# Probability Summarization

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## 1.2 Set Relations

**Disjoint:** In a collection of sets, no two of theem have a common element. **Partition:** In a collection of sets which are disjoint and their union is  $\Omega$ .

## 1.3 Set Algebra

Theorem:

Commutative laws:  $A \cup B = B \cup A$ 

**Associative laws:**  $(A \cup B) \cup C = A \cup (B \cup C)$ 

 $(A \cap B) \cap C = A \cap (B \cap C)$ 

**Distributive laws:**  $(A \cup B) \cap C = (A \cap C) \cup (B \cap C)$ 

 $(A\cap B)\cup C=(A\cup C)\cap (B\cup C)$ 

## 2 Counting

## 2.1 The Counting Principle (Multiplication Principle)

Consider a process that consist of r stages, and there are  $n_i$  possible results at the ith stage. Then the total number of possible results of the r-stage process is:

Theorem:

$$n_1 n_2 \cdot \cdot \cdot \cdot \cdot n_r$$

## 2.2 Counting Results

Theorem:

**Permutation**(Distinguishable, without replacement, order matters)

n!

**K-Permutation**(Distinguishable, without replacement, order matters)

$$\frac{n!}{(n-k)!}$$

Combination(Distinguishable, without replacement, order no matters)

$$\binom{n}{k} = \frac{n!}{k!(n-k)!}$$

Partition(Distinguishable, without replacement, order no matters)

$$\binom{n}{n_1, n_2, \cdots, n_r} = \frac{n!}{n_1! n_2! \cdots n_r!}$$

Number of Subsets

 $2^n$ 

## 3 Probability Axioms

#### 3.1 Probability Laws

1. Nonnegativity

$$P(A) \ge 0$$

#### 2. Additivity

If A and B are two disjoint events then:

$$P(A \cup B) = P(A) + P(B)$$

3. Normalization

$$P(\Omega) = 1$$

### 3.2 Some Properties of Probability Laws

- 1. If  $A \subset B$ , then  $P(A) \leq P(B)$
- 2.  $P(A \cup B) = P(A) + P(B) P(A \cap B)$
- 3.  $P(A \cup B) < P(A) + P(B)$

## 4 Conditional Probability

## 4.1 Definition

$$P(A|B) = \frac{P(A \cap B)}{P(B)}$$

## 4.2 Multiplication Rule

Theorem:

$$P\left(\bigcap_{i=1}^{n} = P(A_1)P(A_2|A_1)P(A_3|A_1 \cap A_2)\cdots P(A_n|\bigcap_{i=1}^{n-1} A_i\right)$$

#### 4.3 Total Probability Theorem

Theorem

$$P(B) = P(A_1)P(B|A_1) + P(A_2)P(B|A_2) + \dots + P(A_n)P(B|A_n)$$

#### 4.4 Bayes' Rule

Bayes' rule is often used for inference. There are a number of "cause" that may result in a certain "effect". We observe the effect and we wish to infer the cause. Let  $A_i$  associate with "cause" and B represents "effect".  $P(A_i)$  is called *prior probability* and  $P(A_i|B)$  is called *posterior probability*. What Bayes want to do is to find out posterior probability given prior probability.

#### Bayes' Rule

Let  $A_1, A_2, \dots A_n$  be disjoint events that form a partition of the sample space and assume that  $P(A_i) > 0$ , for all i. Then for any event B we have:

$$P(A_i|B) = \frac{P(A_i)P(B|A_i)}{P(B)}$$

$$= \frac{P(A_i)P(B|A_i)}{P(A_1)P(B|A_1) + \dots + P(A_n)P(B|A_n)}$$

- 4.5 Independence
- 4.5.1 Definition

$$P(A|B) = P(A)$$

- 4.6 Conditioning Independence
- 4.6.1 Definition

$$P(A \cap B|C) = P(A|C)P(B|C)$$

- 4.7 Independence of Events
- 4.7.1 Definition

$$P\left(\bigcap_{i\in B}A_i\right) = \prod_{i\in S}P(A_i)$$

- 5 Discrerte Random Variables
- 5.1 Probability Mass Function
- 5.1.1 Definition

