              Val. Loss: 2.403 | Val. PPL: 11.057
    Epoch: 03 | Time: 0m 17s
             Train Loss: 2.296 | Train PPL:
              Val. Loss: 1.914 | Val. PPL: 6.782
    Epoch: 04 | Time: 0m 17s
             Train Loss: 1.864 | Train PPL: 6.452
              Val. Loss: 1.697 | Val. PPL: 5.458
     Epoch: 05 | Time: 0m 17s
             Train Loss: 1.586 | Train PPL:
                                               4.883
```

Обучение модели

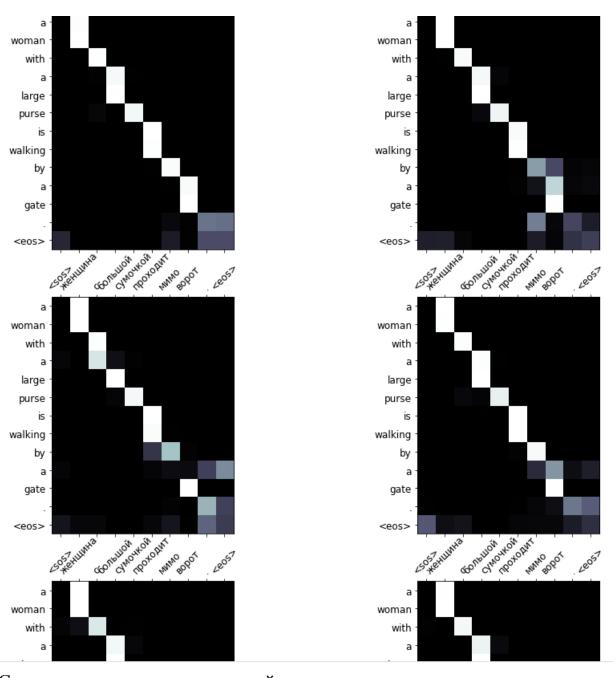
```
[] example_idx = 8

src = vars(train_data.examples[example_idx])['src']
trg = vars(train_data.examples[example_idx])['trg']

print(f'src = {src}')
print(f'trg = {trg}')

src = ['женщина', 'c', 'большой', 'сумочкой', 'проходит', 'мимо', 'ворот', '.']
trg = ['a', 'woman', 'with', 'a', 'large', 'purse', 'is', 'walking', 'by', 'a', 'gate', '.']
```

Результат: пример из обучающего набора



Сосредоточение внимания каждой из голов

```
[ ] translation, attention = translate_sentence(src, SRC, TRG, model, device)

print(f'predicted trg = {translation}')

predicted trg = ['a', 'brown', 'dog', 'runs', 'behind', 'a', 'black', 'dog', '.', '<eos>']

[ ] src = ['внимание', 'это', 'всё', 'что', 'тебе', 'нужно']

translation, attention = translate_sentence(src, SRC, TRG, model, device)

print(f'predicted trg = {translation}')

predicted trg = ['the', 'attention', 'is', 'this', 'is', 'seen', 'to', 'be', 'taking', 'the', 'attention', '<eos>']

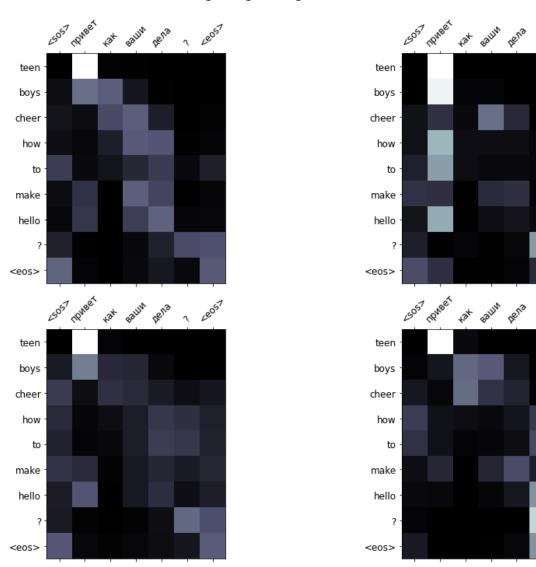
[ ] src = ['привет', 'как', 'ваши', 'дела', '?']

translation, attention = translate_sentence(src, SRC, TRG, model, device)

print(f'predicted trg = {translation}')

predicted trg = ['teen', 'boys', 'cheer', 'how', 'to', 'make', 'hello', '?', '<eos>']
```

Несколько собственных примеров перевода



Сосредоточение внимания

```
[ ] from torchtext.data.metrics import bleu_score
    from tqdm.auto import tqdm

def calculate_bleu(data, src_field, trg_field, model, device, max_len = 50):

    trgs = []
    pred_trgs = []
    pbar = tqdm(total=len(data))
    for datum in data:

        src = vars(datum)['src']
        trg = vars(datum)['trg']

        pred_trg, _ = translate_sentence(src, src_field, trg_field, model, device, max_len)

    #cut off <eos> token
        pred_trg = pred_trg[:-1]

        pred_trgs.append(pred_trg)
        trgs.append([trg])
        pbar.update(1)

    return bleu_score(pred_trgs, trgs)
```

Мы получаем оценку BLEU в 42 балла, что превышает ~ 40 баллов сверточной модели. Все это при меньшем количестве параметров и более быстром времени обучения!

```
[ ] bleu_score = calculate_bleu(test_data, SRC, TRG, model, device)
print(f'BLEU score = {bleu_score*100:.2f}')

100%
1000/1000 [47:32<00:00, 20.29it/s]
BLEU score = 41.20</pre>
```

Расчёт оценки ВЕЦИ