

# Smart Traffic Light

Senior Design Presentation

Kelsey Duke

Christopher Buck

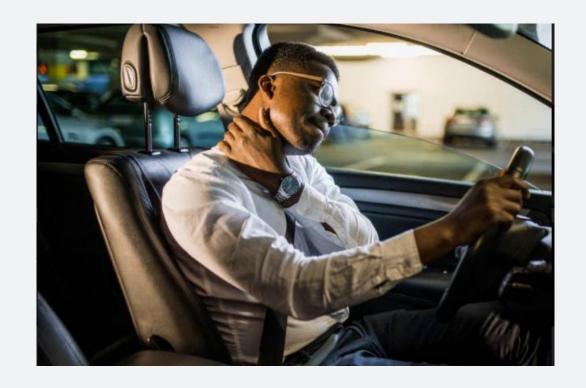
Johnny Lawson

## Team Members

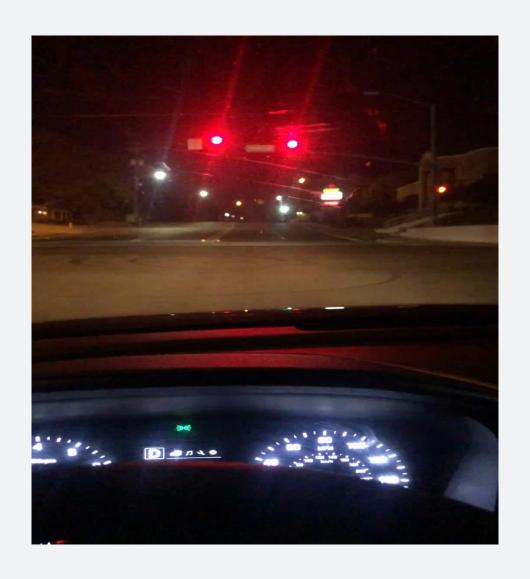
- Kelsey Duke Electrical Engineer
- Johnny Lawson Electrical Engineer
- Christopher Buck Computer Engineer / Computer
   Science

## Overview

- The general idea of this project is to create a smart, density-based traffic system that will always update states to traffic lights from IR sensor data.
   The states of the lights will be determined by the detection of a car by the IR sensor and how many vehicles are detected from the sensors.
- Reduction of Traffic
- Increase in Traffic Safety

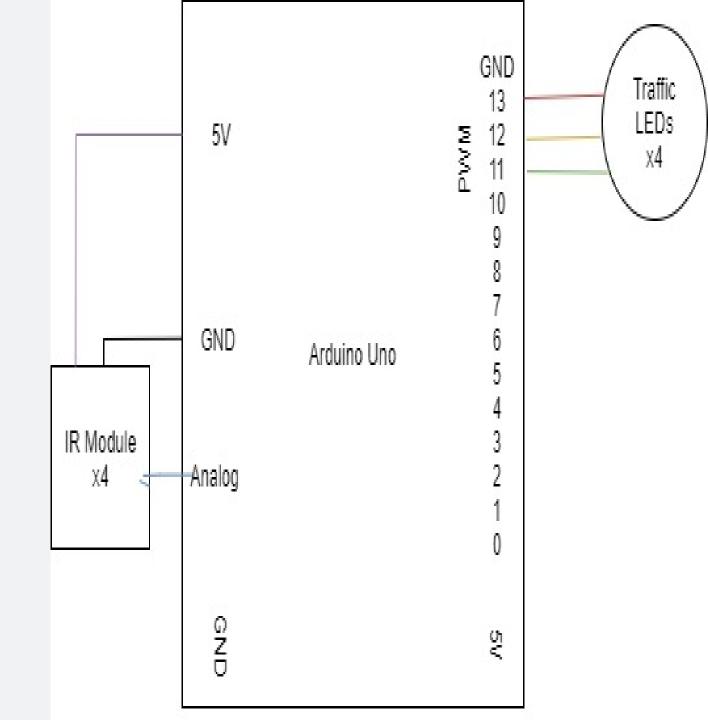


## Overview



## Hardware Diagram

 This is a representation of the hardware components used and how they are interconnected



# \*\*\*\*\*\* ........ ::::::::: fritzing

## Fritzing Diagram

This Fritizing diagram
illustrates the pin out of
the IR sensors and traffic
lights to the
microcontroller.