$$P_X(x) = P(X = x)$$

- 5.2 Cumulative Distribution Function
- 5.2.1 Definition

$$F_X(x) = P(X \le x)$$

- 5.3 Expectation
- 5.3.1 Definition

$$E[X] = \sum_{x} x P_X(x)$$

- 5.4 Variance
- 5.4.1 Definition

$$Var[X] = E[(X - E[X])^2] = E[X^2] - (E[X])^2$$

5.4.2 Standard Deviation

**Definition:** 

$$\sigma_X = \sqrt{Var[X]}$$

## 5.5 nth Moment

#### 5.5.1 Definition

$$E[X^n]$$

## 5.6 Functions of Random Variables

Let Y = g(X) then we have:

Theorem:

$$P_Y(y) = \sum_{\{x | g(x) = y\}} P_X(x)$$

## 5.6.1 Expectation for Functions of Random Variables

Theorem:

$$E[g(X)] = \sum_{x} g(x) P_X(x)$$

## 5.6.2 Linear Function of a Random Variable

Let Y = aX + b then:

Theorem:

$$E[Y] = aE[X] + b$$
$$Var[Y] = a^{2}Var[X]$$

#### 5.7 Joint PMF

#### 5.7.1 Definition

$$P_{X,Y}(x,y) = P(X = x, Y = y)$$

## 5.7.2 Marginal PMF

Theorem:

$$P_X(x) = \sum_{y} P_{X,y}(x,y)$$
$$P_Y(y) = \sum_{x} P_{X,y}(x,y)$$

## 5.7.3 Functions of Multiple Random Variable

Let Z = g(X, Y) then:

Theorem:

$$P_{Z}(z) = \sum_{\{(x,y)|g(x,y)=z\}} P_{X,Y}(x,y)$$

$$E[g(x,y)] = \sum_{x} \sum_{y} g(x,y) P_{X,Y}(x,y)$$

$$E[aX + bY + c] = aE[X] + bE[Y] + c$$

## 5.8 Conditional PMF on Events

#### 5.8.1 Definition

$$P_{X|A}(x) = P(X = x|A) = \frac{P(\{X = x\} \cap A)}{P(A)}$$

Theorem:

$$P_X(x) = \sum_{i=1}^{n} P(A_i) P_{X|A_i}(x)$$

## 5.9 Conditional PMF on Random Variable

#### 5.9.1 Definition

$$P_{X|Y}(x|y) = P(X = x|Y = y)$$

$$= \frac{P(X = x, Y = y)}{P(Y = y)}$$

$$= \frac{P_{X,Y}(x,y)}{P_{Y}(y)}$$

Theorem:

$$P_{X,Y}(x,y) = P_Y(y)P_{X|Y}(x|y)$$
  
$$P_X(x) = \sum_{y} P_Y(y)P_{X|Y}(x|y)$$

## 5.10 Conditional Expectation

## 5.10.1 Definition

$$E[X|A] = \sum_{x} x P_{X|A}(x)$$

Theorem:

$$E[g(x)|A] = \sum_{x} g(x) P_{X|A}(x)$$

If  $A_1, A_2, \dots, A_n$  are disjoint partition then:

$$E[X] = \sum_{i=1} P(A_i)E[X|A_i]$$

- 5.11 Independence of a Random Variable from an Event
- 5.11.1 Definition

$$P_{X|A}(x) = P_X(x)$$

- 5.12 Independence of a Random Variable from a Random Variable
- 5.12.1 Definition

$$P_{X|Y}(x|y) = P_X(x)$$

Theorem:

If X and Y are independent then:

$$\begin{split} E[X|Y] &= E[X]E[Y] \\ E[g(X)h(Y)] &= E[g(X)]E[h(Y)] \\ Var[X+Y] &= Var[X] + Var[Y] \end{split}$$

