10.1
1.
$$T_{pM} = span \begin{pmatrix} J_{2} \\ -J_{3} \end{pmatrix} \begin{pmatrix} J_{2} \\ 0 \\ -J_{6} \end{pmatrix}$$

2. $(2dx_{p} + 3dy_{p})(\vec{V})$
 $= 2 \times J_{2} + 3x - J_{3}) = 2J_{2} - 3J_{3}$
3.

$$\vec{V} = \begin{pmatrix} (\alpha tb)J\Sigma \\ -J3a \\ -J6b \end{pmatrix} \cdot \forall a,b \in \mathbb{R}$$

$$dx_{p}(\vec{V}) = (\alpha + b)J\Sigma$$

$$d_{yp}(\vec{v}) = -Ja \Rightarrow Jad_{xp}(\vec{v}) + Jzd_{yp}(\vec{v}) + dz_{p}(\vec{v}) = 0$$

$$d_{yp}(\vec{v}) = -Jbb \Rightarrow Jad_{xp} + Jzd_{yp} + dz_{p} = 0$$

4.
$$dxp \& dxp$$
 are linearly dependent
$$\Rightarrow \forall \vec{v} \in T_p M, \vec{v} = \begin{pmatrix} 2 \\ 2 \end{pmatrix}$$

5.
$$\int_{Y} dx = \int_{Y} dy = 0$$
. $\int_{T} dz = 2$
6. $\int_{Y} (yzdx + zxdy + xydz) = \int_{T} d(xyz) = \frac{5}{8} - \frac{1}{6}$

$$\begin{array}{c}
1. & f(p) = \begin{pmatrix} 2A \\ 2-C \\ 2b \\ 2-c \end{pmatrix} \\
2. & p \cdot v = 0 \\
\begin{vmatrix} 1 \\ 2 \\ 2 \end{vmatrix}
\end{aligned}$$

2.
$$\vec{p} \cdot \vec{v} = 0 \Rightarrow \vec{j}_3 + \vec{j}_3 \cdot \vec{j}_3$$

$$\Rightarrow y_0 = -1$$

$$\Rightarrow \vec{v} = \begin{pmatrix} 1 \\ -1 \end{pmatrix}$$

$$\uparrow_* (\vec{v}) = \begin{pmatrix} \frac{1}{1-1} \\ -\frac{1}{1-1} \end{pmatrix} = \begin{pmatrix} 3+\sqrt{3} \\ -3-\sqrt{3} \end{pmatrix}$$

$$\frac{-2}{(-3-)3/}$$

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$$\frac{-3}{(-3-)3/}$$

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$$\frac{-3}{(-3-)3/}$$

$$\Rightarrow dg_{(p)} = (-53-1 53+1)$$

$$\Rightarrow f^*(dg_{f(p)}) \begin{pmatrix} \gamma_0 \\ \gamma_2 \end{pmatrix}$$

$$= (2+\sqrt{3}) \left((\sqrt{3}+3)/20 - 2\sqrt{3}/20 + 2\sqrt{3}/20 - (3+\sqrt{3})/20 \right)$$

$$= (-453-6) \times 0 + (453+6) \times 0$$

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$$= dg_{f(p)} \left(f_{*} \left(f_{*}^{(p)} \right) \right)$$

$$= (-J3-1 \ J3+1) \left(\frac{J5 \times (-J3)z_{0}}{25 \times (-J3)z_{0}} \right)$$