## **Special Matrices**

# Diagonally Dominant

A matrix is diagonally dominant when

$$|a_{ii}| \ge \sum_{j=1, j \ne i}^{n} |a_{ij}|$$

holes for each i = 1, 2, ..., n.

It is strictly diagonally dominant when,

$$|a_{ii}| > \sum_{j=1, j \neq i}^{n} |a_{ij}|$$

## Symmetric Positive Definite Matrices (SPD)

A matrix A is symmetric positive definite if it is symmetric and if  $x^t Ax > 0$  for every n-dimensional vector  $x \neq 0$ .

If A is an  $n \times n$  SPD matrix, then

- A has an inverse
- $a_{ii} > 0$  for each i = 1, 2, ..., n
- $max_{1 \le k, j \le n} |a_{kj}| \le max_{1 \le i \le n} |a_{ii}|$
- $(a_{ij})^2 < a_{ii}a_{jj}$ , for each  $i \leq j$

The matrix A is positive definite if and only if A can be factored in the form  $LDL^t$ , where L is lower triangular with 1s on its diagonal and D is a diagonal matrix with positive diagonal entries. The matrix A is positive definite if and only if A can be factored in the form  $LL^t$ , where L is lower triangular with nonzero diagonal entries.

# Cholesky $(LL^T)$

### **Tridiagonal**

O(n) time multiplication

#### **Vector Norms**

A vector norm on  $\mathbb{R}^n$  is a function,  $||\cdot||$ , from  $\mathbb{R}^n$  into  $\mathbb{R}$  with the following properties:

- ||x|| > 0 for all  $x \in \mathbb{R}^n$
- ||x|| = 0 if and only if x = 0
- $||\alpha x|| = |\alpha|||x||$  for all  $\alpha \in R$ ,  $x \in R^n$
- $||x + y|| \le ||x|| + ||y||$  for all  $x, y \in \mathbb{R}^n$

The  $l_2$  norm is defined as such:

$$||x||_2 = \left\{\sum_{i=1}^n x_i^2\right\}^{\frac{1}{2}}$$

The  $l_{\infty}$  norm is defined as such:

$$||x||_{\infty} = max_{1 \le i \le n} |x_i|$$

The distance between two vectors is defined as the norm of the difference of the vectors.

A sequence  $\{x^{(k)}\}_{k=1}^{\infty}$  of vectors in  $\mathbb{R}^n$  is said to converge to x with respect to the norm  $||\cdot||$  if, given any  $\epsilon > 0$ , there exists an integer  $N(\epsilon)$  such that

$$||x^{(\epsilon)} - x|| < \epsilon$$
, for all  $k \ge N(\epsilon)$ 

The sequence of vectors  $\{x^{(k)}\}$  converges to x in  $\mathbb{R}^n$  with respect to the  $l_{\infty}$  norm if and only if  $\lim_{k\to\infty}x^{(k)}=x_i$ , for each i=1,2,...,n.

#### **Matrix Norms**

A matrix norm on the set of all  $n \times n$  matrices is a real-valued function,  $||\cdot||$ , defined on this set, satisfying for all  $n \times n$  matrices A and B and all real numbers  $\alpha$ :

- $||A|| \ge 0$
- ||A|| = 0 if and only if A is 0, the matrix with all 0 entries
- $||\alpha A|| = |\alpha|||A||$
- $||A + B|| \le ||A|| + ||B||$
- $||AB|| \le ||A||||B||$

The distance between  $n \times n$  matrices A and B with respect to this matrix norm is ||AB||. If  $||\cdot||$  is a vector norm on  $\mathbb{R}^n$ , then

$$||A|| = max_{||x||=1} ||Ax||$$

is a matrix norm.

For any vector  $z \neq 0$ , matrix A, and any natural norm  $||\cdot||$ , we have

$$||Az|| \leq ||A|| \cdot ||z||$$

If A = (aij) is an  $n \times n$  matrix, then

$$||A||_{\infty} = \max_{1 \le i \le n} \sum_{i=1}^{n} |a_{ij}|$$

(max row sum).

## Spectral Radius

The spectral radius  $\rho(A)$  of a matrix A is defined by

$$\rho(A) = \max |\lambda|$$
, where  $\lambda$  is an eigenvalue of A

## Jacobi Method

The Jacobi method can be written in the form  $x^{(k)} = Tx^{(k-1)} + c$  by splitting A into its diagonal and off-diagonal parts.

$$A = D - L - U$$

So we have,

$$x^{(k)} = D^{-1}(L+U)x^{(k-1)} + D^{-1}b, k = 1, 2, \dots$$

To shorten,

$$T_j = D^{-1}(L+U)$$
 and  $c_j = D^{-1}b$ 

So we have

$$x^{(k)} = T_j x^{(k-1)} + c_j$$

## Gauss-Siedel Method

We have

$$x^{(k)} = (D-L)^{-1}Ux^{(k-1)} + (D-L)^{-1}b$$

Letting

$$T_q = (D - L)^{-1}U$$
 and  $c_q = (D - L)^{-1}b$ 

We get

$$x^{(k)} = T_g x_{(k-1)} + c_g$$

Note: for D-L to be nonsingular, it is necessary and sufficient that  $a_{ii} \neq 0$ .

# Conjugate Gradient Method

Matrix must be positive definite.