

Revisiting the Architectures like Pointer Networks to Efficiently Improve the Next Word Distribution, Summarization Factuality, and Beyond

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**Can Large LM Learn to Output
Arbitrary Next Word Distribution?**

No

A Simple Example



- There are **plates**, **keys**, **scissors**, **toys**, and **balloons** in front of me, and I pick up the ...
- Ideal distribution
 - **plates** ~0.2
 - **keys** ~0.2
 - **scissors** ~0.2
 - **toys** ~0.2
 - **balloons** ~0.2

GPT3.5's Output



There are plates, keys, scissors, toys, and balloons in front of me, and I pick up the **scissors**.

I pick up the scissors and

keys = 65.42%

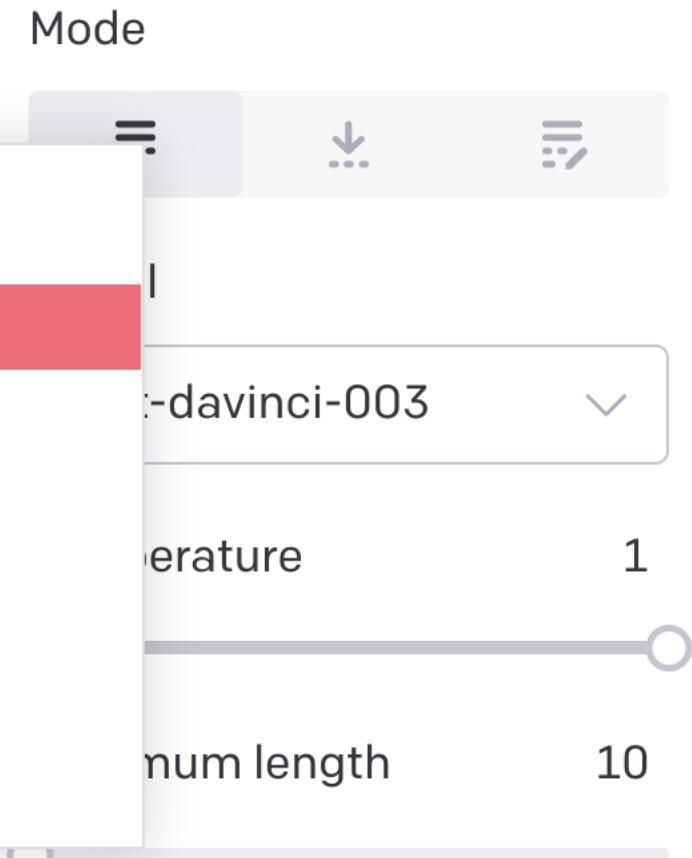
scissors = 18.80%

balloons = 10.29%

plates = 2.00%

toys = 1.94%

Total: -1.67 logprob on 1 tokens
(98.44% probability covered in top 5 logits)



There are toys, plates, scissors, keys, and balloons in front of me, and I pick up the **keys**.

The keys are cold and metallic

scissors = 46.91%

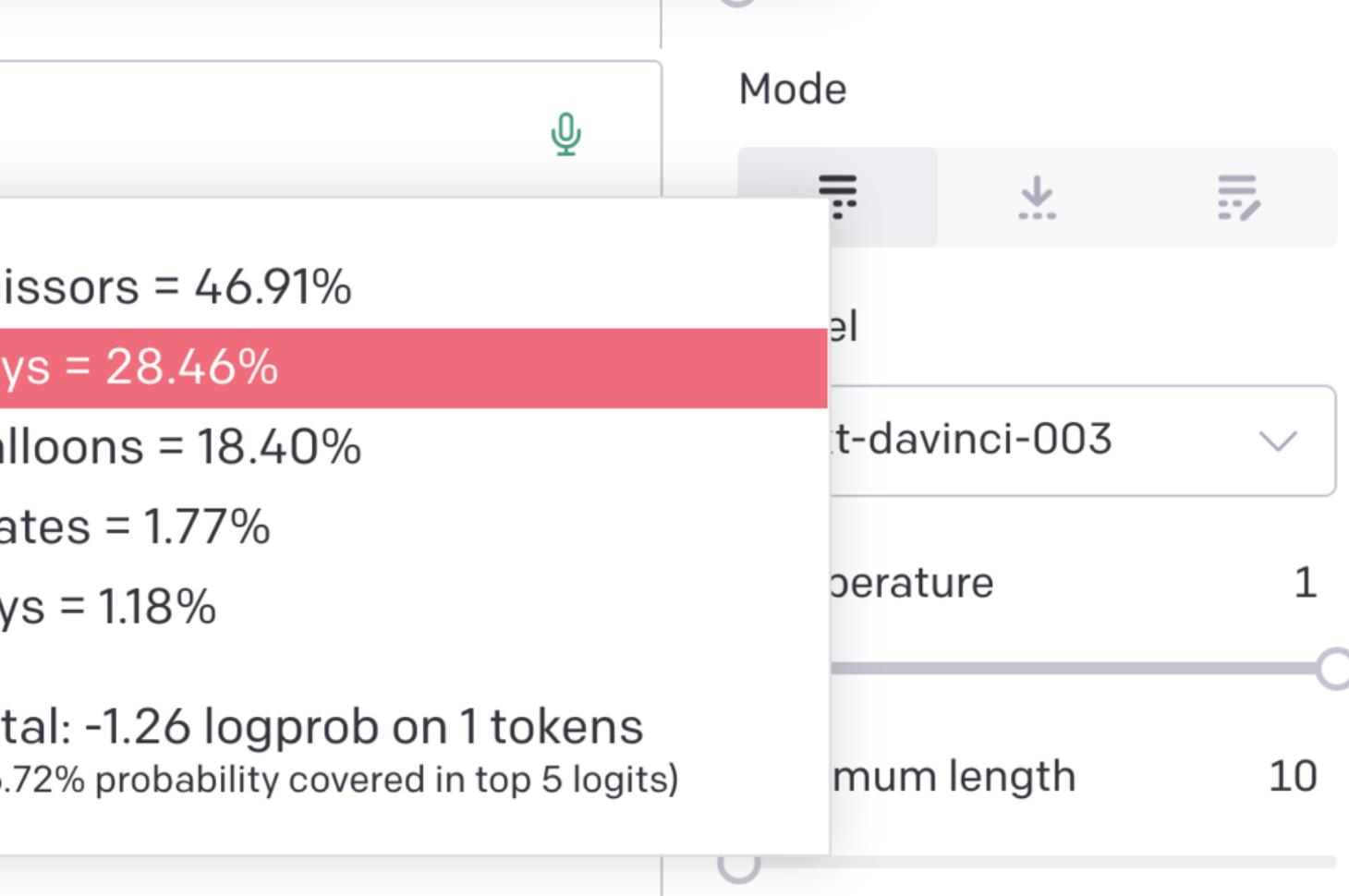
keys = 28.46%

balloons = 18.40%

plates = 1.77%

toys = 1.18%

Total: -1.26 logprob on 1 tokens
(96.72% probability covered in top 5 logits)



Hallucination and Repetition

- There are **plates**, **keys**, **scissors**, **toys**, and **balloons** in front of me, and I pick up the ...
 - **phone** (from GPT-2)?
 - **Hallucination**
 - Should copy but not copy
- I like **tennis**, **baseball**, **golf**, **basketball**, and ...
 - **tennis** (from GPT-2)?
 - **Repetition**
 - Should not copy but copy

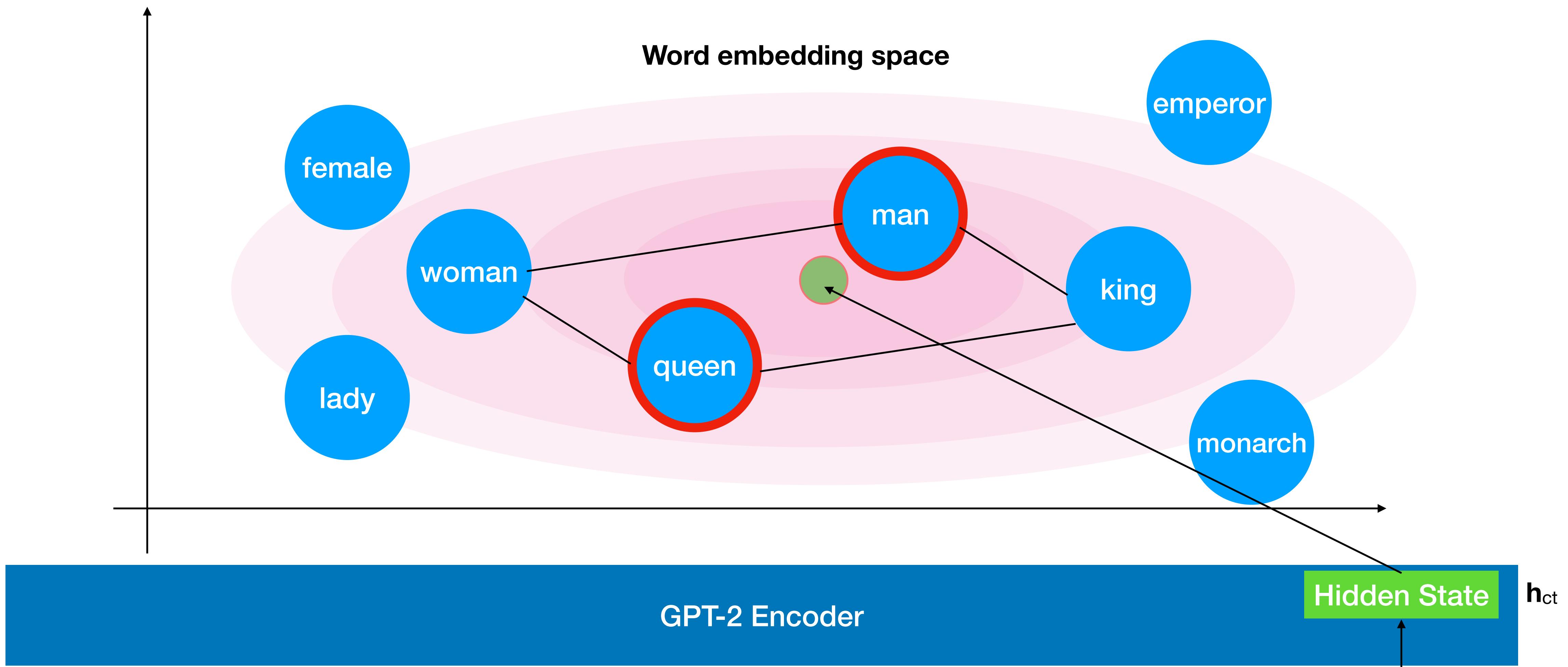
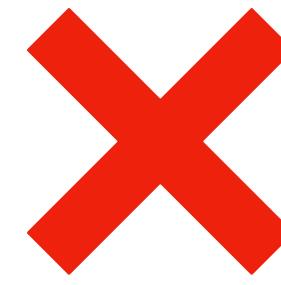
	Softmax (GPT-2)	Pointer Network	Unlikelihood Training	Ours
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Hallucination Yes No Yes No

