

## CS 331 Group Project (Component A and B)

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# Chapter 1

## Hierarchical Index

### 1.1 Class Hierarchy

This inheritance list is sorted roughly, but not completely, alphabetically:

bTree< T > . . . . .	7
Node< T > . . . . .	20
InteriorNode< T > . . . . .	11
LeafNode< T > . . . . .	15





## Chapter 2

# Class Index

### 2.1 Class List

Here are the classes, structs, unions and interfaces with brief descriptions:

<a href="#">bTree&lt; T &gt;</a>	<a href="#">7</a>
<a href="#">InteriorNode&lt; T &gt;</a>	<a href="#">11</a>
<a href="#">LeafNode&lt; T &gt;</a>	<a href="#">15</a>
<a href="#">Node&lt; T &gt;</a>	<a href="#">20</a>



## Chapter 3

# File Index

### 3.1 File List

Here is a list of all documented files with brief descriptions:

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Implementation of <a href="#">bTree</a> class . . . . .	27
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## Chapter 4

# Class Documentation

### 4.1 bTree< T > Class Template Reference

#### Public Member Functions

- [bTree](#) ()
- [Node](#)< T > \* [searchLeaf](#) ([Node](#)< T > \*aNodePtr, int keyToFind)
- bool [treeContains](#) (int keyToFind)
- void [printRecord](#) (int key)
- bool [insertRecord](#) (key, value)
- bool [deleteRecord](#) (int key)
- bool [checkTree](#) ([bTree](#) aTree)
- void [rebuildTree](#) ([bTree](#) &aTree)

#### 4.1.1 Constructor & Destructor Documentation

##### 4.1.1.1 `template<class T> bTree< T >::bTree ( )`

Creates a [bTree](#)

#### Precondition

Called onto a interior node

#### Postcondition

Set the child to the node which is being called by

#### 4.1.2 Member Function Documentation

##### 4.1.2.1 `template<class T> bool bTree< T >::checkTree ( bTree< T > aTree )`

Checks the tree to see if it is balanced

#### Precondition

Called onto a interior node

## Parameters

<i>aTree</i>	The tree to be checked
--------------	------------------------

## Postcondition

Returns true or false depending if the tree is balanced or not

4.1.2.2 `template<class T> bool bTree< T>::deleteRecord ( int key )`

Deletes a record from the tree

## Parameters

<i>key</i>	the key corresponding to the record value
------------	---

## Postcondition

Returns true or false depending if the record was successfully deleted

Here is the call graph for this function:

4.1.2.3 `template<class T> bool bTree< T>::insertRecord ( key , value )`

Inserts a key/record pair into the B+ Tree

## Parameters

<i>key</i>	A key used to insert the value into the tree
<i>value</i>	The record to be stored into a Leaf <a href="#">Node</a>

## Precondition

N/A

**Postcondition**

Returns true or false depending if the key/value pair was successfully added

Here is the call graph for this function:



#### 4.1.2.4 template<class T> void bTree< T >::printRecord ( int key )

Prints a record found within the tree

**Precondition**

N/A

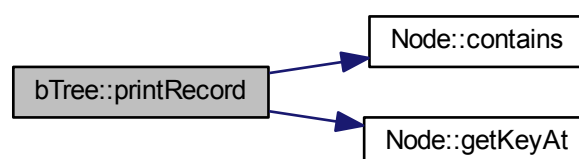
**Parameters**

<i>key</i>	The key to the record that is to be printed
------------	---

**Postcondition**

Print all information about the record

Here is the call graph for this function:



#### 4.1.2.5 template<class T> void bTree< T >::rebuildTree ( bTree< T > & aTree )

Rebuild the tree to be balance

**Precondition**

Tree is currently unbalanced

## Parameters

	post Change the tree to be balanced
--	-------------------------------------

4.1.2.6 `template<class T> Node< T> * bTree< T>::searchLeaf ( Node< T> * aNodePtr, int keyToFind )`

Searches down the tree to find the Leaf [Node](#) corresponding to a key

## Parameters

<i>keyToFind</i>	A key to find within the tree
------------------	-------------------------------

## Precondition

A [treeContains\(\)](#) has been called before this function

## Postcondition

Returns the Leaf [Node](#) containing the key

Here is the call graph for this function:



4.1.2.7 `template<class T> bool bTree< T>::treeContains ( int keyToFind )`

Searches down the tree to see if a key exists within it.

## Parameters

<i>keyToFind</i>	A key to find within the tree
------------------	-------------------------------

## Postcondition

Returns true or false depending on whether the key was found or not

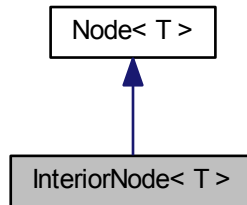
The documentation for this class was generated from the following files:

- C:/Users/Brandon/Desktop/CS 331 Final Project/[bTree.h](#)
- C:/Users/Brandon/Desktop/CS 331 Final Project/[bTree.cpp](#)

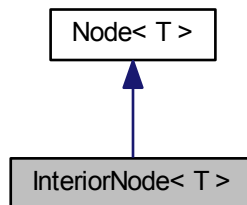


## 4.2 InteriorNode< T > Class Template Reference

Inheritance diagram for InteriorNode< T >:



Collaboration diagram for InteriorNode< T >:



