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Norwegian University of Science and Technology

Fenchel Duality Theory and a Primal-Dual Algorithm on Riemannian Manifolds

Ronny Bergmann

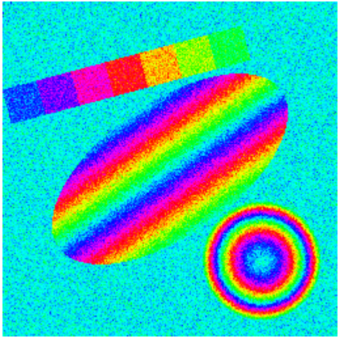
joint work with
R. Herzog, M. Silva Louzeiro, D. Tenbrinck, J. Vidal-Núñez.

IMADA Seminar, SDU, June 2nd, 2022

Manifold-valued Signal & Image Processing

Tasks in image processing is phrased as an optimisation problem.
Here. The pixel take values on a manifold

- phase-valued data ($\mathbb{S}^1$)
- wind-fields, GPS ($\mathbb{S}^2$)
- DT-MRI ($\mathcal{P}(3)$)
- EBSD, (grain) orientations ($\mathrm{SO}(n)$)



Artificial noisy phase-valued data.

Tasks. Denoising, Inpainting, labeling (classification), deblurring,...

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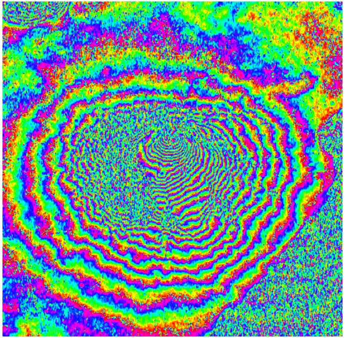

InSAR-Data of Mt. Vesuvius.
[Rocca, Prati, and Guarnieri 1997]

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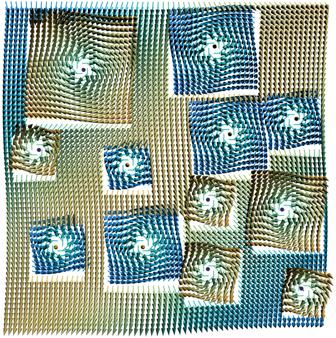

Artificial noisy data on the sphere $\mathbb{S}^2$.

Tasks. Denoising, Inpainting, labeling (classification), deblurring,...

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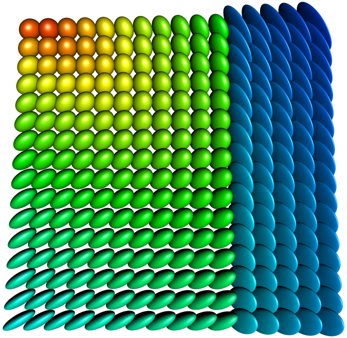

Artificial diffusion data,
each pixel is a symmetric positive matrix.

Tasks. Denoising, Inpainting, labeling (classification), deblurring,...

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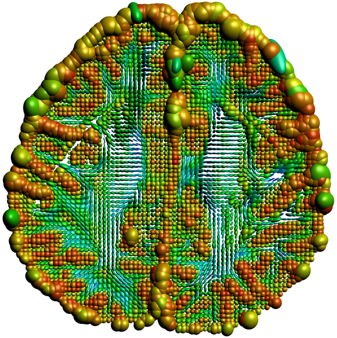

DT-MRI of the human brain.
Camino Profject: cmic.cs.ucl.ac.uk/camino

Tasks. Denoising, Inpainting, labeling (classification), deblurring,...

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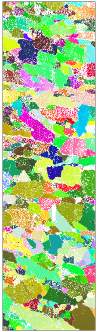


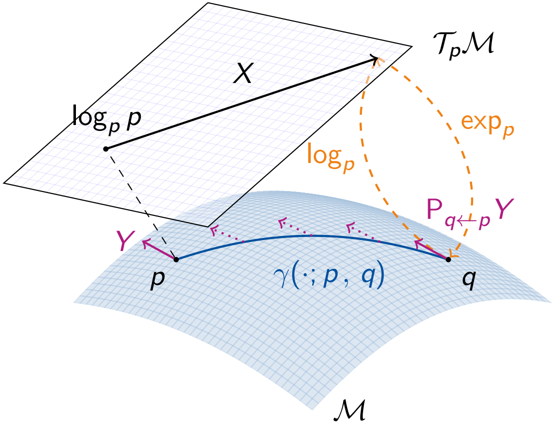
Grain orientations in EBSD data.
MTEX toolbox: mtex-toolbox.github.io

Tasks. Denoising, Inpainting, labeling (classification), deblurring,...