Repetition Yes Yes No No

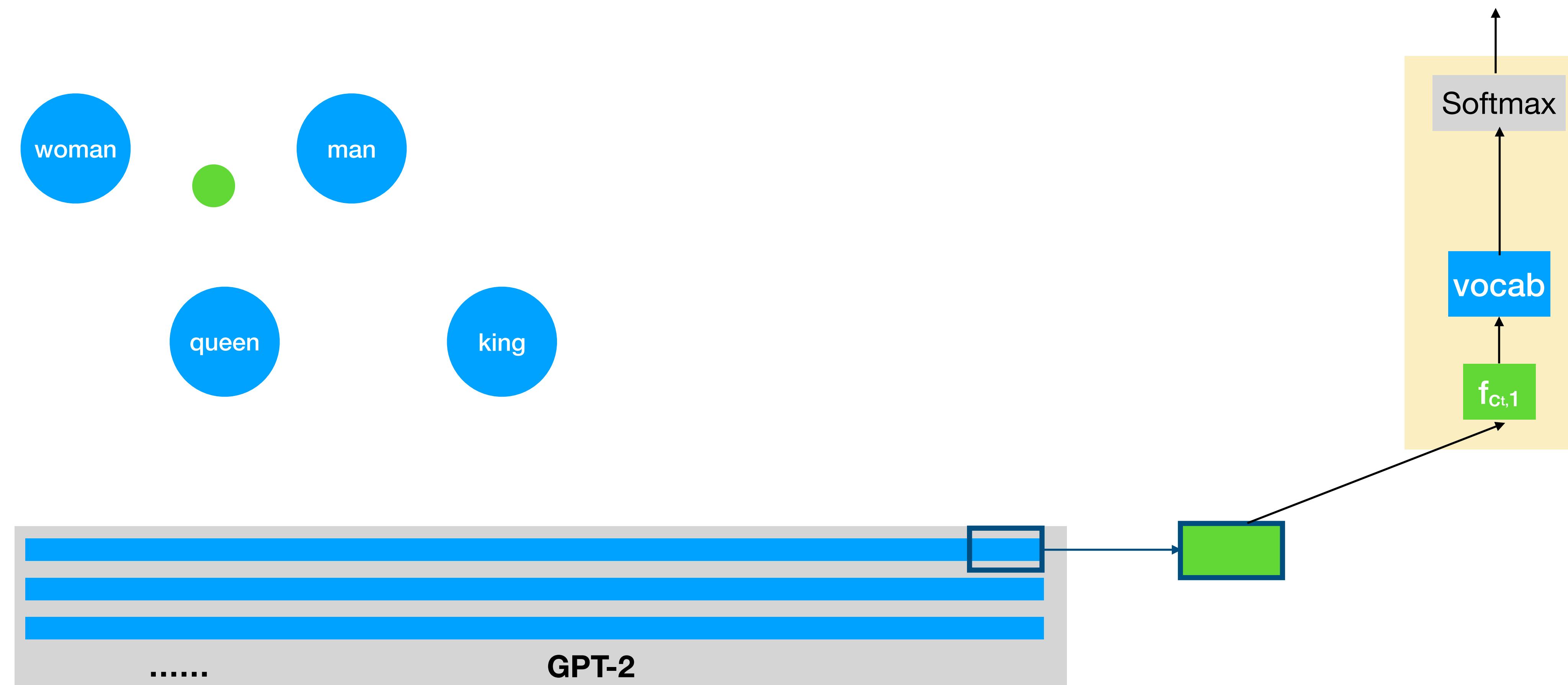
**Why is GPT Unable to Learn to
Copy Properly?**

GPT-2 cannot predict both “woman” and “king” as the next word



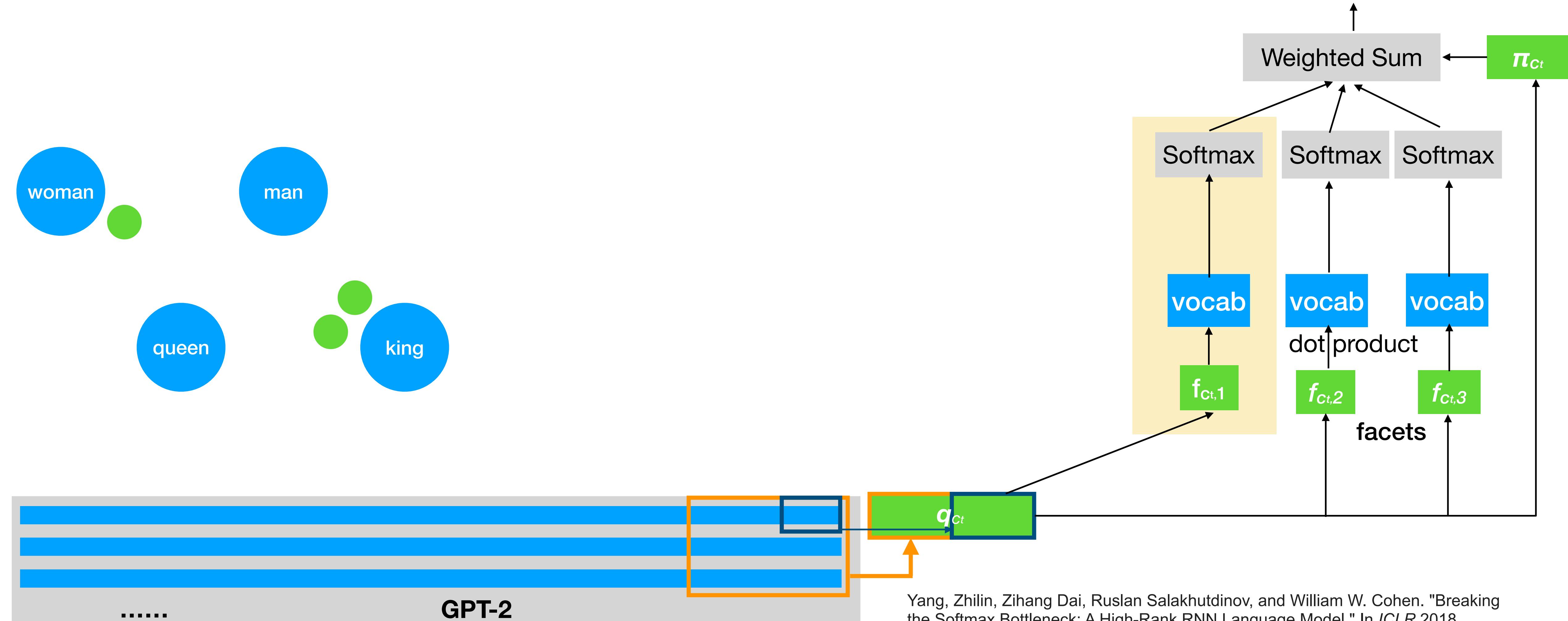
After debating whether to bow to the **king** or the **woman** first, the jester decided on the

Softmax



After debating whether to bow to the **king** or the **woman** first, the jester decided on the

Mixture of Softmax (MoS)