### Public Member Functions

- `InteriorNode ()`
- `InteriorNode (int cap)`
- `InteriorNode (const Node< T > &newCopy)`
- `int getChildSize ()`
- `Node< T > * getChild (int key)`
- `void setChild (Node< T > *newChild, int position)`
- `void removeChild (int position)`
- `int searchKey (int key)`
- `int addKey (int newKey)`
- `void removeKey (int position)`
- `void split (Node< T > *&newNodePtr)`
- `void mergeNodes (Node< T > *&otherNodePtr)`
- `int getSize ()`
- `Node< T > * getParent ()`
- `void setParent (Node< T > *newParentPtr)`
- `int getKeyAt (int position)`
- `bool contains (int key)`

## Additional Inherited Members

### 4.2.1 Constructor & Destructor Documentation

#### 4.2.1.1 `template<class T> InteriorNode< T >::InteriorNode ( )`

Default Constructor for [InteriorNode](#)

##### Postcondition

Creates a interiorNode

#### 4.2.1.2 `template<class T> InteriorNode< T >::InteriorNode ( int cap )`

Default Constructor for [Node](#) with capacity

##### Precondition

Accepts a capacity for a node, depending on what type of node is being created

##### Parameters

<i>cap</i>	capacity of the size in the node
------------	----------------------------------

##### Postcondition

Creates a base [Node](#) for either a leaf node or a interior node with a capacity

#### 4.2.1.3 `template<class T> InteriorNode< T >::InteriorNode ( const Node< T > & newCopy )`

Copy constructor that copies the node that calls it

##### Precondition

Accepts a node to be copied

##### Parameters

<a href="#">Node</a>	to be copied
----------------------	--------------

##### Postcondition

Copies the node that called the constructor

### 4.2.2 Member Function Documentation

#### 4.2.2.1 `template<class T> int InteriorNode< T >::addKey ( int newKey ) [virtual]`

Add a key

##### Precondition

[Node](#) must have room for the new key. `size() <= capacity`

## Parameters

<i>newKey</i>	key that will be entered
---------------	--------------------------

## Postcondition

Return true or false on if the key was successfully added

Implements [Node< T >](#).

Here is the call graph for this function:



#### 4.2.2.2 `template<class T> Node< T > * InteriorNode< T >::getChild ( int key ) [virtual]`

Returns the child where the key located

## Parameters

<i>key</i>	key to be searched for
------------	------------------------

## Postcondition

Returns the node where the key is located

Implements [Node< T >](#).

#### 4.2.2.3 `template<class T> int InteriorNode< T >::getChildSize ( ) [virtual]`

Get size of the node

## Postcondition

Returns the size of the node

Reimplemented from [Node< T >](#).

#### 4.2.2.4 `template<class T> void InteriorNode< T >::mergeNodes ( Node< T > *& otherNodePtr ) [virtual]`

Merge two nodes together

## Parameters

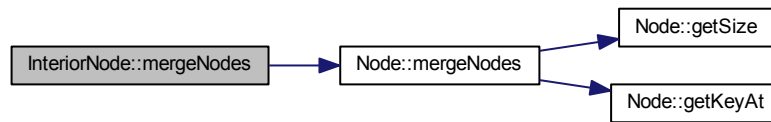
<i>otherNodePtr</i>	Pointer of the node the be merged with
---------------------	--

**Postcondition**

Merges the two nodes together, placing all keys into the orinigal node

Implements [Node< T >](#).

Here is the call graph for this function:



#### 4.2.2.5 `template<class T> void InteriorNode< T>::removeKey ( int position )`

Remove a key

**Precondition**

Key must be located in the node

**Parameters**

<i>position</i>	Location of the key in the vector
-----------------	-----------------------------------

**Postcondition**

Removes the key from the vector

#### 4.2.2.6 `template<class T> int InteriorNode< T>::searchKey ( int key ) [virtual]`

Searches for a key in a node

**Precondition**

Called from a interior node

**Parameters**

<i>key</i>	The key to be searched for
------------	----------------------------

**Postcondition**

Returns the position of the key

Reimplemented from [Node< T >](#).

#### 4.2.2.7 `template<class T> void InteriorNode< T>::setChild ( Node< T> * newChild, int position )`

Sets the child of a node

**Precondition**

Called onto a interior node

## Parameters

<i>newChild</i>	The child to be set
<i>position</i>	Position of the node

## Postcondition

Set the child to the node which is being called by

4.2.2.8 `template<class T> void InteriorNode< T >::split ( Node< T > *& newNodePtr )` [virtual]

Split node

## Parameters

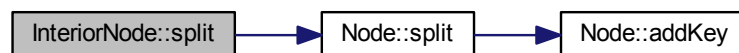
<i>newNodePtr</i>	Pointer to the new node that is being created
-------------------	---

## Postcondition

Splits the node by placing half of the key into a new node

Implements [Node< T >](#).

Here is the call graph for this function:

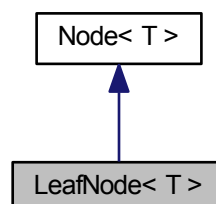


The documentation for this class was generated from the following files:

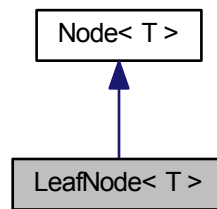
- C:/Users/Brandon/Desktop/CS 331 Final Project/[InteriorNode.h](#)
- C:/Users/Brandon/Desktop/CS 331 Final Project/[InteriorNode.cpp](#)

## 4.3 LeafNode< T > Class Template Reference

Inheritance diagram for LeafNode< T >:



Collaboration diagram for LeafNode< T >:



