

CSCE 636 Neural Networks (Deep Learning)

Lecture 7: Deep Learning for Computer Vision

Anxiao (Andrew) Jiang

Based on the interesting lecture of Prof. Hung-yi Lee,

https://www.youtube.com/watch?v=FrKWIRv254g&list=PLJV_el3uVTsPy9oCRY30oBPNLCo89yu49&index=19

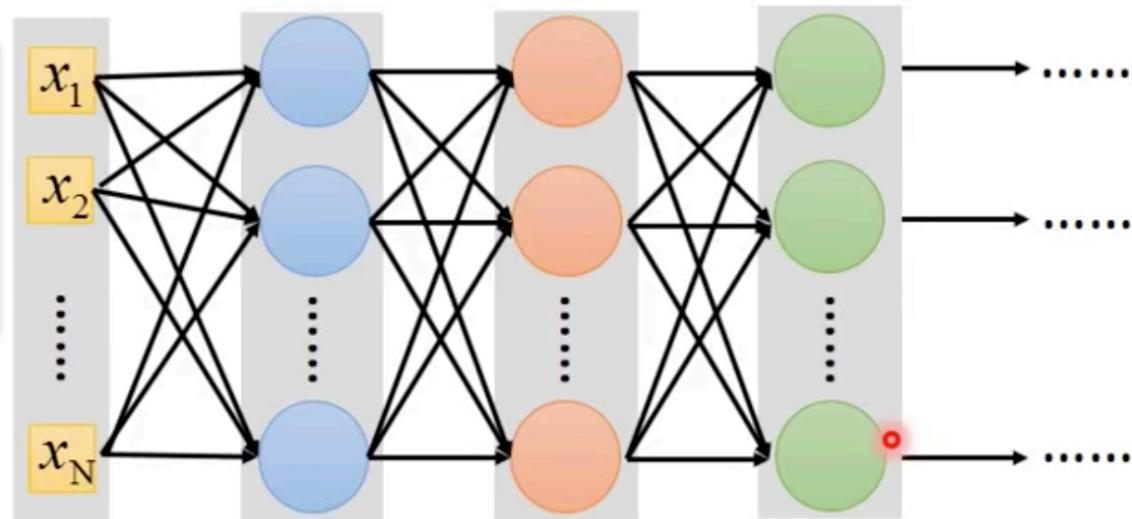
Convolutional Neural Network (CNN)

Why CNN for Image?

[Zeiler, M. D., ECCV 2014]

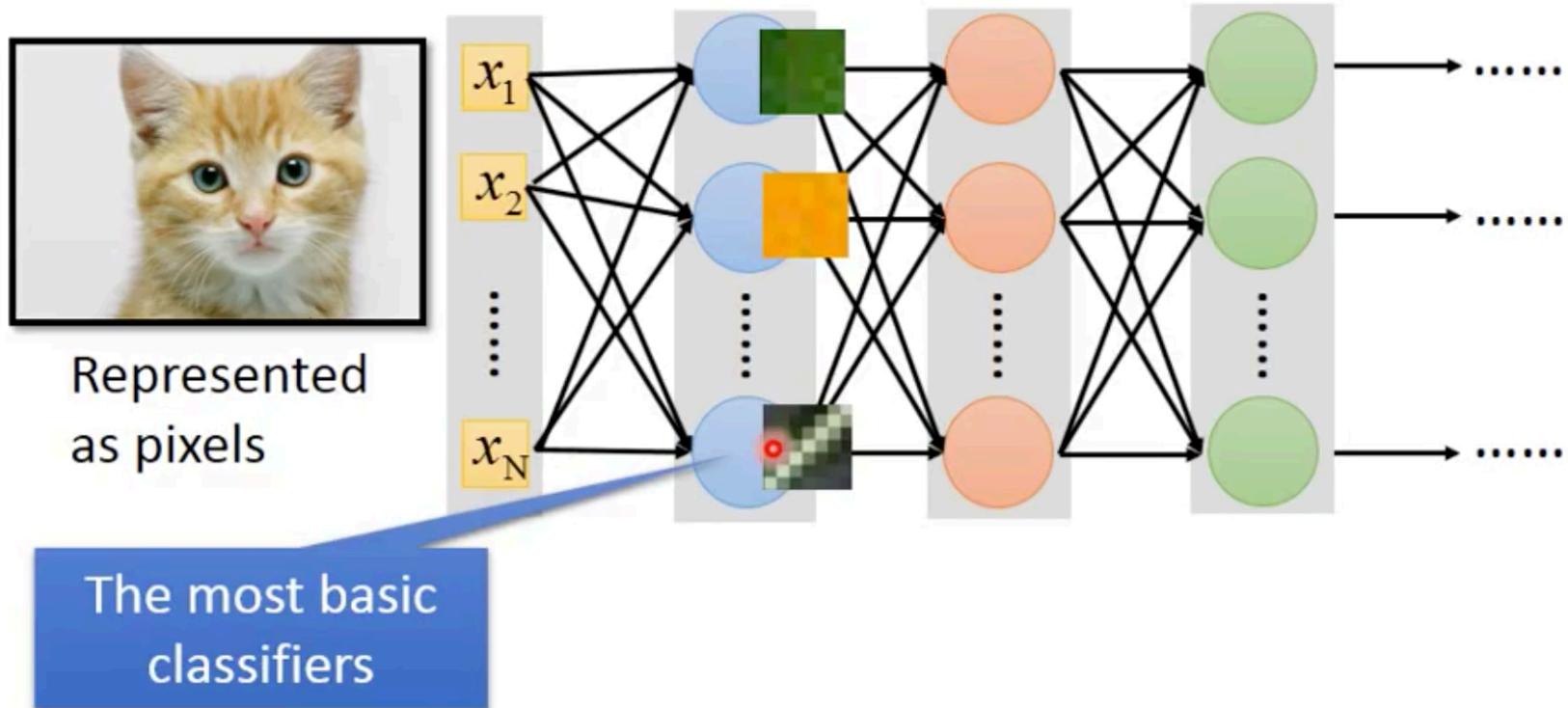


Represented
as pixels



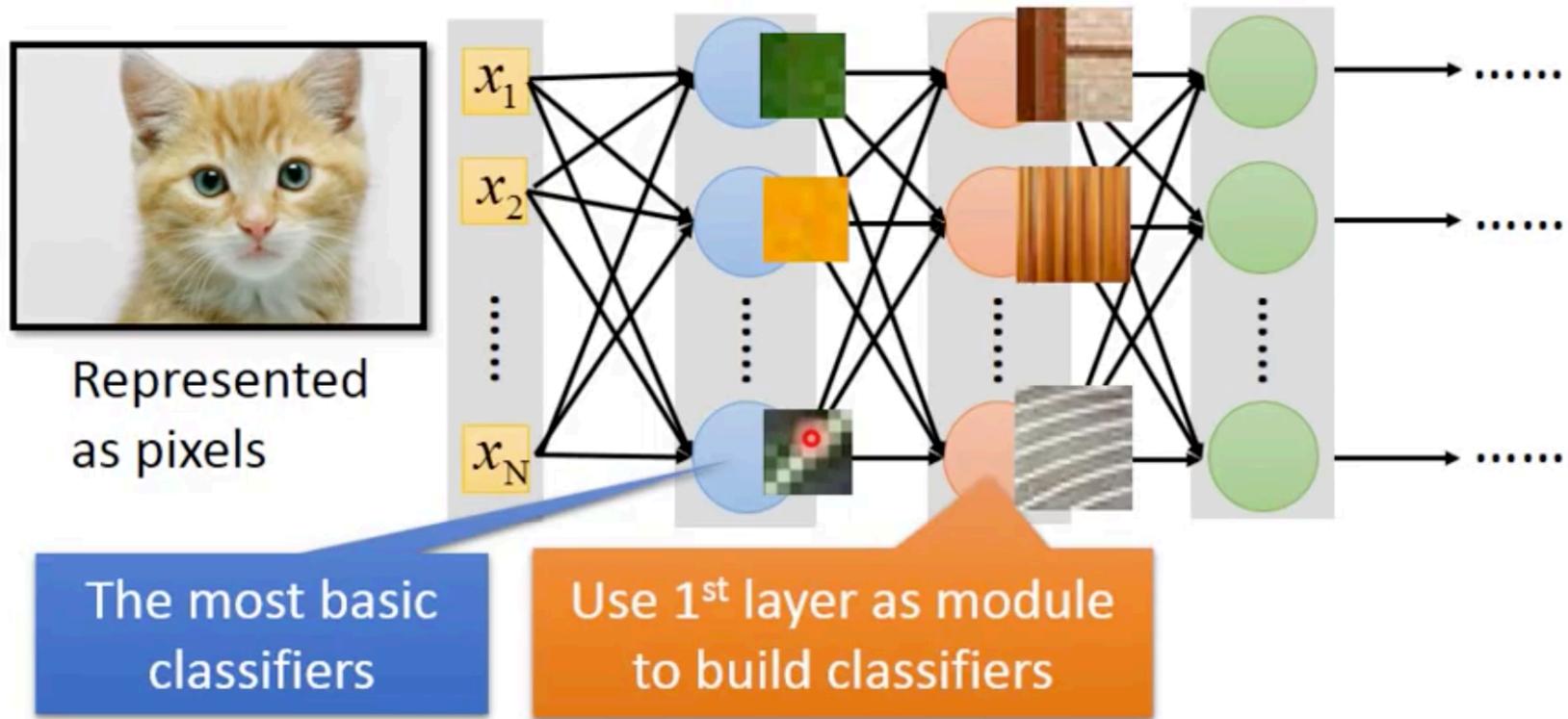
Why CNN for Image?

