

# Introduction to mathematical programming

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# Damn, it is about mathematics?!

Nope, it is not - at least not really if you're not delving into the theory.

This will be more about modelling of problems from practice and the theoretical basics.

# Why should we care?

Because...

1. we can easily **solve difficult problems**
2. it serves as a **first approach**
3. it might help **approximating** problems
4. **Braun** loves it! (awesome for your PA)
5. it is widely used in **practice**

# Agenda

1. Example problems
2. Basics of modelling
3. Applying the techniques
4. Staying realistic

# What can we model?

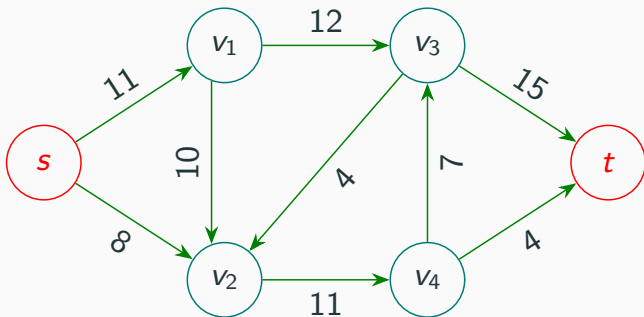
A lot!

Let's look at some examples...

## Example: Maximum flow (“easy” problem)

**Problem:** Maximum flow

**Goal:** How much flow can you push from node  $s$  to node  $t$  while complying with capacity constraints.

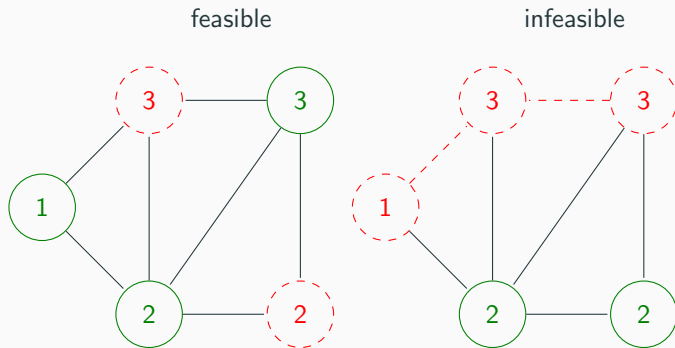


**Figure 1:** Example for maximum flow. Upper bound is 19 units due to the capacity constraints of the edges going into  $t$ .

## Example: Minimum Vertex Cover ( $\mathcal{NP}$ -hard)

**Problem:** Minimum Vertex Cover

**Goal:** Find a subset of vertices that cover each edge while minimizing costs.

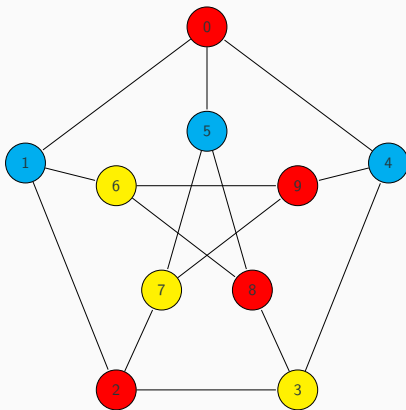


**Figure 2:** Example for minimum vertex cover. Numbers in nodes are associated costs. Dashed edges are not covered which renders the instance infeasible. All dashed nodes are not included in the subset.

## Example: Graph coloring ( $\mathcal{NP}$ -hard)

**Problem:** Graph coloring

**Goal:** Color each node with adjacent nodes colored distinctly.



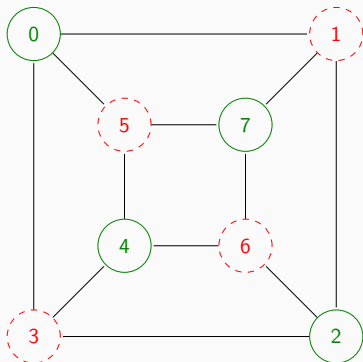
**Figure 3:** Example for graph coloring. Adjacent nodes are colored distinctly.



## Example: Maximum Independent Set ( $\mathcal{NP}$ -hard)

**Problem:** Maximum Independent Set

**Goal:** Find a maximum subset of vertices that are not adjacent.



**Figure 4:** Example for maximum independent set. Dashed edges are excluded from the set. Note that none of the vertices included are adjacent.

## Short “reminder” on what’s $\mathcal{NP}$ -hard

A problem being  $\mathcal{NP}$ -hard means

*“probably not solvable deterministically in sub-exponential time”*

→ difficult problem...

More precisely, a problem  $B$  is  $\mathcal{NP}$ -hard if you can reduce another  $\mathcal{NP}$ -hard problem  $A$  to it. Basic idea: Solve  $A$  by solving  $B$ .

Reduction:  $A \rightarrow B$  (formulate problem  $A$  as problem  $B$ , solve it, then derive knowledge from that)

# How do we model these problems?

Well, that's easy!