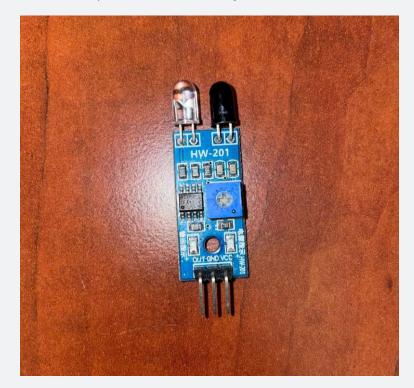
## Hardware

Arduino Uno
 Arduino Uno is a microcontroller board based on the ATmega328P.



IR sensors

The transmitter emits a light that bounces off of objects and is reflected back to the receiver to detect the presence of objects.



## Hardware

Traffic Light LEDs
 The traffic light module contains 3 LEDs in the colors red, yellow, and green to simulate a traffic light



9V Battery

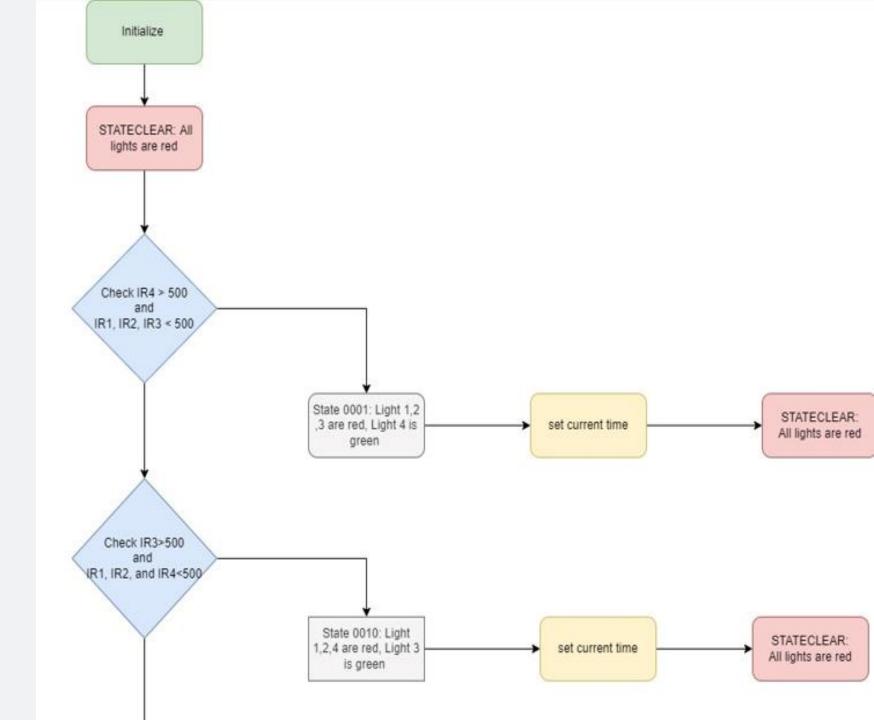
The power source for our project



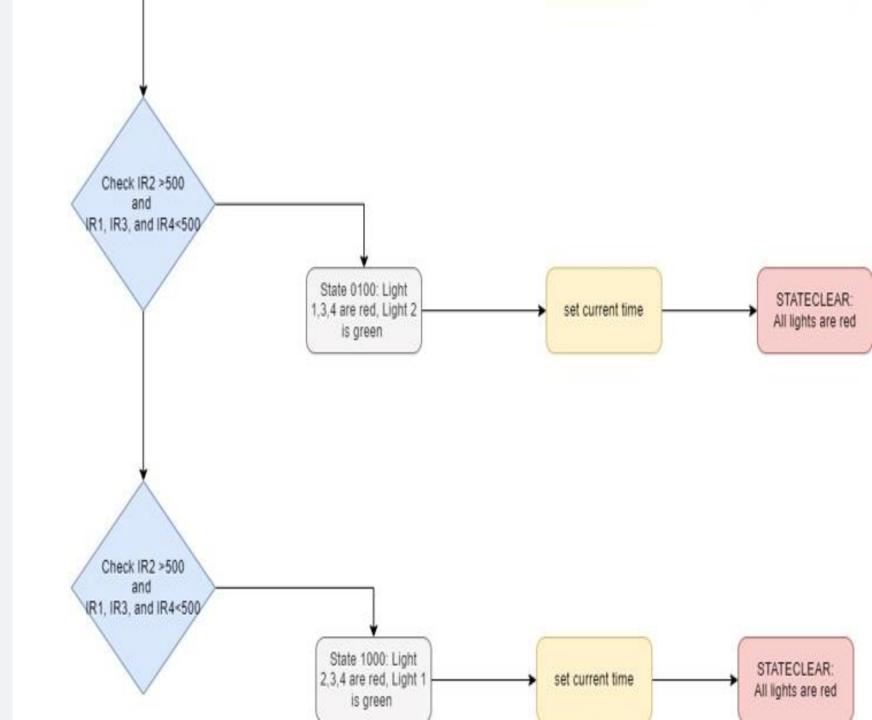
## Power Consumption

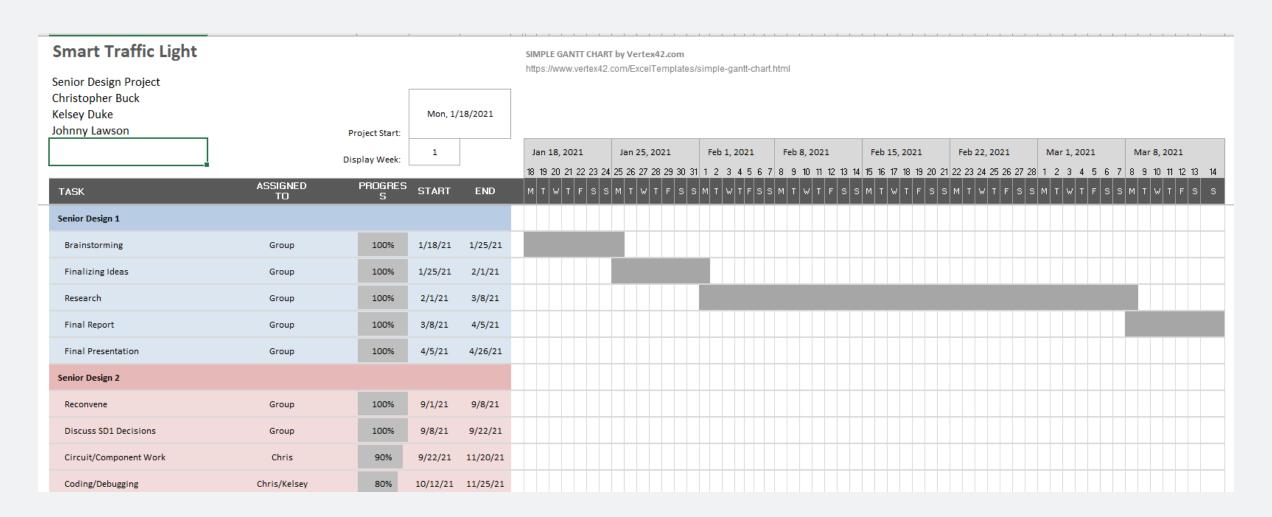
	Arduino Uno	HW-201 IR Sensor	Traffic LEDs	Total
Operating Voltage	3.3V - 5V	3.3V - 5V	3.3V - 5V	5V
Current Requirement	11.45mA	20mA	R/Y = 13mA G = 25mA	70 mA

