

Lecture #14: Trees Summary

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10.5 Trees

- Definitions: circuit-free, tree, trivial tree, forest
- Characterizing trees: terminal vertex (leaf), internal vertex

10.6 Rooted Trees

- Definitions: rooted tree, root, level, height, child, parent, sibling, ancestor, descendant
- Definitions: binary tree, full binary tree, subtree
- Binary tree traversal: breadth-first-search (BFD), depth-first-search (DFS)

10.7 Spanning Trees and Shortest Paths

- Definitions: spanning tree, weighted graph, minimum spanning tree (MST)
- Kruskal's algorithm, Prim's algorithm
- Dijkstra's shortest path algorithm (non-examinable)

Definition: Tree

A **graph** is said to be **circuit-free** iff it has no circuits.

A graph is called a **tree** if it is circuit-free and connected.

A **trivial tree** is a graph that consists of a single vertex.

A graph is called a **forest** iff it is circuit-free and not connected.

Definitions: Terminal vertex (leaf) and internal vertex

Let T be a tree. If T has only one or two vertices, then each is called a **terminal vertex** (or **leaf**). If T has at least three vertices, then a vertex of degree 1 in T is called a **terminal vertex** (or **leaf**), and a vertex of degree greater than 1 in T is called an **internal vertex**.

Summary

10.5 Trees

Lemma 10.5.1

Any non-trivial tree has at least one vertex of degree 1.

Theorem 10.5.2

Any tree with n vertices ($n > 0$) has $n - 1$ edges.

Lemma 10.5.3

If G is any connected graph, C is any circuit in G , and one of the edges of C is removed from G , then the graph that remains is still connected.

Theorem 10.5.4

If G is a connected graph with n vertices and $n - 1$ edges, then G is a tree.

Definitions: Rooted Tree, Level, Height

A **rooted tree** is a tree in which there is one vertex that is distinguished from the others and is called the **root**.

The **level** of a vertex is the number of edges along the unique path between it and the root.

The **height** of a rooted tree is the maximum level of any vertex of the tree.

Definitions: Child, Parent, Sibling, Ancestor, Descendant

Given the root or any internal vertex v of a rooted tree, the **children** of v are all those vertices that are adjacent to v and are one level farther away from the root than v .

If w is a child of v , then v is called the **parent** of w , and two distinct vertices that are both children of the same parent are called **siblings**.

Given two distinct vertices v and w , if v lies on the unique path between w and the root, then v is an **ancestor** of w , and w is a **descendant** of v .

Definitions: Binary Tree, Full Binary Tree

A **binary tree** is a rooted tree in which every parent has at most two children. Each child is designated either a **left child** or a **right child** (but not both), and every parent has at most one left child and one right child.

A **full binary tree** is a binary tree in which each parent has exactly two children.

Definitions: Left Subtree, Right Subtree

Given any parent v in a binary tree T , if v has a left child, then the **left subtree** of v is the binary tree whose root is the left child of v , whose vertices consist of the left child of v and all its descendants, and whose edges consist of all those edges of T that connect the vertices of the left subtree.

The **right subtree** of v is defined analogously.

Summary

10.6 Rooted Trees

Theorem 10.6.1: Full Binary Tree Theorem

If T is a full binary tree with k internal vertices, then T has a total of $2k + 1$ vertices and has $k + 1$ terminal vertices (leaves).

Theorem 10.6.2

For non-negative integers h , if T is any binary tree with height h and t terminal vertices (leaves), then

$$t \leq 2^h$$

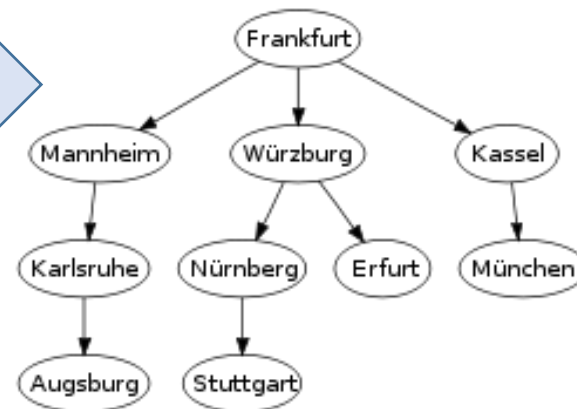
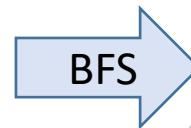
Equivalently,

