



PROFILE

Junior Mechanical Engineer with good experience in electronics and programming. Strong foundation in with MATLAB, Simulink, python and java. Good understanding of sensors, motor drivers and computer vision.

CONTACT

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INTEREST

- ROS (Robotic Operating System)
- Brushless motors (controllers and drivers)
- Dynamic systems
- Design and prototype
- Logic coding for robotic systems

KELVIN JARAMILLO

EDUCATION

University of Twente

2019-2021/07

Bachelor Mechanical Engineering

Holland International Study Centre

2019/01 – 2019/06

Foundation Year

SENESCYT Full Scholarship

2018

Obtained a 960/1000 in the standard university entry test, which gave me the chance for a Full scholarship for my bachelor

EXPERIENCE

Mirror-manipulator

Feedforward control-Precision mechatronic system with an elastic guidance (leaf springs)-SOLDIWORKS for designing and Simulink for developing controllers

Robot to travel through maze

PID controllers - Distance sensors for self-guidance

Server-client Collecto board game (JAVA)

Client-Server Socket communication ◦ Given SERVER and protocol to connect-UML diagrams for designing program

Collecto board game (PYTHON) with OpenCV integration

MinMax algorithm-Game developed with PyGame library-OpenCV to interact with game-multithreading used for synchronization

Robotic serial manipulator for SPE

2 DOF robotic manipulator with electromagnetic end effector. User interface with Unity to pick objects to be moved from one location to another. I made the controllers, design, prototype, software for communication and trajectory generation.

Cable driven robot for SPE

The 2 DOF serial manipulator was found not feasible for the SPE. Then I worked on a cable driven robot, that uses that same software, controllers and user interface, but using a parallel 2 DOF manipulator

SKILLS

Programming: Good foundation for: PYTHON/ JAVA/ MATLAB.

Languages used for project: C#, JavaScript/html, C++ (Arduino)

Modelling: SOLIDWORKS

Sensors/ Circuits and Electronics: 10 weeks course with practical exercises for sensors (distance, force, capacitive, resistance) and 1st and 2nd order electric circuits.