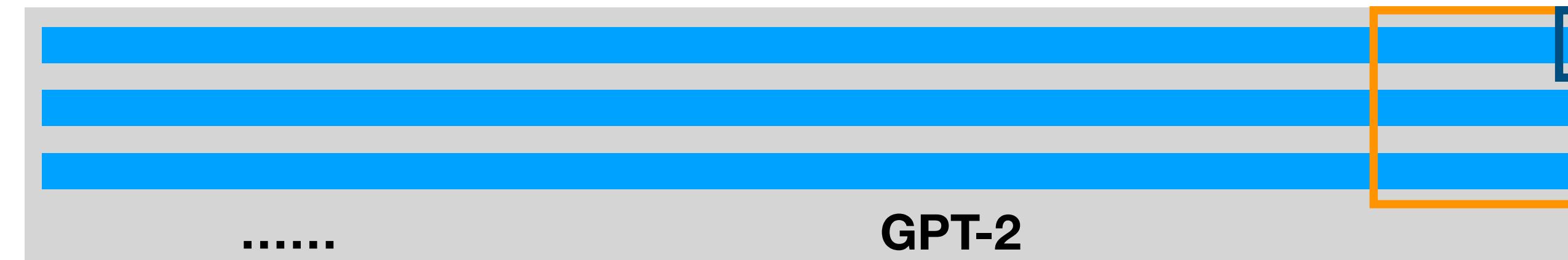
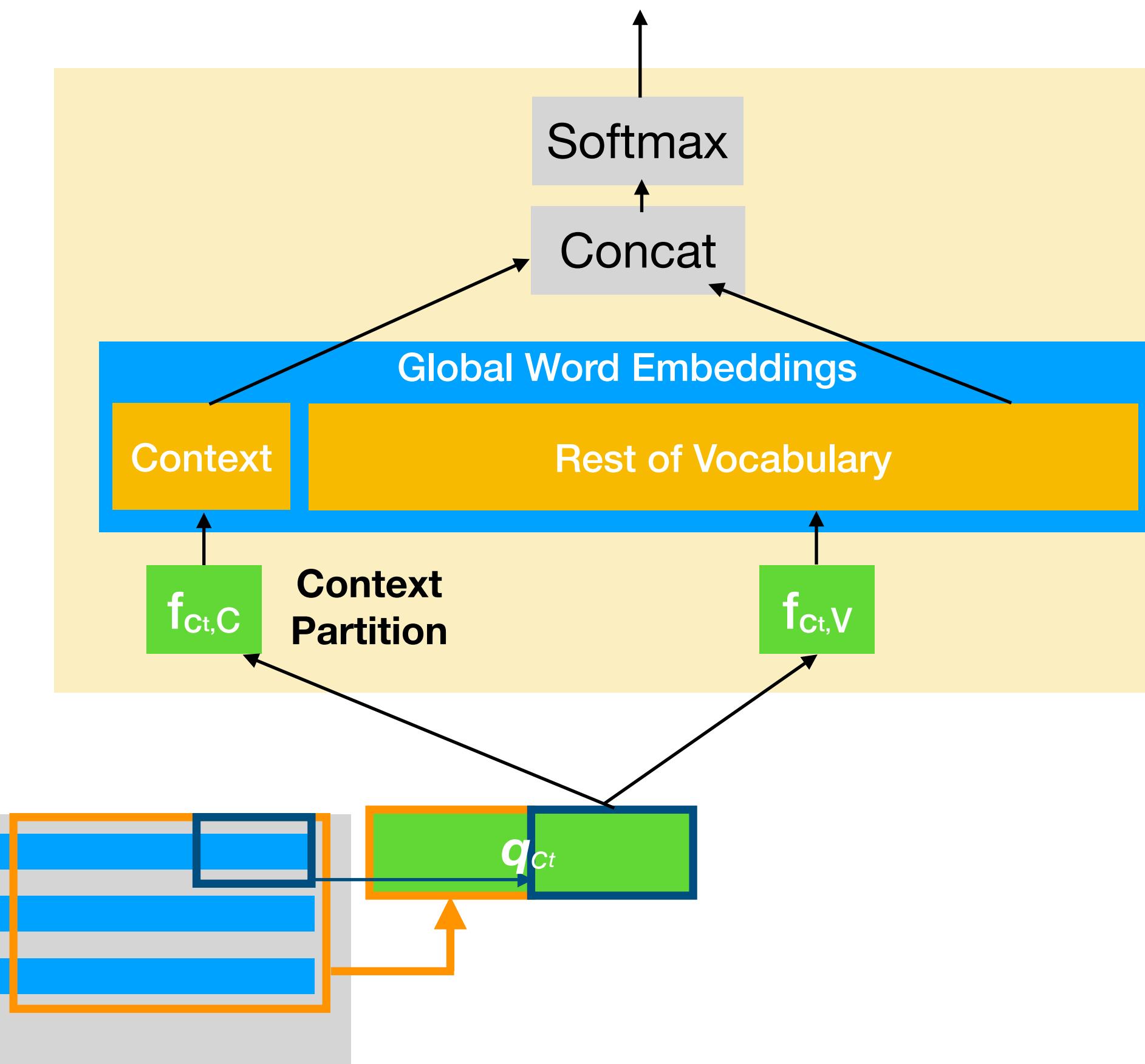
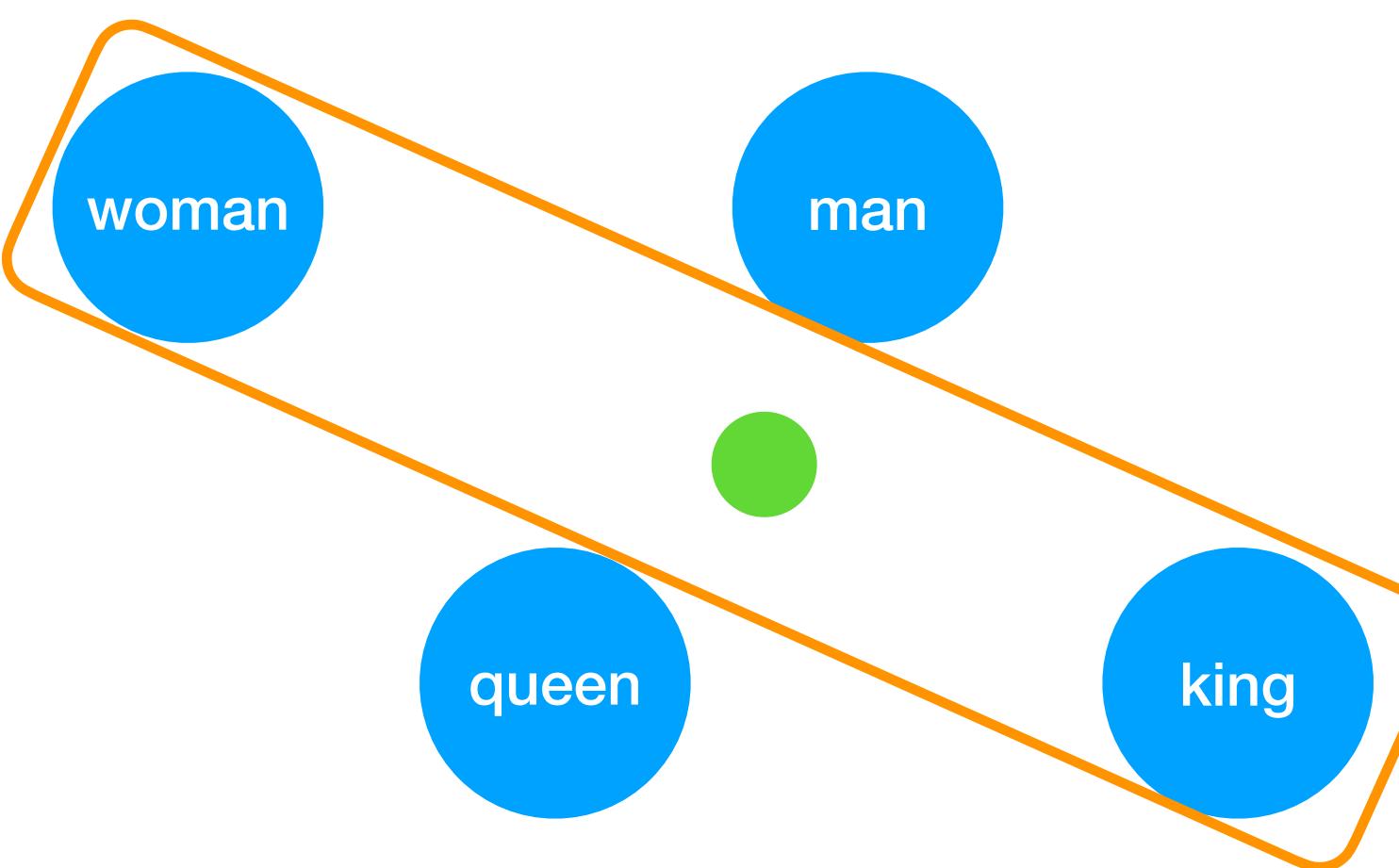


After debating whether to bow to the **king** or the **woman** first, the jester decided on the

Yang, Zhilin, Zihang Dai, Ruslan Salakhutdinov, and William W. Cohen. "Breaking the Softmax Bottleneck: A High-Rank RNN Language Model." In *ICLR* 2018.