## Public Member Functions

- [LeafNode](#) ()
- [LeafNode](#) (int cap)
- [LeafNode](#) (const [Node](#)< T > &newCopy)
- int [addKey](#) (int newKey)
- [Node](#)< T > \* [getChild](#) (int key)
- void [setChild](#) ([Node](#)< T > \*newChild, int position)
- void [split](#) ([Node](#)< T > \*&newNodePtr)
- void [mergeNodes](#) ([Node](#)< T > \*&otherNodePtr)
- int [getSize](#) ()
- [Node](#)< T > \* [getParent](#) ()
- void [setParent](#) ([Node](#)< T > \*newParentPtr)
- int [getKeyAt](#) (int position)
- bool [contains](#) (int key)

## Additional Inherited Members

### 4.3.1 Constructor & Destructor Documentation

#### 4.3.1.1 `template<class T> LeafNode< T>::LeafNode ( )`

Default Constructor for [LeafNode](#)

#### Postcondition

Creates a leaf node

#### 4.3.1.2 `template<class T> LeafNode< T>::LeafNode ( int cap )`

Default Constructor for [LeafNode](#)

#### Parameters

---

<i>cap</i>	Capacity of the node
------------	----------------------

**Postcondition**

Creates a leaf node with a set capacity

Here is the call graph for this function:



#### 4.3.1.3 `template<class T > LeafNode< T >::LeafNode ( const Node< T > & newCopy )`

Copy constructor that copies the node that calls it

**Precondition**

Accepts a node to be copied

**Parameters**

<i>Node</i>	to be copied
-------------	--------------

**Postcondition**

Copies the node that called the constructor

### 4.3.2 Member Function Documentation

#### 4.3.2.1 `template<class T > int LeafNode< T >::addKey ( int newKey ) [virtual]`

Add a key

**Precondition**

*Node* must have room for the new key. `size() <= capacity`

**Parameters**

<i>newKey</i>	key that will be entered
---------------	--------------------------

**Postcondition**

Return true or false on if the key was successfully added into the vector of keys

Implements `Node< T >`.

Here is the call graph for this function:



**4.3.2.2** `template<class T> Node<T> * LeafNode<T>::getChild ( int key ) [virtual]`

Returns the child where the key located

Parameters

<i>key</i>	key to be searched for
------------	------------------------

Postcondition

Returns the node where the key is located

Implements [Node<T>](#).

**4.3.2.3** `template<class T> void LeafNode<T>::mergeNodes ( Node<T> *& otherNodePtr ) [virtual]`

Merge two nodes together

Parameters

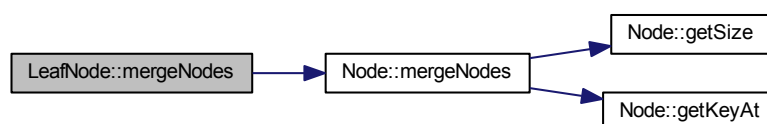
<i>otherNodePtr</i>	Pointer of the node the be merged with
---------------------	--

Postcondition

Merges the two nodes together, placing all keys into the orinigal node

Implements [Node<T>](#).

Here is the call graph for this function:



**4.3.2.4** `template<class T> void LeafNode<T>::setChild ( Node<T> * newChild, int position )`

Sets the child of a node



**Precondition**

Called onto a interior node

**Parameters**

<i>newChild</i>	The child to be set
<i>position</i>	Position of the node

**Postcondition**

Set the child to the node which is being called by

4.3.2.5 `template<class T> void LeafNode< T >::split ( Node< T > *& newNodePtr ) [virtual]`

**Split node****Parameters**

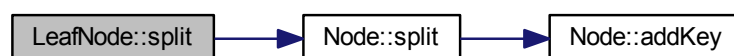
<i>newNodePtr</i>	Pointer to the new node that is being created
-------------------	---

**Postcondition**

Splits the node by placing half of the key into a new node

Implements [Node< T >](#).

Here is the call graph for this function:

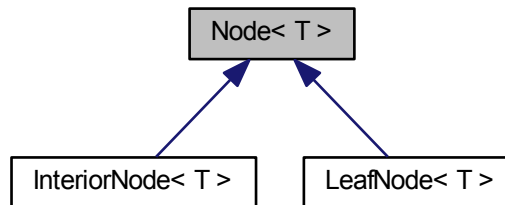


The documentation for this class was generated from the following files:

- C:/Users/Brandon/Desktop/CS 331 Final Project/[LeafNode.h](#)
- C:/Users/Brandon/Desktop/CS 331 Final Project/[LeafNode.cpp](#)

## 4.4 Node< T > Class Template Reference

Inheritance diagram for Node< T >:



### Public Member Functions

- [Node](#) ()
- [Node](#) (int cap)
- [Node](#) (const [Node](#) &newCopy)
- int [getKeyAt](#) (int position)
- virtual int [searchKey](#) (int key)
- virtual int [addKey](#) (int newKey)=0
- [Node](#)< T > \* [getParent](#) ()
- void [setParent](#) ([Node](#)< T > \*newParentPtr)
- int [getSize](#) ()
- virtual int [getChildSize](#) ()
- virtual [Node](#)< T > \* [getChild](#) (int key)=0
- bool [contains](#) (int key)
- virtual void [split](#) ([Node](#)< T > \*&newNodePtr)=0
- virtual void [mergeNodes](#) ([Node](#)< T > \*&otherNodePtr)=0

### Protected Attributes

- vector< int > **keys**
- [Node](#)< T > \* **parentPtr**
- int **capacity**

### 4.4.1 Constructor & Destructor Documentation

#### 4.4.1.1 template<class T > [Node](#)< T >::Node ( )

Default Constructor for [Node](#)