Using:

1. A bunch of **variables**
2. An **objective function** we want to *minimize/maximize*
3. A lot of **constraints** in the form of **inequalities**

# Component 1: Variables

Variables  $x_1, \dots, x_n$  can be defined to be constrained to:

1.  $x_i \in \mathbb{R}$
2.  $x_i \in \mathbb{Z}$  (makes it difficult)

Using a suited solver and the “program” we define, we can get the variables’ optimal values.

## Component 2: Objective function (1)

The solver is given an objective function that should be *minimized/maximized*.

Thus, the optimal value is a *variable assignment* that has minimal/maximal value.

## Component 2: Objective function (2)

How does it look like?

$$\max\{ 2x_1 + 3x_2 - 4x_3 \} \quad (1)$$

Trivial! Why not set everything to either  $\infty$  or  $-\infty$ ?

In the real world, everything is constrained.

The objective function **should** be linear.

## Component 2: Objective function (3)

What could we minimize/maximize?

Examples:

- Minimize the colors used in the coloring problem.
- Maximize the flow in the max flow problem.
- Minimize the cost in Minimum Vertex Cover.
- Maximize the cardinality of the Maximum Independent Set problem.

## Component 3: Constraints (1)

Constraints are linear inequalities of the form:

$$3x_2 - 4x_3 \leq 5 \quad (2)$$

In general with  $m$  inequalities and  $n$  variables

$$\sum_{i=1}^n a_{j,i} \cdot x_i \leq b_j, \quad j \in \{ 1, \dots, m \} \quad (3)$$

with constants  $a_{j,i} \in \mathbb{R}$ ,  $b_j \in \mathbb{R}$  and decision variables  $x_i$ .



## Component 3: Constraints (2)

What can we model using  $\leq$ -constraints?

Well, in the “easy” case (none of the variables is integral)

1.  $\geq$  by multiplying with  $-1$ .
2.  $a = b$  by splitting into  $a \leq b$  and  $a \geq b$ .

## Component 3: Constraints (3)

We can define “binary” values as follows:

$$0 \leq x \leq 1, \quad x \in \mathbb{Z} \quad (4)$$

Using binary values we can create constraints of the form  $a! = b$ .

We define  $x \in \mathcal{B} = \{ 0, 1 \}$  to indicate that  $x \in \mathbb{Z}$  and  $0 \leq x \leq 1$ .

# Putting it all together

Let's solve the Maximum Independent Set problem using a MILP:

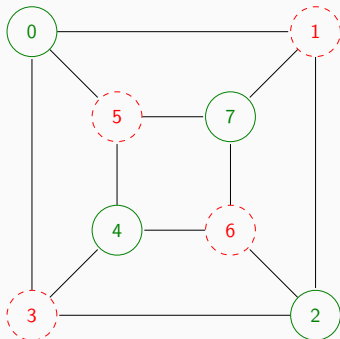
**Variables:**  $x_0, x_1, \dots, x_7 \in \mathcal{B}$

**Objective:**  $\max \left\{ \sum_{i=0}^7 x_i \right\}$

**Constraints:**

For every edge  $e = \{ i, j \}$ ,  
we create a constraint:

$$x_i + x_j \leq 1$$



# Demo (1): Maximum Independent Set

# One Ring to rule them all [...]

Let's do graph coloring (minimizing distinct colors)

**Variables:**  $x_0, \dots, x_9 \in \mathbb{Z}, x_\lambda \in \mathbb{R}$

**Objective:**  $\min\{x_\lambda\}$

**Constraints:**

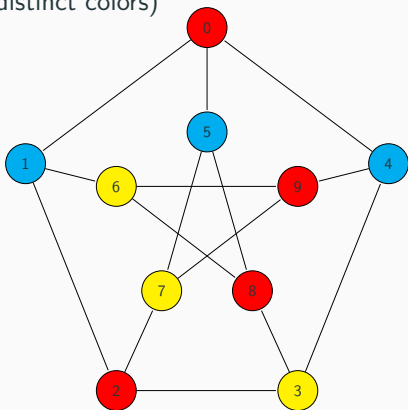
For every node  $i$ :

$$x_i \geq 0$$

$$x_i \leq x_\lambda$$

For every edge  $e = \{i, j\}$ :

$$x_i \neq x_j$$



# Demo (2): Graph coloring



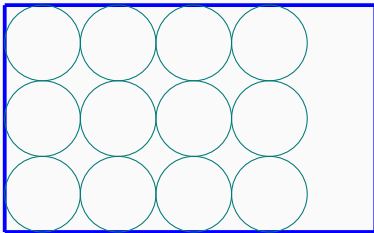
Well...

**Nope.**



# Counterexample

**Problem:** Circle packing into a rectangle.



**Figure 5:** As many circles as possible should be packed into the rectangle without the circles overlapping. Well, for that we need quadratic constraints...

We will not solve that.

**Thank you for staying.**