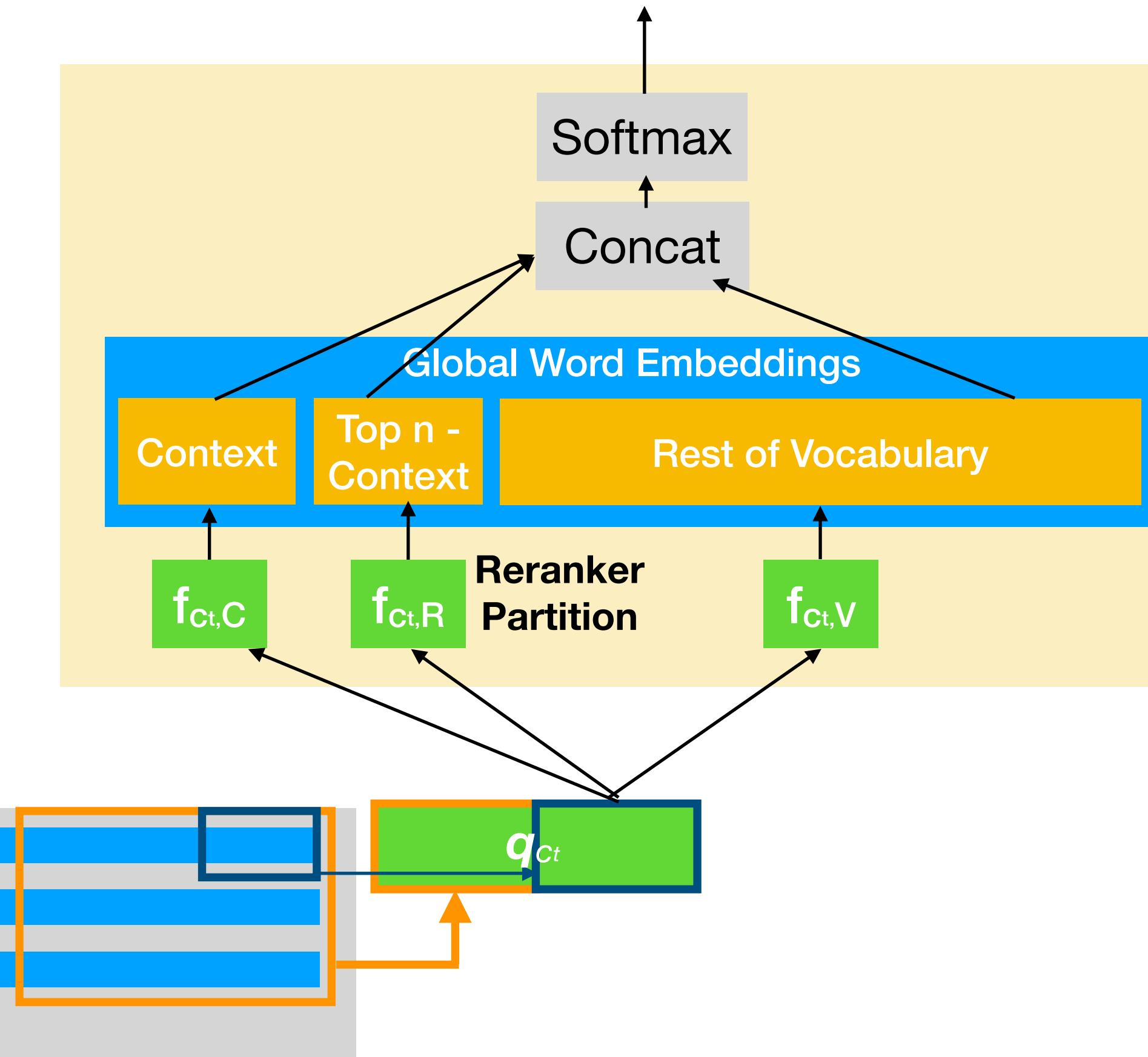
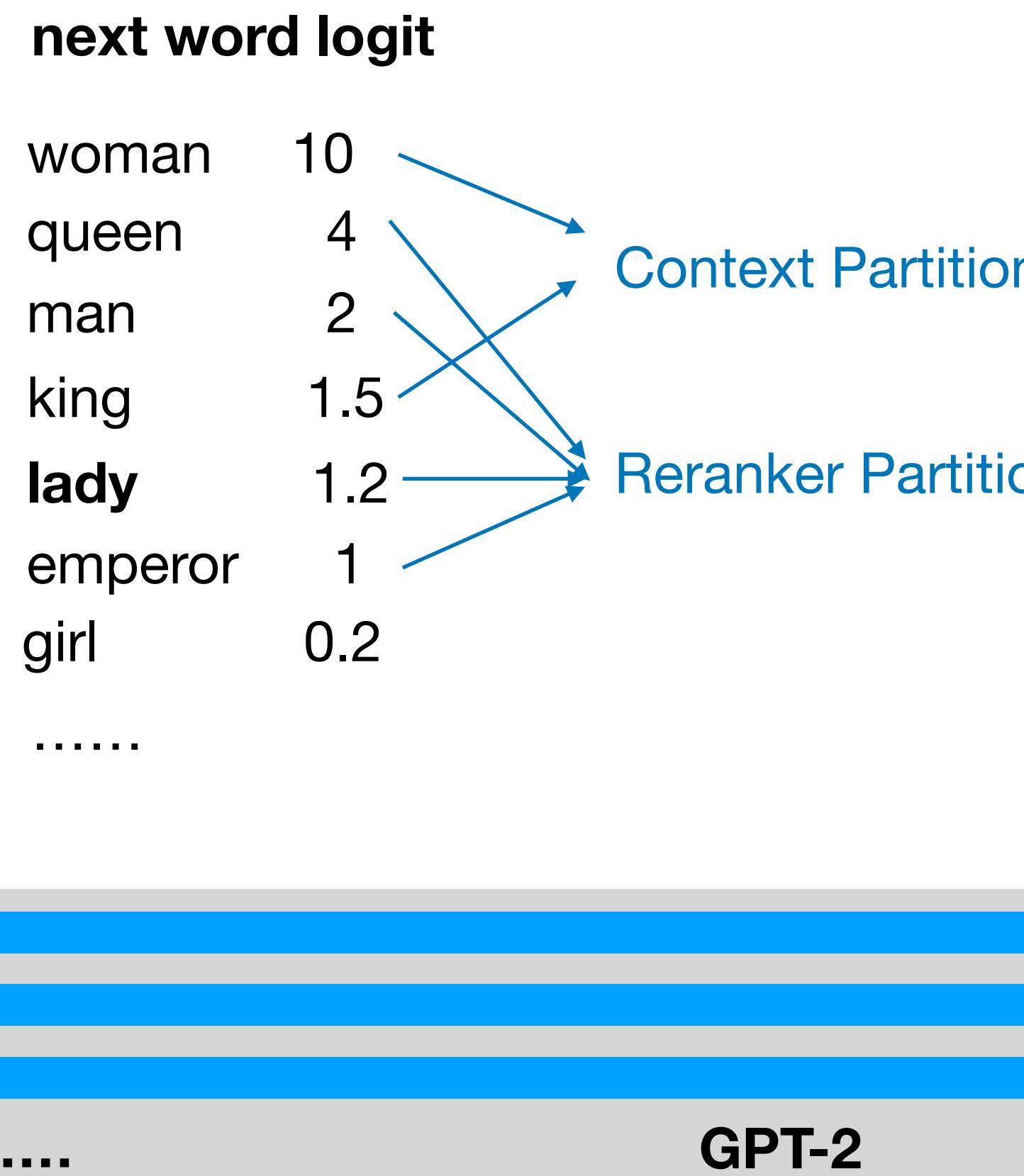
Chang, Haw-Shiuan, and Andrew McCallum. "Softmax bottleneck makes language models unable to represent multi-mode word distributions." In *ACL* 2022.

Context Partition



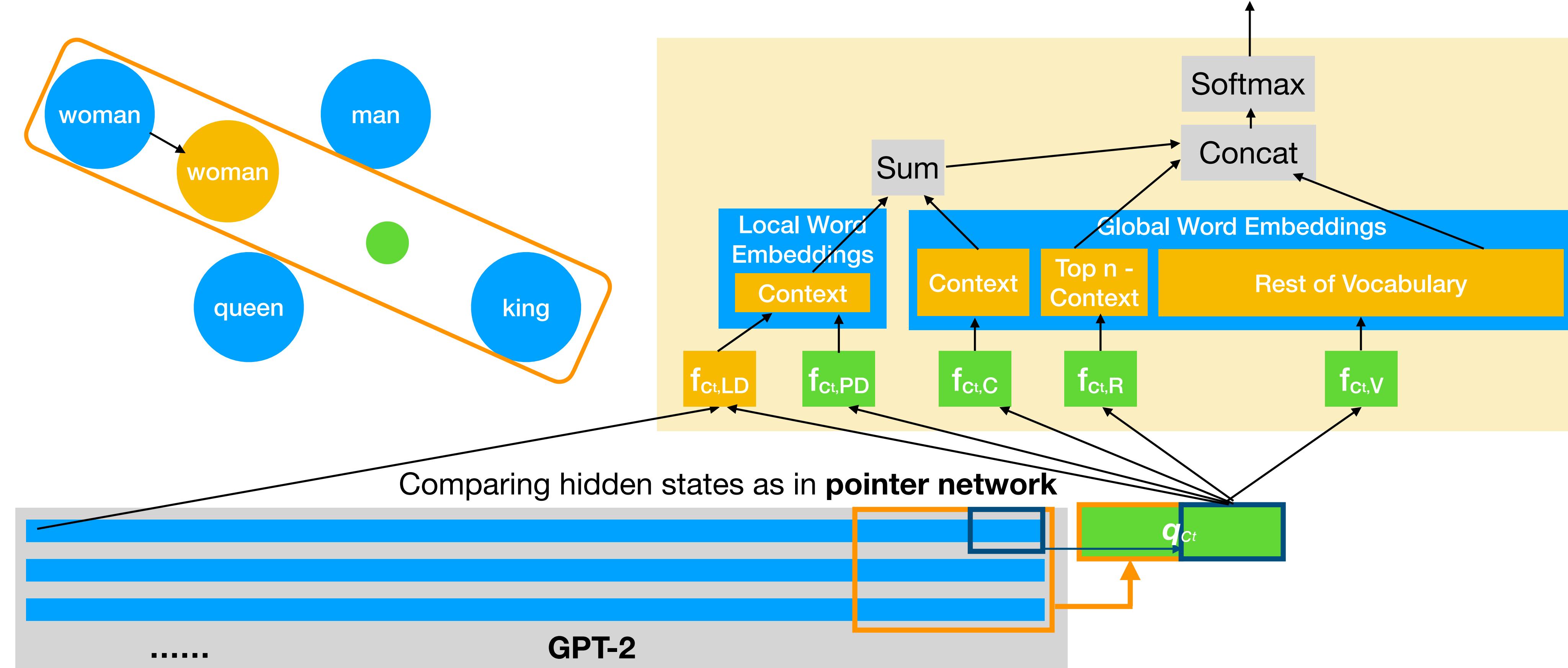
After debating whether to bow to the **king** or the **woman** first, the jester decided on the

Context + Reranker Partition



After debating whether to bow to the **king** or the **woman** first, the jester decided on the