[Zeiler, M. D., *ECCV 2014*]



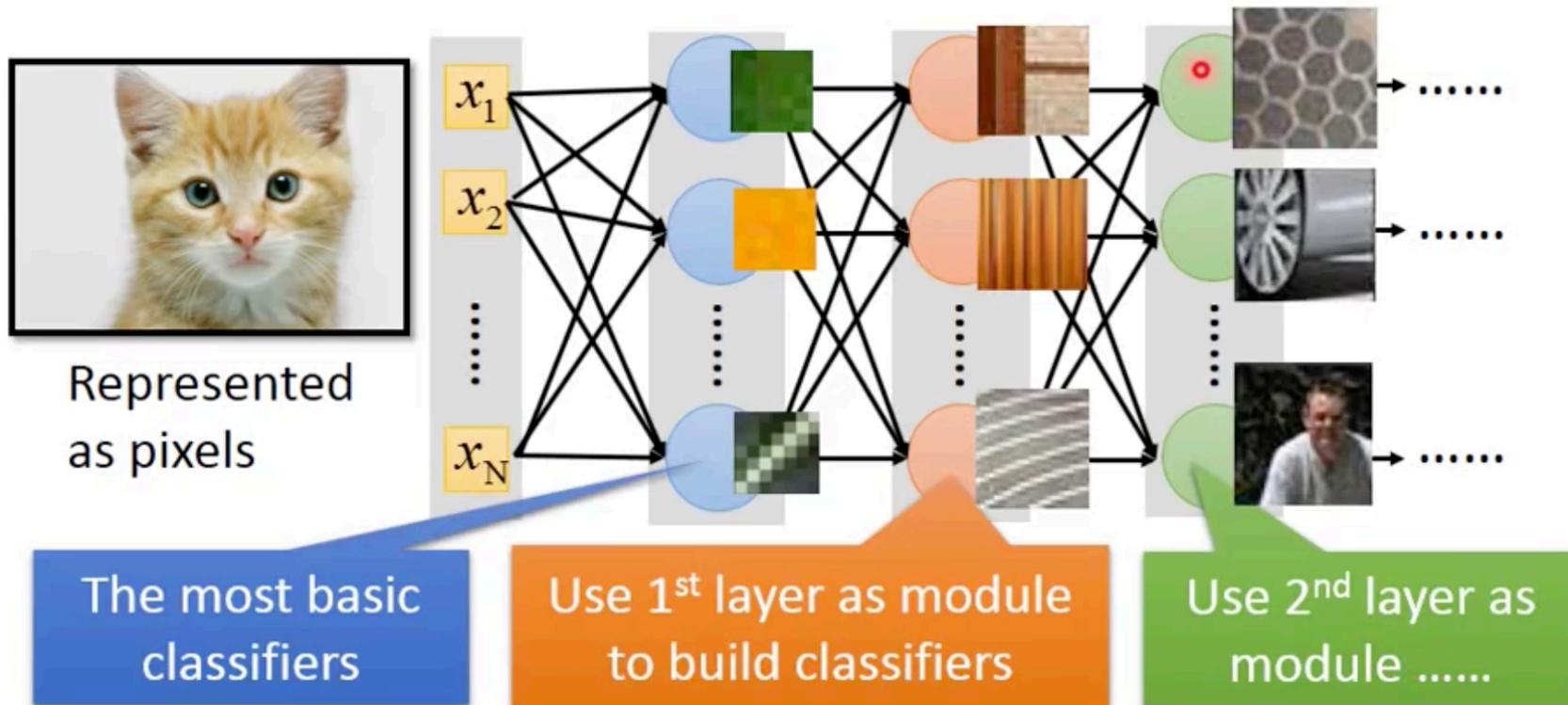
Why CNN for Image?

[Zeiler, M. D., *ECCV 2014*]



Why CNN for Image?

[Zeiler, M. D., ECCV 2014]



Too many weights in a dense network!

Why CNN for Image

- Some patterns are much smaller than the whole image.

A neuron does not have to see the whole image to discover the pattern.



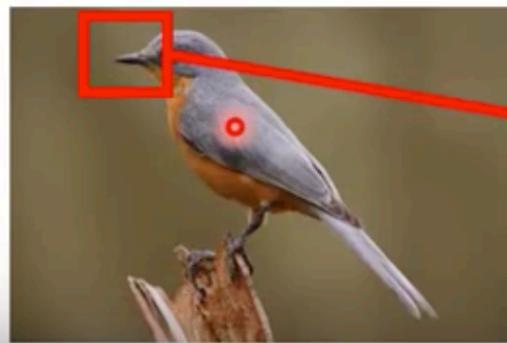
有沒有某一個 pattern 出現

Why CNN for Image

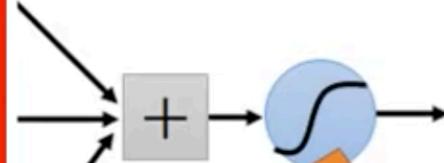
- Some patterns are much smaller than the whole image

A neuron does not have to see the whole image to discover the pattern.

Connecting to small region with less parameters



整張完整的圖



“beak” detector

Why CNN for Image

- The same patterns appear in different regions.



同樣的這個 pattern

Why CNN for Image

- The same patterns appear in different regions.