$$\log_2 t \leq h$$

In breadth-first search (by E.F. Moore), it starts at the root and visits its adjacent vertices, and then moves to the next level.

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graph TD; 1((1)) --- 2((2)); 1 --- 3((3)); 2 --- 4((4)); 2 --- 5((5)); 3 --- 6((6)); 5 --- 7((7)); 6 --- 8((8)); 6 --- 9((9));
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Depth-First Search

There are three types of depth-first traversal:

- **Pre-order**

- Print the data of the root (or current vertex)
- Traverse the left subtree by recursively calling the pre-order function
- Traverse the right subtree by recursively calling the pre-order function

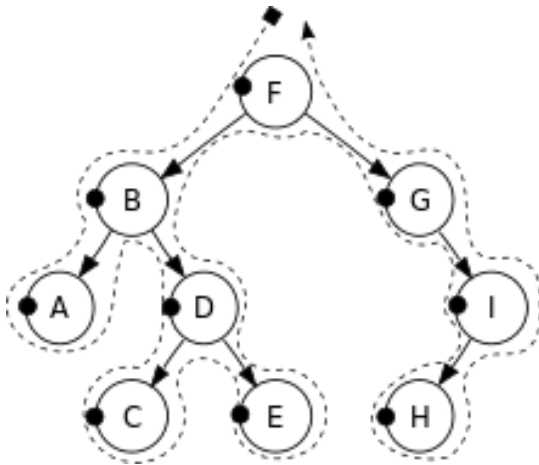
- **In-order**

- Traverse the left subtree by recursively calling the in-order function
- Print the data of the root (or current vertex)
- Traverse the right subtree by recursively calling the in-order function

- **Post-order**

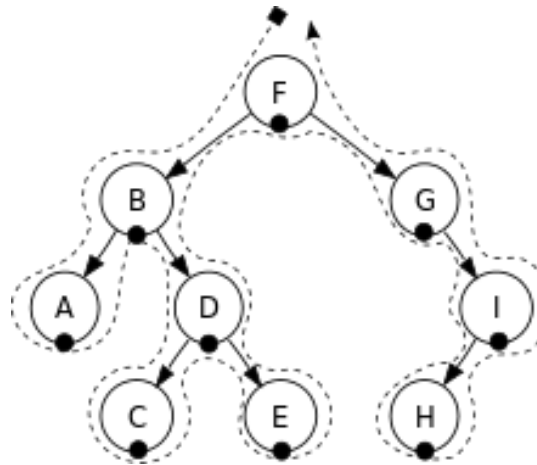
- Traverse the left subtree by recursively calling the post-order function
- Traverse the right subtree by recursively calling the post-order function
- Print the data of the root (or current vertex)

Depth-First Search



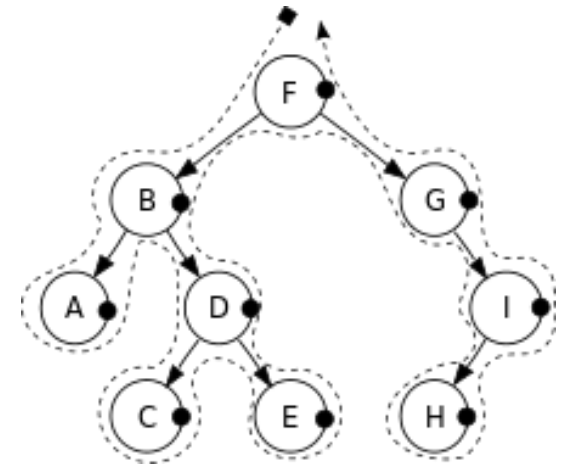
Pre-order:

F, B, A, D, C, E, G, I, H



In-order:

A, B, C, D, E, F, G, H, I



Post-order:

A, C, E, D, B, H, I, G, F

Summary

10.7 Spanning Trees and Shortest Paths

Definition: Spanning Tree

A **spanning tree** for a graph G is a subgraph of G that contains every vertex of G and is a tree.

