



University  
of Glasgow

# EARTH4072 – Igneous Geology

Introduction to Computational Geosciences

WKSHP 4 | Introduction to Comp Modelling II

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@maggmatters

**WORLD  
CHANGING  
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# Intro Comp Geosci | Programme

Week	WKSHP I	WKSHP II	WKSHP III	WKSHP IV
20/10/2020	First Steps Coding	Comp Data Analysis	Comp Modelling I	Comp Modelling II

# Comp GeoSci | Intended Learning Outcomes

## Introduction to Computational Modelling II

- understand why and how scientist use modelling
- understand role of conceptual, analytical, numerical models
- understand model dimensionality (0-D, 1-D, 2-D, 3-D)
- understand the fundamentals of discretisation
- understand the fundamentals of numerical stability
- program and use a 1-D box model of crustal heat transport

```
% update constitutive relations
txx = eta .* exx + chi .* txxo;      % x-normal stress
tzz = eta .* ezz + chi .* tzzo;      % z-normal stress
txz = etac.* exz + chic.* txzo;      % xz-shear stress

p    = - zeta .* Div_V + xi .* po;    % compaction pressure
p([1 end],:) = p([end-1 2],:);       % periodic boundaries
p(:, [1 end]) = p(:, [end-1 2]);

w    = - (K(1:end-1,:).*K(2:end,:)).^0.5 .* (diff(P,1,1)./h + 1);
w(:, [1 end]) = w(:, [end-1 2]);

u    = - (K(:,1:end-1).*K(:,2:end)).^0.5 .* (diff(P,1,2)./h);
u([1 end],:) = u([end-1 2],:);

% update z-reference velocity
Div_tz = diff(tzz(:,2:end-1),1,1)./h + diff(txz,1,2)./h;

res_W(:,2:end-1) = - Div_tz + diff(P(:,2:end-1),1,1)./h + diff(p(:,2:end-1),1,1);

res_W([1 end],:) = [sum(res_W([1 end],:),1)./2;sum(res_W([1 end],:),2)];
res_W(:, [1 end]) = res_W(:, [end-1 2]);

W = Wi - alpha.*res_W.*dtW + beta.*(Wi-Wii);

% update x-reference velocity
Div_tx = diff(txx(2:end-1,:),1,2)./h + diff(txz,1,1)./h;

res_U(2:end-1,:) = - Div_tx + diff(P(2:end-1,:),1,2)./h + diff(p(2:end-1,:),1,1);

res_U([1 end],:) = res_U([end-1 2],:);
res_U(:, [1 end]) = [sum(res_U(:, [1 end]),2)./2,sum(res_U(:, [1 end]),1)];

U = Ui - alpha.*res_U.*dtU + beta.*(Ui-Uii);

% update reference pressure
Div_V(2:end-1,2:end-1) = diff(U(2:end-1,:),1,2)./h + diff(W(:,2:end-1),1,1);
Div_v(2:end-1,2:end-1) = diff(u(2:end-1,:),1,2)./h + diff(w(:,2:end-1),1,1);

res_P = Div_V + Div_v;

res_P([1,end],:) = res_P([end-1,2],:);
res_P(:, [1,end]) = res_P(:, [end-1,2]);

P = Pi - alpha.*res_P.*dtP + beta.*(Pi-Pii);

% update liquid evolution equation (enforce min/max limits on f)
flxdiv_fromm; % upwind-biased advection/compaction term for liquid

res_f = (f-fo)./dt - (theta.*Div_fV + (1-theta).*(Div_fVo));

res_f([1,end],:) = res_f([end-1,2],:);
res_f(:, [1,end]) = res_f(:, [end-1,2]);

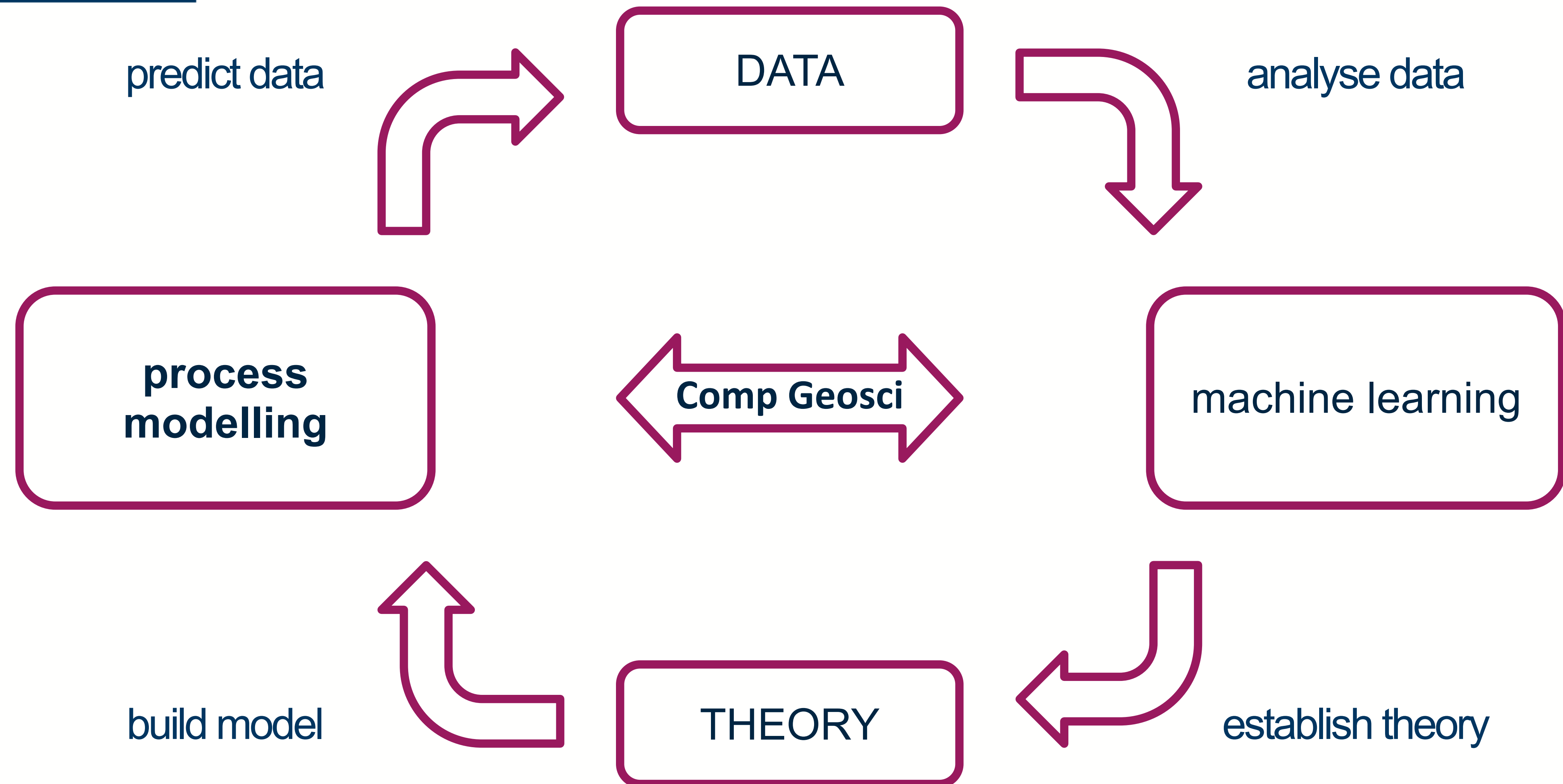
if ~mod(step,nup); res_f = res_f - mean(res_f(:)); end

f = fi - alpha.*res_f.*dt/50;
f = max(0.001/f0,min(0.999/f0, f));

% check and report convergence every nup iterations
if ~mod(it,nup); report; end
```



