



PROFILE

Junior Mechanical Engineer with experience in rapid prototyping and designing in SOLIDWORKS. Strong foundation in programming with MATLAB, Simulink, python and java. Good understanding of sensors, motor drivers and computer vision.

Enthusiastic person towards robot manipulators. Looking for starting a career in robotics development.

CONTACT

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HOBBIES

Work in personal projects involving hardware and software.
Research about personal interest: ROS, Three JS-PyBullet (Javascript), quadruped robots.

KELVIN JARAMILLO

EDUCATION

University of Twente (soon to obtain)

2019-2021/07

Bachelor Mechanical Engineering

Holland International Study Centre

2019/01 – 2019/06

Foundation Year

SENESCYT Scholarship

2018

Obtained a 960/1000 in the standard university entry test, which gave me the chance for a Full scholarship for my bachelor

EXPERIENCE

Mirror-manipulator

Feedforward control-Precision mechatronic system with an elastic guidance (leaf springs)-SOLIDWORKS for designing and Simulink for developing controllers

Robot to travel through maze

PID controllers - Distance sensors for self-guidance

Server-client Collecto board game (JAVA)

Client-Server Socket communication ◦ Given SERVER and protocol to connect-UML diagrams for designing program

Collecto board game (PYTHON) with OpenCV integration

MinMax algorithm-Game developed with PyGame library-OpenCV to interact with game-multithreading used for synchronization

Robotic manipulator for SPE

Robotic toolbox for trajectory generation-Socket communication to connect to Unity 3D environment-PID controller for 2 DOF robotic manipulator (DC motors, Incremental encoders)

SKILLS

Programming: Good foundation for: PYTHON/ JAVA/ MATLAB.

Languages used for project: C#, JavaScript/html, C++ (Arduino)

Modelling: SOLIDWORKS for modelling and SIMULINK for numerical simulations

Sensors/ Circuits and Electronics: 10 weeks course with practical exercises for sensors (distance, force, capacitive, resistance) and 1st and 2nd order electric circuits.