**Postcondition**

Creates a base [Node](#) for either a leaf node or a interior node

Here is the caller graph for this function:

**4.4.1.2 template<class T> Node< T >::Node ( int cap )**

Default Constructor for [Node](#) with capacity

**Precondition**

Accepts a capacity for a node, depending on what type of node is being created

**Parameters**

<i>cap</i>	capacity of the size in the node
------------	----------------------------------

**Postcondition**

Creates a base [Node](#) for either a leaf node or a interior node with a capacity

**4.4.1.3 template<class T> Node< T >::Node ( const Node< T > & newCopy )**

Copy constructor that copies the node that calls it

**Precondition**

Accepts a node to be copied

**Parameters**

<a href="#">Node</a>	to be copied
----------------------	--------------

**Postcondition**

Copies the node that called the constructor

**4.4.2 Member Function Documentation****4.4.2.1 template<class T> int Node< T >::addKey ( int newKey ) [pure virtual]**

Add a key

**Precondition**

[Node](#) must have room for the new key. size() <= capacity

## Parameters

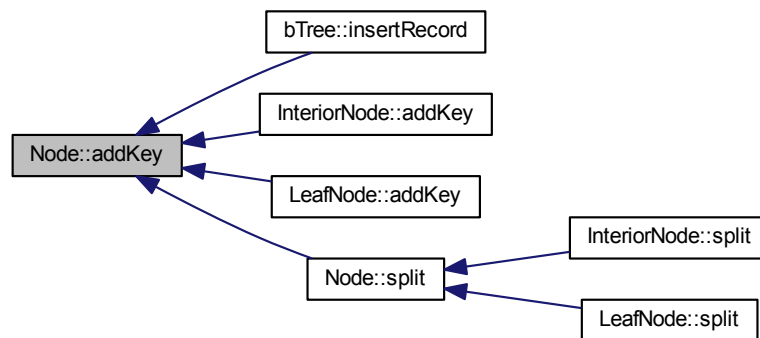
<i>newKey</i>	key that will be entered
---------------	--------------------------

## Postcondition

Return true or false on if the key was successfully added

Implemented in [InteriorNode< T >](#), and [LeafNode< T >](#).

Here is the caller graph for this function:



#### 4.4.2.2 `template<class T> bool Node< T >::contains ( int key )`

Checks to see if a key is contained in the node

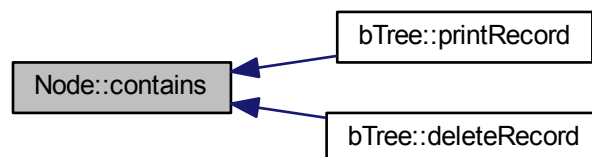
## Parameters

<i>key</i>	key that will be searched for
------------	-------------------------------

## Postcondition

Return true or false depending if the key was found

Here is the caller graph for this function:



#### 4.4.2.3 `template<class T> int Node< T >::getChildSize ( ) [virtual]`

Get the size of the nodes child

##### Postcondition

Return the size the child node

Reimplemented in [InteriorNode< T >](#).

Here is the caller graph for this function:



#### 4.4.2.4 `template<class T> int Node< T >::getKeyAt ( int position )`

Returns the key at its position

##### Precondition

Position must be less than keys.size()

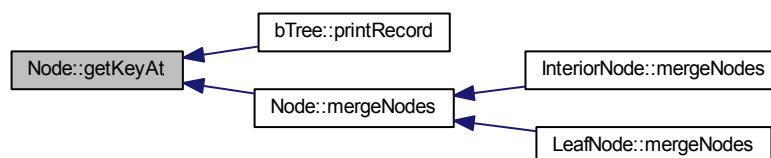
##### Parameters

<i>position</i>	position of key that is being called
-----------------	--------------------------------------

##### Postcondition

Returns the position of the key being searched

Here is the caller graph for this function:



#### 4.4.2.5 `template<class T> Node< T > * Node< T >::getParent ( )`

Get Parent of [Node](#)

**Postcondition**

Return the parent of the node, otherwise will return NULL

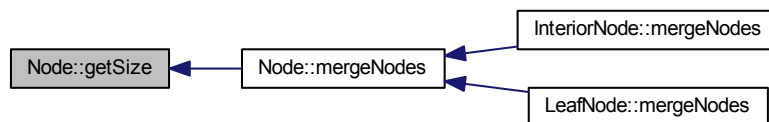
**4.4.2.6** `template<class T> int Node< T >::getSize ( )`

Get the size of the node

**Postcondition**

Return the number of items in the node

Here is the caller graph for this function:

**4.4.2.7** `template<class T> void Node< T >::mergeNodes ( Node< T > *& otherNodePtr )` [pure virtual]

Merge two nodes together

**Parameters**

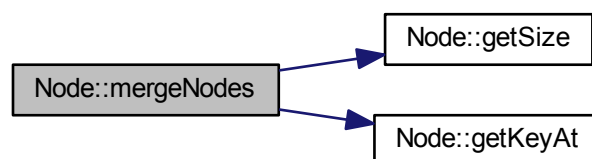
<i>otherNodePtr</i>	Pointer of the node the be merged with
---------------------	--

**Postcondition**

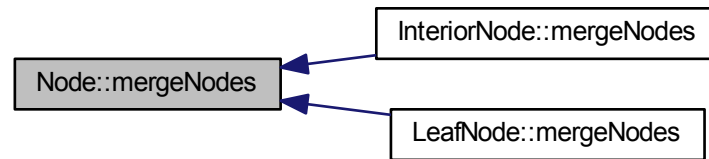
Merges the two nodes together, placing all keys into the orinigal node

Implemented in [InteriorNode< T >](#), and [LeafNode< T >](#).