A d-dimensional Riemannian manifold $\mathcal{M}$

Notation.

- Geodesic $\gamma(\cdot; p, q)$
- Tangent space $\mathcal{T}_p\mathcal{M}$
- inner product $(\cdot, \cdot)_p$
- Logarithmic map $\log_p q = \dot\gamma(0; p, q)$
- Exponential map $\exp_p X = \gamma_{p,X}(1)$ where $\gamma_{p,X}(0) = p$ and $\dot\gamma_{p,X}(0) = X$
- Parallel transport $\mathrm{P}_{q\leftarrow p} Y$ “move” tangent vectors from $\mathcal{T}_p\mathcal{M}$ to $\mathcal{T}_q\mathcal{M}$



The Model

We consider a minimization problem

$$\operatorname*{arg\,min}_{p\in\mathcal{C}} F(p) + G(\Lambda(p))$$

- $\mathcal{M},\mathcal{N}$ are (high-dimensional) Riemannian Manifolds
- $F\colon \mathcal{M} \to \overline{\mathbb{R}}$ nonsmooth, (locally, geodesically) convex
- $G\colon \mathcal{N} \to \overline{\mathbb{R}}$ nonsmooth, (locally) convex
- $\Lambda\colon \mathcal{M} \to \mathcal{N}$ nonlinear
- $\mathcal{C} \subset \mathcal{M}$ strongly geodesically convex.

In image processing.
choose a model, such that finding a minimizer yields the reconstruction

Splitting Methods & Algorithms

On a Riemannian manifold $\mathcal{M}$ we have

- Cyclic Proximal Point Algorithm (CPPA) [Bačák 2014]
- (parallel) Douglas–Rachford Algorithm (PDRA) [RB, Persch, and Steidl 2016]

On $\mathbb{R}^n$ PDRA is known to be equivalent to [Setzer 2011; O'Connor and Vandenberghe 2018]

- Primal-Dual Hybrid Gradient Algorithm (PDHGA) [Esser, Zhang, and Chan 2010]
- Chambolle-Pock Algorithm (CPA) [Chambolle and Pock 2011; Pock, Cremers, Bischof, and Chambolle 2009]

But on a Riemannian manifold $\mathcal{M}$: ⚠ no duality theory!

Goals of this talk.
Formulate Duality on a Manifold
Derive a Riemannian Chambolle–Pock Algorithm (RCPA)

Musical Isomorphisms

[Lee 2003]

The dual space $\mathcal{T}_p^*\mathcal{M}$ of a tangent space $\mathcal{T}_p\mathcal{M}$ is called cotangent space.
We denote by $\langle\cdot\,,\cdot\rangle$ the duality pairing.

We define the musical isomorphisms

- $\flat\colon \mathcal{T}_p\mathcal{M} \ni X \mapsto X^\flat \in \mathcal{T}_p^*\mathcal{M}$ via $\langle X^\flat\,, Y\rangle = (X, Y)_p$ for all $Y \in \mathcal{T}_p\mathcal{M}$
- $\sharp\colon \mathcal{T}_p^*\mathcal{M} \ni \xi \mapsto \xi^\sharp \in \mathcal{T}_p\mathcal{M}$ via $(\xi^\sharp, Y)_p = \langle\xi\,, Y\rangle$ for all $Y \in \mathcal{T}_p\mathcal{M}$.

which introduces an inner product and parallel transport on/between $\mathcal{T}_p^*\mathcal{M}$

(Geodesic) Convexity

[Sakai 1996; Udriște 1994]

A set $\mathcal{C} \subset \mathcal{M}$ is called (strongly geodesically) convex
if for all $p, q \in \mathcal{C}$ the geodesic $\gamma(\cdot; p, q)$ is unique and lies in $\mathcal{C}$.

