SOC Design Laboratory

Lab 5 - Caravel SoC FPGA Integration

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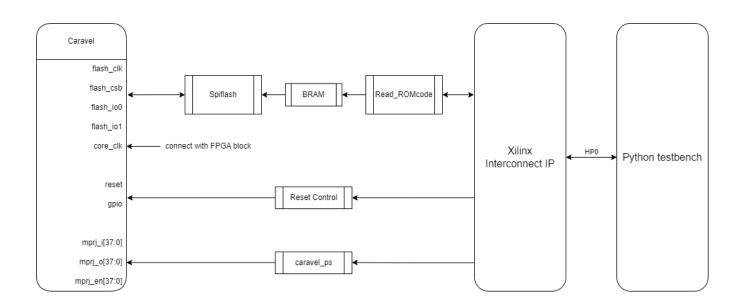
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Block Diagram:

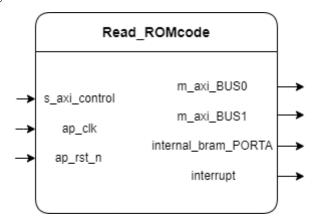
本次 lab 5 主要為三個部分組成,為 Read_ROMcode、Spiflash、Caravel 三部分,下圖是整個 lab 5 的架構圖:

The lab5 architecture:



並且以下展示三個部分的 block diagram。

Read_ROMcode block diagram:

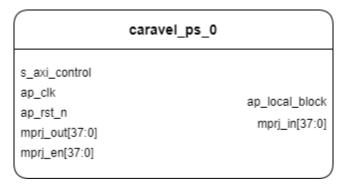


Spiflash block diagram:

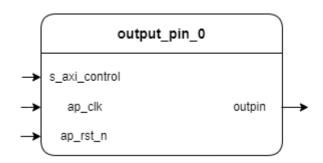
spiflash_0					
ap_clk ap_rst romcode_Dout_A[31:0] csb spiclk lo0[0:0]	romcode_Addr_A[31:0] romcode_EN_A romcode_WEN_A[:31:0] romcode_Din_A[31:0] romcode_Clk_A romcode_Rst_A				
	io1				

Caravel block diagram:

Caravel PS:



Caravel reset control:



FPGA utilization:

Counter utilization:

1. Slice Logic

+	+	++		+
Site Type	Used	Fixed	Prohibited	Available Util%
Slice LUTs LUT as Logic	5327 5149	0 0	0	53200 10.01 53200 9.68
LUT as Memory	178	0	0	17400 1.02
LUT as Distributed RAM LUT as Shift Register	18 160	0 0		
Slice Registers Register as Flip Flop	6051 6051	0 0	0 0	106400 5.69 106400 5.69
Register as Latch F7 Muxes	0 169	0 0	0 0	106400 0.00 26600 0.64
F8 Muxes	47	j 0 j	0	13300 0.35

GCD utilization:

1. Slice Logic

+	+	+	+	+
Site Type	Used	Fixed	Prohibited	Available Util%
+	+	+	+	+
Slice LUTs	6457	0	0	53200 12.14
LUT as Logic	6279	0	0	53200 11.80
LUT as Memory	178	0	0	17400 1.02
LUT as Distributed RAM	18	0		i i
LUT as Shift Register	160	j o	İ	i i
Slice Registers	6082	j o	0	106400 5.72
Register as Flip Flop	6082	j o	j 0	106400 5.72
Register as Latch	0	i o	I 0	106400 0.00
F7 Muxes	168	i o	i 0	26600 0.63
F8 Muxes	47	i o	i 0	13300 0.35
<u>+</u>	+	+	+	+

Explain the function of IP:

HLS IP read romcode:

此 IP 是由 read_romcode.cpp 中設計,主要的功能為使用 AXI-Master 寫入 PS Memory 中,能夠透過 AXI-Master 將 caravel testbench 轉換成的 RISCV code (in hex file)載入至 PS Memory buffer 中。再將 host 端設計的 code 載入至 BRAM 之中,最後將兩者 buffer 中的 content 進行比較是否相同。

