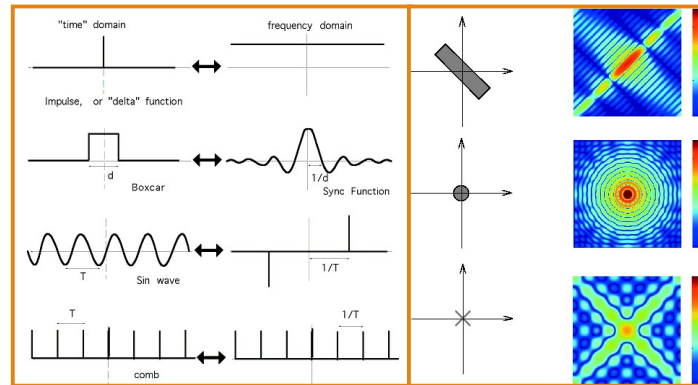


Weeks 06: THE FOURIER TRANSFORM

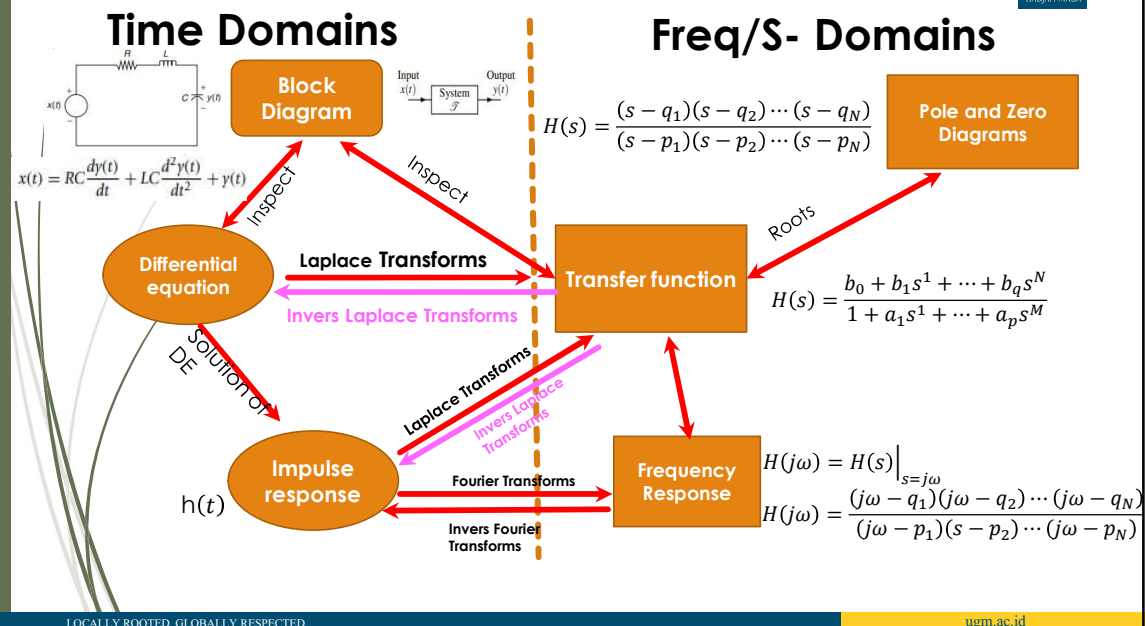
Objectives:

- Derivation
- Transform Pairs
- Response of LTI Systems
- Transforms of Periodic Signals
- Examples



Continuous-Time System Relationships

PSE - UGM

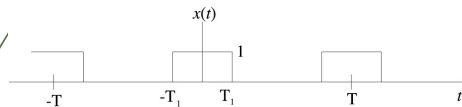


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Motivation

- We have introduced a **Fourier Series** for analyzing **periodic signals**. What about **aperiodic signals**? (e.g., a pulse instead of a pulse train)
- We can view an **aperiodic signal** as the **limit of a periodic signal** as $T \rightarrow \infty$.
- The **harmonic components** are spaced $\omega_0 = \frac{2\pi}{T}$ apart.
- As $T \rightarrow \infty$, $\omega_0 \rightarrow 0$, then $k\omega_0$ becomes **continuous**.
- The **Fourier Series** becomes the **Fourier Transform**.