# Comp Modelling | Basics





# Comp Modelling | Basics

## Definition

*A simplified representation of a natural process or system aimed at interpreting, understanding, and predicting data.*

## “Universal Law” of Modelling

*All models are wrong – some are useful.*



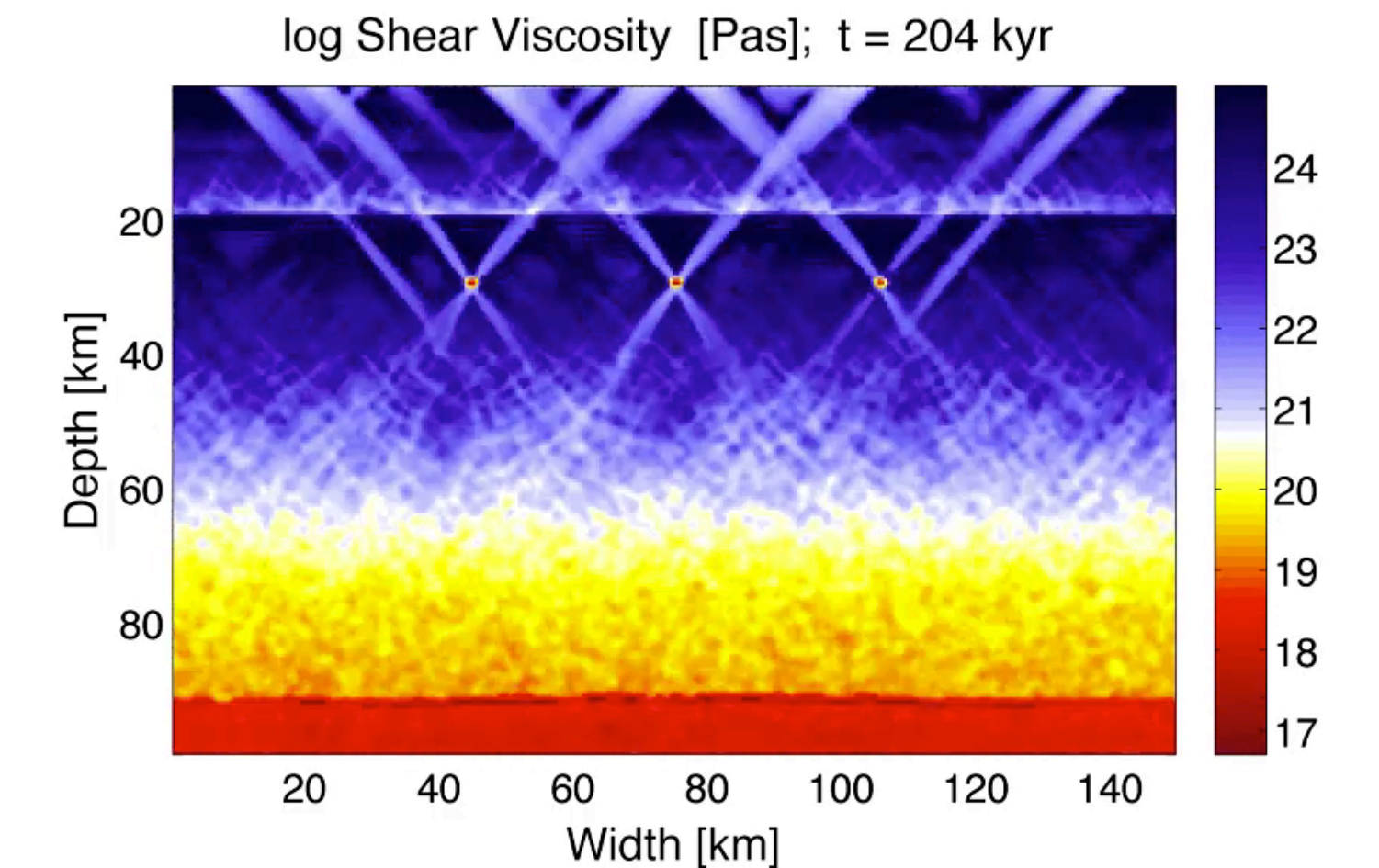
# Comp Modelling | Example Application

## Magma Intrusion into Crust

- hot magma rises into cool crust
- magma-filled tensile fractures: dyke
- heat transfer from magma to crust



[en.wikipedia.org/wiki/Dike\\_\(geology\)](https://en.wikipedia.org/wiki/Dike_(geology))