- 5.13 Conditional Independence
- 5.13.1 Definition

$$P_{X,Y|A}(x,y) = P_{X|A}(x)P_{Y|A}(y)$$

- 6 Continuous Random Variable
- 6.1 Probability Density Function(PDF)
- 6.1.1 Definition

$$P(X \in B) = \int_{B} f_{X}(x)dx$$
$$f_{X}(x) isPDF$$

- 6.2 Expectation
- 6.2.1 Definition

$$E[X] = \int_{-\infty}^{\infty} x f_X(x) dx$$

Theorem:

$$E[g(X)] = \int_{-\infty}^{\infty} g(x) f_X(x) dx$$

#### 6.3 Variance

#### 6.3.1 Definition

$$Var[X] = E[(X - E[X])^2]$$

Theorem:

$$Var[X] = \int_{-\infty}^{\infty} (x - E[x])^2 f_X(x) dx$$
$$Var[X] = E[X^2] - (E[X])^2$$

If Y = aX + b then we have:

$$E[Y] = aE[X] + b$$
$$Var[Y] = a^{2}Var[X]$$

## 6.4 Cumulative Distribution Function(CDF)

#### 6.4.1 Definition

$$F_X(x) = P(X \le x) = \begin{cases} \sum\limits_{k \le x} P_X(k) & \text{if X is discrete} \\ \int_{-\infty}^x f_X(t) dt & \text{if X is continuous} \end{cases}$$

## 6.5 Relation Between CDF and PDF

Theorem:

$$f_X(x) = \frac{dF_X(x)}{dx}$$

#### 6.6 Joint PDF

#### 6.6.1 Definition

$$P((X,Y) \in B) = \int \int_{(x,y)\in B} f_{X,Y}(x,y) dxdy$$
$$f_{X,Y}(x,y) isPDF$$

## 6.6.2 Marginal PDF

$$f_X(x) = \int_{-\infty}^{\infty} f_{X,Y}(x,y)dy$$
$$f_Y(y) = \int_{-\infty}^{\infty} f_{X,Y}(x,y)dx$$

## 6.7 Joint CDF

#### 6.7.1 Definition

$$F_{X,Y}(x,y) = P(X \le x, Y \le y)$$
$$= \int_{-\infty}^{x} \int_{-\infty}^{y} f_{X,Y}(s,t)dtds$$

## 6.8 Relation Between Joint CDF and Joint PDF

$$f_{X,Y}(x,y) = \frac{\delta^2 F_{X,Y}(x,y)}{\delta x \delta y}$$

## 6.9 Conditioning a Random Variable on an Event

#### 6.9.1 Definition

$$f_{X|A} = \frac{f_X(x)}{P(X \in A)}$$

If  $A_1, A_2, \dots, A_n$  are disjoint partition, then **Theorem:** 

$$f_X(x) = \sum_{i=1}^{n} P(A_i) f_{X|A_i}(x)$$

#### 6.10 Joint Conditional PDF

#### 6.10.1 Definition

$$f_{X,Y|C}(x,y) = \frac{f_{X,Y}(x,y)}{P(C)}$$

Theorem:

$$f_{X|C}(x) = \int_{-\infty}^{\infty} f_{X,Y|C}(x,y)dy$$

## 6.11 Conditioning a Random Variable on another Random Variable

#### 6.11.1 Definition

$$f_{X|Y}(x|y) = \frac{f_{X,Y}(x,y)}{f_Y(y)}$$

Theorem:

$$P(X \in A|Y = y) = \int_{A} f_{X|Y}(x|y)dx$$

## 6.12 Condition Expectation

## 6.12.1 Definition

$$E[X|A] = \int_{-\infty}^{\infty} x f_{X|A}(x) dx$$
$$E[X|Y=y] = \int_{-\infty}^{\infty} x f_{X|Y}(x|y) dx$$

Theorem:

$$\begin{split} E[g(X)|A] &= \int_{-\infty}^{\infty} g(x) f_{X|A}(x) dx \\ E[g(X)|Y &= y] &= \int_{-\infty}^{\infty} g(x) f_{X|Y}(x|y) dx \end{split}$$