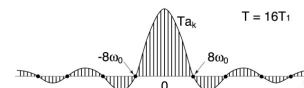
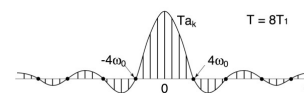
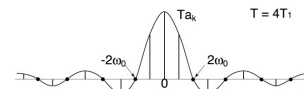
$$\tilde{x}(t) = \sum_{k=-\infty}^{\infty} c_k e^{jk\omega_0 t} \quad c_k = \frac{1}{T} \int_{-T/2}^{T/2} \tilde{x}(t) e^{-jk\omega_0 t} dt$$



$$c_k = \frac{\sin(k\omega_0 T_1)}{k\pi} = \frac{2\sin(k2\pi(T_1/T))}{k\omega_0 T}$$

$$T_1 \text{ fixed, } T \rightarrow \infty, k\omega_0 \rightarrow \omega$$

$$Tc_k = \frac{2\sin(\omega T_1)}{\omega}$$



Derivation of Analysis Equation

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- Assume $x(t)$ has a **finite duration**.
- Define $\tilde{x}(t)$ as a **periodic extension** of $x(t)$:

$$\tilde{x}(t) = \begin{cases} x(t) & -\frac{T}{2} \leq t \leq \frac{T}{2} \\ \text{periodic} & |t| > \frac{T}{2} \end{cases}$$

- As $T \rightarrow \infty$, $\tilde{x}(t) \rightarrow x(t)$

- Recall our Fourier series pair:

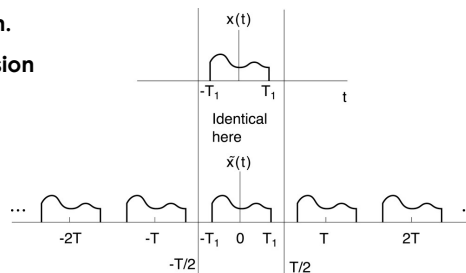
$$\tilde{x}(t) = \sum_{k=-\infty}^{\infty} c_k e^{jk\omega_0 t} \quad c_k = \frac{1}{T} \int_{-T/2}^{T/2} \tilde{x}(t) e^{-jk\omega_0 t} dt$$

- Since $x(t)$ and $\tilde{x}(t)$ are **identical** over this interval:

$$c_k = \frac{1}{T} \int_{-T/2}^{T/2} \tilde{x}(t) e^{-jk\omega_0 t} dt = \frac{1}{T} \int_{-T/2}^{T/2} x(t) e^{-jk\omega_0 t} dt$$

- As $T \rightarrow \infty$, $k\omega_0 \rightarrow \omega$

$$X(j\omega) = \frac{1}{T} \int_{-\infty}^{\infty} x(t) e^{-j\omega t} dt$$



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Derivation of the Synthesis Equation

- **Recall:** $\tilde{x}(t) = x(t) = \sum_{k=-\infty}^{\infty} c_k e^{jk\omega_0 t}$ for $-\frac{T}{2} \leq t \leq \frac{T}{2}$
- We can substitute for c_k the sampled value of $X(j\omega)$:

$$\begin{aligned}\tilde{x}(t) = x(t) &= \sum_{k=-\infty}^{\infty} \left(\frac{1}{T} X(j\omega_0) \right) e^{jk\omega_0 t} \\ &= \frac{1}{2\pi} \sum_{k=-\infty}^{\infty} \omega_0 X(j\omega_0) e^{jk\omega_0 t}\end{aligned}$$

- As $T \rightarrow \infty$, $\omega_0 \rightarrow 0$, $\sum_{k=-\infty}^{\infty} \omega_0 \rightarrow \int d\omega$, $k\omega_0 \rightarrow \omega$

and we arrive at our **Fourier Transform pair**:

$$x(t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} X(j\omega) e^{j\omega t} d\omega \quad \text{(synthesis)}$$

$$X(j\omega) = \frac{1}{T} \int_{-\infty}^{\infty} x(t) e^{-j\omega t} dt \quad \text{(analysis)}$$

- Note the presence of the **eigenfunction**: $e^{st} \big|_{s=j\omega} = e^{j\omega t}$
- Also note the **symmetry** of these equations (e.g., integrals over time and frequency, change in the sign of the exponential, difference in scale factors).

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Frequency Response of a CT LTI System

- Recall that the **impulse response** of a CT system, $h(t)$, defines the properties of that system.
- We apply the **Fourier Transform** to obtain the **system's frequency response**:

$$\begin{aligned}h(t) &= \frac{1}{2\pi} \int_{-\infty}^{\infty} H(j\omega) e^{j\omega t} d\omega \\ H(j\omega) &= \frac{1}{T} \int_{-\infty}^{\infty} h(t) e^{-j\omega t} dt\end{aligned}$$

except that now this is valid for **finite duration (energy) signals** as well as **periodic signals**!