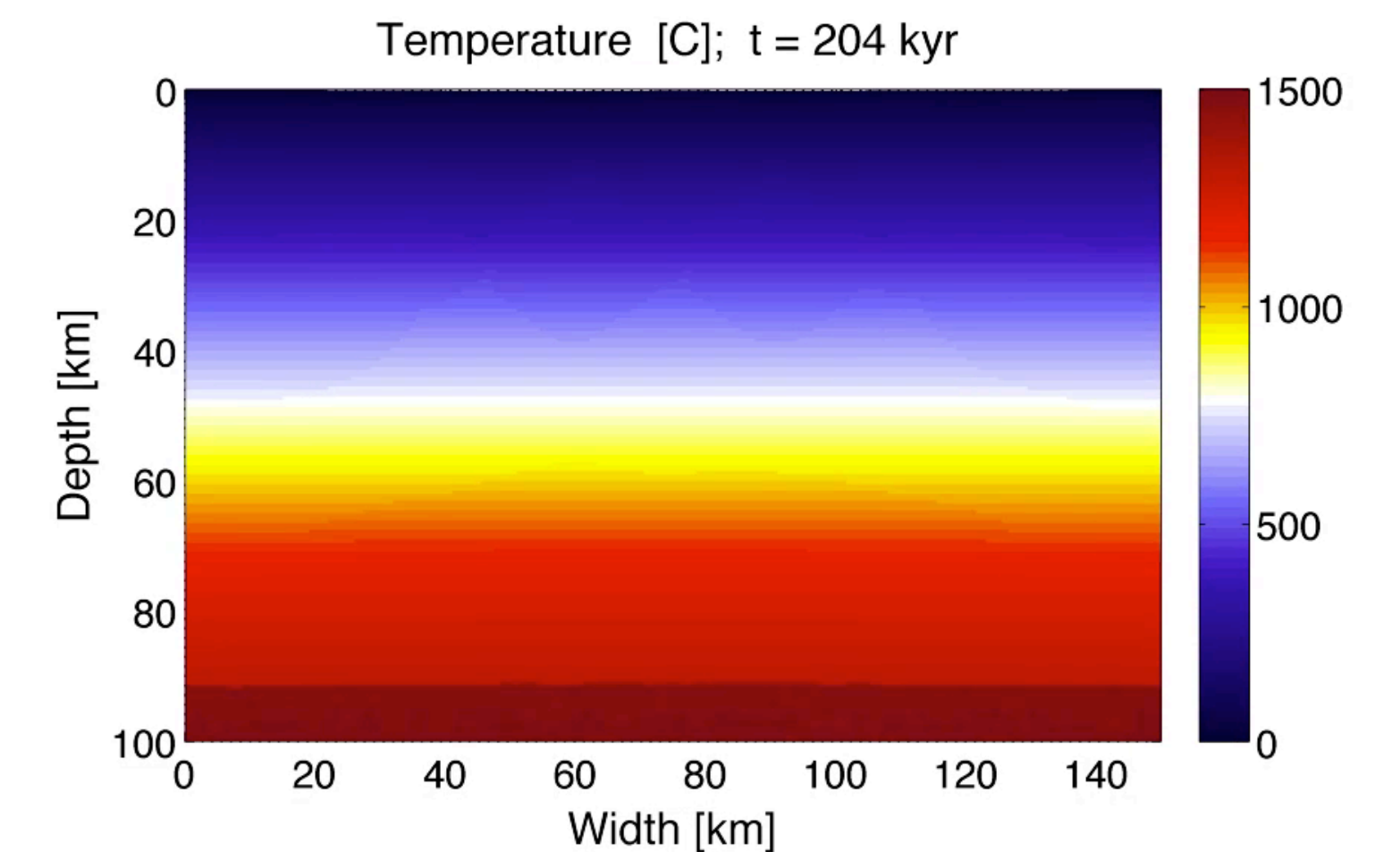
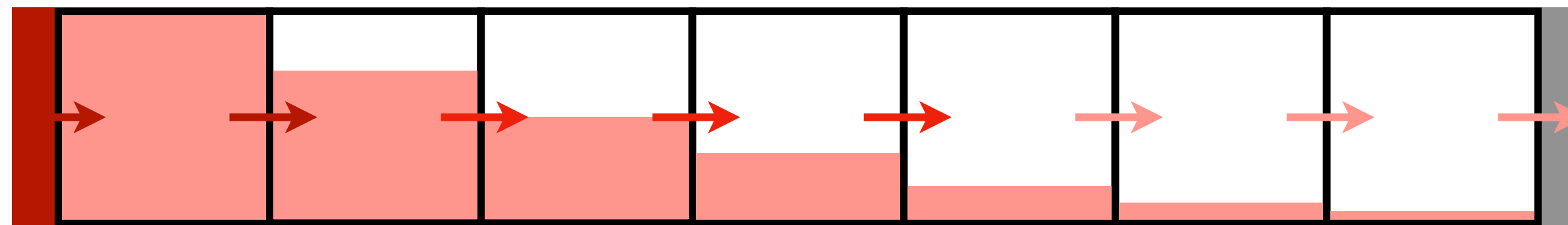


## Conceptual Model

hot intrusion

heat diffusion

cool crust



*2-D model of magma ascent, heat transfer*

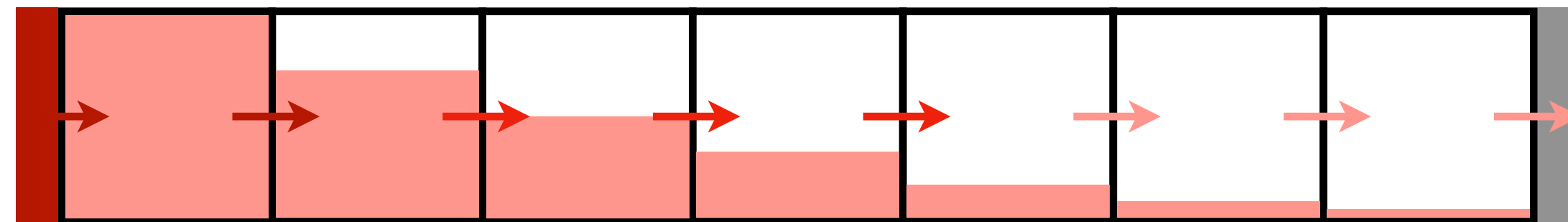
# Comp Modelling | Model to Solution

## Dimensionality

- decide how many spatial dimensions and/or time to represent model in
- 1-dimensional model, time-dependence, one spatial dimension

### Intrusive Contact Heating Model

hot intrusion      heat diffusion      cool crust



crustal layer as row of 'storage heaters'