Control flow:

讀取 DRAM 中的 ROM code, PS 透過 m_axi_BUSO 給予 address 並且要求讀取,然後此 IP 就會讀取 DRAM ROM code 並且回傳 PS;相反的,寫入 ROM code 時,PS 透過 m_axi_BUS1 給予 address 並且要求寫入,然後此 IP 就會寫入 DRAM ROM code 並且回傳 PS。

HLS IP caravel ps:

此 IP 是由 caravel_ps.cpp 中設計,主要的功能為提供 PS CPU 一個 AXI-Lite interface,因此 PS CPU 能夠讀取 MPRJ_IO/OUT/EN bits。

HLS IP ResetControl:

此 IP 是由 output_pin.cpp 中設計,主要的功能為輸出 1 或 0 以開啟或關閉 Caravel reset pin。並且在提供 PS CPU 與上述不同的一個 AXI-Lite interface,因此 PS CPU 能夠控制 output。

spiflash

此部分為 BRAM 與 Caravel 之間的 SPI interface control。用以暫存 BRAM 輸出資料的 flash 記憶體,並當作 SPI slave 進行資料傳輸,在 CPU 讀取 BRAM 資料時將資料傳輸給 CPU。

FPGA running result

In the first run, select file "counter_wb. hex".

```
npROM_index = 0
npROM_offset = 0
fiROM = open("counter_wb.hex", "r+")
#fiROM = open("counter_la.hex", "r+")
#fiROM = open("gcd la.hex", "r+")
```

And the result is the following, the value at address 0x1c is 0xab61.

```
1 # Check MPRJ_IO input/out/en
 2 # 0x10 : Data signal of ps mprj in
 3 #
             bit 31~0 - ps_mprj_in[31:0] (Read/Write)
 4 # 0x14 : Data signal of ps mprj in
             bit 5~0 - ps_mprj_in[37:32] (Read/Write)
 5 #
 6 #
             others - reserved
 7 # 0x1c : Data signal of ps mprj out
             bit 31~0 - ps_mprj_out[31:0] (Read)
 8 #
 9 # 0x20 : Data signal of ps_mprj_out
             bit 5~0 - ps_mprj_out[37:32] (Read)
10 #
             others - reserved
11 #
12 # 0x34 : Data signal of ps_mprj_en
13 #
             bit 31~0 - ps mprj en[31:0] (Read)
14 # 0x38 : Data signal of ps_mprj_en
15 #
             bit 5~0 - ps_mprj_en[37:32] (Read)
             others - reserved
16 #
17
18 print ("0x10 = ", hex(ipPS.read(0x10)))
19 print ("0x14 = ", hex(ipPS.read(0x14)))
print ("0xlc = ", hex(ipPS.read(0xlc)))
21 print ("0x20 = ", hex(ipPS.read(0x20)))
22 print ("0x34 = ", hex(ipPS.read(0x34)))
23 print ("0x38 = ", hex(ipPS.read(0x38)))
0x10 = 0x0
0x14 =
       0x0
0x1c =
       0xab610008
0x20 = 0x2
0x34 = 0xfff7
0x38 = 0x37
```

In the second run, we select the file "counter_la. hex".

