

Observer absent

Hypotheses:



Goal:

Learning

Performance



$U_{\text{learn}}(\text{Single})$
(Pull handle only)

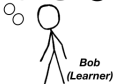
$>$

$U_{\text{learn}}(\text{Double})$
(Pull handle AND
push button)

$U_{\text{learn}}(\text{Single})$

$>$

$U_{\text{learn}}(\text{Double})$



Bob
(Learner)

Observer present

Hypotheses:



Goal:

Learning

Self-presentation



$U_{\text{learn}}(\text{Single})$

$>$

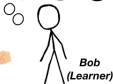
$U_{\text{learn}}(\text{Double})$



Bob: I know exactly
how to make this toy go!



Ann
(Observer)



Bob
(Learner)