*change in temperature  
through time*

$$\frac{\partial T(t, x)}{\partial t} = - \frac{\partial q(x)}{\partial x}$$

***how to describe  
heat flux?***

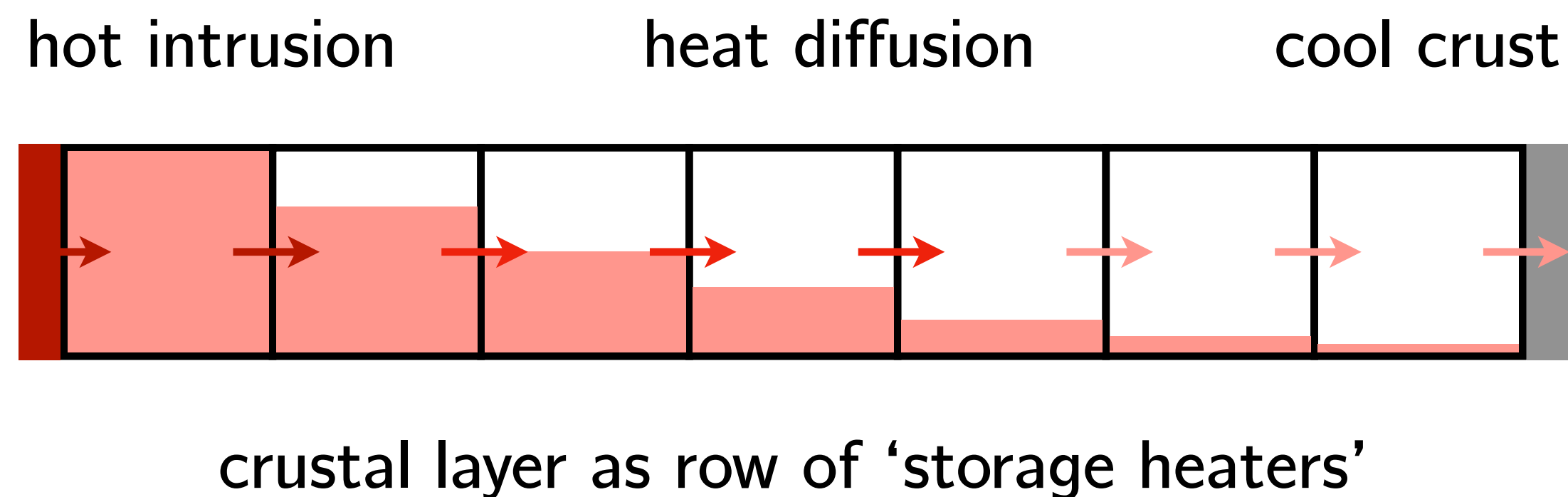


# Comp Modelling | Model to Solution

## Constitutive Relations

- relating fluxes to driving forces: use empirical law or derive from theory
- general constitutive relation: *flux = driving force x material resistance*
- Fourier's Law: heat flows from high to low  $T$ , resisted by thermal diffusivity,  $K$