The value at address 0x1c is 0xab51.

```
1 # Check MPRJ IO input/out/en
 2 # 0x10 : Data signal of ps_mprj_in
             bit 31~0 - ps mprj in[31:0] (Read/Write)
 4 # 0x14 : Data signal of ps_mprj_in
             bit 5~0 - ps_mprj_in[37:32] (Read/Write)
             others - reserved
 6 #
 7 # 0x1c : Data signal of ps mprj out
             bit 31~0 - ps mprj out[31:0] (Read)
 9 # 0x20 : Data signal of ps mprj out
10 #
             bit 5~0 - ps_mprj_out[37:32] (Read)
             others - reserved
11 #
12 # 0x34 : Data signal of ps mprj en
           bit 31\sim0 - ps mprj en[\overline{3}1:0] (Read)
13 #
14 # 0x38 : Data signal of ps mpri en
15 #
           bit 5~0 - ps mprj en[37:32] (Read)
16 #
            others - reserved
17
print ("0x10 = ", hex(ipPS.read(0x10)))
print ("0x14 = ", hex(ipPS.read(0x14)))
20 print ("0x1c = ", hex(ipPS.read(0x1c)))
21 print ("0x20 = ", hex(ipPS.read(0x20)))
print ("0x34 = ", hex(ipPS.read(0x34)))
print ("0x38 = ", hex(ipPS.read(0x38)))
0x10 = 0x0
0x1c = 0xab51d56d
0x38 = 0x3f
```

0x14 = 0x00x20 = 0x00x34 = 0x0

Last, select the file "gcd la. hex".

```
npROM index = 0
npROM offset = 0
#fiROM = open("counter_wb.hex", "r+")
#fiROM = open("counter la.hex", "r+")
fiROM = open("gcd la.hex", "r+")
```

The value at address 0x1c is 0xab51.

```
# Check MPRJ IO input/out/en
# 0x10 : Data signal of ps mprj in
         bit 31~0 - ps mprj in[31:0] (Read/Write)
# 0x14 : Data signal of ps mprj in
          bit 5~0 - ps_mprj_in[37:32] (Read/Write)
          others - reserved
# 0x1c : Data signal of ps mprj out
         bit 31~0 - ps mprj out[31:0] (Read)
# 0x20 : Data signal of ps mprj_out
         bit 5~0 - ps mprj out[37:32] (Read)
         others - reserved
# 0x34 : Data signal of ps_mprj_en
          bit 31~0 - ps_mprj_en[31:0] (Read)
# 0x38 : Data signal of ps mprj en
         bit 5~0 - ps mprj en[37:32] (Read)
          others - reserved
print ("0x10 = ", hex(ipPS.read(0x10)))
print ("0x14 = ", hex(ipPS.read(0x14)))
print ("0x1c = ", hex(ipPS.read(0x1c)))
print ("0x20 = ", hex(ipPS.read(0x20)))
print ("0x34 = ", hex(ipPS.read(0x34)))
print ("0x38 = ", hex(ipPS.read(0x38)))
0x10 = 0x0
0x14 = 0x0
0x1c =
        0xab510041
0x20 =
        0x0
0x34 = 0x0
0x38 = 0x3f
```