A function $F\colon \mathcal{C} \to \overline{\mathbb{R}}$ is called (geodesically) convex
if for all $p, q \in \mathcal{C}$ the composition $F(\gamma(t; p, q)), t \in [0, 1]$, is convex.

The Subdifferential

The subdifferential of F at $p \in \mathcal{C}$ is given by [Lee 2003; Udriște 1994]

$$\partial_{\mathcal{M}} F(p) := \bigl\{\xi \in \mathcal{T}_p^*\mathcal{M} \bigm| F(q) \geq F(p) + \langle \xi \,, \log_p q\rangle \quad \text{for } q \in \mathcal{C}\bigr\},$$

where

- $\mathcal{T}_p^*\mathcal{M}$ is the dual space of $\mathcal{T}_p\mathcal{M}$,
- $\langle\cdot\,,\cdot\rangle$ denotes the duality pairing on $\mathcal{T}_p^*\mathcal{M} \times \mathcal{T}_p\mathcal{M}$

The Euclidean Fenchel Conjugate

Let $f\colon \mathbb{R}^n \to \overline{\mathbb{R}}$ be proper and convex.
We define the Fenchel conjugate $f^*\colon \mathbb{R}^n \to \overline{\mathbb{R}}$ of f by

$$f^*(\xi) := \sup_{x\in\mathbb{R}^n} \langle \xi, x\rangle - f(x) = \sup_{x\in\mathbb{R}^n} \begin{pmatrix} \xi \\ -1 \end{pmatrix}^{\mathsf{T}} \begin{pmatrix} x \\ f(x) \end{pmatrix}$$

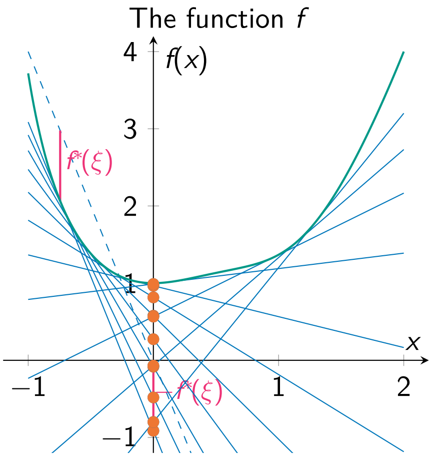
- interpretation: maximize the distance of $\xi^{\mathsf{T}} x$ to f

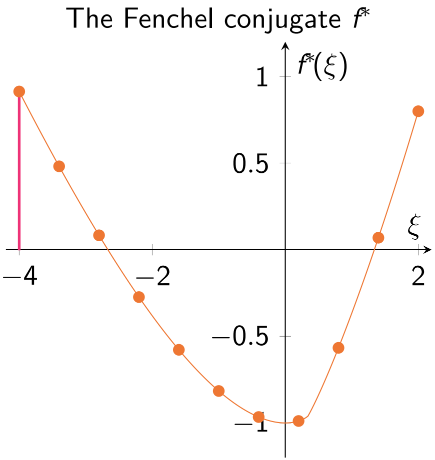
$\Rightarrow$ extremum seeking problem on the epigraph

The Fenchel biconjugate reads

$$f^{**}(x) = (f^*)^*(x) = \sup_{\xi\in\mathbb{R}^n} \{\langle \xi , x\rangle - f^*(\xi)\}.$$

Illustration of the Fenchel Conjugate





Properties of the Euclidean Fenchel Conjugate

[Rockafellar 1970]

- The Fenchel conjugate f^* is convex (even if f is not)
- f^{**} is the largest convex, lsc function with $f^{**} \leq f$
- If $f(x) \leq g(x)$ holds for all $x \in \mathbb{R}^n$ then $f^*(\xi) \geq g^*(\xi)$ holds for all $\xi \in \mathbb{R}^n$
- Fenchel–Moreau theorem: f convex, proper, lsc $\Rightarrow f^{**} = f$.
- Fenchel–Young inequality:

$$f(x) + f^*(\xi) \geq \xi^\mathsf{T} x \quad \text{for all} \quad x, \xi \in \mathbb{R}^n$$

- For a proper, convex function f

$$\xi \in \partial f(x) \Leftrightarrow f(x) + f^*(\xi) = \xi^\mathsf{T} x$$

- For a proper, convex, lsc function f, then

$$\xi \in \partial f(x) \Leftrightarrow x \in \partial f^*(\xi)$$

The Riemannian $m-$Fenchel Conjugate

[RB, Herzog, Silva Louzeiro, Tenbrinck, and Vidal-Núñez 2021]
alternative approaches: [Ahmadi Kakavandi and Amini 2010; Silva Louzeiro, RB, and Herzog 2022]

Idea: Introduce a point on $\mathcal{M}$ to "act as" 0.