- How does this relate to what you have learned in **circuit theory**?

$$e^{j\omega t} \rightarrow \boxed{h(t) \Leftrightarrow H(j\omega)} \rightarrow H(j\omega) e^{j\omega t}$$

$$\begin{array}{ccc} x(t) & \rightarrow & \boxed{h(t) \Leftrightarrow H(j\omega)} \rightarrow y(t) \\ X(j\omega) & \rightarrow & Y(j\omega) \end{array}$$

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Existence of the Fourier Transform

- Under what conditions does this transform exist?

$x(t)$ can be infinite duration but must satisfy these conditions:

a) Finite energy $\int_{-\infty}^{+\infty} |x(t)|^2 dt < \infty$

In this case, there is *zero* energy in the error

$$e(t) = x(t) - \frac{1}{2\pi} \int_{-\infty}^{\infty} X(j\omega) e^{j\omega t} d\omega \quad \text{Then} \quad \int_{-\infty}^{\infty} |e(t)|^2 dt = 0$$

b) Dirichlet conditions (including $\int_{-\infty}^{+\infty} |x(t)|^2 dt < \infty$)

$$(i) \quad \frac{1}{2\pi} \int_{-\infty}^{\infty} X(j\omega) e^{j\omega t} d\omega = \frac{1}{2} [x(t-0) + x(t+0)]$$

$$= \begin{cases} x(t) & \text{at points of continuity} \\ \text{midpoint at discontinuity} \end{cases}$$

(ii) Gibb's phenomenon

- c) By allowing impulses in $x(t)$ or in $X(j\omega)$, we can represent even *more* signals

E.g. It allows us to consider FT for *periodic* signals

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Example: Impulse Function

Example #1

(a) $x(t) = \delta(t)$

$$X(j\omega) = \int_{-\infty}^{+\infty} \delta(t) e^{-j\omega t} dt = 1$$

\Downarrow

$$\delta(t) = \frac{1}{2\pi} \int_{-\infty}^{+\infty} e^{j\omega t} d\omega \quad \text{— Synthesis equation for } \delta(t)$$

(b) $x(t) = \delta(t - t_0)$

$$X(j\omega) = \int_{-\infty}^{+\infty} \delta(t - t_0) e^{-j\omega t} dt$$

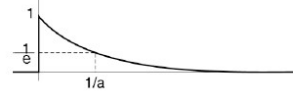
$$= e^{-j\omega t_0} \quad \text{— Linear phase shift in } \omega$$

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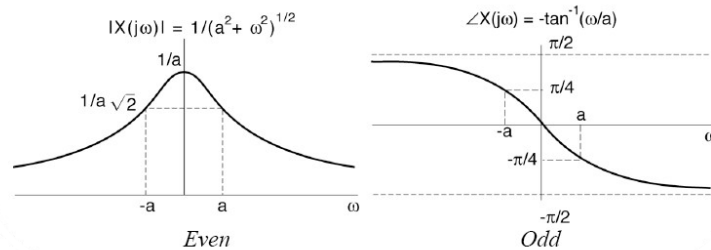
Example: Exponential Function

Example #2: Exponential function

$$x(t) = e^{-at}u(t), \quad a > 0$$



$$\begin{aligned} X(j\omega) &= \int_{-\infty}^{+\infty} x(t)e^{-j\omega t} dt = \int_0^{+\infty} \frac{e^{-at}e^{-j\omega t}}{e^{-(a+j\omega)t}} dt \\ &= -\left(\frac{1}{a+j\omega}\right)e^{-(a+j\omega)t} \Big|_0^{\infty} = \frac{1}{a+j\omega} \end{aligned}$$

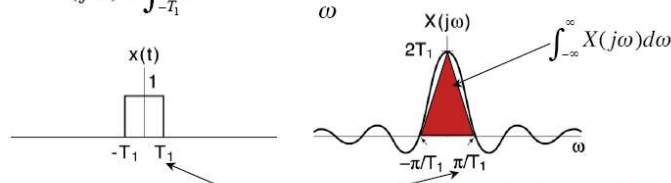


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Example: Square Pulse

Example #3: A square pulse in the time-domain

$$X(j\omega) = \int_{-T_1}^{T_1} e^{-j\omega t} dt = \frac{2 \sin \omega T_1}{\omega}$$



Note the inverse relation between the two widths \Rightarrow **Uncertainty principle**