## 6.13 Total Expectation Theorem

$$E[X] = \sum_{i=1}^{n} P(A_i) E[X|A_i]$$
$$E[X|Y=y] = \int_{-\infty}^{\infty} E[X|Y=y] f_Y(y) dy$$

## 6.14 Independence

### 6.14.1 Definition

$$f_{X|Y}(x|y) = f_X(x)$$

If X, Y independent then:

Theorem:

$$f_{X,Y}(x,y) = f_X(x), f_Y(y)$$

$$F_{X,Y}(x,y) = F_X(x)F_Y(y)$$

$$E[XY] = E[X]E[Y]$$

$$E[g(X)h(Y)] = E[g(X)]E[h(Y)]$$

$$Var[X+Y] = Var[X] + Var[Y]$$

## 6.15 Bayes' Rule for Continuous Random Variable

If X is *continuous*, then:

$$f_Y(y)f_{X|Y}(x|y) = f_X(x)f_{Y|X}(y|x)$$

$$and$$

$$f_{X|Y}(x|y) = \frac{f_X(x)f_{Y|X}(y|x)}{f_Y(y)}$$

$$= \frac{f_X(x)f_{Y|X}(y|x)}{\int_{-\infty}^{\infty} f_X(t)f_{Y|X}(y|t)dt}$$

If N is discrete, then:

$$\begin{split} f_Y(y)P(N = n|Y = y) &= P_N(n)f_{Y|N}(y|n) \\ P(N = n|Y = y) &= \frac{P_N(n)f_{Y|N}(y|n)}{f_Y(y)} = \frac{P_N(n)f_{Y|N}(y|n)}{\sum_i P_N(i)f_{Y|N}(y|i)} \\ f_{Y|N}(y|n) &= \frac{f_Y(y)P(N = n|Y = y)}{P_N(n)} = \frac{f_Y(y)P(N = n|Y = y)}{\int_{-\infty}^{\infty} f_Y(t)P(N = n|Y = t)dt} \end{split}$$

## 7 Further Topics on Random Variables

## 7.1 Calculating PDF of Y=g(X) from Continuous RV X

• Step1. Calculate CDF  $F_Y$ 

$$F_Y(y) = P(g(x) \le y) = \int_{\{x | g(x) \le y\}} f_X(x) dx$$

• Step2. Differentiate to obtain PDF  $f_Y$ 

$$f_Y(y) = \frac{dF_Y(y)}{dy}$$

#### 7.2 Convelution

If Z = X + Y, and X, Y are independent.

When discrete:

$$P_Z(z) = \sum_x P_X(x)P_Y(z-x)$$

When continuous:

$$f_Z(z) = \int_{-\infty}^{\infty} f_X(x) f_Y(z-x) dx$$

#### 7.3 Covariance

#### 7.3.1 Definition

$$Cov(X,Y) = E[(X - E[X])(Y - E[Y])]$$
$$= E[XY] - E[X]E[Y]$$

Theorem:

$$Cov(X, X) = Var[X]$$

$$Cov(X, aY + b) = a \cdot Cov(X, Y)$$

$$Cov(X, Y + Z) = Cov(X, Y) + Cov(X, Z)$$

## 7.4 Correlation Coefficient

#### 7.4.1 Definition

$$\rho(X,Y) = \frac{Cov(X,Y)}{\sqrt{Var[X]Var[Y]}} = \frac{Cov(X,Y)}{\sigma_X \sigma_Y}$$

#### 7.5 Variance of the Sum of Random Variables

Theorem:

$$Var[X_1 + X_2] = Var[X_1] + Var[X_2] + 2Cov(X_1, X_2)$$
$$Var\left[\sum_{i=1}^{n} X_i\right] = \sum_{i=1}^{n} Var[X_i] + \sum_{\{(i,j)|i\neq j\}} Cov(X_i, X_j)$$