Results on Jupyter

"counter_wb.hex":

```
In [1]:
            from __future__ import print_function
            import sys
            import numpy as np
from time import time
            import matplotlib.pyplot as plt
            sys.path.append('/home/xilinx')
from pynq import Overlay
from pynq import allocate
            ROM_SIZE = 0x2000 #8K
            ol = Overlay("/home/xilinx/jupyter_notebooks/ipy_fpga/caravel_fpga.bit")
            #ol.ip_dict
            ipOUTPIN = ol.output_pin_0
            ipPS = ol.caravel_ps_0
ipReadROMCODE = ol.read_romcode_0
In [4]:
           # Create np with 8K/4 (4 bytes per index) size and be initiled to 0 rom_size_final = 0
            # Allocate dram buffer will assign physical address to ip ipReadROMCODE
npROM = allocate(shape=(ROM_SIZE >> 2,), dtype=np.uint32)
            # Initial it by 0
            for index in range (ROM_SIZE >> 2):
                npROM[index] = 0
            npROM_index = 0
           npROM_firex = 0
npROM_offset = 0
firOM = open("counter_wb.hex", "r+")
#firOM = open("counter_la.hex", "r+")
#firOM = open("gcd_la.hex", "r+")
            for line in fiROM:
                 # offset header
                 if line.startswith('@'):
                      # Ignore first char @
npROM_offset = int(line[1:].strip(b'\x00'.decode()), base = 16)
npROM_offset = npROM_offset >> 2 # 4byte per offset
                       #print (npROM_offset)
                       npROM index = 0
                       continue
                 #print (line)
                 # We suppose the data must be 32bit alignment
                 bytecount = 0
                 for line_byte in line.strip(b'\x00'.decode()).split():
    buffer += int(line_byte, base = 16) << (8 * bytecount)
                        # Collect 4 bytes, write to npROM
                       if(bytecount == 4):
                           npROM[npROM_offset + npROM_index] = buffer
                            # Clear buffer and bytecount
buffer = 0
                            bytecount = 0
                            npROM_index += 1
                            #print (npROM_index)
                           continue
                 # Fill rest data if not alignment 4 bytes
                 if (bytecount != 0):
                       npROM[npROM_offset + npROM_index] = buffer
                       npROM index += 1
            fiROM.close()
            rom_size_final = npROM_offset + npROM_index
#print (rom_size_final)
            #for data in npROM:
                print (hex(data))
```

```
In [5]: # 0x00 : Control signals
                     bit 0 - ap_start (Read/Write/COH)
bit 1 - ap_done (Read/COR)
                     bit 2 - ap_idle (Read)
bit 3 - ap_ready (Read)
bit 7 - auto_restart (Read/Write)
others - reserved
            # 0x10 : Data signal of romcode
           # bit 31~0 - romcode[31:0] (Read/Write)
# 0x14 : Data signal of romcode
                      bit 31~0 - romcode[63:32] (Read/Write)
            # 0x1c : Data signal of length_r
                      bit 31~0 - length_r[31:0] (Read/Write)
            # Program physical address for the romcode base address
            ipReadROMCODE.write(0x10, npROM.device_address)
           ipReadROMCODE.write(0x14, 0)
# Program Length of moving data
            ipReadROMCODE.write(0x1C, rom_size_final)
           # ipReadROMCODE start to move the data from rom_buffer to bram ipReadROMCODE.write(0x00, 1) # IP Start
            while (ipReadROMCODE.read(0x00) & 0x04) == 0x00: # wait for done
                continue
           print("Write to bram done")
          Write to bram done
```

```
In [6]: # Check MPRJ_IO input/out/en
                # 0x10 : Data signal of ps_mprj_in
               # bit 31-0 - ps_mprj_in[31:0] (Read/Write)
# 0x14 : Data signal of ps_mprj_in
# bit 5-0 - ps_mprj_in[37:32] (Read/Write)
# others - reserved
                # 0x1c : Data signal of ps_mprj_out
                # bit 31~0 - ps_mprj_out[31:0] (Read)
# 0x20 : Data signal of ps_mprj_out
                             bit 5~0 - ps_mprj_out[37:32] (Read)
others - reserved
                # 0x34 : Data signal of ps_mprj_en
               # 0x38 : Data signal of ps_mprj_en[31:0] (Read)
# 0x38 : Data signal of ps_mprj_en
# bit 5~0 - ps_mprj_en[37:32] (Read)
# others - reserved
               print ("0x10 = ", hex(ipPS.read(0x10)))
print ("0x14 = ", hex(ipPS.read(0x14)))
print ("0x1c = ", hex(ipPS.read(0x1c)))
print ("0x20 = ", hex(ipPS.read(0x20)))
print ("0x34 = ", hex(ipPS.read(0x34)))
print ("0x38 = ", hex(ipPS.read(0x38)))
              0x10 = 0x0
               0x14 = 0x0
              0x1c = 0x8
              0x20 = 0x0
               0x34 = 0xfffffff7
              0x38 = 0x3f
In [7]: # Release Caravel reset
                # 0x10 : Data signal of outpin_ctrl
                             bit 0 - outpin_ctrl[0] (Read/Write)
others - reserved
                print (ipOUTPIN.read(0x10))
                ipOUTPIN.write(0x10, 1)
                print (ipOUTPIN.read(0x10))
```