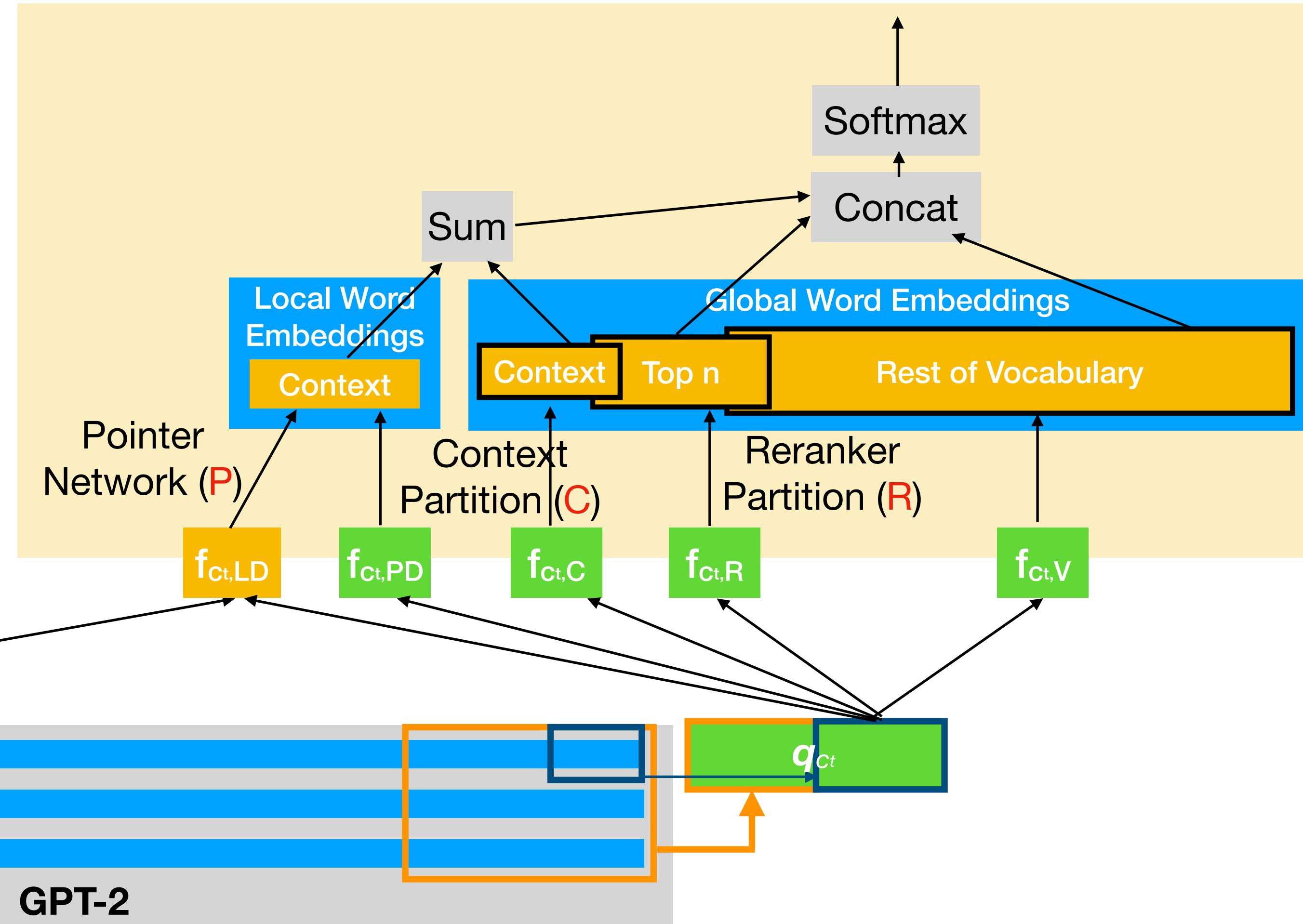
+ Pointer Network



After debating whether to bow to the **king** or the **woman** first, the jester decided on the

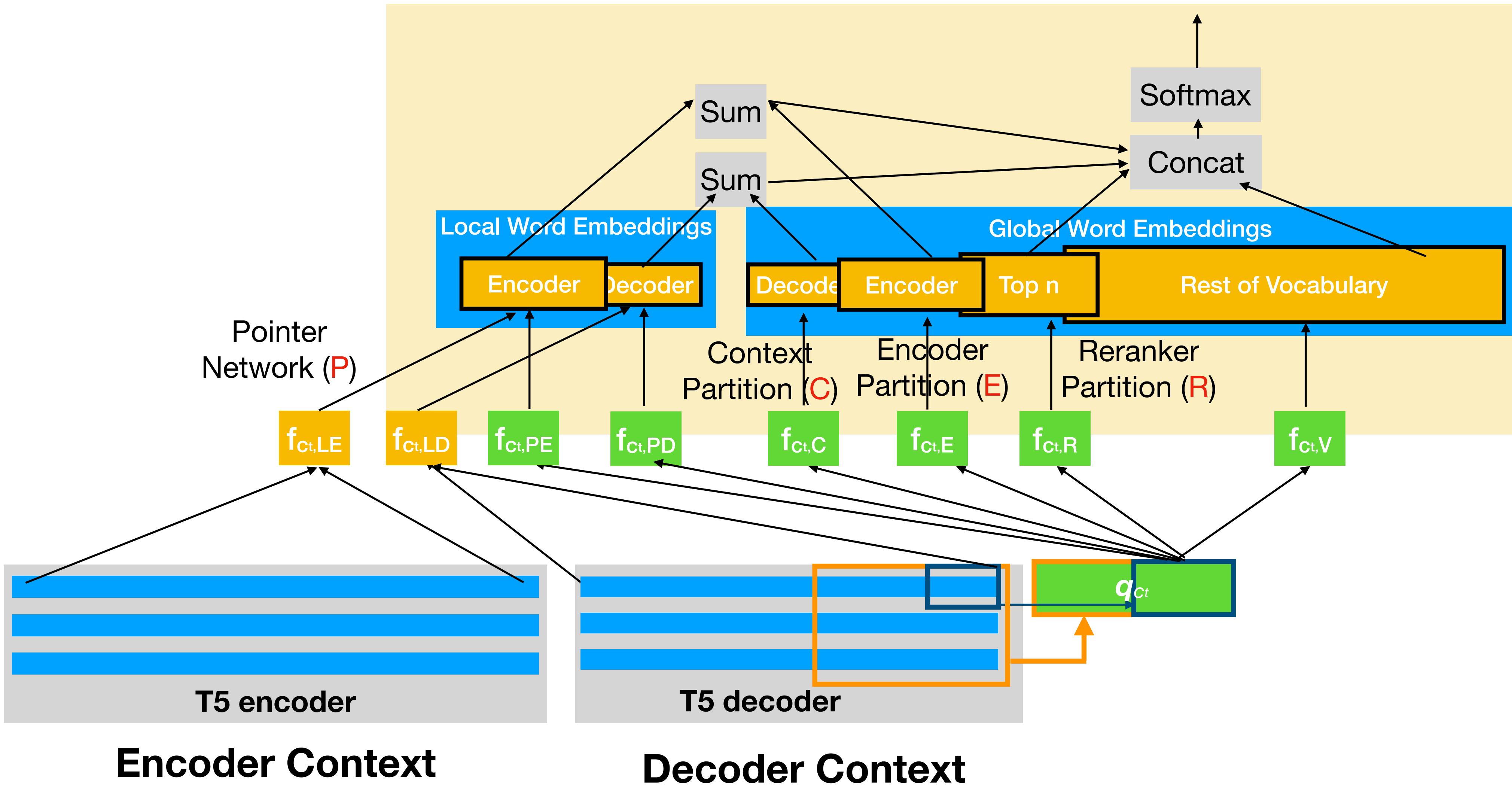
Gu, Jiatao, Zhengdong Lu, Hang Li, and Victor OK Li. "Incorporating Copying Mechanism in Sequence-to-Sequence Learning." In ACL 2016.

Softmax CPR ❤



After debating whether to bow to the **king** or the **woman** first, the jester decided on the

