

25.1

2) There are no edges between  $i$  and  $i$ , so the weight must be 0.

Staying at a vertex should not add to the length of a path. Zero ensures this.

3) In the problem of shortest path, a weight of  $\infty$  is an annihilator weight. It indicates there is no path between the vertices.  $\infty$  is also the identity for min. And, 0 is the identity for addition. In general matrix multiplication, 0 is the annihilator and I is the identity, so  $L^{(0)}$  could be translated to a matrix with I on the diagonal and 0 off of it, which is the identity matrix I.

4) The important computation happens on line 7,

$$L'_{ij} = \min(L_{ij}, b_{ik} + w_{kj})$$

$$\text{from 25.2, } L_{ij}^{(m)} = \min_{1 \leq k \leq n} \sum_{k=1}^{m-1} (l_{ik}^{(m-1)} + w_{kj})$$

min corresponds to +, so replace min w/  $\sum$ :

$$= [A(BC)]_{ij}$$

$\sum_{k=1}^{m-1} a_{ik} \cdot b_{kj}$

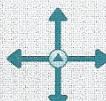
+ corresponds to multiplication in this problem, because it represents the combined edges.

$$= [(AB)C]_{ij}$$

$$\sum_k^n (AB)_{ik} C_{kj} = \sum_k \left( \sum_l^n A_{il} B_{lk} \right) C_{kj}$$

In case of min, the above shows that you can group the mins in any way. So,  $\min_{1 \leq k \leq n} \{ l_{ik}^{(m-1)} + w_{kj} \} = \min_{1 \leq k \leq n} \{ \min_{1 \leq k \leq n} (l_{ik} + w_{kj}) \}$

$$= \min \left\{ \min_{1 \leq k \leq n} (l_{ik} + w_{kj}), \min_{1 \leq k \leq j} (l_{ik} + w_{kj}) \right\}$$



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5)  $\bar{Z}^{n-1} = (X_1, X_2, \dots, X_n)$ , where  $X_j = \text{shortest path } s \rightarrow j$

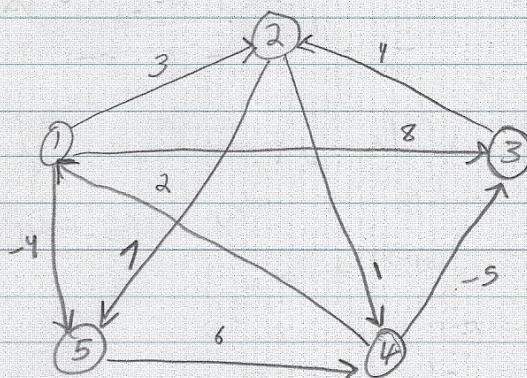
$W = \begin{matrix} & \underset{j}{\overset{i}{\cdots}} \\ i & \left( \begin{matrix} \infty & \cdots & \cdots \\ \vdots & \ddots & \vdots \\ \vdots & \cdots & \infty \end{matrix} \right) \end{matrix}$  weights of the edges  
in the graph

$\bar{Z}^k = (X_1, X_2, \dots, X_n)$ , where  $X_j = \text{wt of min } k\text{-step path from } s \text{ to } j$

to obtain  $\bar{Z}^{n-1}$ , take  $\min_{1 \leq k \leq n} \{ \sum \bar{Z}_k^{(m-1)} + w_{kj} \}$

$$\Rightarrow \sum_{k=1}^n \bar{Z}_k^{(m-1)} \cdot w_{kj}$$

(6)



$$W = \begin{pmatrix} 0 & 3 & \infty & \infty & -4 \\ \infty & 0 & \infty & 1 & 7 \\ \infty & 4 & 0 & \infty & \infty \\ 2 & \infty & -5 & 0 & \infty \\ \infty & \infty & \infty & 6 & 0 \end{pmatrix}$$

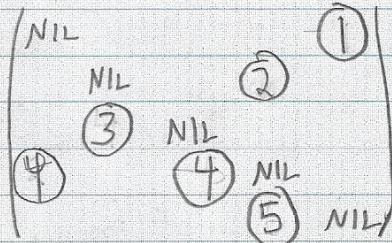
$$\pi_{ij} = \begin{cases} 0 (\text{or NIL}), & i=j \text{ or } l_{ij} = \infty \\ i, & l_{ij} = w_{ij} \\ k, & \text{otherwise} \end{cases}$$

$$L = \begin{pmatrix} 0 & 1 & -3 & 2 & \textcircled{-4} \\ 3 & 0 & -4 & \textcircled{1} & -1 \\ 7 & \textcircled{4} & 0 & 5 & 3 \\ \textcircled{2} & -1 & \textcircled{-5} & 0 & -2 \\ 8 & 5 & 1 & \textcircled{6} & 0 \end{pmatrix}$$

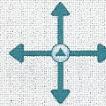
1. Identify edges where  $w_{ij} = l_{ij}$ :

$$\pi_{ij} = i$$

These will be the  $\pi$  values for all other vertices. In the same iteration, set  $\pi_{ij}$  to NIL if either  $i=j$  or  $l_{ij} = \infty$



2. For the remaining empty entries, if only one distinct non-NIL value in the column, set  $\pi_{ij}$  to that value



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- if more than one distinct value exists in the column, compare the L values for the current row and select the min of the L value plus the weight of the candidate predecessor

	1	2	3	4	5
NIL	3	4	<u>5</u>	①	
4	NIL	4	②	1	
4	③	NIL	2	1	
④	3	④	NIL	1	
4	3	4	⑤	NIL	

Example: The example in 25.1 has one column where the choice for predecessor is not trivial. To get to vertex ④, you can either go through ② or ⑤.