1

```
In [8]: # Check MPRJ_IO input/out/en # 0x10: Data signal of ps_mprj_in [31:0] (Read/Write) # 0x14: Data signal of ps_mprj_in [31:0] (Read/Write) # 0x14: Data signal of ps_mprj_in [37:32] (Read/Write) # others - reserved # 0x1c: Data signal of ps_mprj_out # bit 31-0 - ps_mprj_out [31:0] (Read) # 0x20: Data signal of ps_mprj_out # bit 53-0 - ps_mprj_out [37:32] (Read) # 0x34: Data signal of ps_mprj_en # 0x38: Data signal of ps_mprj_en # 0x39: Dat
```

"counter la.hex":

```
In [1]: from _future__ import print_function

import sys
import numpy as np
from time import time
import matplotlib.pyplot as plt

sys.path.append('/home/xilinx')
from pynq import Overlay
from pynq import allocate

ROM_SIZE = 0x2000 #8K
```

```
In [4]: # Create np with 8K/4 (4 bytes per index) size and be initiled to 0
             rom_size_final = 0
             # Allocate dram buffer will assign physical address to ip ipReadROMCODE npROM = allocate(shape=(ROM_SIZE >> 2,), dtype=np.uint32)
             # Initial it by 0
for index in range (ROM_SIZE >> 2):
                  npROM[index] = 0
             npROM_index = 0
npROM_offset = 0
             #fiROM = open("counter_wb.hex", "r+")
fiROM = open("counter_la.hex", "r+")
#fiROM = open("gcd_la.hex", "r+")
              for line in fiROM:
                   # offset header
                   if line.startswith('@'):
                        # Ignore first char @
npROM_offset = int(line[1:].strip(b'\x00'.decode()), base = 16)
npROM_offset = npROM_offset >> 2 # 4byte per offset
# int (npROM_offset)
npROM_index = 0
                   #print (line)
                   # We suppose the data must be 32bit alignment buffer = 0 \,
                   bytecount = 0
                   bytecount = 0
for line_byte in line.strip(b'\x00'.decode()).split():
    buffer += int(line_byte, base = 16) << (8 * bytecount)
    bytecount += 1</pre>
                            Collect 4 bytes, write to npROM
                         if(bytecount == 4):
                              npROM[npROM_offset + npROM_index] = buffer
# Clear buffer and bytecount
buffer = 0
                               bytecount = 0
                               npROM_index += 1
                               #print (npROM_index)
                              continue
                   # Fill rest data if not alignment 4 bytes
if (bytecount != 0):
                         npROM[npROM_offset + npROM_index] = buffer
                         npROM index += 1
             fiROM.close()
             rom size final = npROM offset + npROM index
             #print (rom_size_final)
             #for data in npROM:
             # print (hex(data))
```