Softmax CEPR

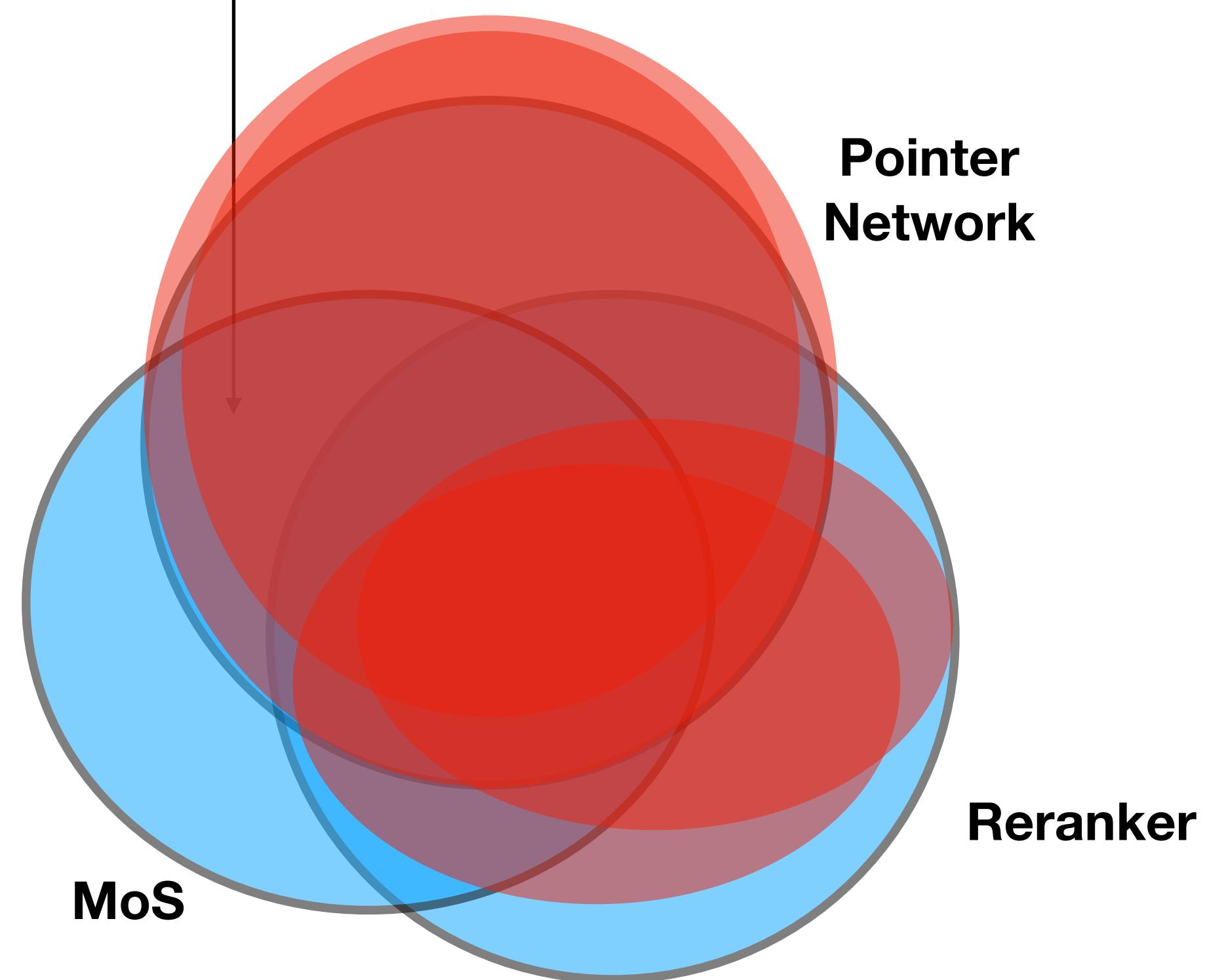


Experiments

GPT-2 Perplexity Comparison

Model Name	GPT-2 Small			
	Size	Time (ms)	OWT (↓)	Wiki (↓)
Softmax (GPT-2)	125.0M	82.9	18.96	24.28
Softmax + Mi	130.9M	85.6	18.74	24.08
Mixture of Softmax (MoS) (Yang et al., 2018)	126.2M	130.2	18.97	24.10
MoS + Mi (Chang and McCallum, 2022)	133.3M	133.2	18.68	23.82
Pointer Generator (PG) (See et al., 2017)	126.2M	106.0	18.67	23.70
Pointer Sentinel (PS) (Merity et al., 2017)	126.2M	94.1	18.70	23.79
Softmax + R:20 + Mi	132.1M	90.4	18.67	24.03
Softmax + R:20,100 + Mi	133.3M	101.1	18.69	23.93
Softmax + C + Mi	132.1M	94.8	18.48	23.56
Softmax + P + Mi	133.3M	99.1	18.58	23.66
PG + Mi	133.3M	111.2	18.43	23.43
PS + Mi	133.3M	98.0	18.48	23.53
Softmax + CR:20,100 + Mi	134.5M	113.3	18.46	23.48
Softmax + CPR:20,100 + Mi	136.8M	119.9	18.43	23.42
MoS + CPR:20,100 + Mi	139.2M	165.1	18.39	23.29

king & woman example could be solved
by pointer network or MoS



Summarization Experiments

- Improve BookSum more
 - Probably because the John in one book is different from the John in another book

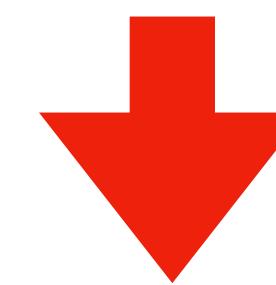
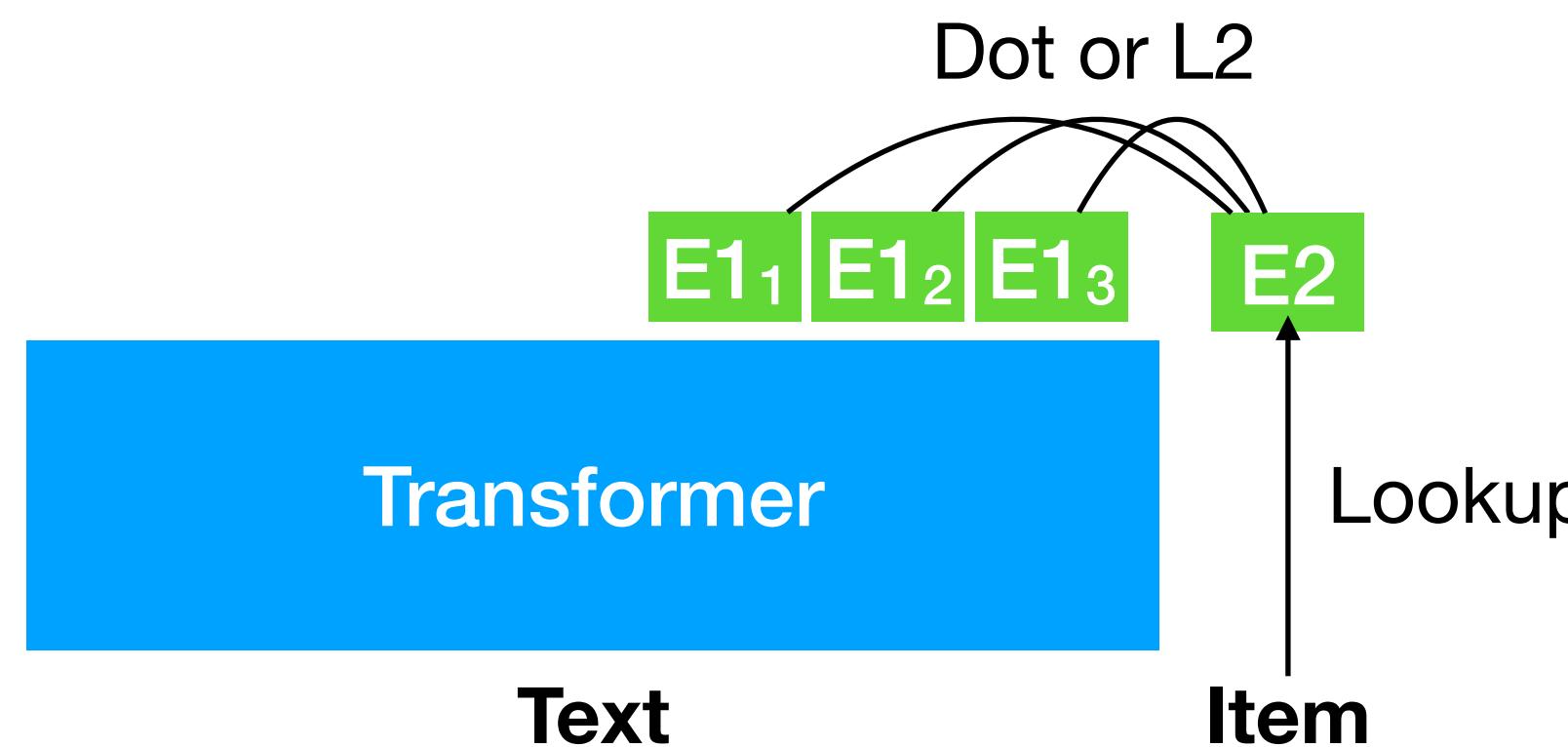
Model Name	CNN/DM				XSUM				BookSum Paragraph				SAMSUM				
	R1	CIDEr	factCC	MAUVE	R1	CIDEr	factCC	MAUVE	R1	CIDEr	factCC	MAUVE	R1	CIDEr	factCC	MAUVE	
T5-Small																	
Softmax (S)	38.255	0.442	0.462	0.861	28.713	0.446	0.254	0.939	16.313	0.083	0.424	0.328	39.472	0.817	0.577	0.898	
CopyNet (Gu et al., 2016)	37.990	0.438	0.482	0.865	28.573	0.442	0.274	0.940	16.666	0.092	0.439	0.402	39.525	0.853	0.579	0.924	
PG (See et al., 2017)	37.913	0.442	0.467	0.874	28.777	0.450	0.257	0.931	16.432	0.088	0.429	0.376	32.451	0.585	0.552	0.153	
PS (Merity et al., 2017)	38.058	0.444			38.058	0.444	0.435	0.267	0.932	16.408	0.090	0.436	0.395	38.731	0.817	0.578	0.865
S + R:20	37.881	0.433			37.881	0.433	0.440	0.256	0.931	16.336	0.086	0.431	+ 30%	39.073	0.752	0.579	0.847
S + E	38.137	0.441			38.137	0.441	0.444	0.272	0.942	16.542	0.090	0.435	0.390	39.056	0.784	0.579	0.904
S + CE	38.461	0.460	0.475	0.874	29.155	0.464	0.270	0.948	16.628	0.093	0.436	0.403	40.055	0.835	0.583	0.943	
S + CER:20	38.346	0.450	0.482	0.890	29.067	0.459	0.276	0.942	16.638	0.093	0.436	0.400	40.505	0.846	0.580	0.915	
S + CEPR:20	38.807	0.456	0.481	0.877	29.395	0.474	0.273	0.942	16.894	0.098	0.440	0.418	40.127	0.891	0.582	0.946	
S + CEPR:20 + Mi	38.675	0.451	0.475	0.878	29.348	0.470	0.275	0.946	16.738	0.096	0.438	0.426	40.328	0.874	0.582	0.932	
T5-Base																	
Softmax (S)	40.198	0.504	0.478	0.907	33.571	0.667	0.249	0.979	16.761	0.096	0.424	0.467	44.348	1.046	0.574	0.986	
CopyNet (Gu et al., 2016)	39.940	0.507	0.484	0.903	33.557	0.666	0.253	0.979	16.918	0.101	0.430	0.531	44.141	1.052	0.570	0.973	
PG (See et al., 2017)	39.982	0.489	0.485	0.911	33.605	0.663	0.255	0.982	16.611	0.095	0.423	0.463	37.597	0.784	0.548	0.140	
PS (Merity et al., 2017)	40.018	0.495	0.483	0.914	33.638	0.672	0.249	0.983	16.905	0.100	0.428	0.504	43.098	1.008	0.575	0.946	
S + CEPR:20	40.354	0.511	0.487	0.919	33.700	0.675	0.260	0.980	16.997	0.100	0.432	0.549	44.860	1.064	0.573	0.963	
S + CEPR:20 + Mi	40.510	0.506	0.481	0.918	33.853	0.683	0.263	0.983	16.975	0.101	0.431	0.546	44.488	1.055	0.576	0.980	

