Verification and Validation Report: Mechatronics

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1 Revision History

Date	Version	Notes
Date 1	1.0	Notes
Date 2	1.1	Notes

2 Symbols, Abbreviations and Acronyms

symbol	description
Т	Test

[[]symbols, abbreviations or acronyms – you can reference the SRS tables if needed —SS]

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3 Functional Requirements Evaluation

Section 5 from VV Plan Hardware:

- 1. Camera Detection
- 2. Raspberry Pi

Machine Learning:

- 1. Joint Recognition
- 2. Display coordinates in space
- 3. Detecting multiple pairs of hands
- 4. Detecting multiple pairs of hands
- 5. Trainable Model

Real-time Data Processing

1. Process data in real-time

HARDWARE FUNCTIONAL REQUIREMENTS The reference for ASL alphabet is Table

	Description	Requirement Ref- Input erence	Input	Expected Output	Actual Output	Result
T1	Camera is set up on Raspberry Pi	CFR1	Raspistill command to take a picture	A picture	A picture	Pass
T2	Real-time video is captured and displayed on screen	CFR1, CFR2	Views in front of the camera	Views in front of the camera are displayed	Views in front of the camera are displayed	Pass
T3	Testing hand detection at a distance	CFR1	hand gesture for "d"	p	р	Pass
T4	Testing if different webcams or cameras impact a sentence	CFR1, CFR2	Sign the sentence "how do you do" alphabetically through 5 different cameras			Pass
T5	Testing hand detection with multiple hands	CFR3	hand gestures for "d"	р	q	Pass
9L	Testing hand detection for similar gestures	CFR1	hand gesture for "m"	m	n	Fail

Testing	Testing hand de-	CFR1	Static hand ges-	No output	p/z	Fail
tection for motion	otion		tures (no mo-			
Testing hand detection for motion	nd de- motion	CFR1	hand motion for "z"	Z	Z	Pass
Testing hand detection for hand at the edges of the camera detection area	and de- hand at of the	CFR1	hand gesture for "d"	р	þ	Pass
Mode Selection	ction	N/A	number "2" on keyboard	System goes into "Training Mode"	System goes into "Training Mode"	Pass
String display for one hand gesture		N/A	Any hand gesture except for the gesture for "Speak"	Text representing the hand gesture is displayed	Text representing the hand gesture is displayed	Pass
String display for a series of hand gestures (slow)	splay for of hand slow)	N/A	A series of hand gestures (except for "Speak") with a pause of 2 seconds	Text representing each hand gesture is displayed as a string	Text representing each hand gesture is displayed as a string	Pass

Fail	Pass	Fail (need to increase fps)
repre- Some gesture's tests Fail each are not displayed as a	"Backspace" deletes a character, "Space" adds a space	for Some letters are miss- g ing s
Text representing each hand gesture is displayed as a string	"Backspace" deletes a char- acter, "Space" adds a space	
A series of hand gestures (except senting each for "Speak") hand gesture is with a pause displayed as a of less than 2 string	Pressing "Backspace" or "Space"	A series of Letters factoring destures corresponding performed in a hand gestures very fast speed
N/A	N/A	CFR1
String display for a series of hand gestures (fast)	Modifying string N/A display	Testing hand detection for a series of hand gestures (fast)
T13	T14	T15

Table 1: HARDWARE FUNCTIONAL REQUIRE-MENTS

MACHINE LEARNING FUNCTION REQUIREMENTS

ID	Description	Requirementhput	dinput	Expected Output	Actual Output	Result
	ı	Refer-		ı		
		ence				
M1	Testing for joint		Hand Gesture	Able to recognize hidden	Able to recognize hidden	Pass
	tracking when	MLFR5,	for "m" and	joints	joints	
	hiding joints	NFR2	"n" (covering			
			thumb)			
M2	Testing for joint	MLFR1,	Hand Gesture	Able to separate differ-	Able to separate differ-	Pass
	tracking when	MLFR3,	for "S", "M",	ent hand joints from each	ent hand joints from each	
	overlapping hands	MLFR5	$\mathrm{``N''},\mathrm{``R''}$	other	other	
M3	Testing if joint	MLFR1,	Moving hand	Able to overlay joint lines	Able to overlay joint lines	Pass
	lines are properly	MLFR6,	from one side	on user's hand continually	on user's hand continually	
	aligned with the	NFR2	of the screen	and is centered on the hand	and is centered on the hand	
	user's joints and		to the other in			
	move accordingly		rapid succession			
	at the center					
M4	Testing if a joint	MLFR1,	Having a third	Unable to detect the third	Unable to detect the third	Pass
	overlay will be	MLFR3,	hand in the	hand	hand	
	placed on more	NFR2	frame after the			
	than two hands		initial two			
M5	Testing if detected	MLFR1,	Have two peo-	Detects the hand from one	Detects both the hands of	Fail
	joints are from	NFR1,	ple with one	person as opposed to two	both people	
	one individual	NFR3	hand each in			
	(the user)		the frame			