Here is the call graph for this function:



Here is the caller graph for this function:



4.4.2.8 `template<class T> int Node< T >::searchKey ( int key ) [virtual]`

Search Keys

Parameters

<i>key</i>	key that will be searched for
------------	-------------------------------

Postcondition

Return the position of the key in the vector of keys

Reimplemented in [InteriorNode< T >](#).

4.4.2.9 `template<class T> void Node< T >::setParent ( Node< T > * newParentPtr )`

Set Parent to a [Node](#)

Parameters

<i>newParentPtr</i>	pointer to be set as parent to a node
---------------------	---------------------------------------

Postcondition

Sets the parent to the node to `newParentPtr`

4.4.2.10 `template<class T> void Node< T >::split ( Node< T > *& newNodePtr ) [pure virtual]`

Split [Node](#)

Parameters

<i>newNodePtr</i>	pointer to node that will be split, provided by the B+ Tree class
-------------------	---

Postcondition

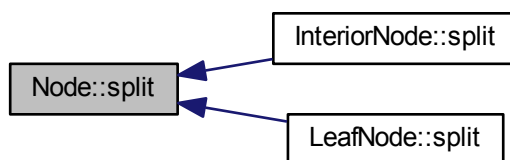
Creates a new node and places half the keys into the new node

Implemented in [InteriorNode< T >](#), and [LeafNode< T >](#).

Here is the call graph for this function:



Here is the caller graph for this function:



The documentation for this class was generated from the following files:

- [C:/Users/Brandon/Desktop/CS 331 Final Project/Node.h](#)
- [C:/Users/Brandon/Desktop/CS 331 Final Project/Node.cpp](#)



## Chapter 5

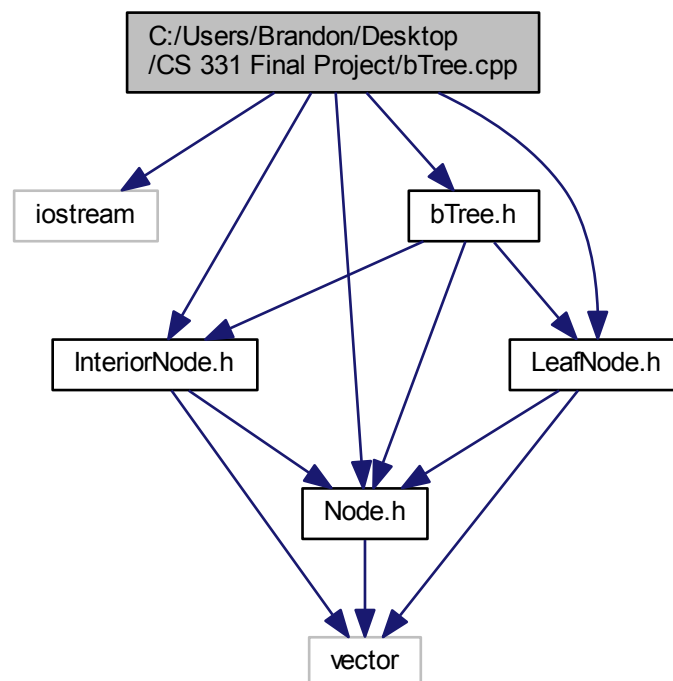
# File Documentation

### 5.1 C:/Users/Brandon/Desktop/CS 331 Final Project/bTree.cpp File Reference

Implementation of `bTree` class.

```
#include <iostream>
#include "Node.h"
#include "InteriorNode.h"
#include "LeafNode.h"
#include "bTree.h"
```

Include dependency graph for `bTree.cpp`:



### 5.1.1 Detailed Description

Implementation of `bTree` class.

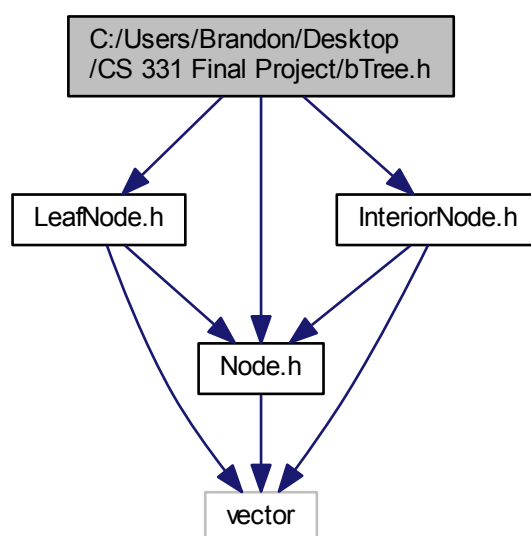
#### Author

Brandon Theisen, Jason Pederson, Kelvin Schutz, Chris Scholl, Jared Kareniemi

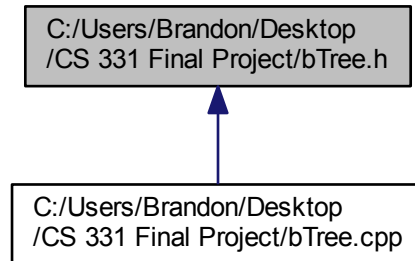
## 5.2 C:/Users/Brandon/Desktop/CS 331 Final Project/bTree.h File Reference