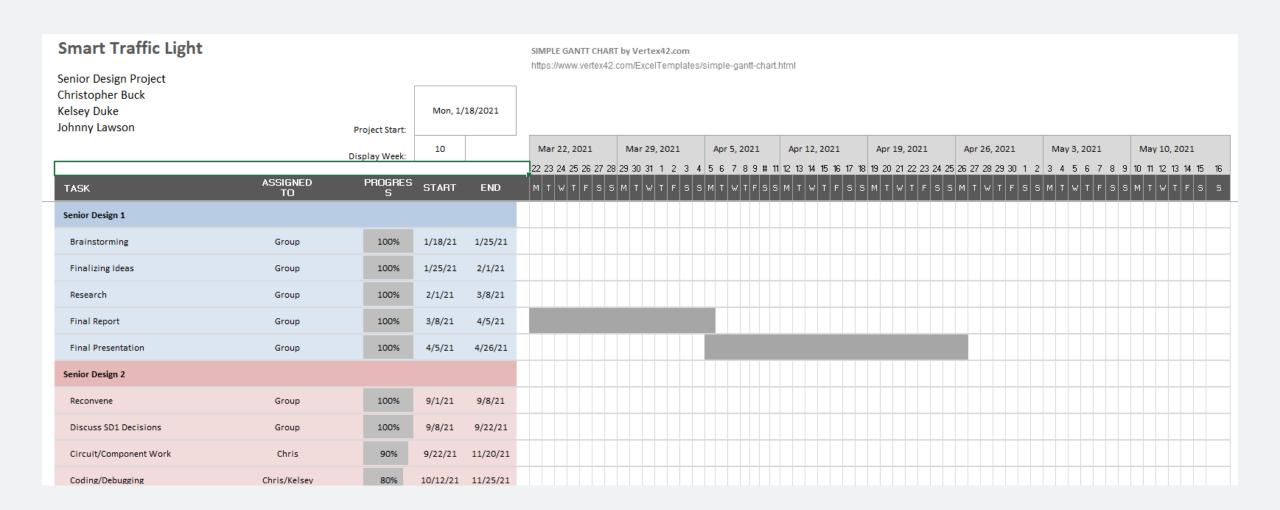
## Software Diagram

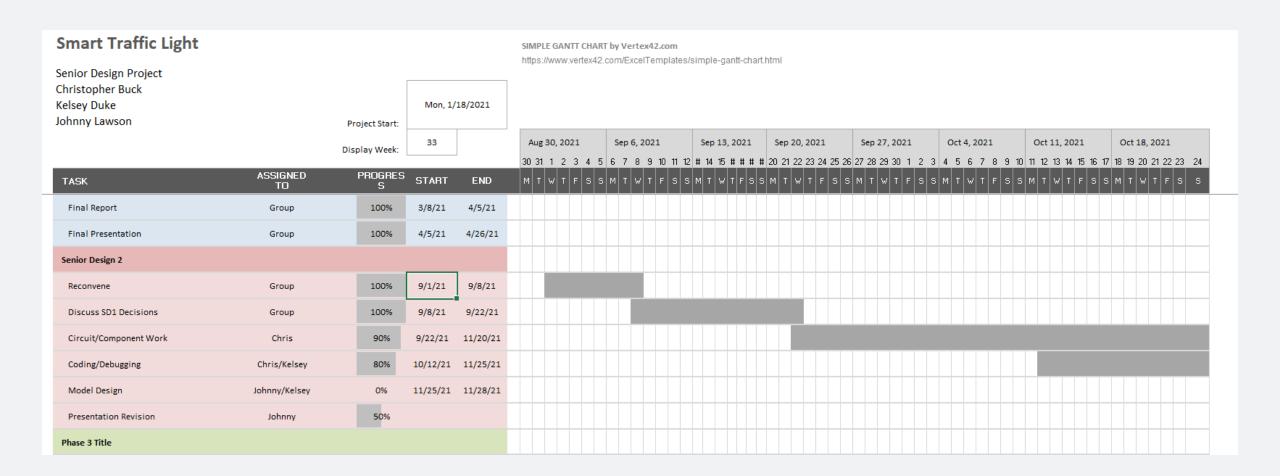


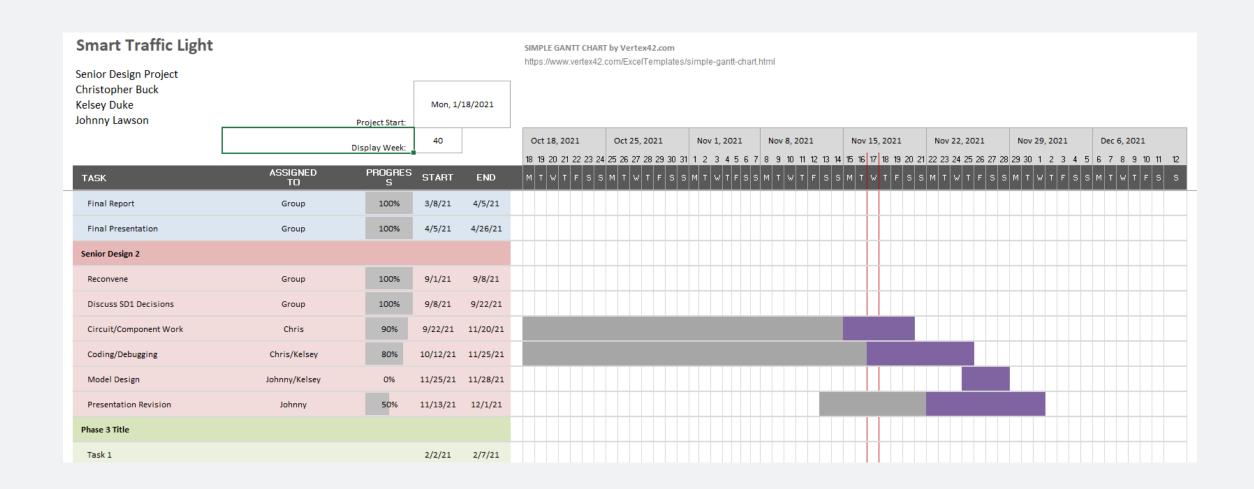
Software Diagram



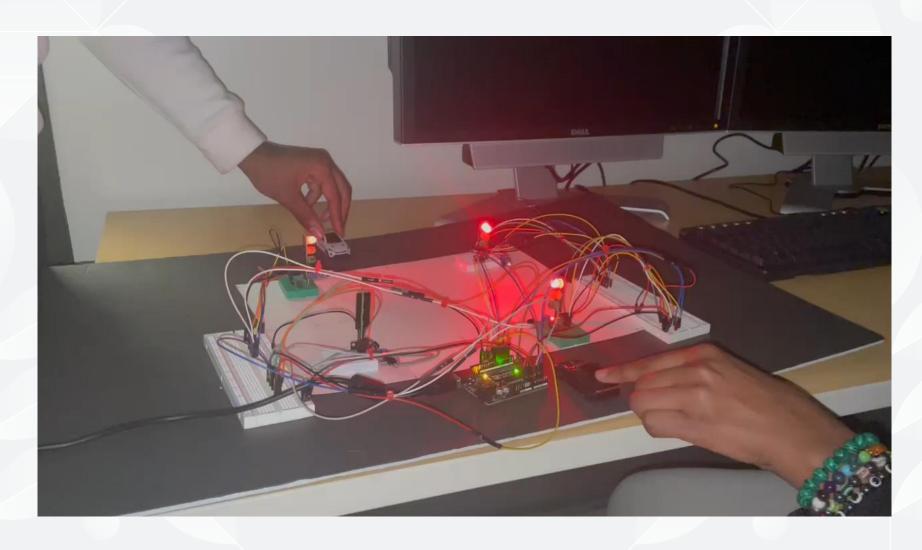






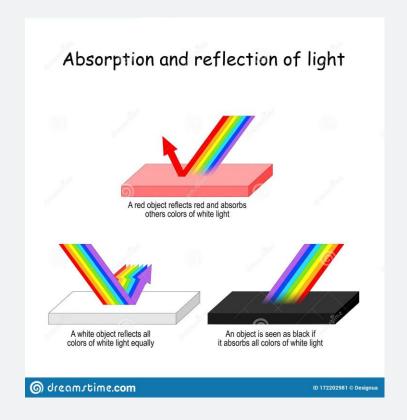


## Video Demonstration



## Important Discoveries

- · Limitation of IR sensors due to science of light
- Limitations of LiDAR and Arduino compatibility





## **Future Works**

Due to time constraints, we were not able to utilize the LiDAR's sensing capabilities as first intended. For future works, we would like to see multiple LiDAR scanners implemented into the system to provide a clearer picture of the traffic intersection. We would also utilize a more powerful processor so that the information received from the LiDAR is easier to work with.



Questions?