Proposition 10.7.1

1. Every connected graph has a spanning tree.
2. Any two spanning trees for a graph have the same number of edges.

Definitions: Weighted Graph, Minimum Spanning Tree

A **weighted graph** is a graph for which each edge has an associated positive real number **weight**. The sum of the weights of all the edges is the **total weight** of the graph.

A **minimum spanning tree** for a connected weighted graph is a spanning tree that has the least possible total weight compared to all other spanning trees for the graph.

If G is a weighted graph and e is an edge of G , then $w(e)$ denotes the weight of e and $w(G)$ denotes the total weight of G .

Algorithm 10.7.1 Kruskal

Input: G [a connected weighted graph with n vertices]

Algorithm:

1. Initialize T to have all the vertices of G and no edges.
 2. Let E be the set of all edges of G , and let $m = 0$.
 3. While ($m < n - 1$)
 - 3a. Find an edge e in E of least weight.
 - 3b. Delete e from E .
 - 3c. If addition of e to the edge set of T does not produce a circuit, then add e to the edge set of T and set $m = m + 1$
- End while

Output: T [T is a minimum spanning tree for G]

Algorithm 10.7.2 Prim

Input: G [a connected weighted graph with n vertices]

Algorithm:

1. Pick a vertex v of G and let T be the graph with this vertex only.
2. Let V be the set of all vertices of G except v .
3. For $i = 1$ to $n - 1$
 - 3a. Find an edge e of G such that (1) e connects T to one of the vertices in V , and (2) e has the least weight of all edges connecting T to a vertex in V . Let w be the endpoint of e that is in V .
 - 3b. Add e and w to the edge and vertex sets of T , and delete w from V .

Output: T [T is a minimum spanning tree for G]

Algorithm 10.7.3 Dijkstra

Inputs:

- G [a connected simple graph with positive weight for every edge]
- ∞ [a number greater than the sum of the weights of all the edges in G]
- $w(u, v)$ [the weight of edge $\{u, v\}$]
- a [the source vertex]
- z [the destination vertex]

Algorithm:

1. Initialize T to be the graph with vertex a and no edges.
Let $V(T)$ be the set of vertices of T , and let $E(T)$ be the set of edges of T .
2. $L(a) \leftarrow 0$, and for all vertices u in G except a , $L(u) \leftarrow \infty$.
[The number $L(u)$ is called the **label** of u .]
3. Initialize $v \leftarrow a$ and $F \leftarrow \{a\}$. [The symbol v is used to denote the vertex most recently added to T .]

Algorithm 10.7.3 Dijkstra (continued...)

Let $\text{Adj}(x)$ denote the set of vertices adjacent to vertex x .

4. While ($z \notin V(T)$)

a. $F \leftarrow (F - \{v\}) \cup \{\text{vertices} \in \text{Adj}(v) \text{ and } \notin V(T)\}$

[The set F is the set of fringe vertices.]

b. For each vertex $u \in \text{Adj}(v)$ and $\notin V(T)$,
if $L(v) + w(v, u) < L(u)$ then

$L(u) \leftarrow L(v) + w(v, u)$

$D(u) \leftarrow v$

[The notation $D(u)$ is introduced to keep track of which vertex in T gave rise to the smaller value.]

c. Find a vertex x in F with the smallest label.

Add vertex x to $V(T)$, and add edge $\{D(x), x\}$ to $E(T)$.

$v \leftarrow x$

Output: $L(z)$ [this is the length of the shortest path from a to z .]

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