Pass
0,0,0,-0.374045802,- 0.038167939,- 0.709923664,- 0.381679389,- 0.824427481,-1,- 0.824427481,-1,- 0.541984733,- 0.65648855,-0.671755725,- 0.610687023,- 0.465648855,- 0.389312977,- 0.328244275,- 0.328244275,- 0.328244275,- 0.328244276,- 0.541984733,- 0.541984733,- 0.551908397,- 0.551908397,- 0.763358779,- 0.122137405,- 0.122137405,- 0.076335878,- 0.076
0,0,0,-0.374045802,- 0.038167939,- 0.709923664,- 0.824427481,-0.72519084,- 0.824427481,-1,- 0.541984733,- 0.65648855,-0.671755725,- 0.610687023,- 0.465648855,- 0.389312977,- 0.389312977,- 0.3885496183,- 0.72519084,-0.480916031,- 0.85496183,- 0.725190837,- 0.541984733,- 0.551908397,- 0.551908397,- 0.122137405,- 0.251908397,- 0.122137405,- 0.0763358779,- 0.0763358779,- 0.076335878,- 0.076308,- 0.076308,- 0.076308,- 0.076308,- 0.076308,- 0.076308,-
Repeatedly recording the gesture "a" at the center of the screen
MLFR2
Testing if the coordinates (x,y) of each joint is accurately recorded
M6

M7	Testing if the co-	MLFR2,	Repeatedly	6,0,0,0.121428571,-	6,0,0,0.121428571,-	Pass
	ordinates (x,y) of	MLFR3	recording the	0.232142857,0.357142857,-	0.232142857, 0.357142857,	
	each joint is accu-		gesture "F" at	0.328571429,0.578571429,-	0.328571429,0.578571429,-	
	rately recorded for		the center of	0.342857143,0.728571429,-	0.342857143,0.728571429,-	
	two handed ges-		the screen	0.357142857,0.328571429,-	0.357142857,0.328571429,-	
	tures			0.310714286,0.660714286,-	0.310714286,0.660714286,-	
				0.314285714,0.85,-	0.314285714,0.85,-	
				0.307142857,1,-	0.307142857,1,-	
				0.292857143,0.346428571,-	0.292857143,0.346428571,-	
				0.121428571,0.628571429,-	0.121428571,0.628571429,-	
				0.171428571,0.560714286,-	0.171428571,0.560714286,-	
				0.203571429,0.457142857,-	0.203571429,0.457142857,-	
				0.196428571, 0.342857143, 0.0	0.196428571,0.342857143,0.04 \@a@a@tha@a \f\d\ @a@s \f\d\a\gag	42857143,0.5
				0.039285714,0.496428571,-	0.039285714, 0.496428571,	
				0.071428571,0.403571429,-	0.071428571,0.403571429,-	
				0.064285714,0.339285714,0.	0.064285714,0.339285714,0.175,06 328578 471,33 9285714 39,174506242885	745005042887
M8	Testing if ges-		Signing"j" and j z	z j	jz	Pass
	tures that require	MLFR6	"Z"			
	movement are					
	able to be rec-					
	ognized (motion					
	gestures)					

M9	Test if TTS string creation speed can	MLFR6, MLFR4	Signing letters in sequence at	a b c d e f g	a b c d e f g	Pass
	keep up with sign-	NFR1	one gesture per			
	ing speed at one		second			
	gesture per second					
M10	Test if a .tflite file	MLFR5,	A CSV file with	A .tflite file that can be	A tflite file that can be	Pass
	can be generated	NFR5	data points	used to recognize the ges-	used to recognize the ges-	
	from the CSV files		from different	tures that were recorded	tures that were recorded	
			ASL gestures			
M11	Testing if retrain-	MLFR7,	Adding 50 accu-	The accuracy prediction	The accuracy prediction	Pass
	ing by adding new	NFR1,	rate data points	increases	decrease from 60% to 80%	
	data points can	NFR5	to the gesture			
	change recogni-		"Hello"			
	tion					
M12	Test model	model MLFR4,	Sign letters	letters a,b,c,d d,f,z,j with 100% a,b,c,d d,f,z,j	a,b,c,d d,f,z,j	Pass
	accuracy by	NFR1	in sequence of	accuracy		
	signing differ-		a,b,c,d then			
	ent sequences of		sign with d, f,			
	gestures / intro-		z, j			
	ducing variance					
	into the system					