Let $m \in \mathcal{C} \subset \mathcal{M}$ be given and $F\colon \mathcal{C} \to \overline{\mathbb{R}}$.
The m-Fenchel conjugate $F^*_m\colon \mathcal{T}^*_m\mathcal{M} \to \overline{\mathbb{R}}$ is defined by

$$F^*_m(\xi_m) := \sup_{X \in \mathcal{L}_{\mathcal{C},m}} \bigl\{\langle \xi_m \,, X\rangle - F(\exp_m X)\bigr\},$$

where $\mathcal{L}_{\mathcal{C},m} := \{X \in \mathcal{T}_m\mathcal{M} \mid q = \exp_m X \in \mathcal{C} \text{ and } \|X\|_p = d(q,p)\}$.

Let $m' \in \mathcal{C}$. The mm'-Fenchel-biconjugate $F^{**}_{mm'}\colon \mathcal{C} \to \overline{\mathbb{R}}$ is given by

$$F^{**}_{mm'}(p) = \sup_{\xi_{m'} \in \mathcal{T}^*_{m'}\mathcal{M}} \bigl\{\langle \xi_{m'} \,, \log_{m'} p\rangle - F^*_m(\mathrm{P}_{m\leftarrow m'}\xi_{m'})\bigr\}.$$

usually we only use the case $m = m'$.

Properties of the m-Fenchel Conjugate

[RB, Herzog, Silva Louzeiro, Tenbrinck, and Vidal-Núñez 2021]

- F_m^* is convex on $\mathcal{T}_m^*\mathcal{M}$
- If $F(p) \leq G(p)$ holds for all $p \in \mathcal{C}$ $F_m^*(\xi_m) \geq G_m^*(\xi_m)$ holds for all $\xi_m \in \mathcal{T}_m^*\mathcal{M}$
- Fenchel-Moreau theorem: $F \circ \exp_m$ convex (on $\mathcal{T}_m\mathcal{M}$), proper, lsc, then $F_{mm}^{**} = F$ on $\mathcal{C}$.
- Fenchel-Young inequality: For a proper, convex function $F \circ \exp_m$

$$\xi_p \in \partial_{\mathcal{M}} F(p) \Leftrightarrow F(p) + F_m^*(\mathrm{P}_{m\leftarrow p}\xi_p) = \langle \mathrm{P}_{m\leftarrow p}\xi_p \,, \log_m p \rangle.$$

- For a proper, convex, lsc function $F \circ \exp_m$

$$\xi_p \in \partial_{\mathcal{M}} F(p) \Leftrightarrow \log_m p \in \partial F_m^*(\mathrm{P}_{m\leftarrow p}\xi_p).$$

Proximal Map

For $F\colon \mathcal{M} \to \overline{\mathbb{R}}$ and $\lambda > 0$ we define the Proximal Map as
[Moreau 1965; Rockafellar 1970; Ferreira and Oliveira 2002]

$$\operatorname{prox}_{\lambda F} p := \operatorname*{arg\,min}_{u \in \mathcal{M}} d(u, p)^2 + \lambda F(u).$$

! For a Minimizer u^* of F we have $\operatorname{prox}_{\lambda F} u^* = u^*$.

- For F proper, convex, lsc:
  - the proximal map is unique.
  - PPA $x_k = \operatorname{prox}_{\lambda F} x_{k-1}$ converges to $\operatorname{arg\,min} F$
- $q = \operatorname{prox}_{\lambda F} p$ is equivalent to

$$\frac{1}{\lambda}\bigl(\log_q p\bigr)^\flat \in \partial_{\mathcal{M}} F(q)$$

The Chambolle-Pock Algorithm

[Chambolle and Pock 2011]