Useful facts about CTFT's

$$X(0) = \int_{-\infty}^{+\infty} x(t) dt$$

Example above: $\int_{-\infty}^{\infty} x(t) dt = 2T_1 = X(0)$

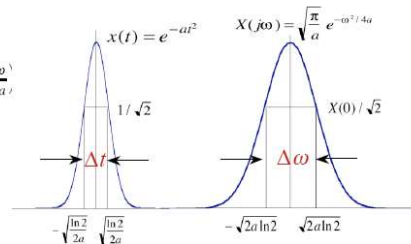
$$\begin{aligned} x(0) &= \frac{1}{2\pi} \int_{-\infty}^{+\infty} X(j\omega) d\omega \quad \text{Ex. above: } x(0) = 1 = \frac{1}{2\pi} \underbrace{\int_{-\infty}^{\infty} X(j\omega) d\omega}_{2\pi} = \frac{1}{2\pi} \cdot \frac{1}{2} \left(2T_1 \times \frac{2\pi}{T_1} \right) \\ &= \frac{1}{2\pi} \times (\text{Area of the triangle}) \end{aligned}$$

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Example: Gaussian Pulse

Example #4: $x(t) = e^{-at^2}$ — A Gaussian, important in probability, optics, etc.

$$\begin{aligned} X(j\omega) &= \int_{-\infty}^{\infty} e^{-at^2} e^{-j\omega t} dt \\ &= \int_{-\infty}^{\infty} e^{-a \left[t^2 + j\frac{\omega}{a}t + \left(\frac{j\omega}{2a}\right)^2 \right] + a \left(\frac{j\omega}{2a}\right)^2} dt \\ &= \underbrace{\left[\int_{-\infty}^{\infty} e^{-a \left(t + \frac{j\omega}{2a} \right)^2} dt \right]}_{\sqrt{\pi/a}} \cdot e^{-\frac{\omega^2}{4a}} \\ &= \sqrt{\frac{\pi}{a}} e^{-\frac{\omega^2}{4a}} \end{aligned}$$



(Pulse width in t) • (Pulse width in ω)
 $\Rightarrow \Delta t \Delta \omega \sim (1/a)^{1/2} \cdot (a)^{1/2} = 1$

Also a Gaussian!

Uncertainty Principle! Cannot make *both* Δt and $\Delta \omega$ arbitrarily small.

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CT Fourier Transforms of Periodic Signals

CT Fourier Transforms of Periodic Signals

Suppose $X(j\omega) = \delta(\omega - \omega_0)$

\Downarrow

$$x(t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} \delta(\omega - \omega_0) e^{j\omega t} d\omega = \frac{1}{2\pi} e^{j\omega_0 t} \quad \text{— periodic in } t \text{ with frequency } \omega_0$$

That is

$$e^{j\omega_0 t} \longleftrightarrow 2\pi \delta(\omega - \omega_0)$$

— All the energy is concentrated in one frequency — ω_0

More generally, if $x(t) = x(t+T)$, then

$$x(t) = \sum_{k=-\infty}^{+\infty} a_k e^{jk\omega_0 t} \longleftrightarrow X(j\omega) = \sum_{k=-\infty}^{+\infty} 2\pi a_k \delta(\omega - k\omega_0) \quad \text{Discrete spectra}$$

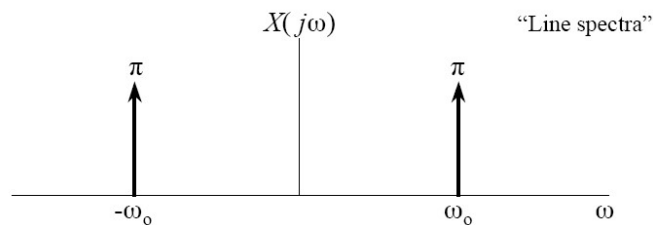
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Example: Cosine Function**Example #4:**

$$x(t) = \cos \omega_0 t = \frac{1}{2} e^{j\omega_0 t} + \frac{1}{2} e^{-j\omega_0 t}$$

$$\Downarrow$$

$$X(j\omega) = \pi \delta(\omega - \omega_0) + \pi \delta(\omega + \omega_0)$$



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Example: Periodic Pulse Train**Example #5:**