M13	Testing	for ges-	MLFR7,	Retraining the	Hello	Hello	Pass
	ture	variation	NFR1,	model with			
	based	on user	NFR3,	a different			
	habits	habits through	NFR7	method of			
	retraining	1g		signing "Hello"			

Table 2: MACHINE LEARNING FUNCTION RE-QUIREMENTS

Real-time Data Processing

ID	Description	Requirementuput	dinput	Expected Output	Actual Output	Result
		Keier- ence				
	test process data in real-time	RDP1	hand gestures for "d" and "a"	Output the corresponding letters "da" right after the hand gestures	Letters "da" were detected and displayed right after the hand gestures	Pass
	Testing if the relative coordinates (x,y) is written to the CSV file	RDP1, NFR5	Hand gesture for "a"	Coordinates with identifier "0" (identifier for the letter "a") are written to the CSV file	Coordinates with identifier "0" were written to the CSV file	Pass
	Testing if the point history coordinates (x,y) is written to the CSV file	RDP1, NFR5	Hand gesture for "j"	Multiple coordinates with identifier "9" (identifier for the letter "j") are written to the CSV file	Multiple coordinates with identifier "9" get written to the CSV file	Pass
	Text to Speech	RDP2	Hand gesture for "Speak"	Current string is read out and then cleared	Current string is read out and then cleared	Pass
	Text-to-speech in real-time for individual letters	RDP2	Hand gestures for "a", "b" and "c"	Audio output for letters "a", "b" and "c"	Audio output for letters "a", "b" and "c"	Pass
	Text-to-speech in real-time for sentence	RDP2	hand gesture for "I love you"	Audio output for "I love you"	Audio output for "I love you"	Pass

2	Switching from N/A	rom	N/A	Pressing either	The interface no longer	The interface no longer	Pass
	translating mode	ode		2 or 3	tries to record hand motion	tries to record hand motion	
	to retraining	ning					
	mode stop de-	de-					
	tecting h	hand					
	gestures						

Table 3: Real-time Data Processing

4 Nonfunctional Requirements Evaluation

accuracy, usability, portability, cultural

ID	Description	Requirementuput	admput	Expected Output	Actual Output	Result
		Refer-				
		ence				
1	Test if GUI is dis-	N/A	Program is	The resolution, FPS,	The resolution, FPS,	Pass
	played on screen		started and	mode, and current text are	mode, and current text are	
			camera is	displayed on screen	displayed on screen	
			turned on			
2	Test if gestures	N/A	Program is	Nothing is being added to	Nothing is being added to Nothing is added to the	Pass
	are not written		started, in	the string	string	
	to string when in		training mode,			
	training mode		and gestures			
			are being per-			
			formed			
3	Test if output is	NFR7	Trying three	Hello	Hello	Pass
	accurate for varia-		variations of			
	tions in user ges-		"Hello"			
	tures					
4	Usability: the		Instructions	The user should know how	The user is able to use	Pass
	ease of use of a		and example	to use the ASL device	the ASL device and input	
	user without the		hand gestures	and can input some sam-	some sample ASL words af-	
	knowledge of ASL		are provided to	ple ASL words after read-	ter reading the instructions	
			the user	ing the instructions		

ഹ	Test if the Rasp-	Program is	is The Raspberry Pi should The Raspberry Pi camera	The Raspberry Pi camera	Fail
	berry Pi can cap-	started on the	started on the be able to use the cam- does not display the video	does not display the video	
	ture and translate	Raspberry Pi	era to detect and translate	with an adequate frame	
	ASL in real time		ASL in real time	rate, making translation	
				undoable	

Table 4: accuracy, usability, portability, cultural

- 4.1 Usability
- 4.2 Performance
- 4.3 etc.
- 5 Comparison to Existing Implementation

This section will not be appropriate for every project.

- 6 Unit Testing
- 7 Changes Due to Testing

[This section should highlight how feedback from the users and from the supervisor (when one exists) shaped the final product. In particular the feedback from the Rev 0 demo to the supervisor (or to potential users) should be highlighted. —SS]

- 8 Automated Testing
- 9 Trace to Requirements
- 10 Trace to Modules
- 11 Code Coverage Metrics

Appendix — Reflection

The information in this section will be used to evaluate the team members on the graduate attribute of Reflection. Please answer the following question:

1. In what ways was the Verification and Validation (VnV) Plan different from the activities that were actually conducted for VnV? If there were differences, what changes required the modification in the plan? Why did these changes occur? Would you be able to anticipate these changes in future projects? If there weren't any differences, how was your team able to clearly predict a feasible amount of effort and the right tasks needed to build the evidence that demonstrates the required quality? (It is expected that most teams will have had to deviate from their original VnV Plan.)