### Intrusive Contact Heating Model



### **Fourier's Law of heat transfer**

$$q(x) = -K \frac{\partial T(x)}{\partial x}$$

flux

material resistance

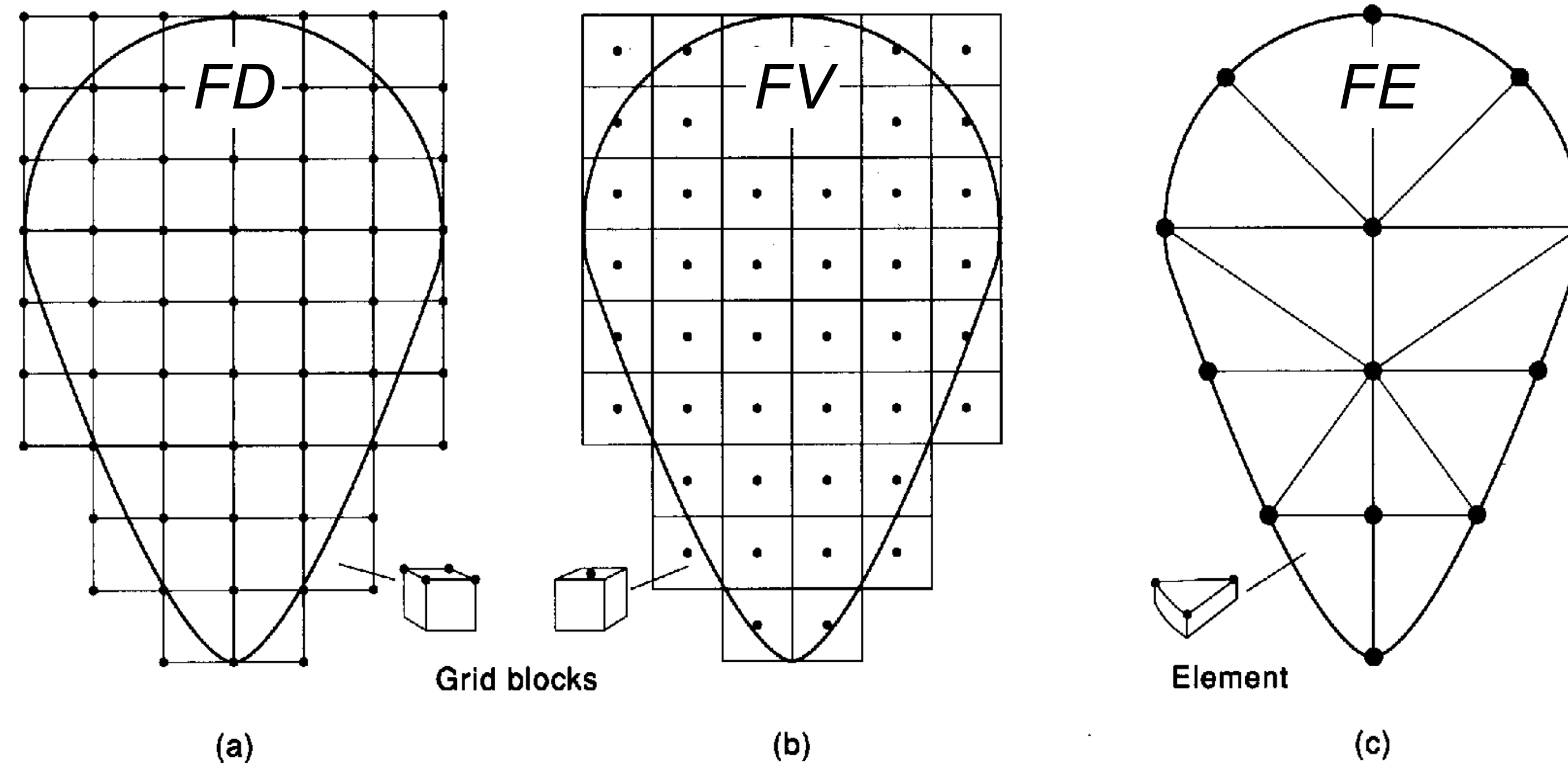
driving force



# Comp Modelling | Model to Solution

## Spatial Discretisation

- different discretisation schemes, ways to divide space into cells, elements, etc.
- most common schemes: finite difference (FD), finite volume (FV), finite element (FE)



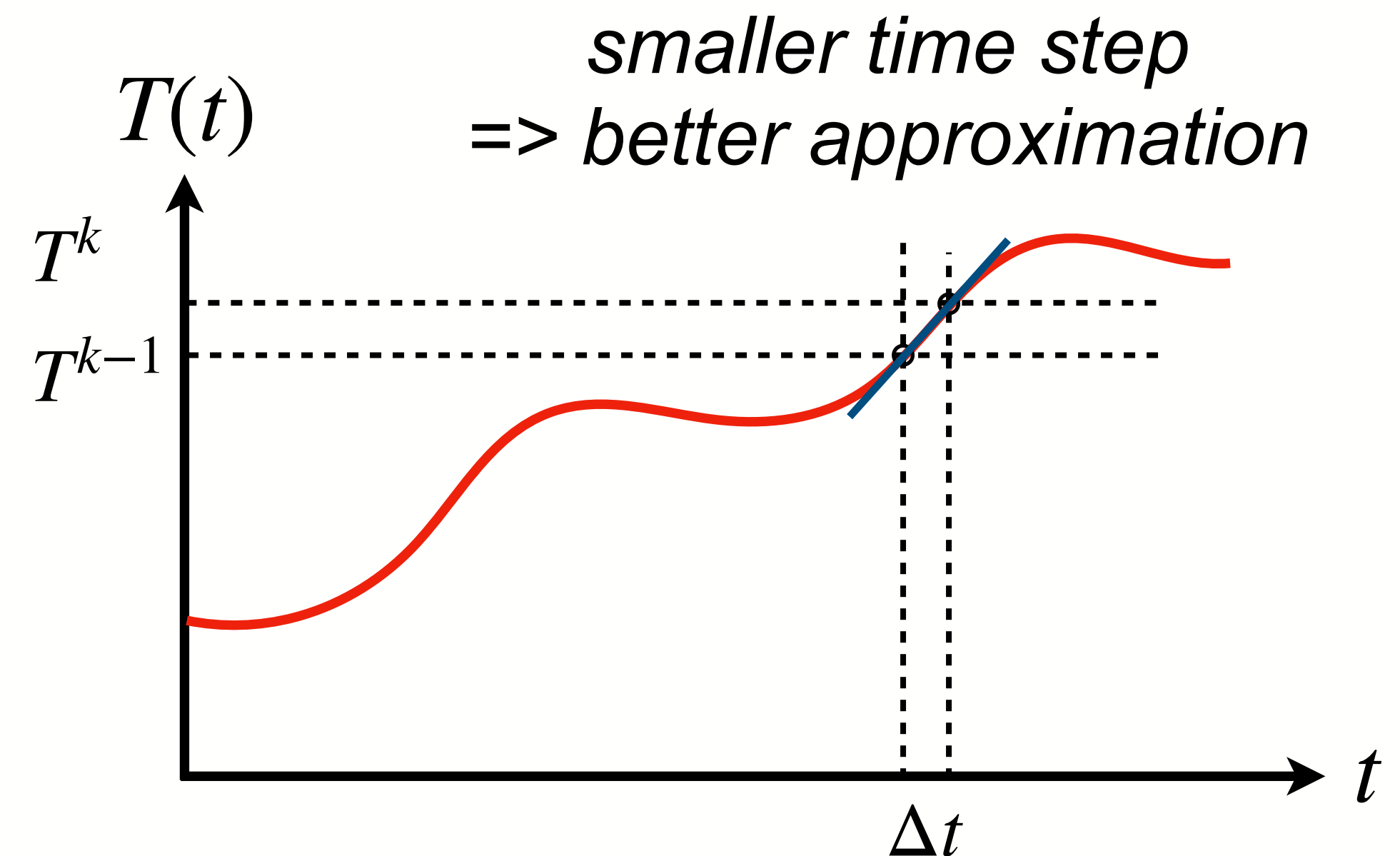
# Comp Modelling | Model to Solution

## Temporal Discretisation (1-D layer model)

- approximate continuous rate of change as discrete steps of change
- approximate *infinitesimal derivative* by *finite difference*

*finite difference approximation*

$$\frac{T^k - T^{k-1}}{\Delta t} \approx \frac{\partial T}{\partial t} \text{ for } \Delta t \rightarrow 0$$





# Comp Modelling | Model to Solution

## Discretisation: 1-D FV heat transfer model

- cell centre coordinates:  $x^i$  ( $i = 1, \dots, n$ ); cell face coordinates:  $x^{i\pm 1/2} = (x^i + x^{i\pm 1})/2$
- discrete temperatures:  $T^{i,k} = T(x = x^i, t = t^k)$ , located at cell centres
- discrete heat fluxes:  $q^{i\pm 1/2} = q(x = x^{i\pm 1/2})$