Only one distinct value for a direct shortest path to vertex ④, so all other must indirect paths go through it

In column 3 there are two possible predecessors for getting to vertex ④

To solve this, all we need to do is to take the min of  $L_{ij}$  plus wt of last edge. For example,

$$\pi_{14} = \min(L_{12} + w_{24}, L_{15} + w_{54}) = 2 \quad \text{The index of the winning } j \text{ is } \pi_{14}, \text{ so } ⑤, \text{ and } \pi_{34} = \min(L_{32} + w_{24}, L_{35} + w_{54}) = 5, \text{ where } j=2$$

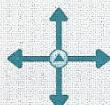
More formally:  $\pi_{ij} = \begin{cases} NIL, i=j \text{ or } L_{ij} = \infty \\ \text{ }, L_{ij} = w_{ij} \\ \min(L_{ik} + w_{kj}), \text{ otherwise, where } k \end{cases}$

Runtime: To get the direct shortest paths (circled above), requires  $n^2$  time to iterate through the L matrix. For determining the rest of the predecessors, you're looking at up to  $n-2$  entries in the matrix (exclude  $i=j$  and self). That adds the third dimension making it  $\Theta(n^3)$

7) In the k for loop for Extend-Shortest-Path, the winning k index will be the predecessor of  $L_{ij}$ .

Extend-Shortest-Path ( $L, \pi, W$ )

- 1  $n = L.\text{rows}$ ; let  $L' = (L'_{ij})$   $n \times n$  matrix; let  $\pi'$  new  $n \times n$  matrix
- 2 for  $i = 1$  to  $n$
- 3 for  $j = 1$  to  $n$
- 4  $L'_{ij} = \infty$ ;  $\pi'_{ij} = \pi_{ij}$
- 5 for  $k = 1$  to  $n$



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6       $L'_{ij} = \min(L'_{ij}, l_{ik} + w_{kj})$   
 7      if  $L'_{ij} = l_{ik} + w_{kj}$  then  
 8           $\pi_{ij} = \pi_{kj}$   
 9      return  $L'$ ,  $\pi'$

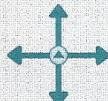
### Slow-all-Pairs-Shortest-Paths( $W$ )

1.  $n = W$ .rows ;  $L'' = W$  ;  $\pi^{(1)}$  new  $n \times n$  matrix  
 2 for  $p = 1$  to  $n$   
 3    for  $q = 1$  to  $n$   
 4      if  $L''_{pq} = \infty$  then  
 5         $\pi''_{pq} = \text{NIL}$   
 6      else  
 7         $\pi''_{pq} = p$   
 8      for  $m = 2$  to  $n-1$   
 9        let  $L^{(m)}$  be a new  $n \times n$  matrix  
 10      let  $\pi^{(m)}$  new  $n \times n$  matrix  
 11       $L^{(m)}, \pi^{(m)} = \text{Extend-Shortest-Paths}(L^{(m-1)}, \pi^{(m-1)}, W)$   
 12 return  $L^{(n-1)}, \pi^{(n-1)}$

### 8) Faster-All-Pairs-Shortest-Paths( $W$ )

1  $n = W$ .rows  
 2  $L = W$   
 3  $L' = W$   
 4  $m = 1$   
 5 while  $m < n-1$   
 6 let  $L = L'$   
 7  $L' = \text{Extended-Shortest-Paths}(L, L)$   
 8  $m = 2m$   
 9 return  $L'$

Since previous matrices are not used, we can overwrite them, only keeping the last one to get the next matrix.



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25.2

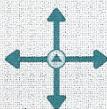
4) At the beginning of each iteration of the k for loop, the D matrix is in the state it needs to be to compute the next step. As line 6 relaxes the paths the two inner loops are always moving forward in the matrix, so modifications to it do not affect further computations. In this way, the D matrix from the previous iteration of k can be recycled.

To use the example from 25.4 :

$$\begin{array}{l}
 \text{already computed} \quad \text{computed} \\
 \begin{array}{c}
 D = \left( \begin{array}{ccccc} 0 & 3 & 8 & \infty & -4 \\ \cancel{\infty} & 0 & \cancel{2} & 1 & 7 \\ \cancel{\infty} & \cancel{4} & 0 & \cancel{2} & \cancel{\infty} \\ \cancel{\infty} & \cancel{5} & -5 & 0 & \cancel{\infty} \\ \cancel{\infty} & \cancel{\infty} & \cancel{\infty} & 6 & 0 \end{array} \right) \rightarrow \left( \begin{array}{ccccc} 0 & 3 & 8 & 4 & -4 \\ 0 & 0 & \cancel{\infty} & 1 & 7 \\ 0 & 4 & 0 & 5 & \cancel{\infty} \\ 2 & 5 & -5 & 0 & \cancel{\infty} \\ 0 & 0 & \cancel{\infty} & 6 & 0 \end{array} \right) \\
 \begin{array}{l}
 K=2 \\
 i=3 \\
 j=4
 \end{array}
 \end{array}
 \end{array}$$

L not yet computed      L not computing

$$d_{34} = \min(d_{34}, d_{32} + d_{24}) = \underline{5}$$



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