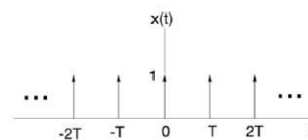
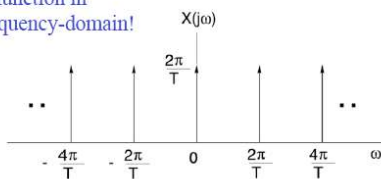
$$x(t) = \sum_{n=-\infty}^{+\infty} \delta(t - nT) \quad \text{— Old friend, sampling function}$$

$$x(t) \longleftrightarrow a_k = \frac{1}{T} \int_{-T/2}^{T/2} x(t) e^{-jk\omega_0 t} dt = \frac{1}{T}$$

$$\Downarrow x(t) = \sum_{k=-\infty}^{+\infty} a_k e^{jk\omega_0 t} = \sum_{k=-\infty}^{+\infty} \frac{1}{T} e^{jk\omega_0 t}$$

$$X(j\omega) = \sum_{k=-\infty}^{+\infty} \frac{2\pi}{T} \delta(\omega - \underbrace{k2\pi}_{k\omega_0})$$

Same function in
the frequency-domain!



Note in this case, periodic
in both time domain (with
a period T) and frequency
domain (with a period
 $2\pi/T$)

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Summary

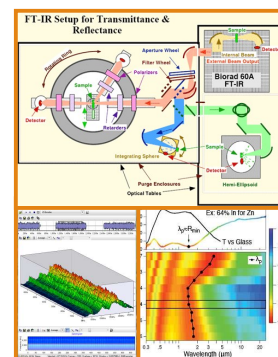
- Motivated the derivation of the CT Fourier Transform by starting with the Fourier Series and increasing the period: $T \rightarrow \infty$
- Derived the analysis and synthesis equations (Fourier Transform pairs).
- Applied the Fourier Transform to CT LTI systems and showed that we can obtain the frequency response of an LTI system by taking the Fourier Transform of its impulse response.
- Discussed the conditions under which the Fourier Transform exists. Demonstrated that it can be applied to periodic signals and infinite duration signals as well as finite duration signals.
- Worked several examples of important finite duration signals.
- Introduced the Fourier Transform of a periodic signal.
- Applied this to a cosinewave and a pulse train.

FOURIER TRANSFORM PROPERTIES

Objectives:

- Linearity
- Time Shift and Time Reversal
- Multiplication
- Integration
- Convolution
- Parseval's Theorem
- Duality

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➤ Linearity

- Recall our expressions for the Fourier Transform and its inverse:

$$x(t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} X(j\omega) e^{j\omega t} d\omega \quad (\text{synthesis})$$

$$X(j\omega) \equiv X(\omega) = \frac{1}{T} \int_{-\infty}^{\infty} x(t) e^{-j\omega t} dt \quad (\text{analysis})$$

- The property of linearity:

$$\mathcal{F}\{ax(t) + by(t)\} = aX(j\omega) + bY(j\omega) \Rightarrow ax(t) + by(t) \leftrightarrow aX(j\omega) + bY(j\omega)$$

Proof:

$$\begin{aligned} \mathcal{F}\{ax(t) + by(t)\} &= \frac{1}{T} \int_{-\infty}^{\infty} \{ax(t) + by(t)\} e^{-j\omega t} dt \\ &= \frac{1}{T} \int_{-\infty}^{\infty} ax(t) e^{-j\omega t} dt + \frac{1}{T} \int_{-\infty}^{\infty} by(t) e^{-j\omega t} dt \\ &= a \left\{ \frac{1}{T} \int_{-\infty}^{\infty} x(t) e^{-j\omega t} dt \right\} + b \left\{ \frac{1}{T} \int_{-\infty}^{\infty} y(t) e^{-j\omega t} dt \right\} \\ &= aX(j\omega) + bY(j\omega) \end{aligned}$$

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➤ Time Shift

- Time Shift:

$$x(t - t_0) \leftrightarrow X(j\omega) e^{-j\omega t_0}$$

Proof:

$$\mathcal{F}\{x(t - t_0)\} = \frac{1}{T} \int_{-\infty}^{\infty} x(t - t_0) e^{-j\omega t} dt$$

make a change of variables: $\lambda = t - t_0$, which implies $t = \lambda + t_0$

$$\begin{aligned} \mathcal{F}\{x(t - t_0)\} &= \frac{1}{T} \int_{-\infty}^{\infty} x(\lambda) e^{-j\omega(\lambda + t_0)} d\lambda \\ &= \frac{1}{T} \left\{ \int_{-\infty}^{\infty} x(\lambda) e^{-j\omega\lambda} d\lambda \right\} e^{-j\omega t_0} \\ &= X(j\omega) e^{-j\omega t_0} \end{aligned}$$

- Note that this means time delay is equivalent to a linear phase shift in the frequency domain (the phase shift is proportional to frequency).
- We refer to a system as an all-pass filter if:

$$|X(j\omega)| = 1 \quad \angle X(j\omega) \neq 0$$
- Phase shift is an important concept in the development of surround sound.

