

5.1

$$1. A = \begin{pmatrix} 1 & 2 \\ -1 & 3 \\ 3 & 4 \\ 4 & 5 \end{pmatrix} \quad A_1 = \begin{pmatrix} 1 & 2 \\ 1 & 1 \end{pmatrix}, A_2 = \begin{pmatrix} 3 & 5 \\ 4 & 4 \end{pmatrix}$$

$$B = \begin{pmatrix} I & X \\ I & I \end{pmatrix}, \quad A_1 X - X A_2 = \begin{pmatrix} 1 & 2 \\ 3 & 4 \end{pmatrix}$$

$$X = \begin{pmatrix} a & b \\ c & d \end{pmatrix} \quad \begin{pmatrix} 11 \\ -2c-2a \\ -2c \\ -5c-3d \end{pmatrix}$$

$$\Rightarrow X = \begin{pmatrix} 2 & -\frac{31}{9} \\ \frac{3}{2} & -\frac{7}{6} \end{pmatrix}$$

$$\Rightarrow B = \begin{pmatrix} 1 & 2 & -\frac{31}{9} \\ 1 & \frac{3}{2} & -\frac{7}{6} \\ 1 & 1 & 1 \end{pmatrix}$$

$$2. \ker(A - 3I) = \ker(B \cdot \begin{pmatrix} -2 & 2 \\ & -2 \\ & & 5 \end{pmatrix} \cdot B^{-1})$$

$$= \text{span}\left(B \cdot \begin{pmatrix} 0 \\ 0 \\ 1 \\ 0 \end{pmatrix}\right) = \text{span}\begin{pmatrix} 2 \\ \frac{3}{2} \\ -1 \\ 0 \end{pmatrix}$$

$$\ker(A - 4I) = \ker(B \cdot \begin{pmatrix} 3 & 2 \\ 3 & -3 \\ & -1 \\ & & 5 \end{pmatrix} B^{-1})$$

$$= \text{span}\left(B \cdot \begin{pmatrix} 0 \\ 0 \\ 5 \\ 1 \end{pmatrix}\right) = \text{span}\begin{pmatrix} \frac{59}{9} \\ \frac{19}{3} \\ 5 \\ 1 \end{pmatrix}$$

$$\Rightarrow \text{basis for } V_3 + V_4: \begin{pmatrix} 2 \\ 3/2 \\ 1 \\ 0 \end{pmatrix} - \begin{pmatrix} 59/9 \\ 19/3 \\ 5 \\ 1 \end{pmatrix}$$

$$3. (x-3)(x-4)(x-1)^2$$

5.2

$$1. \text{ let } X = kI \quad (k \in \mathbb{R})$$

$$\Rightarrow L(X) = L(kI) = kAI - kIA = k(A - A) = 0$$

$$2. \quad L(XY) = AXY - XYA$$

$$\begin{aligned} L(X)Y &= AXY - XYA \\ XL(Y) &= XAY - YTA \end{aligned} \quad \left. \begin{aligned} \Rightarrow L(X)Y - XL(Y) \\ = AXY - XYA = L(XY) \end{aligned} \right\}$$

$$3. \quad \textcircled{1} L(kX) = kAX - kXA$$

$$= k(AX - XA) = L(X) \cdot k$$

$$\textcircled{2} L(X)X = AX^2 - XAX = XL(X) = XAX - X^2A$$

$$\Rightarrow 2XAX = AX^2 + X^2A \Rightarrow 3X^2AX = \frac{3}{2}XAX + \frac{1}{2}X^3A$$

$$\Rightarrow 2AX^2 - 2XAX = AX^2 - X^2A = L(X) \cdot 2X = L(X^2)$$

using induction:

$$k=2 \quad \checkmark$$

$$k+1: \quad L(X^{k+1}) = L(X) \cdot (kX^{k-1}) \quad \checkmark$$

$$\begin{aligned} L(X^{k+1}) &= L(X) \cdot X^k + X \cdot L(X) \cdot (kX^{k-1}) \\ &= L(X) \cdot X^k + X \cdot L(X) \cdot (kX^{k-1}) \\ &= L(X) \cdot X^k + L(X) \cdot X \cdot (kX^{k-1}) \\ &= L(X)(k+1)X^k \quad \checkmark \end{aligned}$$

4.