Conclusion

- Softmax bottleneck
 - -> hallucination and repetition problems
- Breaking the softmax bottleneck
 - -> improvements from pointer networks, rerankers, and mixture of softmax (MoS)
- Pointer networks + rerankers + MoS
 - -> softmax-CPR and softmax-CEPR

Our Other Work on Improving Single Embedding Representation

GPT-like LM decoder for NLG

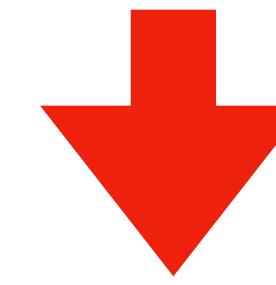
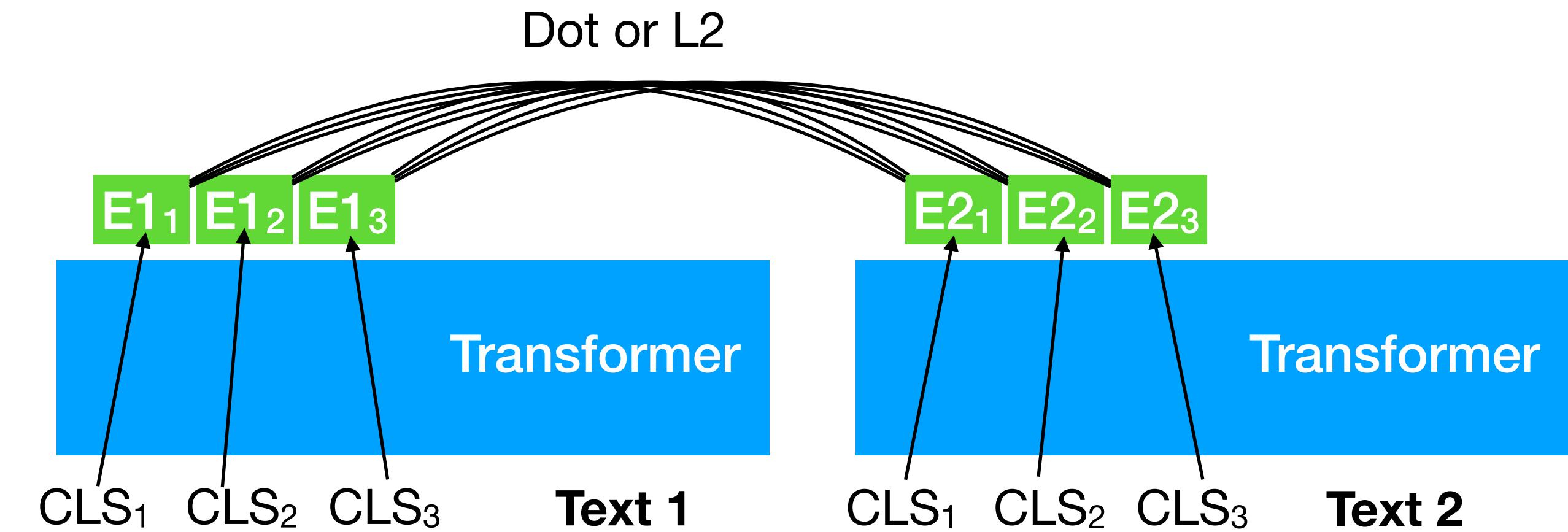


**More Factual and
Less Repetition**

Text Completion

Summarization

BERT-like LM encoder for NLU

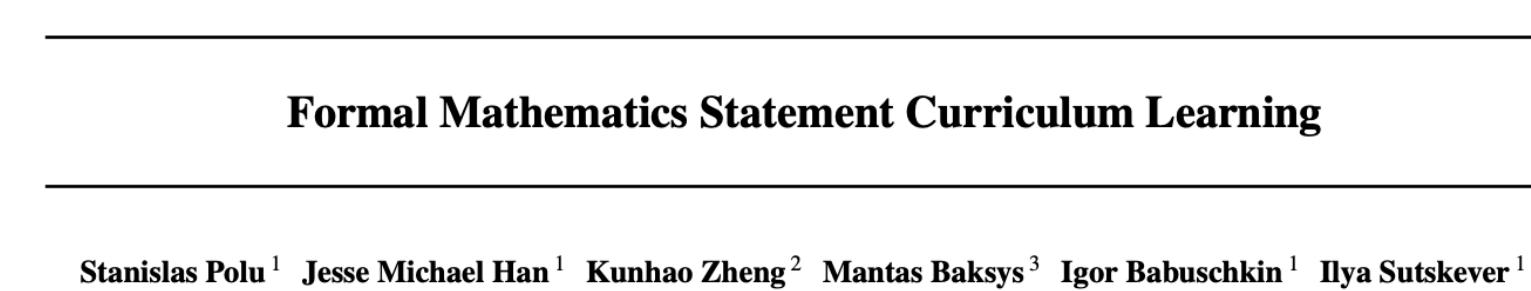


**More Accurate
and Calibrated**

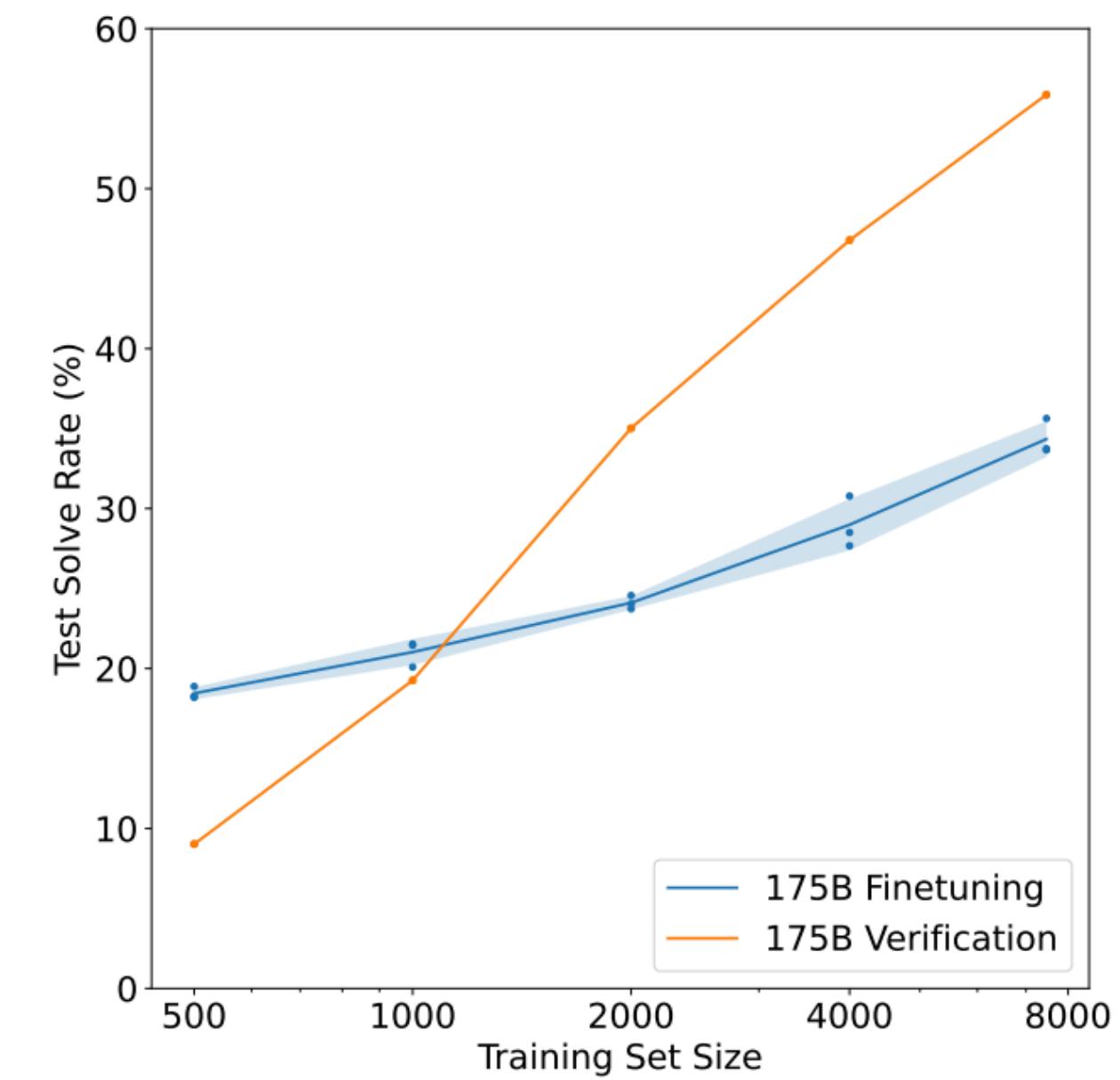
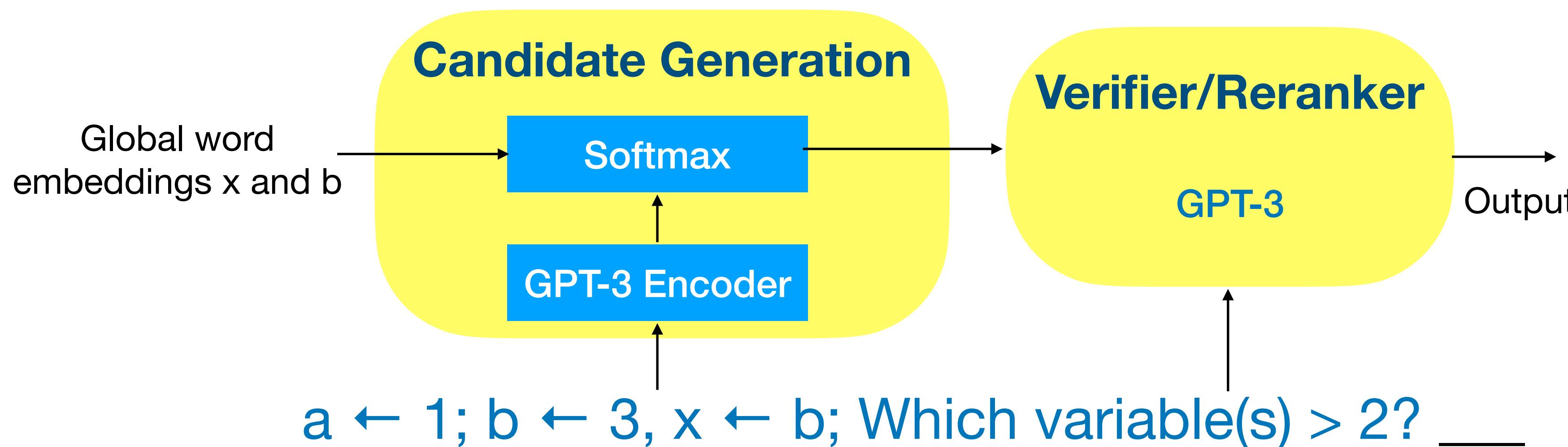
NLI QA IR Sent sim