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Time Scaling

Time Scaling:

$$x(at) \leftrightarrow \frac{1}{|a|} X\left(\frac{j\omega}{a}\right)$$

Proof:

$$\mathcal{F}\{x(at)\} = \frac{1}{T} \int_{-\infty}^{\infty} x(at) e^{-j\omega t} dt$$

assume $a > 0$, make a change of variables: $\lambda = at$, which implies $t = \lambda / a$, and $dt = (1/a)d\lambda$

$$\begin{aligned} \mathcal{F}\{ax(t)\} &= \frac{1}{T} \int_{-\infty}^{\infty} x(\lambda) e^{-j\omega(\frac{\lambda}{a})} \left(\frac{1}{a}\right) d\lambda \\ &= \left(\frac{1}{a}\right) \left\{ \frac{1}{T} \int_{-\infty}^{\infty} x(\lambda) e^{-j(\omega/a)\lambda} d\lambda \right\} \\ &= \left(\frac{1}{a}\right) X\left(\frac{j\omega}{a}\right) \end{aligned}$$

- **Generalization for $a < 0$** , the negative value is offset by the change in the limits of integration.
- What is the implication of $a < 1$ on the time-domain waveform? On the frequency response? What about $a > 1$?
- Any real-world applications of this property? Hint: sampled signals.78

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Time Reversal

Time Reversal:

$$x(-t) \leftrightarrow X(-j\omega)$$

Proof:

$$\mathcal{F}\{x(-t)\} = \frac{1}{|a|} X\left(\frac{j\omega}{a}\right) \Big|_{a=-1} = X(-j\omega)$$

We can also note that for real-valued signals:

$$\begin{aligned} X(-j\omega) &= |X(-j\omega)| \angle X(-j\omega) \\ &= |X(j\omega)| \angle X(-j\omega) = X^*(j\omega) \quad (\text{complex conjugate}) \end{aligned}$$

- Time reversal is equivalent to conjugation in the frequency domain.
- Can we time reverse a signal? If not, why is this property useful?

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➤ Multiplication by a Power of t

- **Multiplication by a power of t :**

$$t^n x(t) \leftrightarrow (j)^n \frac{d^n}{d\omega^n} X(j\omega)$$

Proof: $X(j\omega) = \frac{1}{T} \int_{-\infty}^{\infty} x(t) e^{-j\omega t} dt$

differentiate with respect to ω :

$$\frac{dX(j\omega)}{d\omega} = \frac{1}{T} \int_{-\infty}^{\infty} (-jt) x(t) e^{-j\omega t} dt$$

multiply by j :

$$\begin{aligned} j \frac{dX(j\omega)}{d\omega} &= (j) \frac{1}{T} \int_{-\infty}^{\infty} (-jt) x(t) e^{-j\omega t} dt \\ &= \frac{1}{T} \int_{-\infty}^{\infty} (t) x(t) e^{-j\omega t} dt = \mathcal{F}\{t x(t)\} \end{aligned}$$

- We can repeat the process for higher powers of t .

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➤ Multiplication by a Complex Exponential (Modulation)

- **Multiplication by a complex exponential:**

$$x(t)e^{j\omega_0 t} \leftrightarrow X(j(\omega - \omega_0)) \text{ for any real number } \omega_0$$

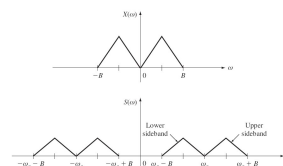
Proof:

$$\begin{aligned} \mathcal{F}\{x(t)e^{j\omega_0 t}\} &= \frac{1}{T} \int_{-\infty}^{\infty} x(t)e^{j\omega_0 t} e^{-j\omega t} dt \\ &= \frac{1}{T} \int_{-\infty}^{\infty} x(t)e^{-j(\omega - \omega_0)t} dt \\ &= X(j(\omega - \omega_0)) \end{aligned}$$

- **Why is this property useful?**
- **First, another property:**

$$x(t) \cos(\omega_0 t) = x(t) \left[\frac{e^{j\omega_0 t} + e^{-j\omega_0 t}}{2} \right] \leftrightarrow \frac{1}{2} [X(j(\omega + \omega_0)) + X(j(\omega - \omega_0))]$$