From the pair of primal-dual problems

$$\min_{x\in\mathbb{R}^n} f(x) + g(Kx), \quad K \text{ linear},$$
$$\max_{\xi\in\mathbb{R}^m} -f^*(-K^*\xi) - g^*(\xi)$$

we obtain for f, g proper convex, lsc the
optimality conditions (OC) for a solution $(\hat{x}, \hat{\xi})$ as ,
Chambolle–Pock Algorithm. with $\sigma > 0$, $\tau > 0$, $\theta \in \mathbb{R}$ reads

$$\begin{aligned} \partial f \quad &\ni -K^*\hat{\xi} \\ \partial g^*(\hat{\xi}) &\ni K\hat{x} \\ \bar{\xi}^{(k+1)} &= \xi^{(k+1)} + \theta(\xi^{(k+1)} - \xi^{(k)}) \end{aligned}$$

Saddle Point Formulation

Let F be geodesically convex, $G \circ \exp_n$ be convex (on $\mathcal{T}_n\mathcal{N}$).

From

$$\min_{p \in \mathcal{C}} F(p) + G(\Lambda(p))$$

we derive the saddle point formulation for the n-Fenchel conjugate of G as

$$\min_{p \in \mathcal{C}} \max_{\xi_n \in \mathcal{T}_n^*\mathcal{N}} \langle \xi_n , \log_n \Lambda(p) \rangle + F(p) - G_n^*(\xi_n).$$

But $\Lambda\colon \mathcal{M} \to \mathcal{N}$ is a non-linear operator!

For Optimality Conditions and the Dual Prolem: What's Λ^*?

Approach. Linearization: [Valkonen 2014]

$$\Lambda(p) \approx \exp_{\Lambda(m)} D\Lambda(m)[\log_m p]$$

The Exact Riemannian Chambolle–Pock Algorithm (eRCPA)

[RB, Herzog, Silva Louzeiro, Tenbrinck, and Vidal-Núñez 2021]

Input: $m,\ p^{(0)} \in \mathbb{R}^d$, $n = \Lambda(m)$, $\xi_n^{(0)} \in \mathbb{R}^d$, and parameters $\sigma, \tau, \theta > 0$

1: $k \leftarrow 0$

2: $\bar{p}^{(0)} \leftarrow p^{(0)}$

3: **while** not converged **do**

4: $\quad \xi_n^{(k+1)} \leftarrow \operatorname{prox}_{\tau G_n^*}\Bigl(\xi_n^{(k)} + \tau\bigl(\log_n \Lambda(\bar{p}^{(k)})\bigr)^\flat\Bigr)$

5: $\quad p^{(k+1)} \leftarrow \operatorname{prox}_{\sigma F}\Bigl(p^{(k)} + \mathrm{P}_{p^{(k)} \leftarrow m}\bigl(-\sigma D\Lambda(m)^*[\xi_n^{(k+1)}]\bigr)^\sharp\Bigr)$

6: $\quad \bar{p}^{(k+1)} \leftarrow p^{(k+1)} + \theta(p^{(k+1)} - p^{(k)})$

7: $\quad k \leftarrow k + 1$

8: **end while**

Output: $p^{(k)}$

Generalizations & Variants of the RCPA

Classically

[Chambolle and Pock 2011]

- change $\sigma = \sigma_k$, $\tau = \tau_k$, $\theta = \theta_k$ during the iterations
- introduce an acceleration γ
- relax dual $\bar{\xi}$ instead of primal $\bar{p}$ (switches lines 4 and 5)

Furthermore we

[RB, Herzog, Silva Louzeiro, Tenbrinck, and Vidal-Núñez 2021]

- introduce the IRCPA: linearize Λ, i. e., adopt the Euclidean case from [Valkonen 2014]

$$\log_n \Lambda(\bar{p}^{(k)}) \quad \to \quad \mathrm{P}_{n \leftarrow \Lambda(m)} D\Lambda(m)[\log_m \bar{p}^{(k)}]$$

- choose $n \neq \Lambda(m)$ introduces a parallel transport

$$D\Lambda(m)^*[\xi_n^{(k+1)}] \quad \to \quad D\Lambda(m)^*[\mathrm{P}_{\Lambda(m) \leftarrow n} \xi_n^{(k+1)}]$$