Write to bram done

```
In [6]: # Check MPRJ_IO input/out/en
                                # Check MPKJ_10 input/out/en
# 0x10 : Data signal of ps_mprj_in
bit 31*0 - ps_mprj_in[31:0] (Read/Write)
# 0x14 : Data signal of ps_mprj_in
# bit 5*0 - ps_mprj_in[37:32] (Read/Write)
# others - reserved
                                 # 0x1c : Data signal of ps_mprj_out
bit 31~0 - ps_mprj_out[31:0] (Read)
# 0x20 : Data signal of ps_mprj_out
# bit 5~0 - ps_mprj_out[37:32] (Read)
others - reserved
# 0x34 : Data signal of ps_mprj_each
                                 # bit 31×0 - ps_mprj_en[31:0] (Read)
# 0x38 : Data signal of ps_mprj_en
bit 5×0 - ps_mprj_en[37:32] (Read)
# others - reserved
                                 print ("0x10 = ", hex(ipPS.read(0x10)))
print ("0x14 = ", hex(ipPS.read(0x14)))
print ("0x1c = ", hex(ipPS.read(0x1c)))
print ("0x20 = ", hex(ipPS.read(0x20)))
print ("0x34 = ", hex(ipPS.read(0x34)))
print ("0x38 = ", hex(ipPS.read(0x38)))
                                0x10 = 0x0
                              0x14 = 0x0

0x14 = 0x0

0x1c = 0x8

0x20 = 0x0

0x34 = 0xfffffff7

0x38 = 0x3f
  In [7]: # Release Caravel reset
                                 # 0x10 : Data signal of outpin_ctrl
# bit 0 - outpin_ctrl[0] (Read/Write)
# others - reserved
                                   print (ipOUTPIN.read(0x10))
                                 ipOUTPIN.write(0x10, 1)
print (ipOUTPIN.read(0x10))
In [8]: # Check MPRJ_IO input/out/en
# 0x10 : Data signal of ps_mprj_in
# bit 31~0 - ps_mprj_in[31:0] (Read/Write)
# 0x14 : Data signal of ps_mprj_in
# bit 5~0 - ps_mprj_in[37:32] (Read/Write)
# others - reserved
# others - reserved
                                 # others - reserved
# 0x1c: Data signal of ps_mprj_out
bit 31.00 - ps_mprj_out[31:0] (Read)
# 0x20: Data signal of ps_mprj_out
# bit 5.00 - ps_mprj_out[37:32] (Read)
tenses - reserved
# 0x34: Data signal of ps_mprj_en
# bit 31.00 - ps_mprj_en[31:0] (Read)
# 0x38: Data signal of ps_mprj_en
# bit 5.00 - ps_mprj_en[37:32] (Read)
# others - reserved
                                 print ("0x10 = ", hex(ipPS.read(0x10)))
print ("0x14 = ", hex(ipPS.read(0x14)))
print ("0x1c = ", hex(ipPS.read(0x1c)))
print ("0x20 = ", hex(ipPS.read(0x20)))
print ("0x34 = ", hex(ipPS.read(0x34)))
print ("0x38 = ", hex(ipPS.read(0x38)))
                                0 \times 10 = 0 \times 0
                                0x14 = 0x0
0x1c = 0xab51f9d2
0x20 = 0x0
                                0x34 = 0x0
0x38 = 0x3f
```