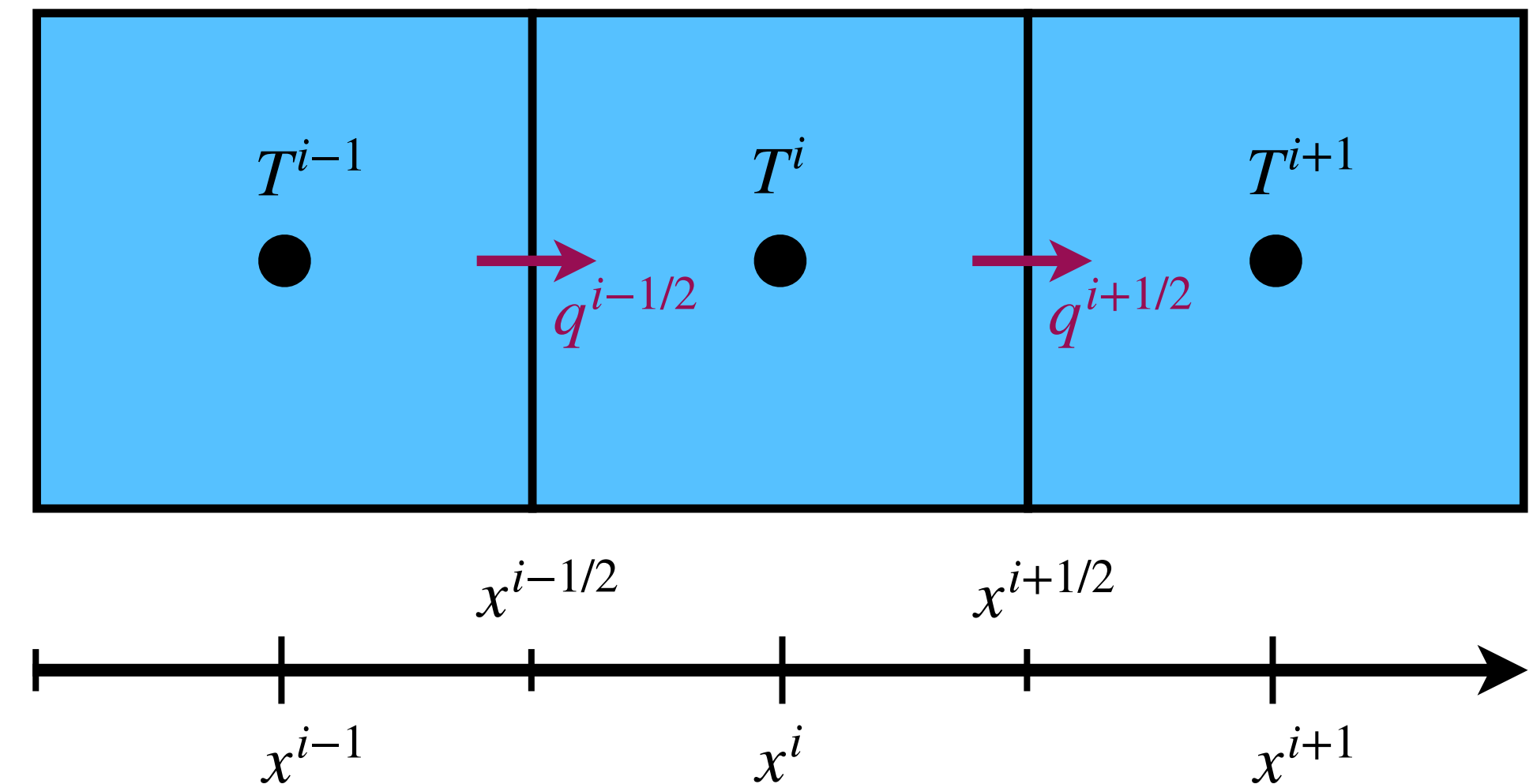
*finite difference  
approximation*

$$\frac{T^{i,k} - T^{i,k-1}}{\Delta t} = - \frac{q^{i+1/2} - q^{i-1/2}}{\Delta x}$$

$$q^{i+1/2} = -K \frac{T^{i+1,k-1} - T^{i,k-1}}{\Delta x}$$

$$q^{i-1/2} = -K \frac{T^{i,k-1} - T^{i-1,k-1}}{\Delta x}$$

*FV stencil*



# Comp Modelling | Model to Solution

## Discretisation: 1-D FV heat transfer model, variable parameter

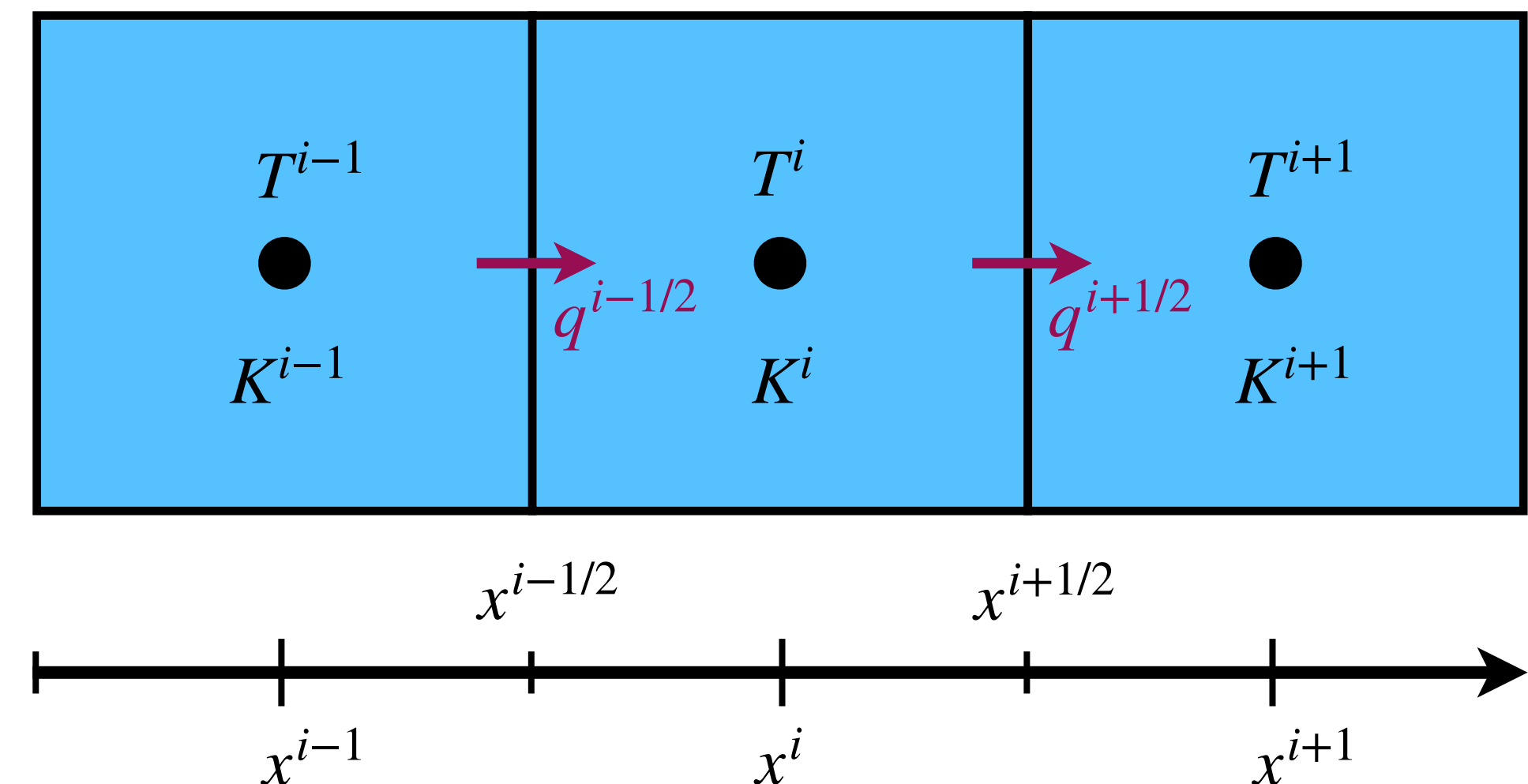
- discrete diffusivities:  $K^i = K(x = i^k)$ , located at cell centres
- discrete heat fluxes:  $q^{i\pm 1/2} = q(x = x^{i\pm 1/2})$ , located on cell faces