- change $m = m^{(k)}$, $n = n^{(k)}$ during the iterations

A Constant and a Conjecture

We define

$$C(k) := \frac{1}{\sigma} d^2(p^{(k)}, \tilde{p}^{(k)}) + \langle \bar{\xi}_n^{(k)}, D\Lambda(m)[\zeta_k] \rangle,$$

where

$$\zeta_k = \mathrm{P}_{m \leftarrow p^{(k)}} \left(\log_{p^{(k)}} p^{(k+1)} - \mathrm{P}_{p^{(k)} \leftarrow \tilde{p}^{(k)}} \log_{\tilde{p}^{(k)}} \widehat{p} \right) - \log_m p^{(k+1)} + \log_m \widehat{p},$$

and $\hat{p}$ is a minimizer of the primal problem.

Remark.
For $\mathcal{M} = \mathbb{R}^d$: $\zeta_k = \tilde{p}^{(k)} - p^{(k)} = -\sigma (D\Lambda(m))^* [\bar{\xi}_n^{(k)}] \Rightarrow C(k) = 0$.

Conjecture.
Assume $\sigma\tau < \|D\Lambda(m)\|^2$. Then $C(k) \geq 0$ for all $k > K$, $K \in \mathbb{N}$.

Convergence of the IRCPA

Theorem. [RB, Herzog, Silva Louzeiro, Tenbrinck, and Vidal-Núñez 2021]
Let $\mathcal{M}$, $\mathcal{N}$ be Hadamard. Assume that the linearized problem

$$\min_{p\in\mathcal{M}} \max_{\xi_n\in\mathcal{T}_n^*\mathcal{N}} \langle (D\Lambda(m))^*[\xi_n]\,, \log_m p\rangle + F(p) - G_n^*(\xi_n).$$

has a saddle point $(\widehat{p}, \widehat{\xi}_n)$.
Choose σ, τ such that

$$\sigma\tau < \|D\Lambda(m)\|^2$$

and assume that $C(k) \geq 0$ for all $k > K$. Then it holds

1. the sequence $(p^{(k)}, \xi_n^{(k)})$ remains bounded,
2. there exists a saddle-point (p', ξ_n') such that $p^{(k)} \to p'$ and $\xi_n^{(k)} \to \xi_n'$.

Implementing a Riemannian manifold

`ManifoldsBase.jl` introduces a manifold type with its field $\mathbb{F} \in \{\mathbb{R}, \mathbb{C}, \mathbb{H}\}$ as parameter to provide an interface for implementing functions like

- `inner(M, p, X, Y)` for the Riemannian metric $(X, Y)_p$
- `exp(M, p, X)` and `log(M, p, q)`,
- more general: `retract(M, p, X, m)`, where `m` is a retraction method
- similarly: `parallel_transport(M, p, X, q)` and `vector_transport_to(M, p, X, q, m)`

for your manifold, which is a subtype of `Manifold`.
☺ mutating version `exp!(M, q, p, X)` works in place in `q`

➔ basis for generic algorithms working on any `Manifold` and generic functions like `norm(M,p,X)`, `geodesic(M, p, X)` and `shortest_geodesic(M, p, q)`

juliamanifolds.github.io/ManifoldsBase.jl/

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Manifolds.jl: A Library of Manifolds in Julia

`Manifolds.jl` is based on the `ManifoldsBase.jl` interface.

Features.

- different metrics
- Lie groups
- Build manifolds using
  - Product manifold $\mathcal{M}_1 \times \mathcal{M}_2$
  - Power manifold $\mathcal{M}^{n\times m}$
  - Tangent bundle
- perform statistics
- well-documented, including formulae and references
- well-tested, >98 % code coverage, unified coding style

Manifolds. For example

- (unit) Sphere
- Circle & Torus
- Fixed Rank Matrices
- Stiefel & Grassmann
- Hyperbolic space
- Rotations
- Symmetric positive definite matrices
- Symplectic & Symplectic Stiefel
- ...

juliamanifolds.github.io/Manifolds.jl/

Manopt.jl: Optimisation on Manifolds in Julia

[RB 2022]

Goal. Provide optimisation algorithms on Riemannian manifolds, i. e. based on `ManifoldsBase.jl` such that it can be used with all manifolds from `Manifolds.jl`.

Features.