## 7.6 Conditional Expectation and Variance Revisited

#### 7.6.1 Law of Iterated Expectation

$$E[E[X|Y]] = E[X]$$

#### 7.6.2 Law of Total Variance

$$Var[X] = E[Var[X|Y]] + Var[E[X|Y]]$$

## 7.7 Moment Generating Function

## 7.7.1 Definition

$$M_X(s) = E[e^{sX}]$$

When discrete:

$$M_X(s) = \sum_{x} e^{sx} P_X(x)$$

When continuous:

$$M_X(s) = \int_{-\infty}^{\infty} e^{sx} f_X(x) dx$$

#### Theorem:

If Y = aX + b then we have:

$$M_Y(s) = E[e^{s(aX+b)}] = e^{sb}M_X(sa)$$

#### 7.7.2 From MGF to Moments

$$\left. \frac{d^n M_X(s)}{d_{s^n}} \right|_{s=0} = \int_{-\infty}^{\infty} x^n f_X(x) dx = E[x^n]$$

#### 7.7.3 MGF of Independent Random Variables

#### Theorem:

If X, Y independent , Z = X + Y then:

$$M_Z(s) = M_X(s)M_Y(s)$$

Generalization: If  $Z = X_1 + \cdots + X_n$  then:

$$M_Z(s) = M_{X_1}(s) \cdots M_{X_n}(s)$$

## 8 Limit Theorems

## 8.1 Markov Inequality

If a randown variable X can only take nonnegative values, then:

$$P(X \ge a) \le \frac{E[X]}{a}$$
, for all  $a > 0$ 

## 8.2 Chebyshev's Inequality

If X is a random variable with mean u and variance  $\sigma^2$ , then:

$$P(|X-u| \ge c) \le \frac{\sigma^2}{c^2}$$
, for all  $c > 0$ 

#### Corollary:

Let  $C = k\sigma$  we have:

$$P(|X - u| \ge k\sigma) \le \frac{1}{k^2}$$

## 8.3 The weak law of large numbers

Let  $X_1, X_2, \cdots$  be a sequence of independent identically distributed random variables with mean u, For every  $\varepsilon > 0$ , we have:

$$P(|M_n - u| \ge \varepsilon) = P\left(\left|\frac{X_1 + \dots + X_n}{n} - u\right| \ge \varepsilon\right) \to 0, \ as \ n \to \infty$$

#### 8.4 Convergence in Probability

Let  $Y_1, Y_2, \cdots$  be a sequence of random variables (not necessary independent) and let a be a real number, we say that the sequence  $Y_n$  converges to a in probability, if for every  $\varepsilon > 0$  we have:

$$\lim_{n \to \infty} P(|Y_n - a| \ge \varepsilon) = 0$$

## 8.5 Convergence with Probability 1

Let  $Y_1, Y_2, \cdots$  be a sequence of random variables(not necessary independent) and let c be a real number, we say that  $Y_n$  convergeces to c with probability 1 if:

$$P\left(\lim_{n\to\infty} Y_n = c\right) = 1$$

## 8.6 The Strong Law of Large Numbers

Let  $X_1, X_2, \cdots$  be a sequence of independent identically distributed random variables with mean u. Then, the sequence of sample means  $M_n = (X_1 + \cdots + X_n)/n$  converges to u with probability 1, that is

$$P\left(\lim_{n\to\infty}\frac{X_1+\dots+X_n}{n}=u\right)=1$$

#### 8.7 Central Limit Theorem

Let  $X_1, X_2, \cdots$  be a sequence of independent identically distributed random variables with common mean u and variance  $\sigma^2$ ,

Define  $S_n = \sum_{i=1}^n X_i$  then:

$$\lim_{n \to \infty} P\left(\frac{S_n}{\sigma\sqrt{n}} \le x\right) = \Phi(x) , -\infty < x < \infty$$

## 9 References

1. Introduction to Probability, 2nd Edition, by Dimitri P. Betsekas and John N. Tsitsiklis, 2008, ISBN 978-1-886529-23-6