*finite difference  
approximation*

$$q^{i+1/2} = -\frac{(K^i + K^{i+1})}{2} \frac{T^{i+1,k-1} - T^{i,k-1}}{\Delta x}$$

$$q^{i-1/2} = -\frac{(K^i + K^{i-1})}{2} \frac{T^{i,k-1} - T^{i-1,k-1}}{\Delta x}$$

*FV stencil*





# Comp Modelling | Model to Solution

## Numerical Stability

- rate of change depends on flux, which depends on spatial gradient, which depends on rate of change: *feedback loop can run out of control!*
- stable time step: limit diffusive flux advance to half grid cell per time step

*diffusivity*

$K$  [m<sup>2</sup>/s]

*limit distance*

$\Delta x/2$  [m]

*limit time step?*

# Comp Modelling | Model to Solution

## Numerical Stability

- rate of change depends on flux, which depends on spatial gradient, which depends on rate of change: *feedback loop can run out of control!*
- stable time step: limit diffusive flux advance to half grid cell per time step

*diffusivity*

$$K \text{ [m}^2\text{/s]}$$

*limit distance*

$$\Delta x/2 \text{ [m]}$$

*limit time step*

$$\Delta t \leq \frac{(\Delta x/2)^2}{K} \text{ [s]}$$

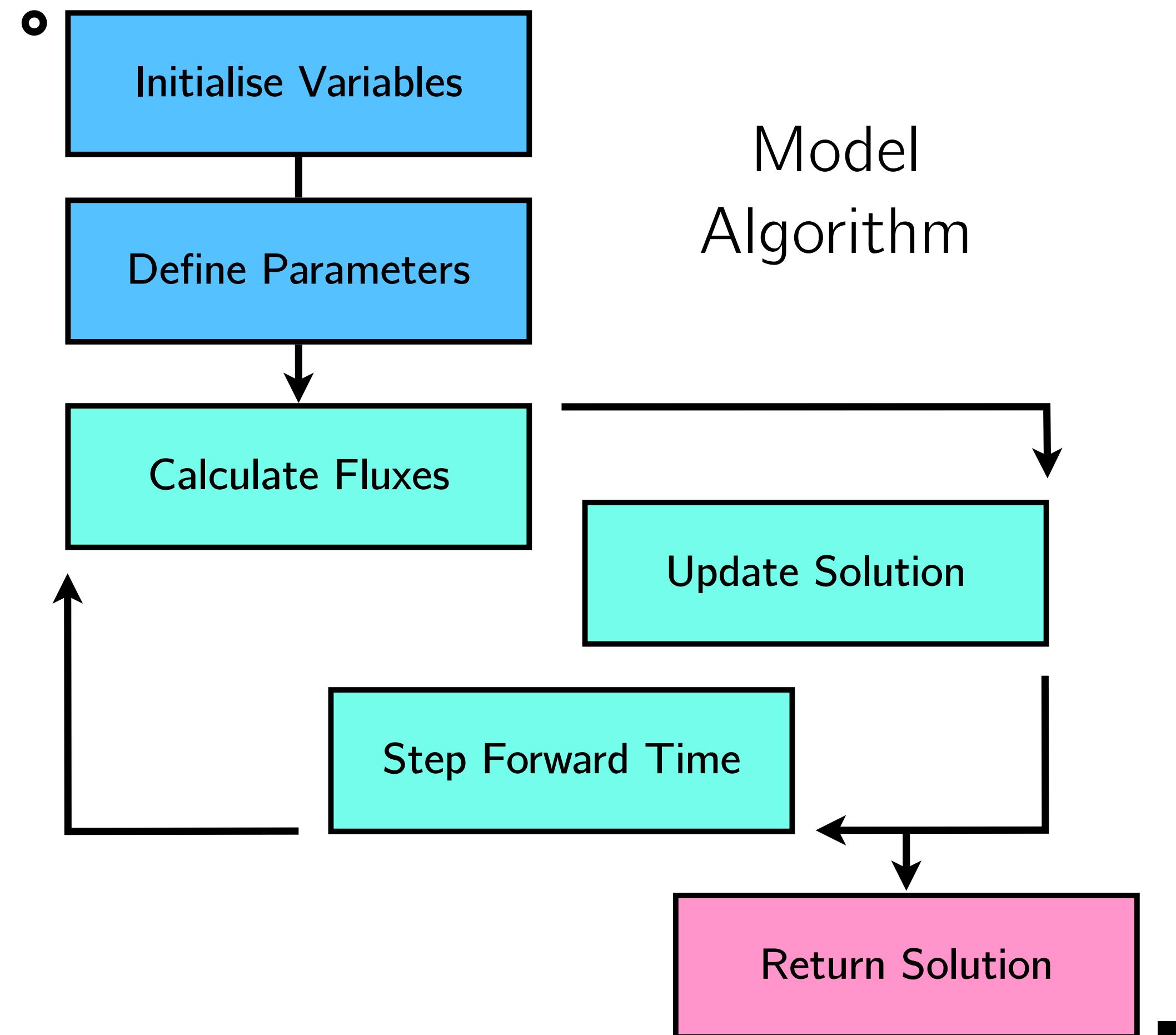




# Comp Modelling | Model to Solution

## Numerical Implementation

- program algorithm to calculate solution step by step
- check if solution is robust, no numerical artefacts
- verify code to ensure accurate numerical solution



