Chapter 1 - Introduction to Time Series

Basic Definitions

- Definition: A time series is a sequence of information which attaches a time period to each value.
- Definition: A time period is the difference between the start and end time.
- Definition: Frequency refers to how often values of the data set are recorded.
- To analyze time series, all time periods must be equal and clearly defined. This results in a constant frequency.
- Patterns observed in time series are expected to persist in the future.
- Example of time series data: Stock market, weather forecast.
- Time series data suffer from seasonality. (eg. Spring, autumn, summer and winter happen every year)

Notation for Time Series

- ullet For the time period, let t denote a single period and let T denote the entire period.
- Let X denote the value variable. (eg. stock price of S&P 500)
- To denote the value of the value variable at single time period t, write X_t . Then, the value of the value variable at the next time period is X_{t+1} .

Peculiarities of Time Series Data

- Time series intervals need to be constant. Inconsistent intervals may be due to missing data. Missing data needs to be approximated.
- Time series data require chronological data. This means that machine learning model cannot shuffle the data when splitting it. It requires splitting the data based on a specific time period

(ie. Values before the time period are training data while values after the time period are test data).

• Time series graphs do not follow any standard model because they do not follow Gauss-Markov assumption.

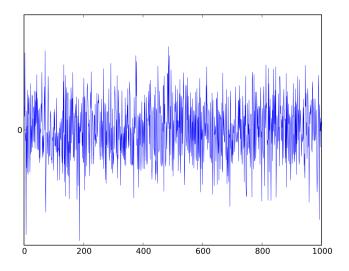
Concepts in Time Series

White Noise

- Definition: White noise is a special type of time series, where the data does not follow any pattern (ie. is random).
- Since it does not follow any pattern, it is unpredictable (ie. Future time step values cannot be predicted using past time steps).
- Definition: Autocorrelation denotes how correlated the time series is with past versions of itself.

$$ho = corr(x_t, x_{t-1})$$

- **▼** Conditions for white noise:
 - Zero mean and constant variance.
 - No autocorrelation (ie. No clear relationship between past and present data).



Random Walk

- Definition: A random walk is a special type of time series where values tend to persist over time and the differences between periods are simply white noise.
- The best estimator for today's value is yesterday's value. The best estimator for tomorrow's value is today's value.
- Suppose that X_t denotes the price at time t, then $X_t=X_{t-1}+\epsilon_t$ where $\epsilon_t-WN(\mu,\sigma^2)$ is a random walk.

Proof:

$$X_t - X_{t-1} = \epsilon_t - \epsilon_{t-1}$$

which is simply white noise.



• If stock market prices are modelled by random walks, then prices cannot be predicted efficiently.

Stationarity

- Definition: A weak form stationarity is satisfied if $cov(S_1)=cov(S_2)$ for two series S_1 and S_2 with the same period, regardless of the starting point.
- **▼** Conditions for weak form stationarity:
 - Constant mean and constant variance.
 - $cov(X_n, x_{n+k}) = cov(x_m, x_{m+k})$
- An example of a stationary time series is white noise.
- Random walks are non-stationary time series.
- Dickey-Fuller test is used to determine if a time series has stationarity.

Seasonality

- ▼ Seasonality in data can be detected by decomposing the data into 3 components:
 - Trend detects pattern in data.
 - Seasonal detects cyclical effects.

- Residual detects error of prediction.
- **▼** Types of naive decomposition:
 - **▼** Additive
 - Observed = Trend + Seasonal + Residual
 - **▼** Multiplicative
 - Observed = Trend * Seasonal * Residual

Autocorrelation Function

Autocorrelation Function (ACF)

- Definition: Autocorrelation function computes the autocorrelation between different lags (ie. current time period and past time period).
- Computes indirect lag.
- Eg. Prices from two days ago affect prices one day ago, which then affect prices today.

Partial Autocorrelation Function (PACF)

- Computes direct lag.
- Definition: PACF at lag k is the autocorrelation between X_t and X_{t-k} that is not accounted for by lags 1 through k-1.
- The ACF measures the accumulated effects past lags have on the current value while PACF measures the direct effect of each lag on the current value.