$$X = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}, A = \begin{pmatrix} 1 & 1 \\ 1 & 1 \end{pmatrix} \Rightarrow L(X)X = AX^2 - XAX = \begin{pmatrix} -1 & 1 \\ 1 & -1 \end{pmatrix}$$

$$XA = \begin{pmatrix} 2 & 1 \\ 1 & 1 \end{pmatrix}$$

$$AX = \begin{pmatrix} 1 & 1 \\ 1 & 2 \end{pmatrix}$$

$$XAX = \begin{pmatrix} 1 & 2 \\ 1 & 1 \end{pmatrix}$$

$$L(X^2) = AX^2 - X^2A = \begin{pmatrix} -2 & 2 \\ 2 & -2 \end{pmatrix}$$

$$XL(X) = XAX - X^2A = \begin{pmatrix} -1 & 1 \\ 1 & -1 \end{pmatrix}$$

$$L(X)X + XL(X) = \begin{pmatrix} -2 & -2 \\ -2 & -2 \end{pmatrix}$$

$$L(X)(2X) = \begin{pmatrix} -2 & -2 \\ -2 & -2 \end{pmatrix}$$

5. if $L(X) = I$ for some X

then $L(X)X = XL(X)$

then $L(p(X)) = L(X)p'(X) = p'(X)$
||

$$A p(X) - p(X) A$$

let $p(X)$ be the minimal polynomial of X

$$\Rightarrow p'(X) = 0$$

$$\Rightarrow P(X) = cI \quad (c \in \mathbb{R})$$

↑ impossible

$$\Rightarrow \text{so } L(X) \neq I \text{ for any } X$$

6. $X \in \ker(L)$ iff $L(X) = AX - XA = 0$

$$\Rightarrow AX = XA$$

since A is diagonalizable with distinct eigenvalues

$$A = C D C^{-1}$$

with distinct diagonal entries

$$\Rightarrow CDC^{-1}X = XCDC^{-1}$$

$$C(DX)C^{-1} = C(XD)C^{-1}$$

$$DX = XD$$

$$D = \begin{pmatrix} \lambda_1 & & \\ & \lambda_2 & \\ & & \ddots & \\ & & & \lambda_n \end{pmatrix} \quad \lambda_1 \neq \lambda_2 \neq \dots \neq \lambda_n \quad \Rightarrow x_{ij} = \lambda_i x_{ij} \lambda_j^{-1} \quad \left. \right\} \Rightarrow X = \begin{pmatrix} x_1 & & \\ & x_2 & \\ & & \ddots & \\ & & & x_n \end{pmatrix}$$

$\frac{\lambda_i}{\lambda_j} x_{ij}$

\Rightarrow so $\dim \ker(L) = n$ (A is a $n \times n$ matrix)

7. $A = \begin{pmatrix} 1 & & \\ & 2 & \\ & & 3 \end{pmatrix}$

5.3

1. $W \xrightarrow{A} W$ then we can restrict A onto W $\Rightarrow A': W \rightarrow W$ A' is also a linear map, which must have at least one eigenvector
obviously, this eigenvector is in W 2. $\forall \vec{v} \in \text{Ker}(A - \lambda I)$,

$$A\vec{v} - \lambda\vec{v} = \vec{0} \Rightarrow B(A\vec{v} - \lambda\vec{v}) = BA\vec{v} - \lambda B\vec{v} = \vec{0}$$

since $AB = BA$

$$\Rightarrow AB\vec{v} - \lambda B\vec{v} = \vec{0}$$

$$= (A - \lambda I)B\vec{v} = \vec{0}$$

$$\Rightarrow B\vec{v} \in \text{Ker}(A - \lambda I)$$

then $\text{Ker}(A - \lambda I)$ is B -invariant for all $\lambda \in \mathbb{C}$ 3. from 1&2 $\Rightarrow B$ has an eigenvector in $\text{Ker}(A - \lambda I)$ \Rightarrow same eigenvector means same eigenvalue λ 4. suppose \vec{v} is the common eigenvector for A & B

$$x_1 = (\vec{v}, \dots)$$

↑
arbitrary find some vectors to form a basis with \vec{v} then x_1 must be invertibleusing Schur decomposition, we can get $A = x_1 \begin{pmatrix} a_1 & * \\ & A_1 \end{pmatrix} x_1^{-1}$
 $B = x_1 \begin{pmatrix} b_1 & * \\ & B_1 \end{pmatrix} x_1^{-1}$ since $A_1 B_1 = B_1 A_1$

$$\Rightarrow \begin{pmatrix} a_1 b_1 & * \\ A_1 B_1 \end{pmatrix} = \begin{pmatrix} a_1 b_1 & * \\ B_1 A_1 \end{pmatrix} \Rightarrow A_1 B_1 = B_1 A_1$$

5. in the last subproblem, we have done 1st step of triangularization
since $A_1 B_1 = B_1 A_2 \Rightarrow$ have a common eigenvector

we can use induction:

$$A_1 = x_2 \begin{pmatrix} a_2 & * \\ & A_2 \end{pmatrix} x_2^{-1} \Rightarrow A_2 B_2 = B_2 A_2 \Rightarrow \dots$$

$$B_1 = x_2 \begin{pmatrix} b_2 & * \\ & B_2 \end{pmatrix} x_2^{-1}$$

then we get $A = X R_A X^{-1}$, $X = x_1 x_2 x_3 \dots$
 $B = X R_B X^{-1}$