Why CNN for Image

- Subsampling the pixels will not change the object

bird



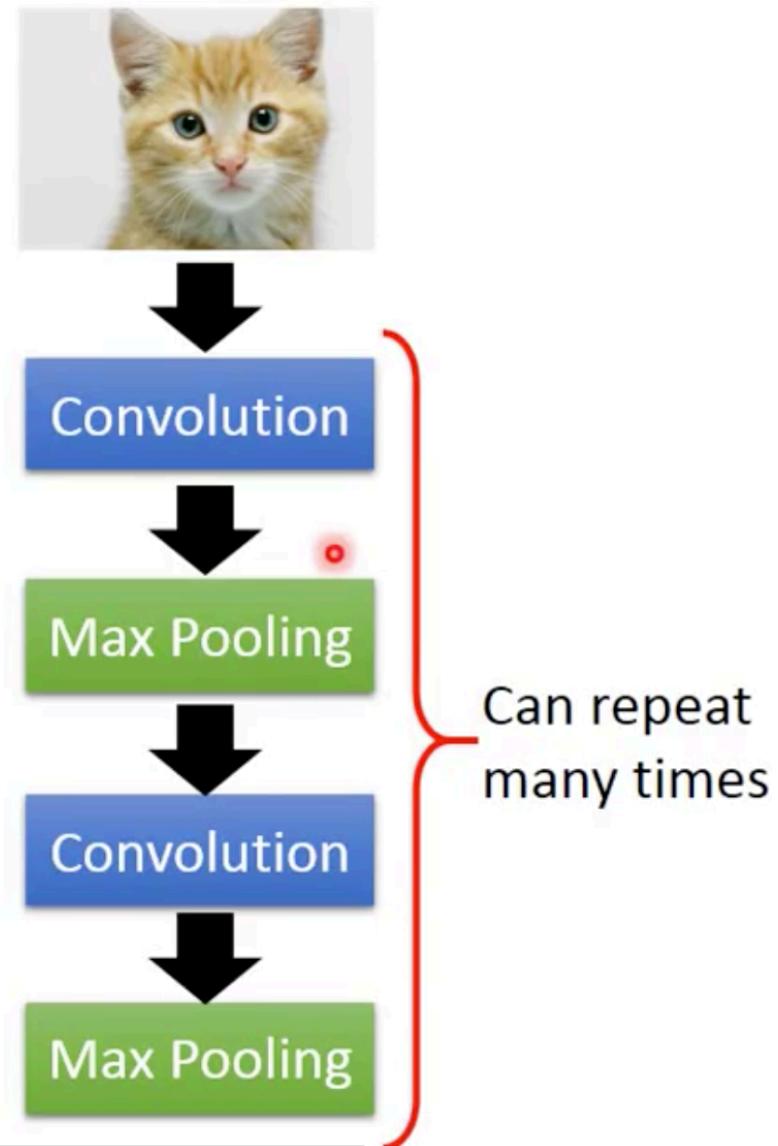
subsampling

bird

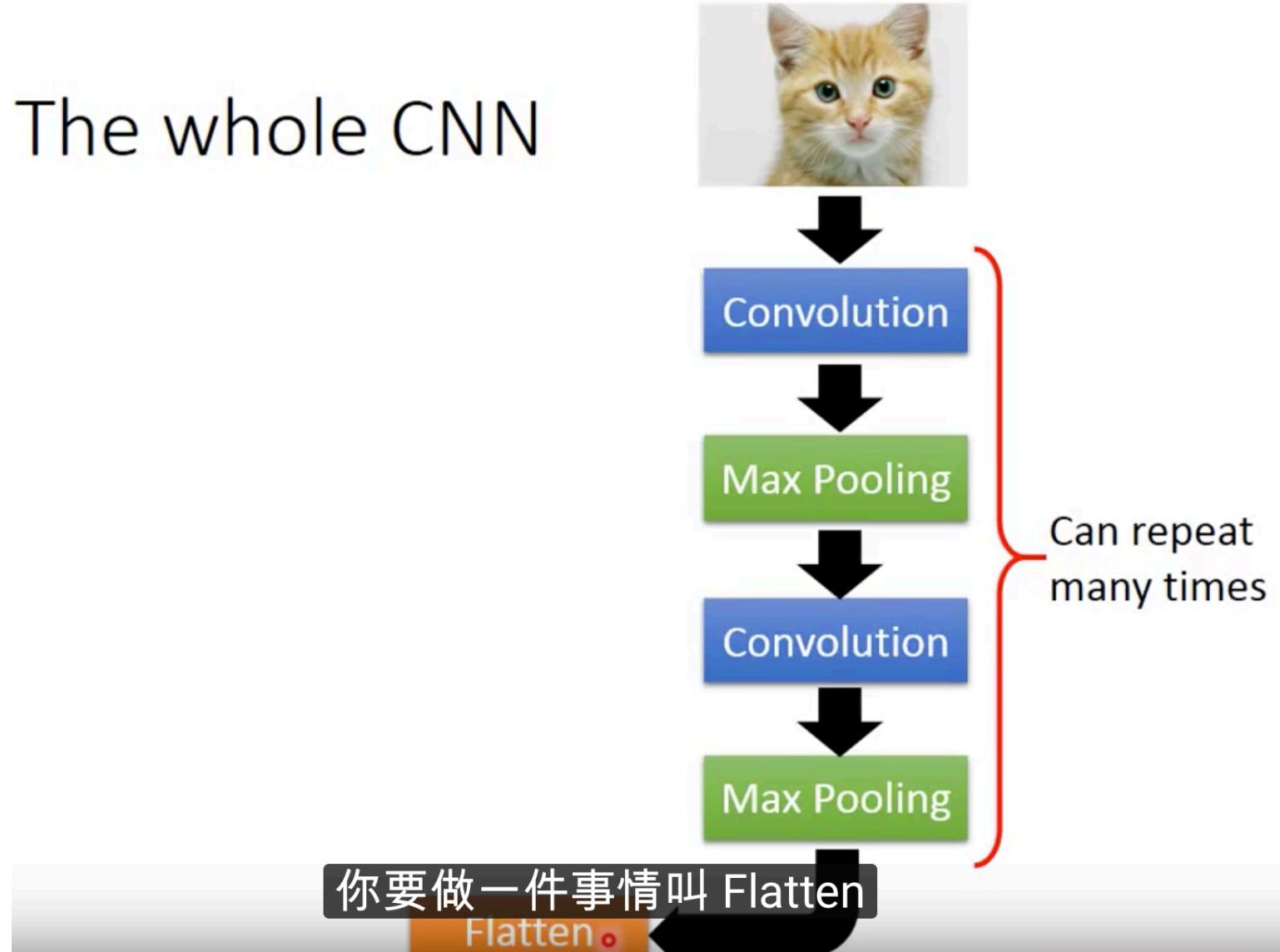


We can subsample the pixels to make image smaller

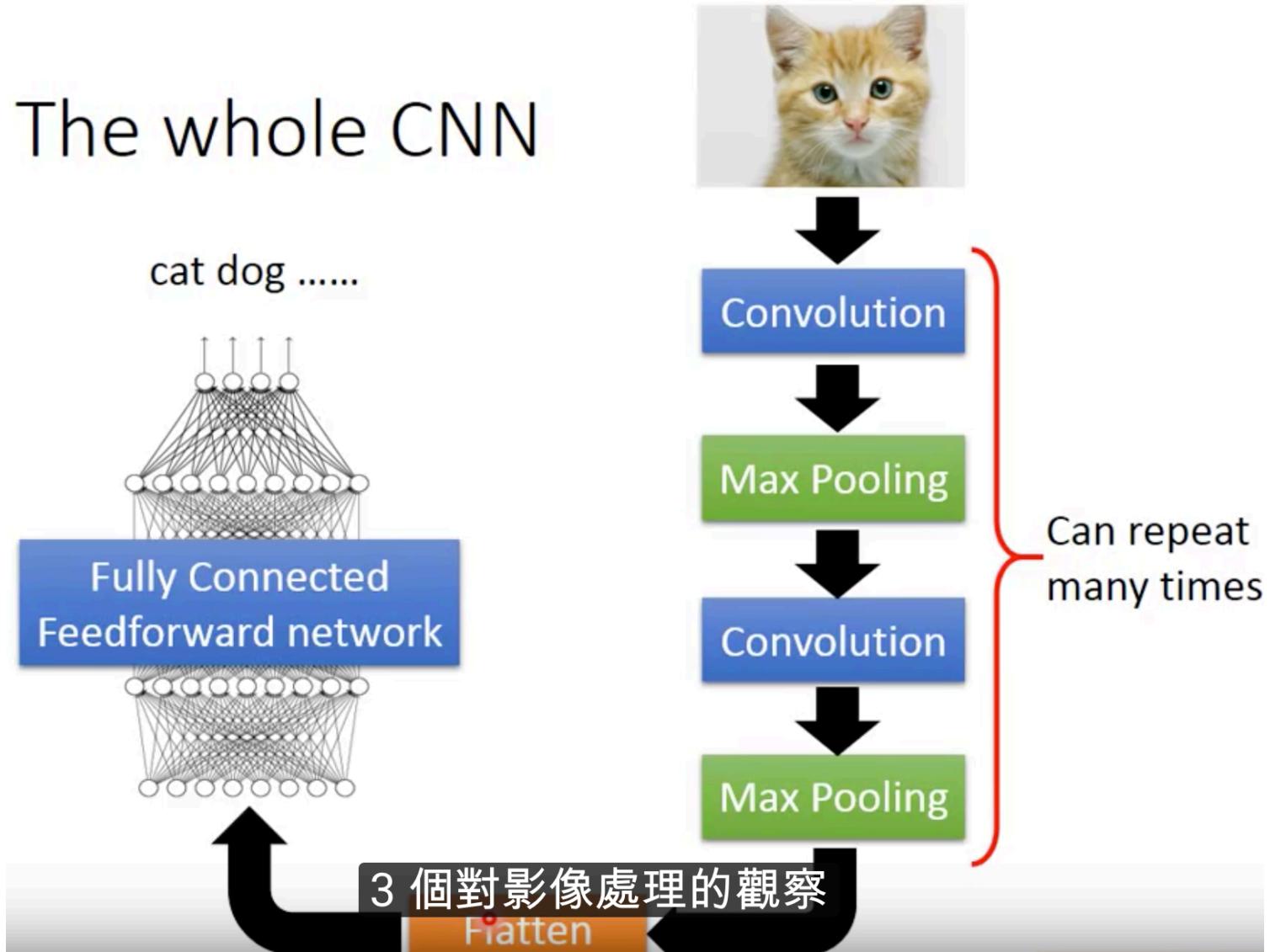
The whole CNN



The whole CNN



The whole CNN



The whole CNN

Property 1

- Some patterns are much smaller than the whole image

Property 2

- The same patterns appear in different regions.

Property 3

- Subsampling the pixels will not change the object



Convolution

Max Pooling

Convolution

Max Pooling

Can repeat
many times

最後這個 property
Flatten

CNN – Convolution



1	0	0	0	0	1
0	1	0	0	1	0
0	0	1	1	0	0
1	0	0	0	1	0
0	1	0	0	1	0
0	0	1	0	1	0

6 x 6 image

CNN – Convolution

1	0	0	0	0	1
0	1	0	0	1	0
0	0	1	1	0	0
1	0	0	0	1	0
0	1	0	0	1	0
0	0	1	0	1	0

6 x 6 image

1	-1	-1
-1	1	-1
-1	-1	1

Filter 1

-1	1	-1
-1	1	-1
-1	1	-1

Filter 2

⋮

CNN – Convolution

A filter corresponds to a set of neurons

Those are the network
parameters to be learned.

1	0	0	0	0	1
0	1	0	0	1	0
0	0	1	1	0	0
1	0	0	0	1	0
0	1	0	0	1	0
0	0	1	0	1	0

6 x 6 image

1	-1	-1
-1	1	-1
-1	-1	1

Filter 1

Matrix

-1	1	-1
-1	1	-1
-1	1	-1

Filter 2

Matrix

⋮

CNN – Convolution

1	-1	-1
-1	1	-1
-1	-1	1

Filter 1

1	0	0	0	0	1
0	1	0	0	1	0
0	0	1	1	0	0
1	0	0	0	1	0
0	1	0	0	1	0
0	0	1	0	1	0

How does a filter operate?

6 x 6 image

CNN – Convolution

1	-1	-1
-1	1	-1
-1	-1	1

Filter 1

1	0	0	0	0	1
0	1	0	0	1	0
0	0	1	1	0	0
1	0	0	0	1	0
0	1	0	0	1	0
0	0	1	0	1	0

Do inner product (dot product)

6 x 6 image

CNN – Convolution

1	0	0	0	0	1
0	1	0	0	1	0
0	0	1	1	0	0
1	0	0	0	1	0
0	1	0	0	1	0
0	0	1	0	1	0

6 x 6 image

1	-1	-1
-1	1	-1
-1	-1	1

Filter 1

3

•

CNN – Convolution

stride=1

1	0	0	0	0	1
0	1	0	0	1	0
0	0	1	1	0	0
1	0	0	0	1	0
0	1	0	0	1	0
0	0	1	0	1	0

6 x 6 image

1	-1	-1
-1	1	-1
-1	-1	1

Filter 1



CNN – Convolution

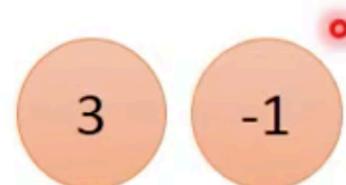
stride=1

1	0	0	0	0	1
0	1	0	0	1	0
0	0	1	1	0	0
1	0	0	0	1	0
0	1	0	0	1	0
0	0	1	0	1	0

6 x 6 image

1	-1	-1
-1	1	-1
-1	-1	1

Filter 1



CNN – Convolution

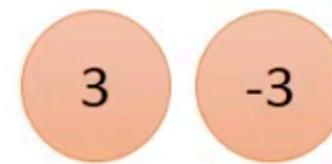
If stride=2

1	0	0	0	0	1
0	1	0	0	1	0
0	0	1	1	0	0
1	0	0	0	1	0
0	1	0	0	1	0
0	0	1	0	1	0

6 x 6 image

1	-1	-1
-1	1	-1
-1	-1	1

Filter 1



We set stride = 1 in the following slides.