- generic algorithm framework:
  With `Problem P` and `Options O`
  - `initialize_solver!(P,O)`
  - `step_solver!(P, O, i)`: ith step
- run algorithm: call `solve(P,O)`
- generic debug and recording
- step sizes and stopping criteria.

Manopt Family.

- manoptjl.org [RB 2022]
- manopt.org [Boumal, Mishra, Absil, and Sepulchre 2014]
- pymanopt.org [Townsend, Koep, and Weichwald 2016]

Algoirthms.

- Gradient Descent
  CG, Stochastic, Momentum, …
- Quasi-Newton
  BFGS, DFP, Broyden, SR1, …
- Nelder-Mead, Particle Swarm
- Subgradient Method
- Trust Regions
- Chambolle-Pock
- Douglas-Rachford
- Cyclic Proximal Point

The ℓ^2-TV Model

[Rudin, Osher, and Fatemi 1992; Lellmann, Strekalovskiy, Koetter, and Cremers 2013; Weinmann, Demaret, and Storath 2014]

For a manifold-valued image $f \in \mathcal{M}$, $\mathcal{M} = \mathcal{N}^{d_1,d_2}$, we compute

$$\operatorname*{arg\,min}_{p\in\mathcal{M}} \frac{1}{\alpha} F(p) + G(\Lambda(p)), \qquad \alpha > 0,$$

with

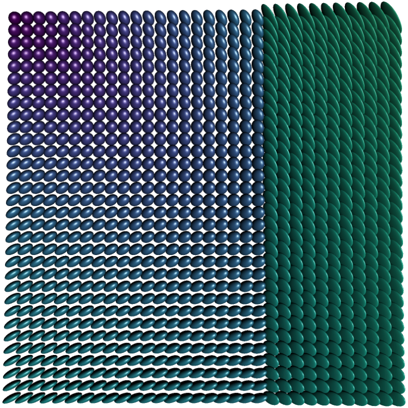
- data term $F(p) = \frac{1}{2} d^2_{\mathcal{M}}(p, f)$
- "forward differences" $\Lambda\colon \mathcal{M} \to (T\mathcal{M})^{d_1-1,\ d_2-1,\ 2}$,

$$p \mapsto \Lambda(p) = \Bigl(\bigl(\log_{p_i} p_{i+e_1},\ \log_{p_i} p_{i+e_2}\bigr)\Bigr)_{i\in\{1,\ldots,d_1-1\}\times\{1,\ldots,d_2-1\}}$$

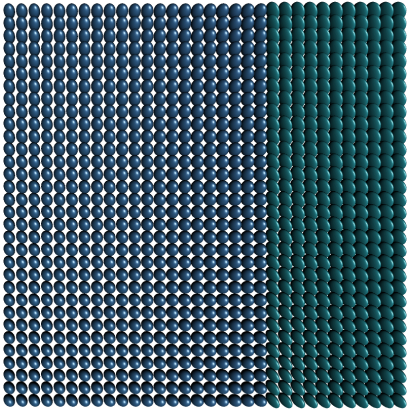
- prior $G(X) = \|X\|_{g,q,1}$ similar to a collaborative TV [Duran, Moeller, Sbert, and Cremers 2016]

$\Rightarrow$ $\operatorname{prox}_{\lambda G^*_n}$ given in closed form for $q = 1$ (anisotropic TV) and $q = 2$ (isotropic TV).

Numerical Example for a $\mathcal{P}(3)$-valued Image



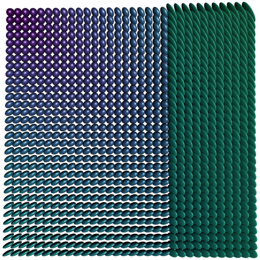
$\mathcal{P}(3)$-valued data.



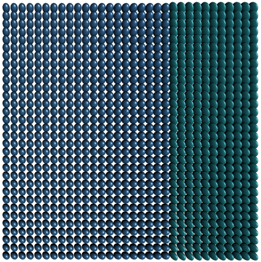
anisotropic TV, $\alpha = 6$.

- in each pixel we have a symmetric positive definite matrix
- Applications: denoising/inpainting e.g. of DT-MRI data

Numerical Example for a $\mathcal{P}(3)$-valued Image



$\mathcal{P}(3)$-valued data.