- **This produces a translation in the frequency domain. How might this be useful in a communication system?**



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➤ Differentiation / Integration

- **Differentiation in the Time Domain:**

$$\frac{d^n}{dt^n} x(t) \leftrightarrow (j\omega)^n X(j\omega)$$

- **Integration in the Time Domain:**

$$\int_{-\infty}^t x(\lambda) d\lambda \leftrightarrow \frac{1}{j\omega} X(j\omega) + \pi X(0) \delta(\omega)$$

- What are the implications of time-domain differentiation in the frequency domain?
- Why might this be a problem? Hint: additive noise.
- How can we apply these properties? Hint: unit impulse, unit step, ...

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➤ Convolution in the Time Domain

- **Convolution in the Time Domain:**

$$x(t) * h(t) \leftrightarrow X(j\omega)H(j\omega)$$

- **Proof:**

$$x(t) * h(t) = \int_{-\infty}^{\infty} x(\lambda) h(t - \lambda) d\lambda$$

$$\begin{aligned} \mathcal{F}\{x(t) * h(t)\} &= \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} x(\lambda) h(t - \lambda) d\lambda e^{-j\omega t} dt \\ &= \int_{-\infty}^{\infty} x(\lambda) \left[\int_{-\infty}^{\infty} h(t - \lambda) e^{-j\omega t} dt \right] d\lambda \end{aligned}$$

change of variables : $\gamma = t - \lambda \Rightarrow d\gamma = dt$

$$\begin{aligned} &= \int_{-\infty}^{\infty} x(\lambda) \left[\int_{-\infty}^{\infty} h(\gamma) e^{-j\omega(\gamma + \lambda)} d\gamma \right] d\lambda \\ &= \left[\int_{-\infty}^{\infty} x(\lambda) e^{-j\omega\lambda} d\lambda \right] \left[\int_{-\infty}^{\infty} h(\gamma) e^{-j\omega\gamma} d\gamma \right] \\ &= X(j\omega)H(j\omega) \end{aligned}$$

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Other Important Properties

• Multiplication in the Time Domain:

$$x(t) \bullet y(t) \leftrightarrow \frac{1}{2\pi} [X(j\omega) * Y(j\omega)] = \frac{1}{2\pi} \int_{-\infty}^{\infty} X(\lambda) Y(\omega - \lambda) d\lambda$$

• Parseval's Theorem:

$$\int_{-\infty}^{\infty} x^2(t) dt = \frac{1}{2\pi} \int_{-\infty}^{\infty} |X(j\omega)|^2 d\omega$$

• Duality:

$$X(t) \leftrightarrow 2\pi x(-\omega)$$

• **Note:** please read the textbook carefully for the derivations and interpretation of these results.

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Summary

TABLE 3.1 Properties of the Fourier Transform

Property	Transform Pair/Property
Linearity	$ax(t) + bv(t) \leftrightarrow aX(\omega) + bV(\omega)$
Right or left shift in time	$x(t - c) \leftrightarrow X(\omega)e^{-j\omega c}$
Time scaling	$x(at) \leftrightarrow \frac{1}{ a } X\left(\frac{\omega}{a}\right) \quad a > 0$
Time reversal	$x(-t) \leftrightarrow X(-\omega) = \overline{X(\omega)}$
Multiplication by a power of t	$t^n x(t) \leftrightarrow j^n \frac{d^n}{d\omega^n} X(\omega) \quad n = 1, 2, \dots$
Multiplication by a complex exponential	$x(t)e^{j\omega_0 t} \leftrightarrow X(\omega - \omega_0) \quad \omega_0 \text{ real}$
Multiplication by $\sin(\omega_0 t)$	$x(t) \sin(\omega_0 t) \leftrightarrow \frac{j}{2} [X(\omega + \omega_0) - X(\omega - \omega_0)]$
Multiplication by $\cos(\omega_0 t)$	$x(t) \cos(\omega_0 t) \leftrightarrow \frac{1}{2} [X(\omega + \omega_0) + X(\omega - \omega_0)]$
Differentiation in the time domain	$\frac{d^n}{dt^n} x(t) \leftrightarrow (j\omega)^n X(\omega) \quad n = 1, 2, \dots$
Integration in the time domain	$\int_{-\infty}^t x(\lambda) d\lambda \leftrightarrow \frac{1}{j\omega} X(\omega) + \pi X(0) \delta(\omega)$
Convolution in the time domain	$x(t) * v(t) \leftrightarrow X(\omega) V(\omega)$
Multiplication in the time domain	$x(t)v(t) \leftrightarrow \frac{1}{2\pi} X(\omega) * V(\omega)$
Parseval's theorem	$\int_{-\infty}^{\infty} x(t)v(t) dt = \frac{1}{2\pi} \int_{-\infty}^{\infty} \overline{X(\omega)} V(\omega) d\omega$
Special case of Parseval's theorem	$\int_{-\infty}^{\infty} x^2(t) dt = \frac{1}{2\pi} \int_{-\infty}^{\infty} X(\omega) ^2 d\omega$
Duality	$X(t) \leftrightarrow 2\pi x(-\omega)$