CNN – Convolution

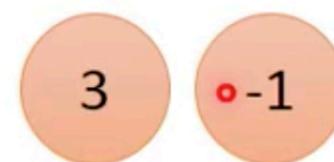
stride=1

1	0	0	0	0	1
0	1	0	0	1	0
0	0	1	1	0	0
1	0	0	0	1	0
0	1	0	0	1	0
0	0	1	0	1	0

6 x 6 image

1	-1	-1
-1	1	-1
-1	-1	1

Filter 1



CNN – Convolution

stride=1

1	0	0	0	0	1
0	1	0	0	1	0
0	0	1	1	0	0
1	0	0	0	1	0
0	1	0	0	1	0
0	0	1	0	1	0

6 x 6 image

1	-1	-1
-1	1	-1
-1	-1	1

Filter 1



CNN – Convolution

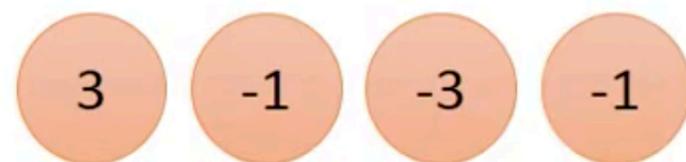
stride=1

1	0	0	0	0	1
0	1	0	0	1	0
0	0	1	1	0	0
1	0	0	0	1	0
0	1	0	0	1	0
0	0	1	0	1	0

6 x 6 image

1	-1	-1
-1	1	-1
-1	-1	1

Filter 1



CNN – Convolution

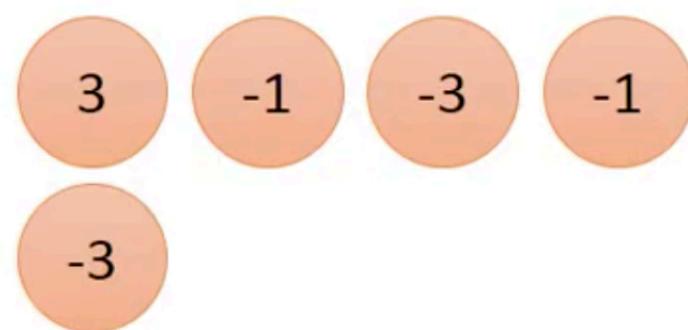
stride=1

1	0	0	0	0	1
0	1	0	0	1	0
0	0	1	1	0	0
1	0	0	0	1	0
0	1	0	0	1	0
0	0	1	0	1	0

6 x 6 image

1	-1	-1
-1	1	-1
-1	-1	1

Filter 1



CNN – Convolution

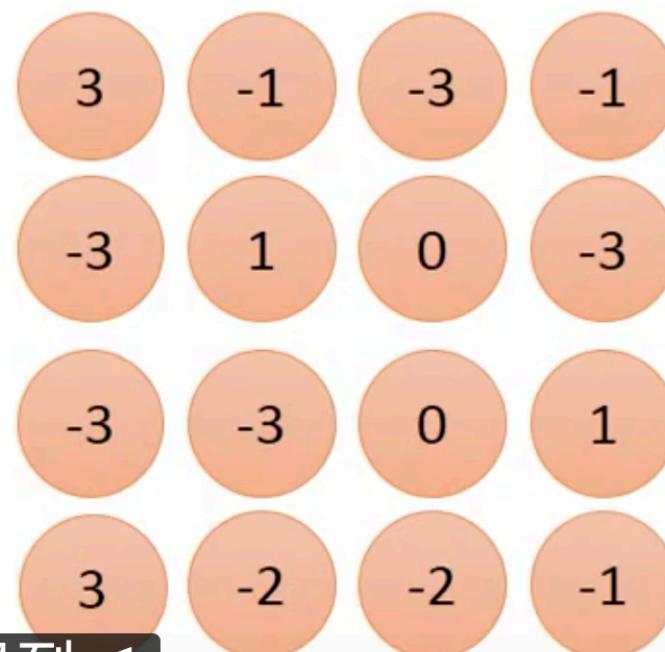
stride=1

1	0	0	0	0	1
0	1	0	0	1	0
0	0	1	1	0	0
1	0	0	0	1	0
0	1	0	0	1	0
0	0	1	0	1	0

6 x 6 image

1	-1	-1
-1	1	-1
-1	-1	1

Filter 1



你就得到 -1

CNN – Convolution

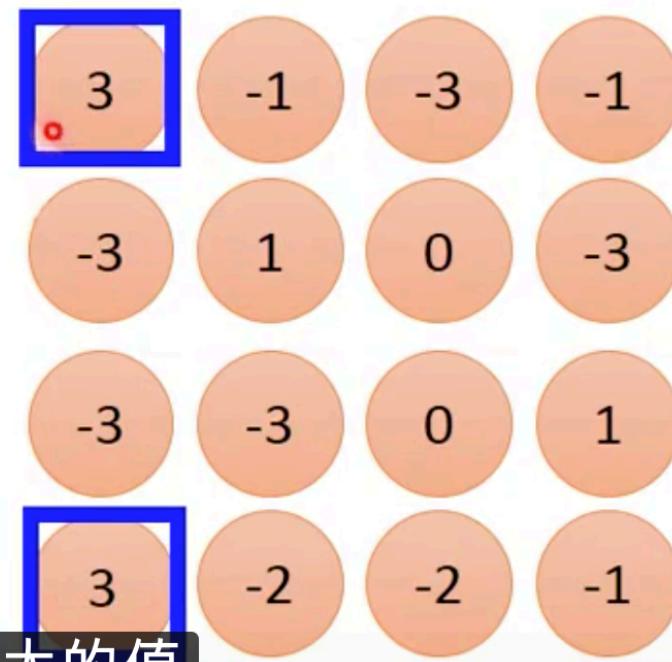
stride=1

1	0	0	0	0	1
0	-	0	0	1	0
0	0	1	1	0	0
1	0	0	0	1	0
0	1	0	0	1	0
0	0	1	0	1	0

6 x 6 image

1	-1	-1
-1	1	-1
-1	-1	1

Filter 1



CNN – Convolution

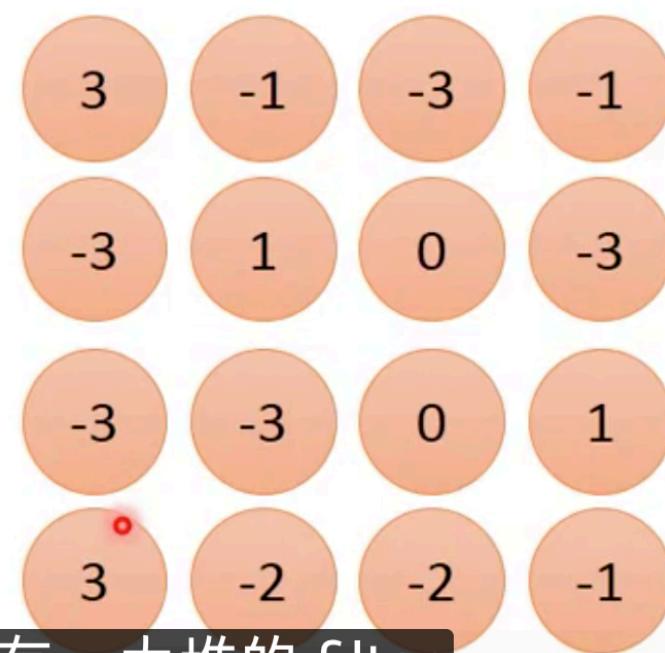
stride=1

1	0	0	0	0	1
0	1	0	0	1	0
0	0	1	1	0	0
1	0	0	0	1	0
0	1	0	0	1	0
0	0	1	0	1	0

6 x 6 image

-1	1	-1
-1	1	-1
-1	1	-1

Filter 2



— filter 它會有一大堆的 filter

CNN – Convolution

stride=1

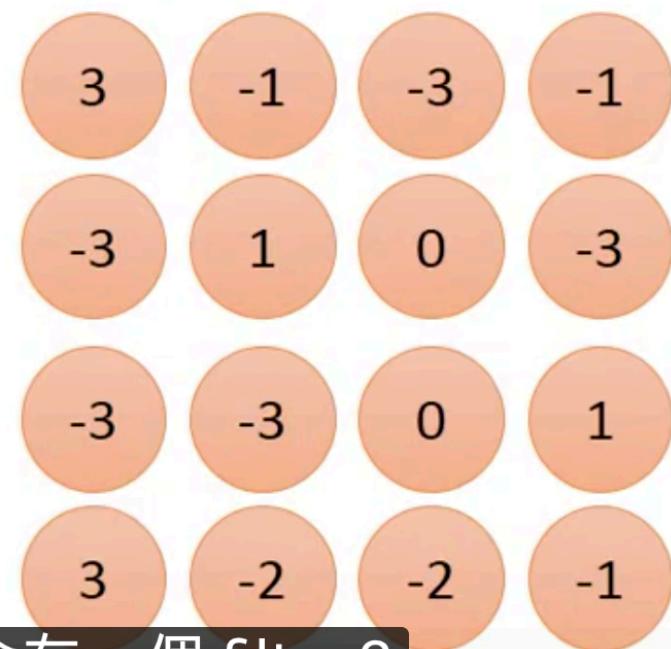
1	0	0	0	0	1
0	1	0	0	1	0
0	0	1	1	0	0
1	0	0	0	1	0
0	1	0	0	1	0
0	0	1	0	1	0