# Comp Modelling | Model Benchmarking

## Once programming is complete...

- test if the algorithm is programmed correctly
- most of model development spent debugging!
- frequent bugs: spelling or capitalisation, numbering or indexing, mistaken +/- signs, logic sequence

## Convergence testing

- test if reduction of grid and time step size improves solution
- for simple test problems analytical (exact) solutions available
- residuals (diff. numerical to analytical solution) should reduce for  $\Delta x \rightarrow 0$ ;  $\Delta t \rightarrow 0$ .  
=> numerical solution *converges* to analytical solution.
- if no exact solution known (often the case!) test if solution converges towards the highest achievable numerical resolution
- ***Always benchmark a new code or new version of existing code!***



# Comp Modelling | Model Documentation

## A model is useless without thorough documentation

- document steps from conceptual to mathematical model
- document steps from continuous to discrete model representation
- document structure and usage of code (e.g., readme file)

## Best practice for shareable, intelligible code

- use notebook format to integrate documentation with code!
- use commenting to describe every block, line of code!
- use descriptive naming convention for notebook or code files, functions, variables, parameters, etc.
- ***Highest standard is to write fully documented, open-source, reproducible code!***

# WKSHP IV | Intro to Comp Modelling II

## Activity | Introduction to Numerical Modelling with Python

### Build 1-D model of intrusive contact heating

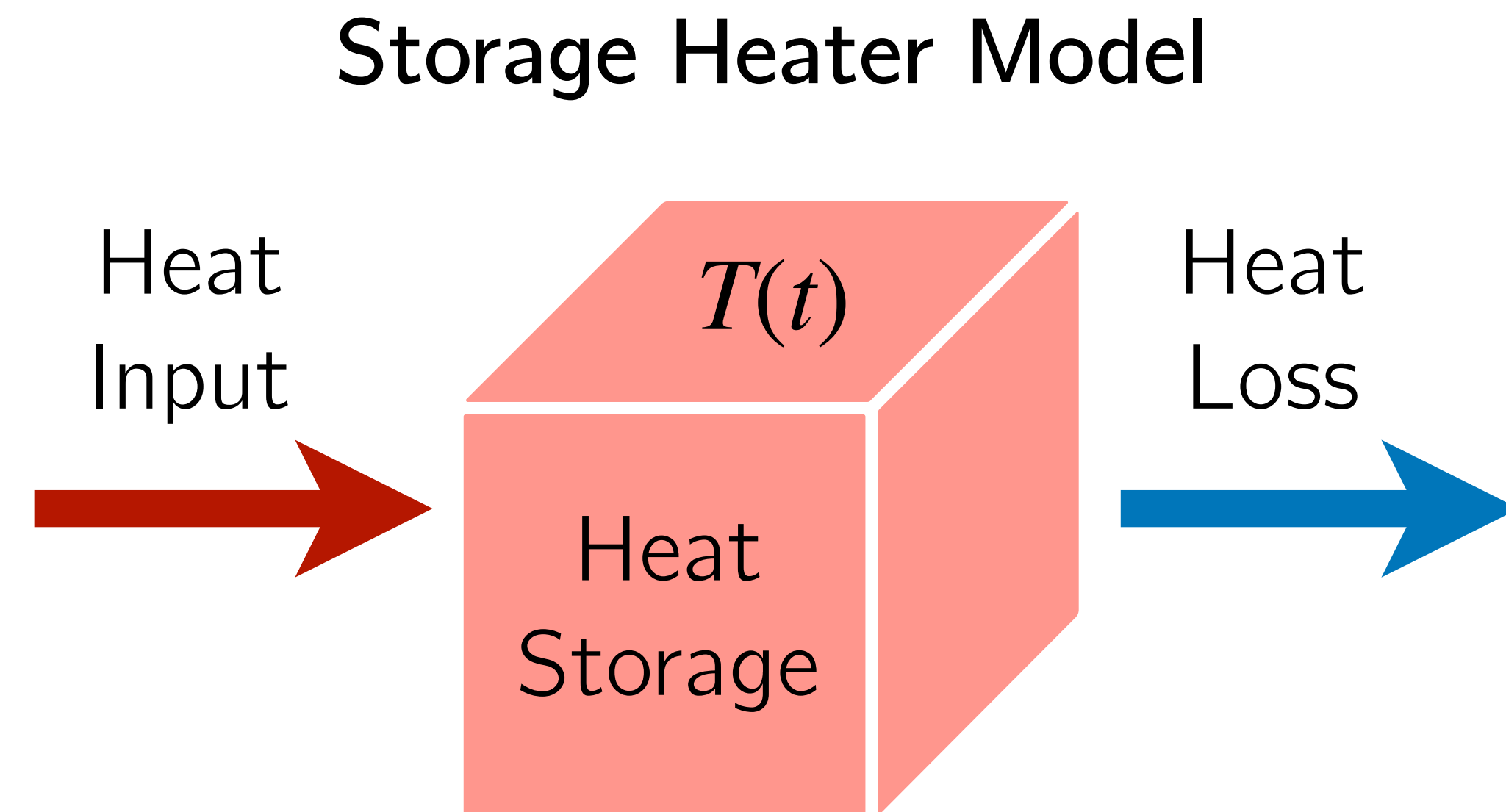
- hot magma intrusion heats crustal wall rock
- simplified representation as row of storage heaters
- heat input vs. heat output rate

### Consolidate basic numerical modelling

- complete prepared model code
- build in stable time step size
- test different initial conditions

### Padlet task

- create new notebook, compose/document intrusive contact heating model from scratch, in your own code/words, post snapshot to Padlet



Ambient  $T_0$