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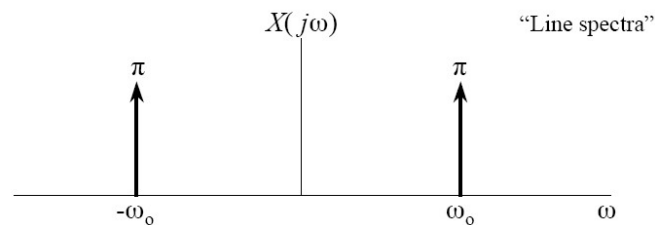
Example: Cosine Function

Example #4:

$$x(t) = \cos \omega_0 t = \frac{1}{2} e^{j\omega_0 t} + \frac{1}{2} e^{-j\omega_0 t}$$

$$\Downarrow$$

$$X(j\omega) = \pi \delta(\omega - \omega_0) + \pi \delta(\omega + \omega_0)$$



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Example: Periodic Pulse Train

Example #5:

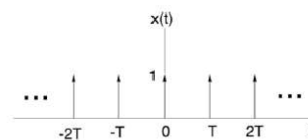
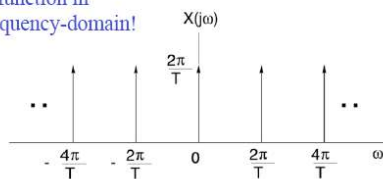
$$x(t) = \sum_{n=-\infty}^{+\infty} \delta(t - nT) \quad \text{— Old friend, sampling function}$$

$$x(t) \longleftrightarrow a_k = \frac{1}{T} \int_{-T/2}^{T/2} x(t) e^{-jk\omega_0 t} dt = \frac{1}{T}$$

$$\Downarrow x(t) = \sum_{k=-\infty}^{+\infty} a_k e^{jk\omega_0 t} = \sum_{k=-\infty}^{+\infty} \frac{1}{T} e^{jk\omega_0 t}$$

$$X(j\omega) = \sum_{k=-\infty}^{+\infty} \frac{2\pi}{T} \delta(\omega - \underbrace{k2\pi}_{k\omega_0})$$

Same function in
the frequency-domain!



Note in this case, periodic
in both time domain (with
a period T) and frequency
domain (with a period
 $2\pi/T$)

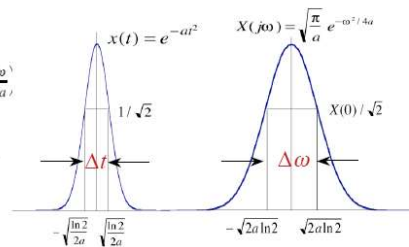
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Example: Gaussian Pulse

Example #4: $x(t) = e^{-at^2}$ — A Gaussian, important in probability, optics, etc.

$$\begin{aligned}
 X(j\omega) &= \int_{-\infty}^{\infty} e^{-at^2} e^{-j\omega t} dt \\
 &= \int_{-\infty}^{\infty} e^{-a \left[t^2 + j\frac{\omega}{a}t + \left(\frac{j\omega}{2a}\right)^2 \right] + a \left(\frac{j\omega}{2a}\right)^2} dt \\
 &= \underbrace{\left[\int_{-\infty}^{\infty} e^{-a \left(t + \frac{j\omega}{2a} \right)^2} dt \right]}_{\sqrt{\pi/a}} \cdot e^{-\frac{\omega^2}{4a}} \\
 &= \sqrt{\frac{\pi}{a}} e^{-\frac{\omega^2}{4a}}
 \end{aligned}$$

Also a Gaussian!



(Pulse width in t) • (Pulse width in ω)
 $\Rightarrow \Delta t \cdot \Delta \omega \sim (1/a)^{1/2} \cdot (a)^{1/2} = 1$

Uncertainty Principle! Cannot make *both* Δt and $\Delta \omega$ arbitrarily small.