6 x 6 image

-1	1	-1
-1	1	-1
-1	1	-1

Filter 2

Do the same process for
every filter



上加給 3 番目右一個 filter 2

CNN – Convolution

stride=1

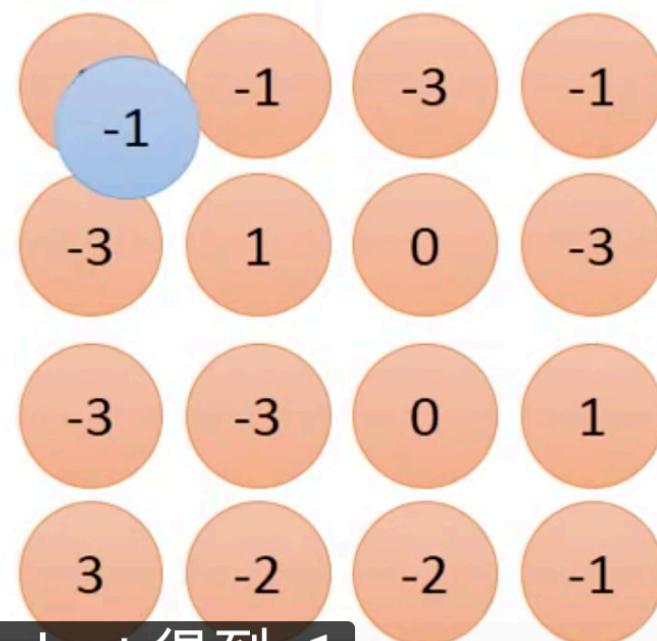
1	0	0	0	0	1
0	1	0	0	1	0
0	0	1	1	0	0
1	0	0	0	1	0
0	1	0	0	1	0
0	0	1	0	1	0

6 x 6 image

-1	1	-1
-1	1	-1
-1	1	-1

Filter 2

Do the same process for every filter



再做 inner product 得到 -1

CNN – Convolution

stride=1

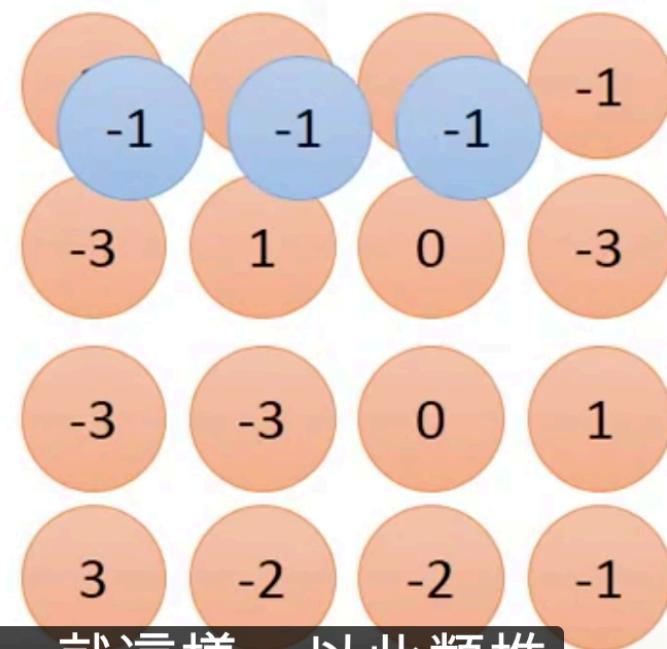
1	0	0	0	0	1
0	1	0	0	1	0
0	0	1	1	0	0
1	0	0	0	1	0
0	1	0	0	1	0
0	0	1	0	1	0

6 x 6 image

-1	1	-1
-1	1	-1
-1	1	-1

Filter 2

Do the same process for
every filter



CNN – Convolution

stride=1

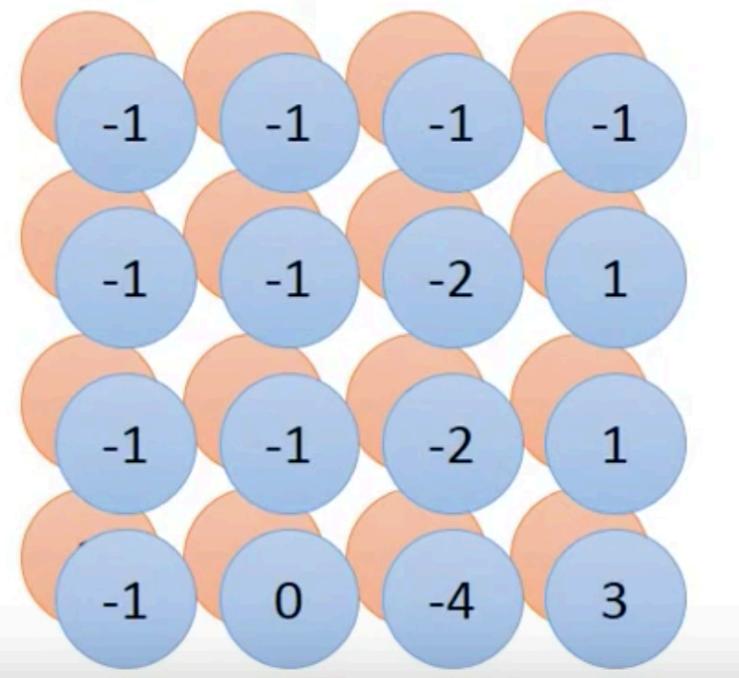
1	0	0	0	0	1
0	1	0	0	1	0
0	0	1	1	0	0
1	0	0	0	1	0
0	1	0	0	1	0
0	0	1	0	1	0

6 x 6 image

-1	1	-1
-1	1	-1
-1	1	-1

Filter 2

Do the same process for every filter



CNN – Convolution

stride=1

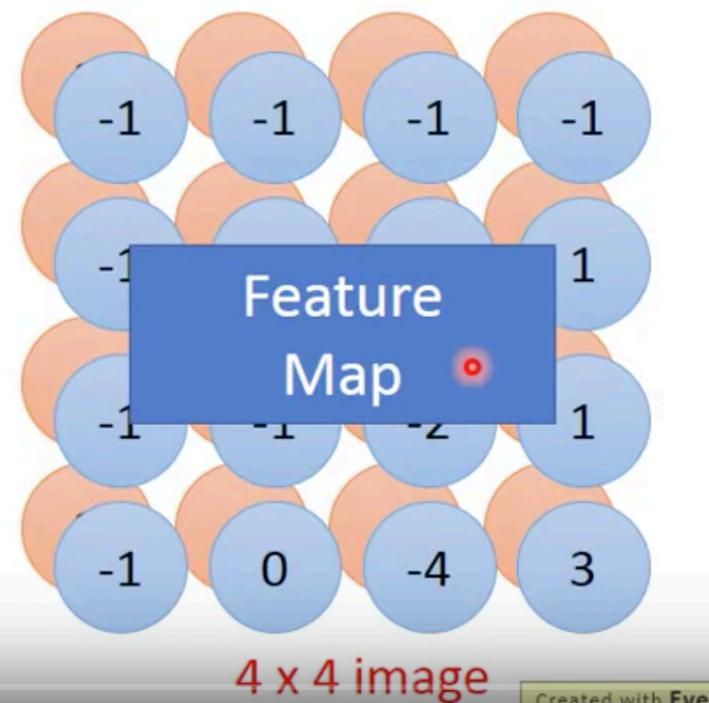
1	0	0	0	0	1
0	1	0	0	1	0
0	0	1	1	0	0
1	0	0	0	1	0
0	1	0	0	1	0
0	0	1	0	1	0