"gcd_la.hex":

```
import sys
import numpy as np
from time import time
import matplotlib.pyplot as plt

sys.path.append('/home/xilinx')
from pynq import Overlay
from pynq import allocate

ROM_SIZE = 0x2000 #8K
```

```
In [3]: ipOUTPIN = ol.output_pin_0 ipPS = ol.caravel_ps_0 ipReadROMCODE = ol.read_romcode_0
```

```
In [4]: # Create np with 8K/4 (4 bytes per index) size and be initiled to 0
                rom_size_final = 0
                # Allocate dram buffer will assign physical address to ip ipReadROMCODE
npROM = allocate(shape=(ROM_SIZE >> 2,), dtype=np.uint32)
                 # Initial it by 0
                for index in range (ROM_SIZE >> 2):
    npROM[index] = 0
                npROM_index = 0
                npxUn_index = 0
npxOM_offset = 0
#fiROM = open("counter_wb.hex", "r+")
#fiROM = open("counter_la.hex", "r+")
fiROM = open("gcd_la.hex", "r+")
                for line in fiROM:
                       # offset header
if line.startswith('@'):
                              # Ignore first char @
npROM_offset = int(line[1:].strip(b'\x00'.decode()), base = 16)
npROM_offset = npROM_offset >> 2 # 4byte per offset
                              #print (npROM_offset)
npROM_index = 0
                              continue
                       #print (line)
                        # We suppose the data must be 32bit alignment
                       buffer = 0
                        bytecount = 0
                      bytecount = 0
for line_byte in line.strip(b'\x00'.decode()).split():
   buffer += int(line_byte, base = 16) << (8 * bytecount)
   bytecount += 1
# Collect 4 bytes, write to npROM
   if(bytecount == 4):
        npROM[npROM_offset + npROM_index] = buffer
        # Clear buffer and bytecount
        buffer = 0
        bytecount = 0</pre>
                                     bytecount = 0
npROM_index += 1
                                      #print (npROM_index)
                                     continue
                       # Fill rest data if not alignment 4 bytes
if (bytecount != 0):
                              npROM[npROM_offset + npROM_index] = buffer
                              npROM index += 1
                fiROM.close()
                rom_size_final = npROM_offset + npROM_index
#print (rom_size_final)
                #for data in npROM:
                # print (hex(data))
```

```
In [5]:
# 0x00 : Control signals
# bit 0 - ap_start (Read/Write/COH)
# bit 1 - ap_done (Read/COR)
# bit 2 - ap_idle (Read)
# bit 3 - ap_ready (Read)
# bit 3 - ap_ready (Read)
# bit 7 - auto_restart (Read/Write)
# others - reserved
# 0x10 : Data signal of romcode
# bit 31-0 - romcode[31:0] (Read/Write)
# 0x14 : Data signal of romcode
# bit 31-0 - romcode[63:32] (Read/Write)
# 0x15 : Data signal of length_r
# bit 31-0 - romcode[63:32] (Read/Write)
# 0x1c : Data signal of length_r
# bit 31-0 - romcode base address
ipReadROMCODE.write(0x14, 0)
# Program physical address for the romcode base address
ipReadROMCODE.write(0x14, 0)
# Program length of moving data
ipReadROMCODE.write(0x14, 0)
# Program length of moving data
ipReadROMCODE.write(0x14, 0)
# ipReadROMCODE start to move the data from rom_buffer to bram
ipReadROMCODE.write(0x00, 1) # IP Start
while (ipReadROMCODE.write(0x00, 1) # IP Start
while (ipReadROMCODE.write(0x00, 1) # IP Start
while (ipReadROMCODE.wraed(0x00, 0x04) == 0x00: # wait for done
continue

print("Write to bram done")
```