`bTree` class

```
#include "Node.h"  
#include "LeafNode.h"  
#include "InteriorNode.h"  
Include dependency graph for bTree.h:
```



This graph shows which files directly or indirectly include this file:



## Classes

- class `bTree< T >`

### 5.2.1 Detailed Description

`bTree` class

#### Author

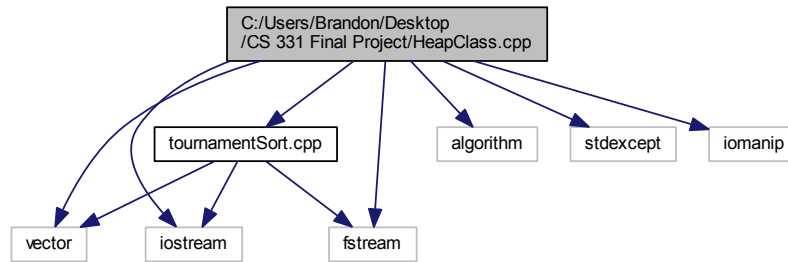
Brandon Theisen, Jason Pederson, Kelvin Schutz, Chris Scholl, Jared Kareniemi

## 5.3 C:/Users/Brandon/Desktop/CS 331 Final Project/HeapClass.cpp File Reference

Replacment Selection Sort.

```
#include <vector>
#include <iostream>
#include <algorithm>
#include <stdexcept>
#include "tournamentSort.cpp"
#include <fstream>
#include <iomanip>
```

Include dependency graph for HeapClass.cpp:



## Functions

- `template<class T >`  
`void activeHeapUp (vector< T > &vect)`
- `template<class T >`  
`void activeHeapDown (vector< T > &vect)`
- `template<class T >`  
`void pendingHeapUp (vector< T > &vect)`
- `void emptyActiveHeap ()`
- `template<class T >`  
`void printVector (vector< T > &vec)`
- `template<class T >`  
`void printVectorList (vector< vector< T > > &vectList)`
- `template<class T >`  
`void emptyActiveHeap (vector< T > &outVect, vector< T > &contVect, vector< vector< T > > &outVectList)`
- `template<class T >`  
`void replacementSort (vector< T > &inputVector, string outputName)`

## Variables

- `int active_heap_size = 0`
- `bool working = true`

### 5.3.1 Detailed Description

Replacment Selection Sort.

#### Author

Brandon Theisen, Jason Pederson, Kelvin Shultz, Chris, Jared

### 5.3.2 Function Documentation

#### 5.3.2.1 `template<class T > void activeHeapDown ( vector< T > & vect )`

Heapify the active heap

**Precondition**

Accepts a vector containing integers or strings

**Parameters**

<i>vect</i>	vector containing integers or strings
-------------	---------------------------------------

**Postcondition**

Sorts the element downwards

Here is the caller graph for this function:

**5.3.2.2** `template<class T> void activeHeapUp ( vector< T> & vect )`

Heapify the active heap so insert smallest element on the top

**Precondition**

Accepts a vector containing integers or strings

**Parameters**

<i>vect</i>	vector containing integers or strings
-------------	---------------------------------------

**Postcondition**

Inserts the smallest element to the top of the active heap

**5.3.2.3** `template<class T> void emptyActiveHeap ( vector< T> & outVect, vector< T> & contVect, vector< vector< T>> & outVectList )`

Heapify the active heap so insert smallest element on the top

**Precondition**

Active heap contains zero elements

Here is the call graph for this function:



#### 5.3.2.4 `template<class T> void pendingHeapUp ( vector< T> & vect )`

Heapify the pending heap

**Precondition**

Accepts a vector containing integers or strings

**Parameters**

<i>vect</i>	vector containing integers or strings
-------------	---------------------------------------

**Postcondition**

Inserts last element to the top of the pending heap

#### 5.3.2.5 `template<class T> void printVector ( vector< T> & vec )`

Prints the vector to output screen

**Precondition**

Accepts a vector containing integers or strings

**Parameters**

<i>vect</i>	vector containing integers or strings
-------------	---------------------------------------

Here is the caller graph for this function:



5.3.2.6 `template<class T> void printVectorList ( vector< vector< T>> & vectList )`

Prints the list of vectors to the output screen

#### Precondition

Accepts a list of vectors containing integers or strings

#### Parameters

<code>vect</code>	vector containing integers or strings
-------------------	---------------------------------------

Here is the call graph for this function:



## 5.4 C:/Users/Brandon/Desktop/CS 331 Final Project/InteriorNode.cpp File Reference

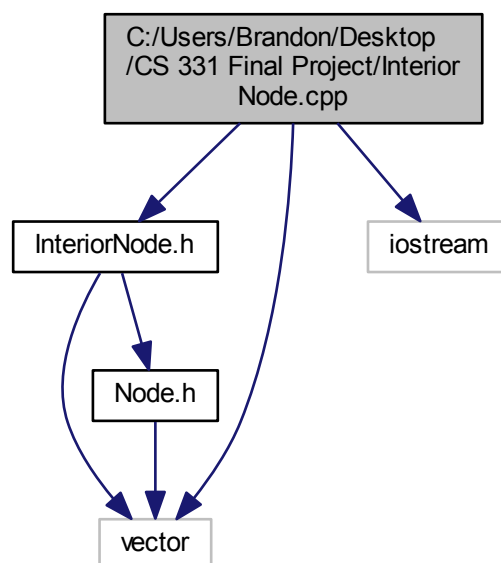
Implementation of [InteriorNode](#) class.

```
#include "InteriorNode.h"
```

```
#include <vector>
```

```
#include <iostream>
```

Include dependency graph for InteriorNode.cpp:



### 5.4.1 Detailed Description

Implementation of [InteriorNode](#) class.