6 x 6 image

-1	1	-1
-1	1	-1
-1	1	-1

Filter 2

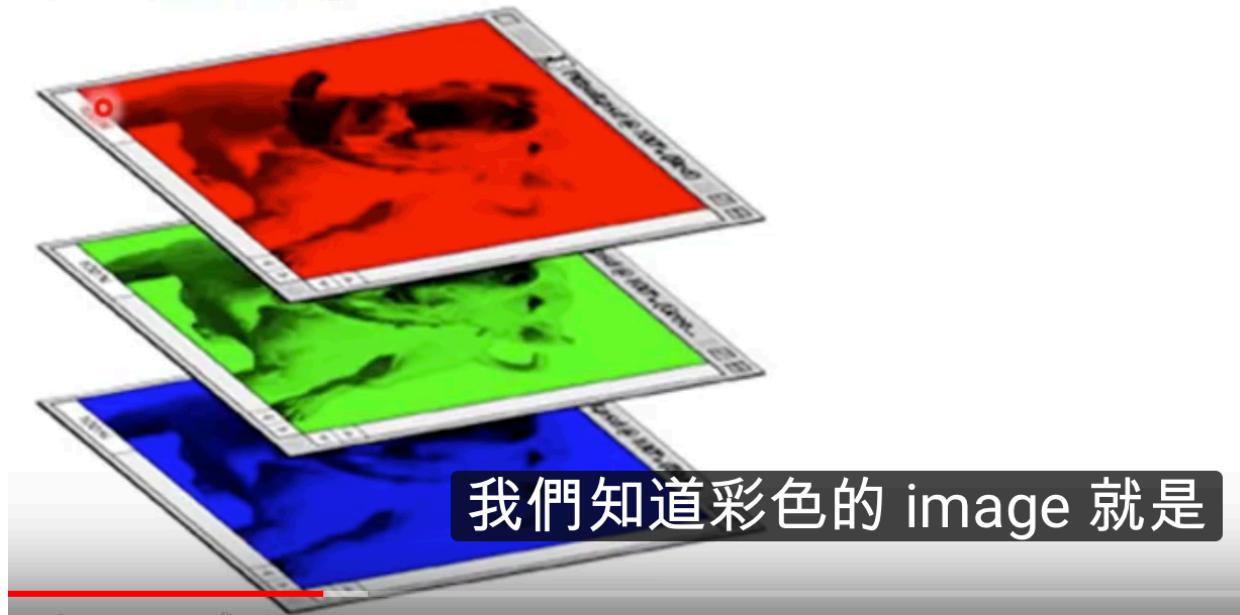
Do the same process for every filter



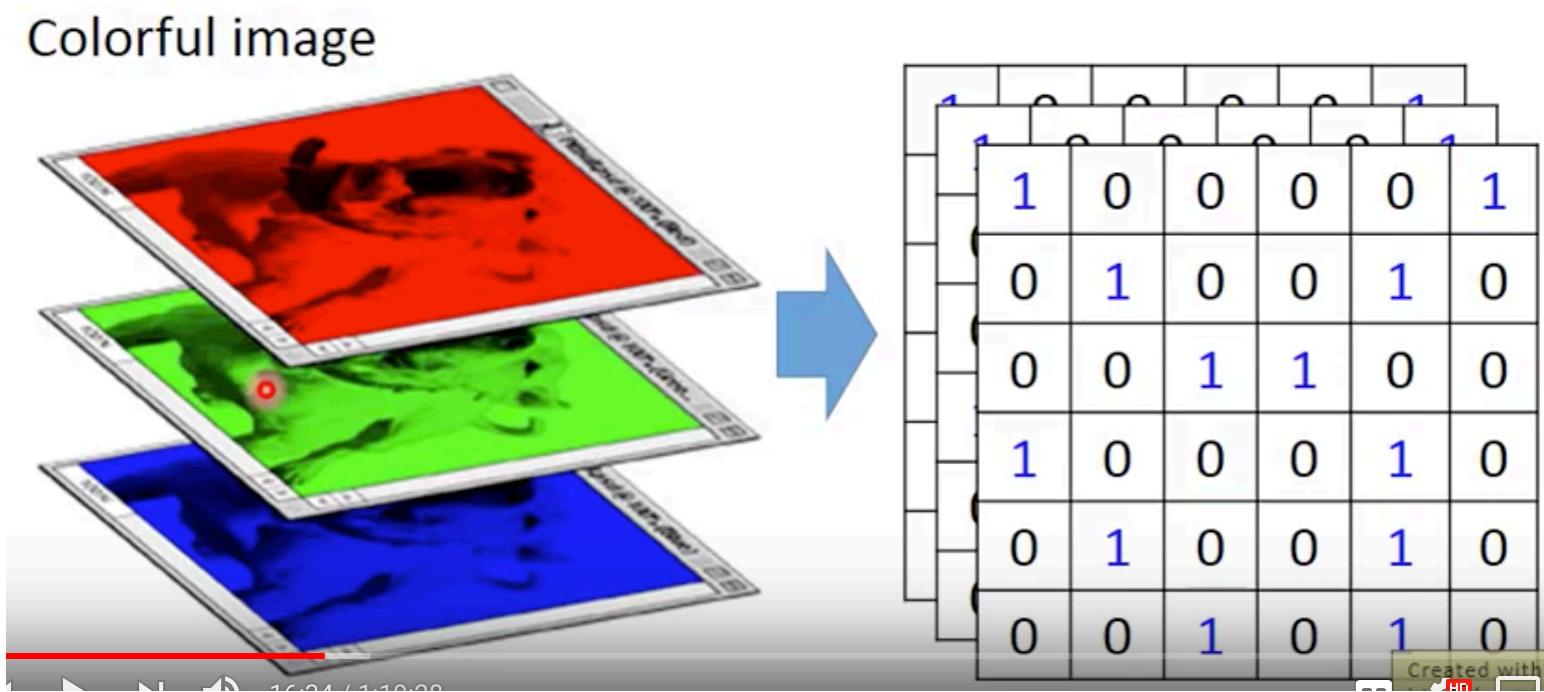
Created with Ever

CNN – Colorful image

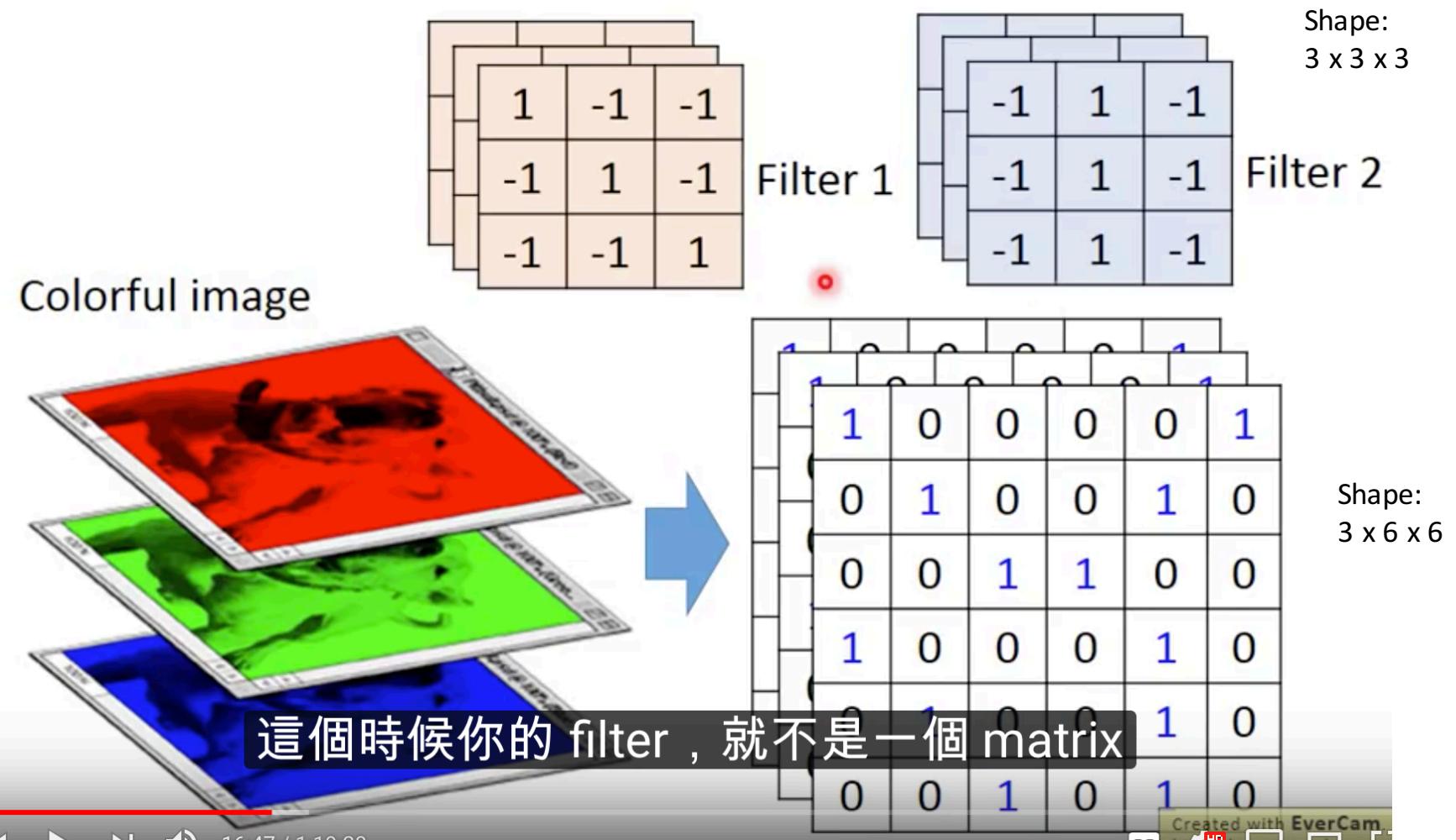
Colorful image



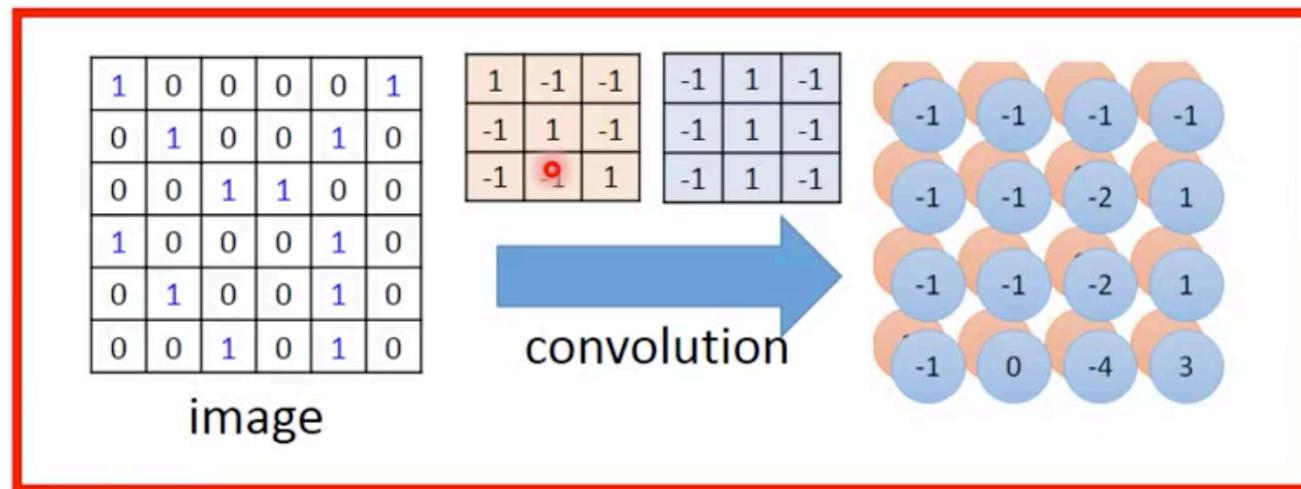
CNN – Colorful image



CNN – Colorful image



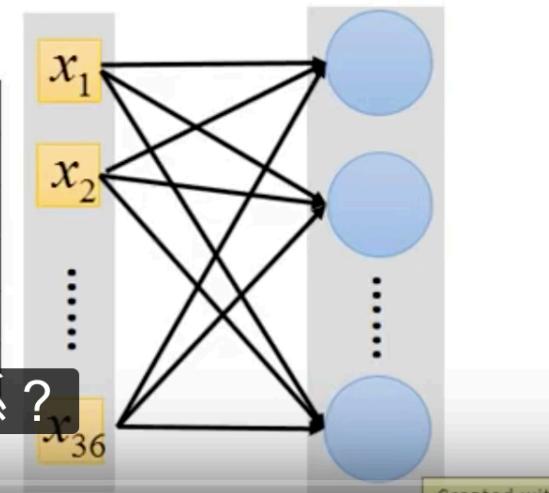
Convolution v.s. Fully Connected



Fully-
connected

1	0	0	0	0	1
0	1	0	0	1	0
0	0	1	1	0	0
1	0	0	0	1	0
0	1	0	0	1	0
0	0	1	0	1	0

有什麼關係？



1	-1	-1
-1	1	-1
-1	-1	1

Filter 1

1	0	0	0	0	1
0	1	0	0	1	0
0	0	1	1	0	0
1	0	0	0	1	0
0	1	0	0	1	0
0	0	1	0	1	0

6 x 6 image

$$\begin{bmatrix} 1 & -1 & -1 \\ -1 & 1 & -1 \\ -1 & -1 & 1 \end{bmatrix}$$

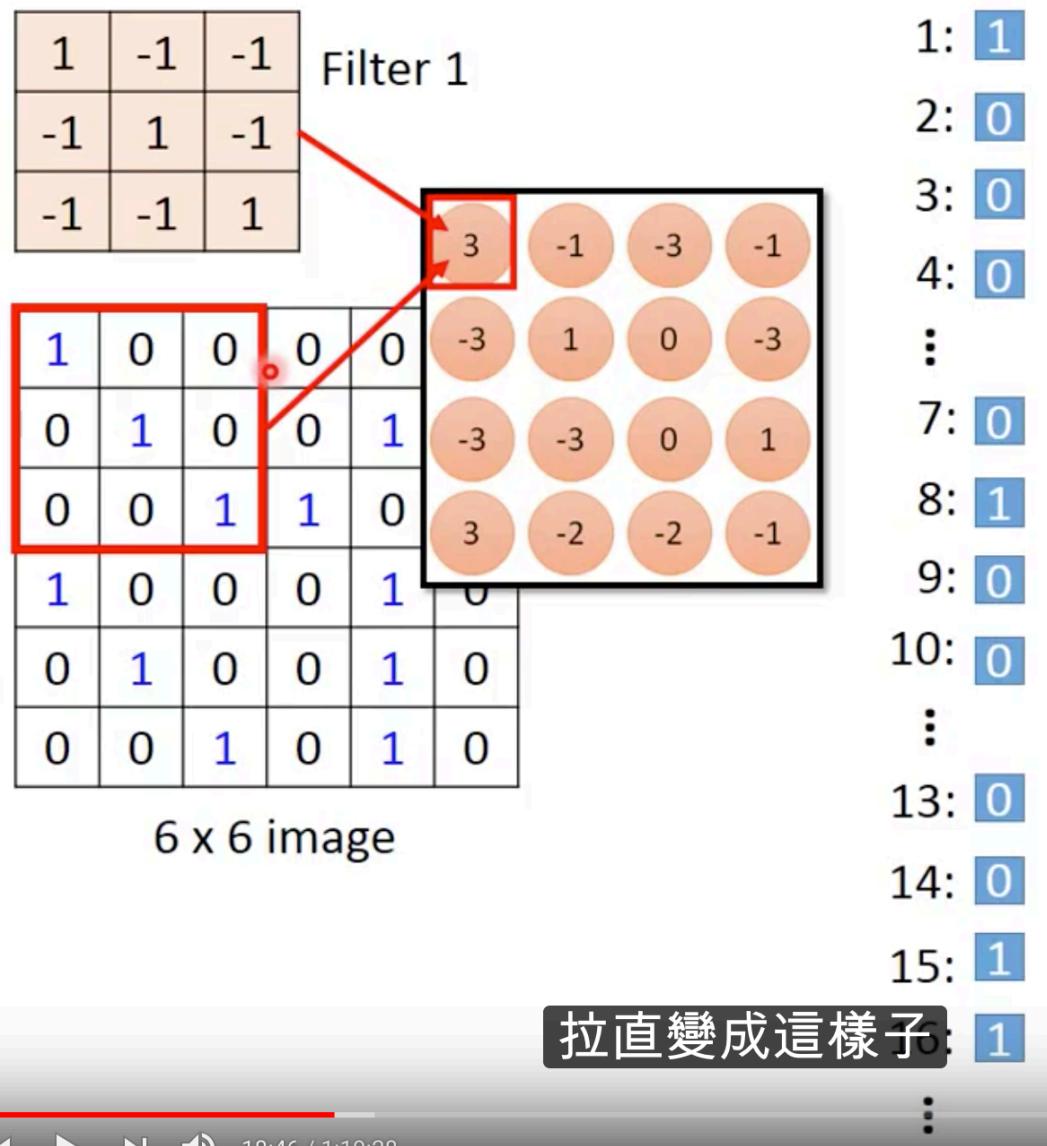
Filter 1

$$\begin{array}{c} \textcircled{1} \\ \boxed{\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}} \\ \begin{bmatrix} 1 & 0 & 0 & 0 & 1 \\ 0 & 1 & 0 & 0 & 1 \\ 0 & 0 & 1 & 1 & 0 \\ 1 & 0 & 0 & 0 & 1 \\ 0 & 1 & 0 & 0 & 1 \\ 0 & 0 & 1 & 0 & 1 \end{bmatrix} \\ \hline \end{array}$$