Write to bram done

```
In [6]: # Check MPRJ_IO input/out/en
                                     # Check runn_ 10 input/out/en
# 0x10 : Data signal of ps mprj in
bit 31~0 - ps mprj in[31:0] (Read/Write)
# 0x14 : Data signal of ps mprj in
bit 5~0 - ps mprj in[37:32] (Read/Write)
others - reserved
#
                                      # others - reserved
# 0x1c : Data signal of ps_mprj_out
bit 31*0 - ps_mprj_out[31:0] (Read)
# 0x20 : Data signal of ps_mprj_out
# bit 5*0 - ps_mprj_out[37:32] (Read)
others - reserved
# 0x34 : Data signal of ps_mprj_en
bit 31*0 - ps_mprj_en[31:0] (Read)
# 0x38 : Data signal of ps_mprj_en
bit 5*0 - ps_mprj_en[37:32] (Read)
# others - reserved
                                      print ("0x10 = ", hex(ipPS.read(0x10)))
print ("0x14 = ", hex(ipPS.read(0x14)))
print ("0x1c = ", hex(ipPS.read(0x1c)))
print ("0x20 = ", hex(ipPS.read(0x20)))
print ("0x34 = ", hex(ipPS.read(0x34)))
print ("0x38 = ", hex(ipPS.read(0x38)))
                                     0x10 = 0x0
                                    0 \times 14 = 0 \times 0
                                   0x14 = 0x0

0x1c = 0x8

0x20 = 0x0

0x34 = 0xfffffff7

0x38 = 0x3f
       In [7]:
                                     # Release Caravel reset
# 0x10 : Data signal of outpin_ctrl
# bit 0 - outpin_ctrl[0] (Read/Write)
# others - reserved
                                        print (ipOUTPIN.read(0x10))
                                        ipOUTPIN.write(0x10, 1)
                                        print (ipOUTPIN.read(0x10))
In [8]:

# Check MPRJ_IO input/out/en

# 0x10 : Data signal of ps_mprj_in

# bit 31~0 - ps_mprj_in[31:0] (Read/Write)

# 0x14 : Data signal of ps_mprj_in

# bit 5~0 - ps_mprj_in[37:32] (Read/Write)

others - reserved

**Corta signal of ps_mprj_out
                                    # otners - reserved
# 0x1c: Data signal of ps_mprj_out
bit 31-0 - ps_mprj_out[31:0] (Read)
# 0x20: Data signal of ps_mprj_out
bit 5~0 - ps_mprj_out[37:32] (Read)
# others - reserved
                                    # others - reserved
# 0x34 : Data signal of ps_mprj_en
bit 31~0 - ps_mprj_en[31:0] (Read)
# 0x38 : Data signal of ps_mprj_en
bit 5~0 - ps_mprj_en[37:32] (Read)
# others - reserved
                                    print ("0x10 = ", hex(ipPS.read(0x10)))
print ("0x14 = ", hex(ipPS.read(0x14)))
print ("0x1c = ", hex(ipPS.read(0x1c)))
print ("0x20 = ", hex(ipPS.read(0x20)))
print ("0x34 = ", hex(ipPS.read(0x34)))
print ("0x38 = ", hex(ipPS.read(0x38)))
                                   0 \times 10 = 0 \times 0
                                 0x10 = 0x0

0x14 = 0x0

0x1c = 0xab510041

0x20 = 0x0

0x34 = 0x0

0x38 = 0x3f
```

Study caravel fpga.ipynb, and be familiar with caravel SoC control flow

本次 lab 5 我們需要實作在 FPGA 版上,因此租借 online FPGA board 進行實作。而我們發現使用 python notebook 的優點有許多,其中最重要的優點就是 notebook 支援多種的 programming language,而我們這次 lab 5 需要使用 PYNQ-Z2 board 就是使用 python language,因此非常方便。我們可以將所需的 bit hwh hex file 上傳至 python notebook kernel,即可在 PYNQ-Z2 上進行實作。

以下是在 notebook 中學習到的實作流程說明。

首先在第二個 cell 中我們先讀取新的 bitstream file,使用函數 overlay("file name") 讀取設計好的 bitstream,並且同時在第三個 cell 之中把 bitstream file 裡面的三個設計好的 IP 讀取出來。

第二步,在 FPGA 板上宣告一個 DRAM buffer,使用 allocate("rom size")宣告。並且將對應的 hex file (firmware c code to RISCV code)打開並讀取。在 hex file 裡,檔案的開始是@為記號,並且其中儲存的內容是每四個 bytes 為一單位,因此我們將 hex file 裡面的資料每 4 bytes 寫入至剛剛宣告的 DRAM buffer,也就是 bytecount==4 時將資料寫入 buffer。

第三步,寫入 DRAM buffer 後需要 reset caravel CPU,因此 caravel reset control IP 會輸出 GPIO 進行 reset。經過 reset 之後 caravel CPU 即可開始透過 SPI interface (上述的 SPI flash)進行 DRAM buffer 中储存的 code 讀取並執行。

最後,Caravel CPU 輸出的結果會經由 MPRJ_I/O/EN 輸出,使用 caravel ps IP 進行讀取並且將讀取結果印在 notebook 上,並且最終結果會顯示在 0x1c 的地址的前 16 個 bits 之中,比較其結果是否與 firmware 結果相同即完成。

Reference

Course material

TA lecture & PPT