

**Exercise 3. Let  $W$  be a walk from  $x$  and  $y$ . Prove that  $W$  contains a path  $P$  from  $x$  and  $y$ . Furthermore, if the edge weights are nonnegative, prove that  $P$ 's total cost is at most  $W$ 's total cost.**

- We can reduce the walk  $W$  to be the path  $P$
- So, with nonnegative edge weights,  $P$ 's total cost is at most  $W$ , both traversing the same set of edges and nodes.

Let  $W$  be a walk from  $x$  to  $y$ . We consider two cases:

[Case 1:  $W$  does not repeat any vertices] Since  $W$  does not repeat any vertices for this case, then it is already a path  $P$ .

[Case 2:  $W$  repeats vertices] Suppose some vertex  $v$  appears at least twice in  $W$ . Consider the first two occurrences of  $v$ . The portion of  $W$  between these occurrences forms a cycle. Removing this cycle yields another walk  $W'$  from  $x$  to  $y$ .

Repeat this process whenever a vertex appears more than once. Each removal shortens the walk, so the process terminates. The resulting walk has no repeated vertices and is therefore a path  $P$  from  $x$  to  $y$ .

Problem 4. Single Source Shortest Path. Given a connected weighted digraph, and a node  $x$ , what is the length of the shortest path from  $x$  to  $y$ , for every node  $y$ ?

Problem 5. Single Destination Shortest Path. Given a connected weighted digraph, and a node  $x$ , what is the length of the shortest path from  $y$  to  $x$ , for every node  $y$ ?

Problem 6. All-Pair Shortest Path. Given a connected weighted digraph, what is the length of the shortest path from  $x$  to  $y$ , for every node  $x$  and every node  $y$ ?

**Exercise 7. Reduce Problem 4 to Problem 5 and vice versa. That is, find an algorithm for Problem 4 assuming you have a magic oracle that can solve instances of Problem 5, and vice versa.**

We can solve SSSP via an SDSP oracle by reversing the graph, then computing the distance to  $x$ , which will be equal to the distance to  $x$ .

To solve SDSP via an SSSP oracle, we do the same: reverse the graph, then compute the distance to every node  $y$ .

**Exercise 8. Reduce Problem 6 to Problem 4 have an algorithm that solves Problem 4 with only a  $\Theta(n)$  overhead. That is, assuming you an algorithm that solve Problem 4 in  $\mathcal{O}(f(n))$  time, find an algorithm that solves Problem 6 in  $\mathcal{O}(n \cdot f(n))$  time.**

We run the SSSP algorithm once per vertex. The  $i$ -th run computes the distances from vertex  $i$  to all others, so running it for all  $n$  nodes would solve Problem 6 since it would yield the distances for all pairs. Since we perform  $n$  runs, the algorithm would run in  $\mathcal{O}(n \cdot f(n))$  time.

**Why do we drop the  $k$  variable in Floyd-Warshall?**

The invariant for Floyd-Warshall's algorithm is: "At the start of iteration  $k$ ,  $d[i][j]$  equals the length of the shortest path from  $i$  to  $j$  whose immediate vertices are  $\{0, 1, \dots, k-1\}$ . Then  $\{0, 1, \dots, k\}$  after iteration  $k$  finishes."

We can update the matrix in place because during iteration  $k$ , we only introduce vertex  $k$  as a new allowed intermediate. Since distances only decrease and don't use vertices beyond  $k$ , the DP invariant remains valid.

**How can we detect cycles in Floyd-Warshall?**

We can detect cycles in Floyd-Warshall by checking whether any diagonal entry is negative. The length of the shortest path from a vertex to itself is 0, so if  $d[i][i] < 0$ , then a negative cycle is reachable from the vertex  $i$ .