Diagram illustrating the convolution process:

- Input Image:** A 6x6 grid of values. A 3x3 receptive field in the center is highlighted with a red box.
- Filter 1:** A 3x3 kernel with values: $\begin{bmatrix} 1 & -1 & -1 \\ -1 & 1 & -1 \\ -1 & -1 & 1 \end{bmatrix}$.
- Output Feature Map:** A 3x4 grid of circular nodes. The node at position (1,1) contains the value 3, which is highlighted with a red box. Arrows point from the highlighted receptive field in the input to this node.

6 x 6 image

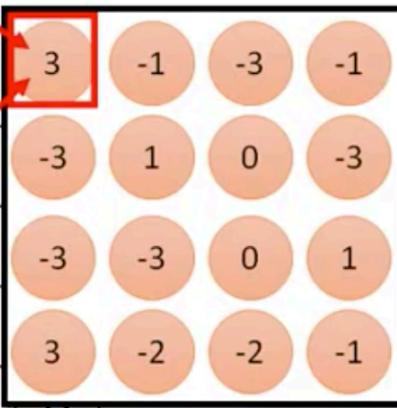


$$\begin{matrix} 1 & -1 & -1 \\ -1 & 1 & -1 \\ -1 & -1 & 1 \end{matrix}$$

Filter 1

$$\begin{matrix} 1 & 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 & 1 \\ 0 & 0 & 1 & 1 & 0 \\ 1 & 0 & 0 & 0 & 1 \\ 0 & 1 & 0 & 0 & 1 \\ 0 & 0 & 1 & 0 & 1 \end{matrix}$$

6 x 6 image



1: 1

2: 0

3: 0

4: 0

⋮

7: 0

8: 1

9: 0

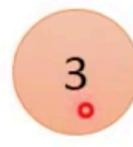
10: 0

⋮

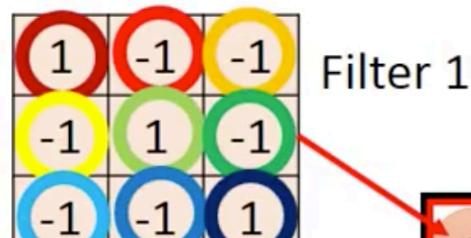
13: 0

14: 0

15: 1

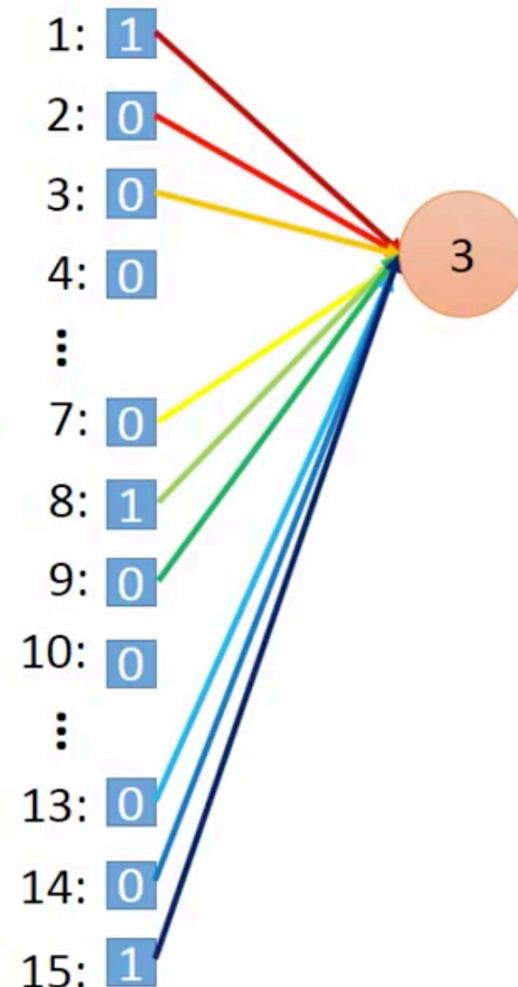
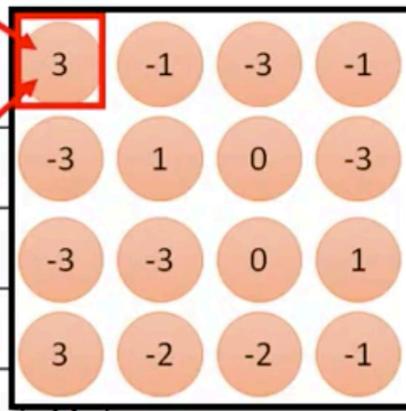