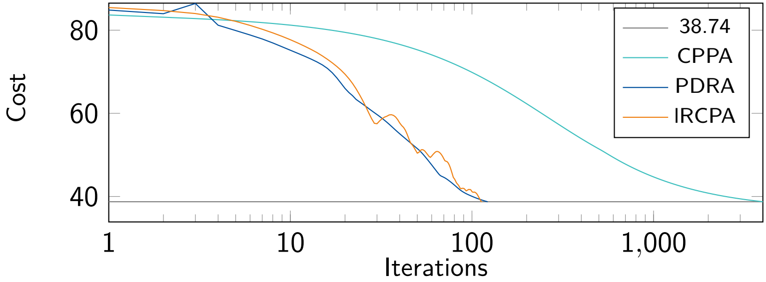


anisotropic TV, $\alpha = 6$.

Approach. CPPA as benchmark [Bačák 2014; RB, Herzog, Silva Louzeiro, Tenbrinck, and Vidal-Núñez 2021]

	CPPA	PDRA	IRCPA
parameters	$\lambda_k = \frac{4}{k}$	$\lambda = 0.58$ $\beta = 0.93$	$\sigma = \tau = 0.4$ $\gamma = 0.2,\ m = I$
iterations	4000	122	**113**
runtime	1235 s.	380 s.	**96.1 s.**

Numerical Example for a $\mathcal{P}(3)$-valued Image

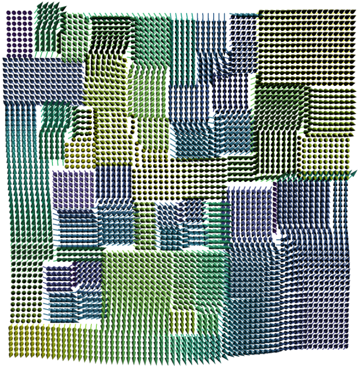


Approach. CPPA as benchmark [Bačák 2014; RB, Herzog, Silva Louzeiro, Tenbrinck, and Vidal-Núñez 2021]

	CPPA	PDRA	IRCPA
parameters	$\lambda_k = \frac{4}{k}$	$\lambda = 0.58$ $\beta = 0.93$	$\sigma = \tau = 0.4$ $\gamma = 0.2,\ m = I$
iterations	4000	122	**113**
runtime	1235 s.	380 s.	**96.1 s.**

Basepoint Effect on $\mathbb{S}^2$-valued Data

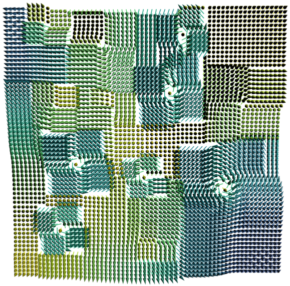
Original data



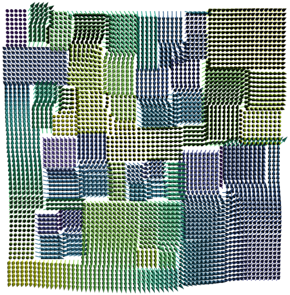
Result, m west (per px.)

- pieceweise constant results for both
- ! different linearizations lead to different models

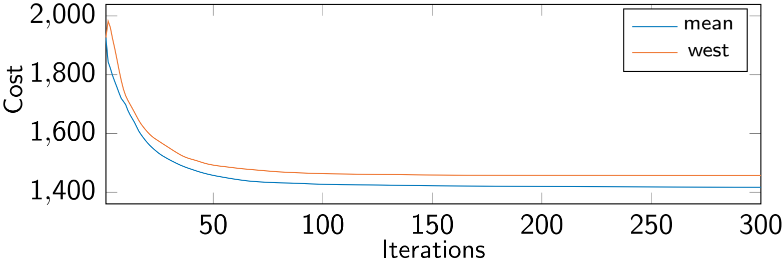
Basepoint Effect on $\mathbb{S}^2$-valued Data



Result, m mean (per px.)



Result, m west (per px.)



Summary

Summary.

- We introduced a duality framework on manifolds
- we introduced a Riemannian Chambolle–Pock algorithm
- We saw a Software framework for Optimisation algorithms on manifolds
- Numerical examples illustrates its performance

Outlook.

- Strategies for choosing base points, investigate $C(k)$
- Investigate constraint optimisation on Manifolds

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