#### Author

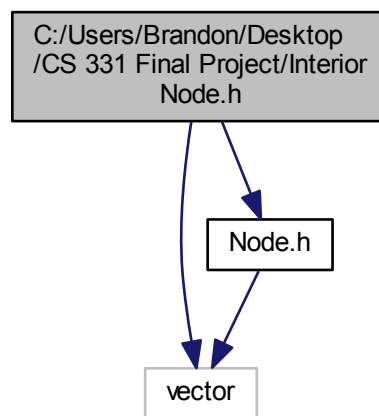
Brandon Theisen, Jason Pederson, Kelvin Shultz, Chris, Jared

## 5.5 C:/Users/Brandon/Desktop/CS 331 Final Project/InteriorNode.h File Reference

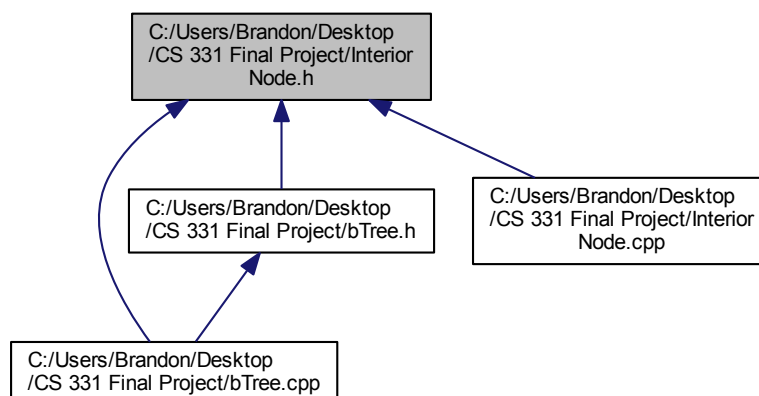
[InteriorNode](#) class.

```
#include <vector>
#include "Node.h"
```

Include dependency graph for InteriorNode.h:



This graph shows which files directly or indirectly include this file:





## Classes

- class [InteriorNode< T >](#)

### 5.5.1 Detailed Description

[InteriorNode](#) class.

#### Author

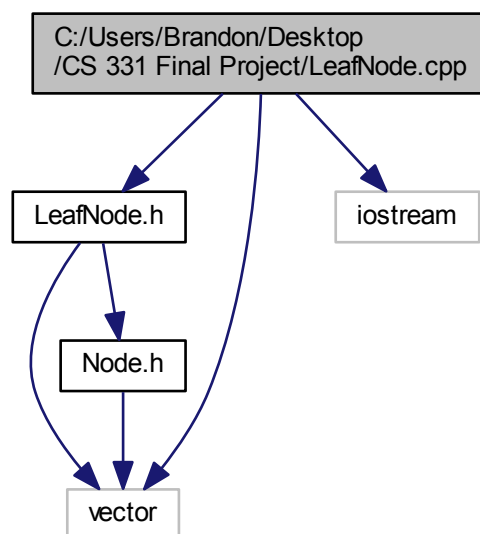
Brandon Theisen, Jason Pederson, Kelvin Shultz, Chris, Jared

## 5.6 C:/Users/Brandon/Desktop/CS 331 Final Project/LeafNode.cpp File Reference

Implementation of [LeafNode](#) class.

```
#include "LeafNode.h"  
#include <vector>  
#include <iostream>
```

Include dependency graph for LeafNode.cpp:



### 5.6.1 Detailed Description

Implementation of [LeafNode](#) class.

#### Author

Brandon Theisen, Jason Pederson, Kelvin Shultz, Chris, Jared

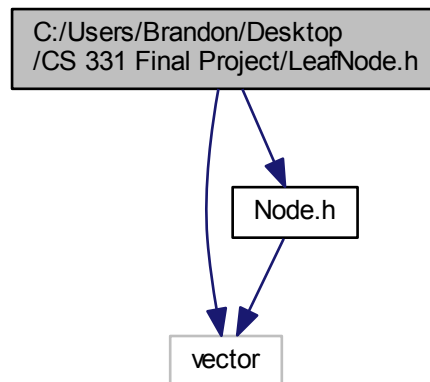
## 5.7 C:/Users/Brandon/Desktop/CS 331 Final Project/LeafNode.h File Reference

[LeafNode](#) class.

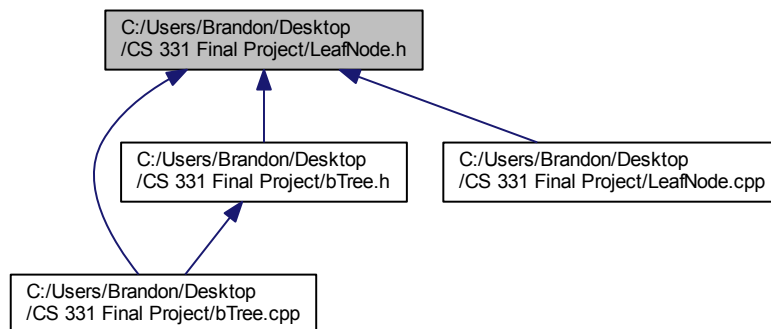
```
#include <vector>
```

```
#include "Node.h"
```

Include dependency graph for LeafNode.h:



This graph shows which files directly or indirectly include this file:



### Classes

- class [LeafNode< T >](#)

### 5.7.1 Detailed Description

[LeafNode](#) class.