Future Work: Variable Assignment

- LM on code examples: Codex (OpenAI), AlphaCode (DeepMind)
- LM on math examples:

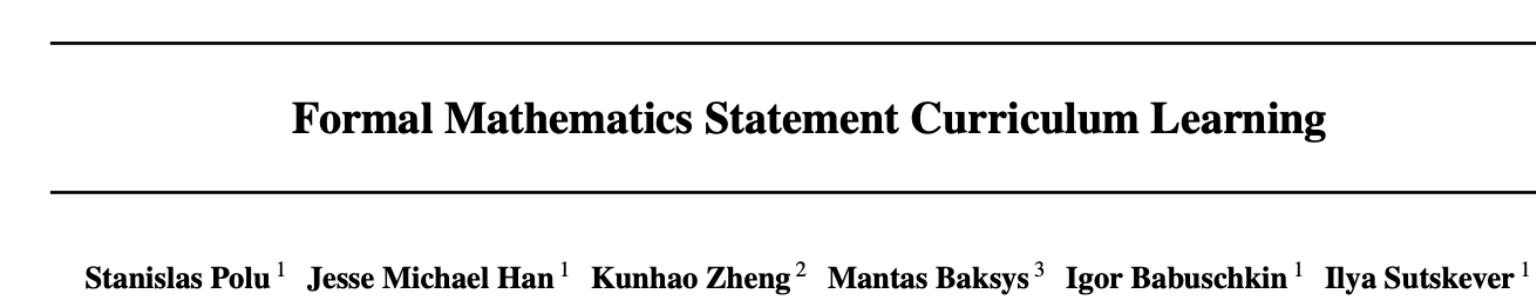


Training Verifiers to Solve Math Word Problems
 Karl Cobbe* Vineet Kosaraju* Mohammad Bavarian Mark Chen
 Heewoo Jun Lukasz Kaiser Matthias Plappert Jerry Tworek
 Jacob Hilton Reiichiro Nakano Christopher Hesse John Schulman
 OpenAI

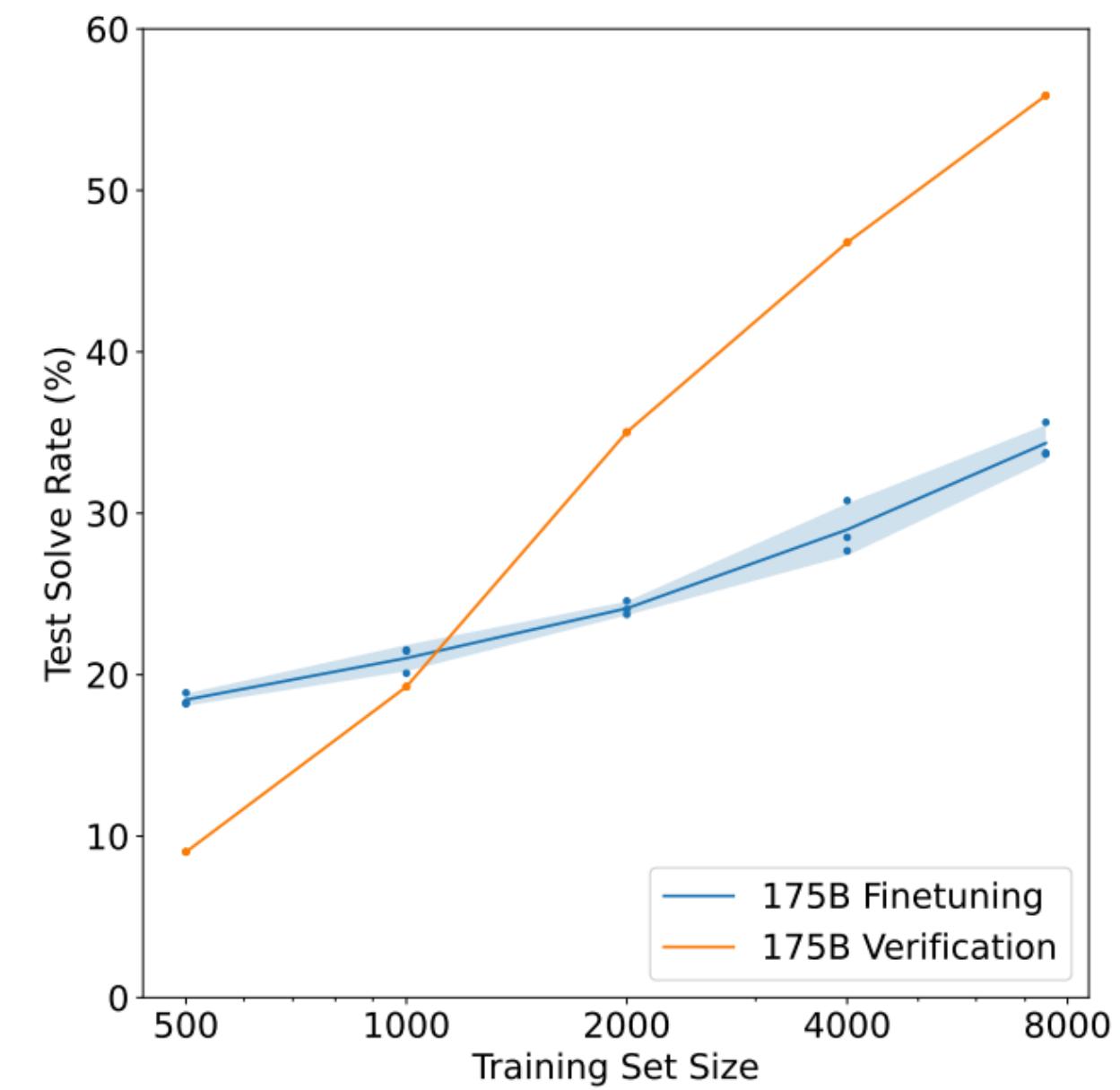
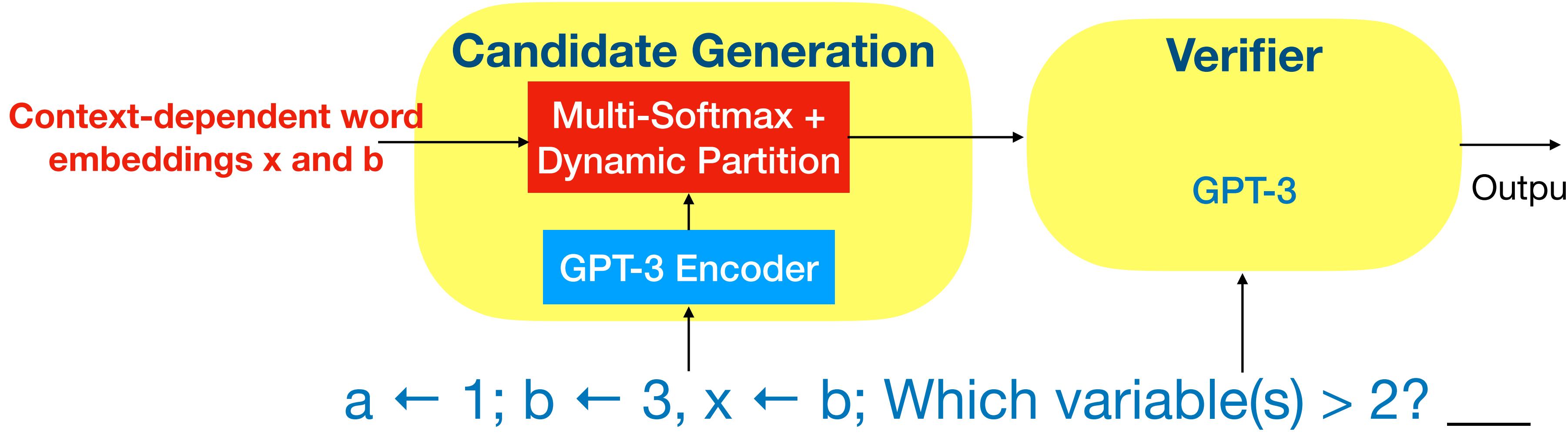


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Q & A