**Author**

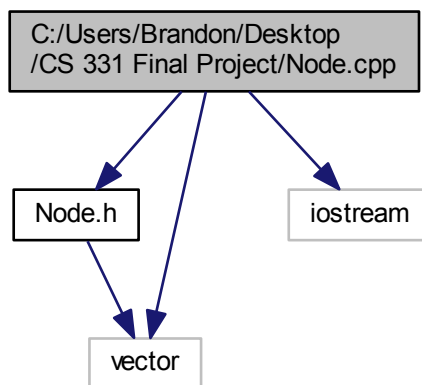
Brandon Theisen, Jason Pederson, Kelvin Shultz, Chris, Jared

## 5.8 C:/Users/Brandon/Desktop/CS 331 Final Project/Node.cpp File Reference

Implementation of base [Node](#) Class.

```
#include "Node.h"  
#include <vector>  
#include <iostream>
```

Include dependency graph for Node.cpp:



### 5.8.1 Detailed Description

Implementation of base [Node](#) Class.

## Author

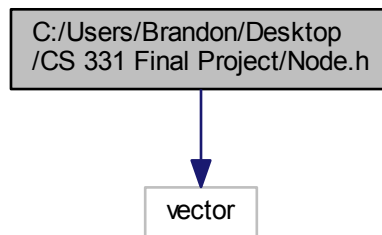
Brandon Theisen, Jason Pederson, Kelvin Shultz, Chris, Jared

## 5.9 C:/Users/Brandon/Desktop/CS 331 Final Project/Node.h File Reference

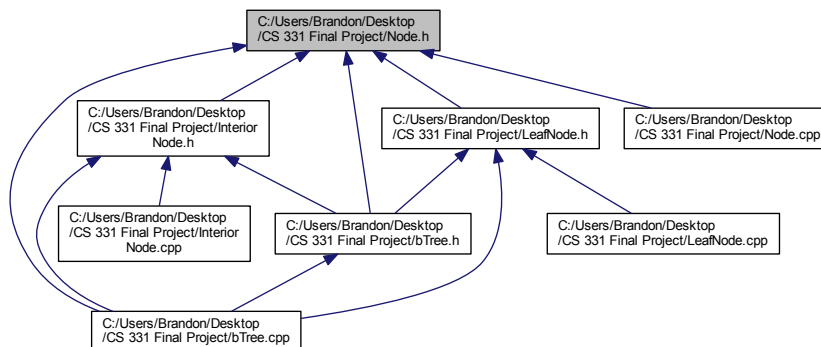
Base [Node](#) Class.

```
#include <vector>
```

Include dependency graph for Node.h:



This graph shows which files directly or indirectly include this file:



### Classes

- class [Node](#)< T >

#### 5.9.1 Detailed Description

Base [Node](#) Class.

## Author

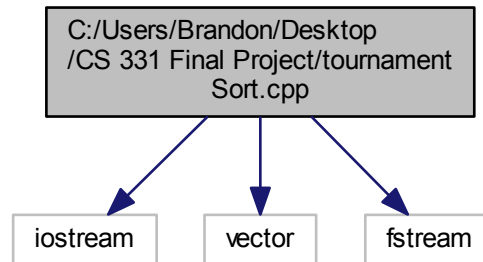
Brandon Theisen, Jason Pederson, Kelvin Shultz, Chris, Jared

## 5.10 C:/Users/Brandon/Desktop/CS 331 Final Project/tournamentSort.cpp File Reference

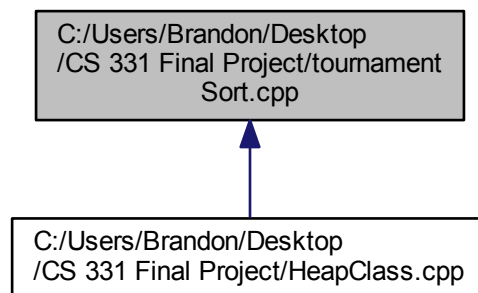
Tournament Sort and Test Program.

```
#include <iostream>
#include <vector>
#include <fstream>
```

Include dependency graph for tournamentSort.cpp:



This graph shows which files directly or indirectly include this file:



### Functions

- `template<class T >`  
`vector< T > tournamentSort (vector< vector< T > > &v)`
- `template<class T >`  
`void printToFile (vector< T > v, ostream &outputFile, string outputName)`
- `template<class T >`  
`void printToFile (vector< T > v, ofstream &outputFile, string outputName)`

### 5.10.1 Detailed Description

Tournament Sort and Test Program.

#### Author

Brandon Theisen, Jason Pederson, Kelvin Shultz, Chris, Jared

### 5.10.2 Function Documentation

#### 5.10.2.1 `template<class T > void printToFile ( vector< T > v, ofstream & outputFile, string outputName )`

Outputs sorted list to file

#### Precondition

Accepts a a vector of a sorted complete list

#### Parameters

<i>v</i>	sorted vector of a complete list of vectors or integers
<i>outputFile</i>	output file to be written to

#### Postcondition

return is void

#### 5.10.2.2 `template<class T > vector< T > tournamentSort ( vector< vector< T > > & v )`

Uses tournament sort to sort a list of vectors

#### Precondition

Accepts a list of vectors that contains sorted integers or strings

#### Parameters

<i>v</i>	vector of vectors that contain sorted integers or strings
----------	---

#### Postcondition

returns a vector of sorted strings or integers

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