然後，你有一個 neuron 的 output 是 3

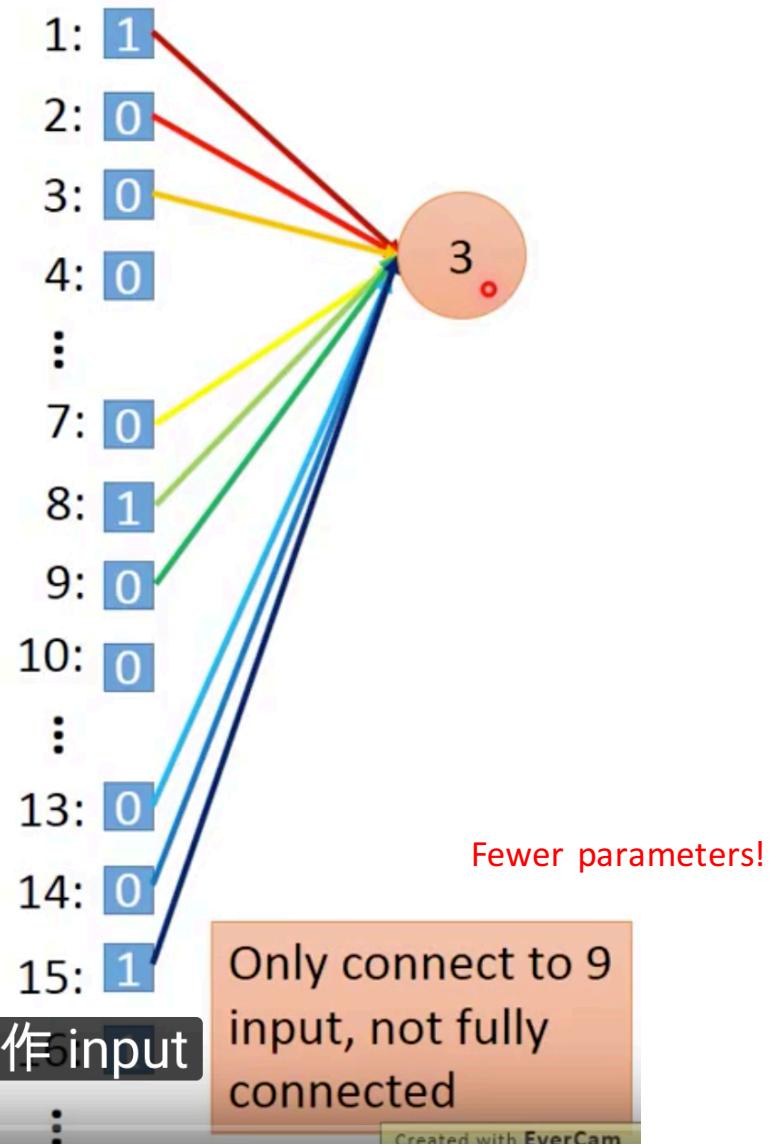
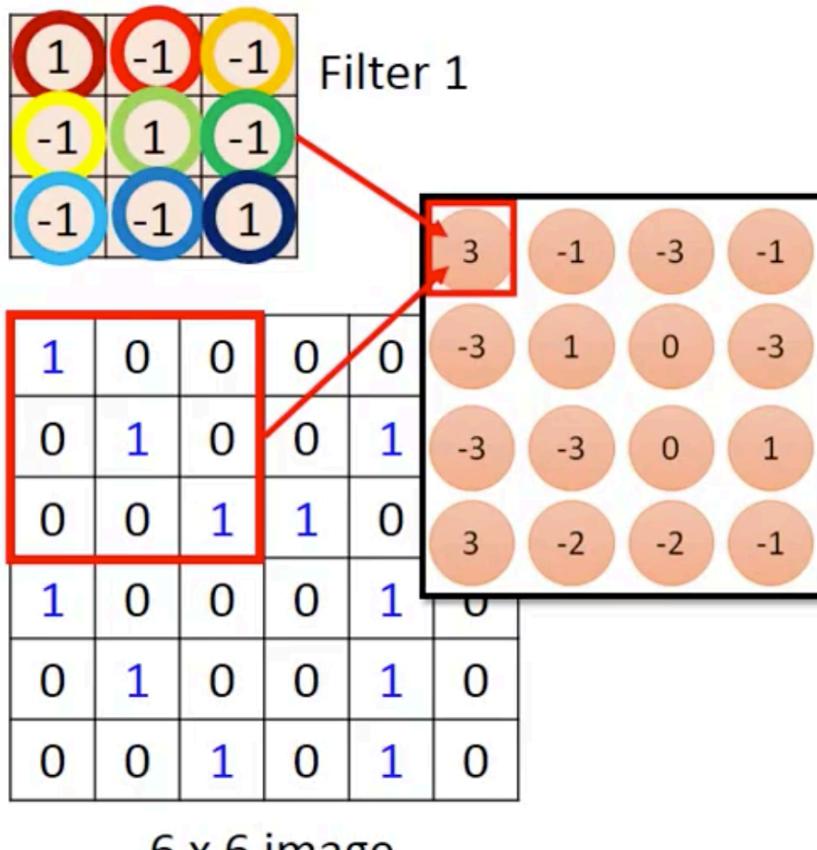


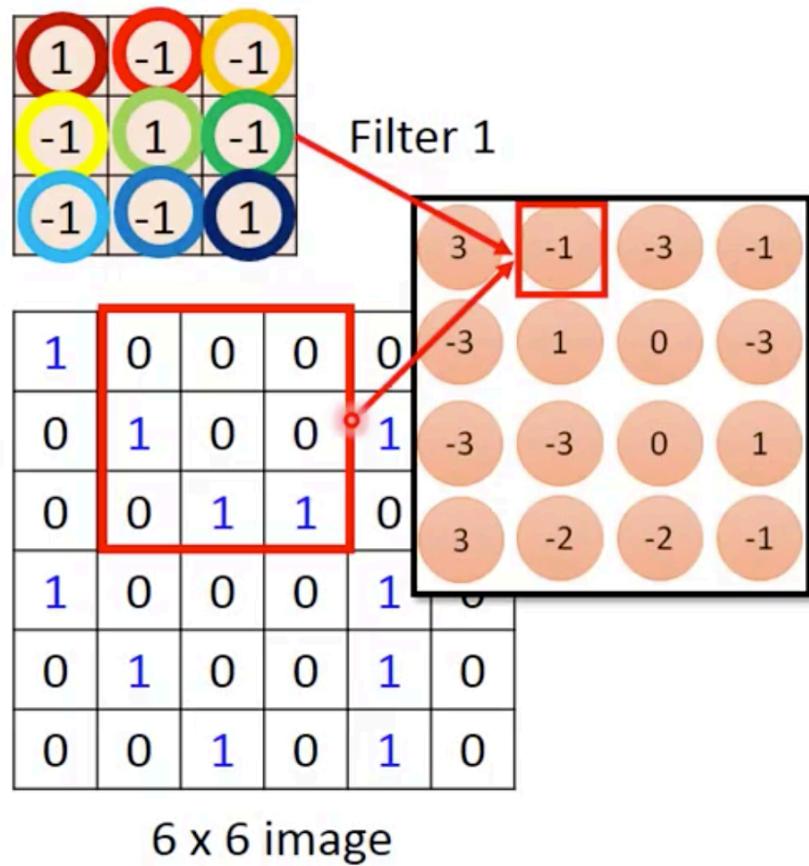
1	0	0	0	0	0
0	1	0	0	0	1
0	0	1	1	0	
1	0	0	0	1	0
0	1	0	0	1	0
0	0	1	0	1	0

6 x 6 image



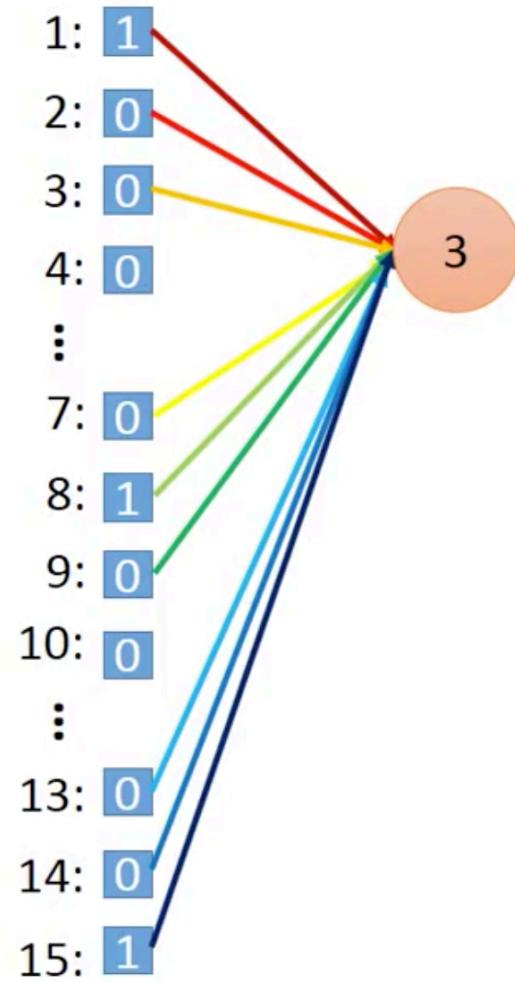
你看這個 filter 6: 1

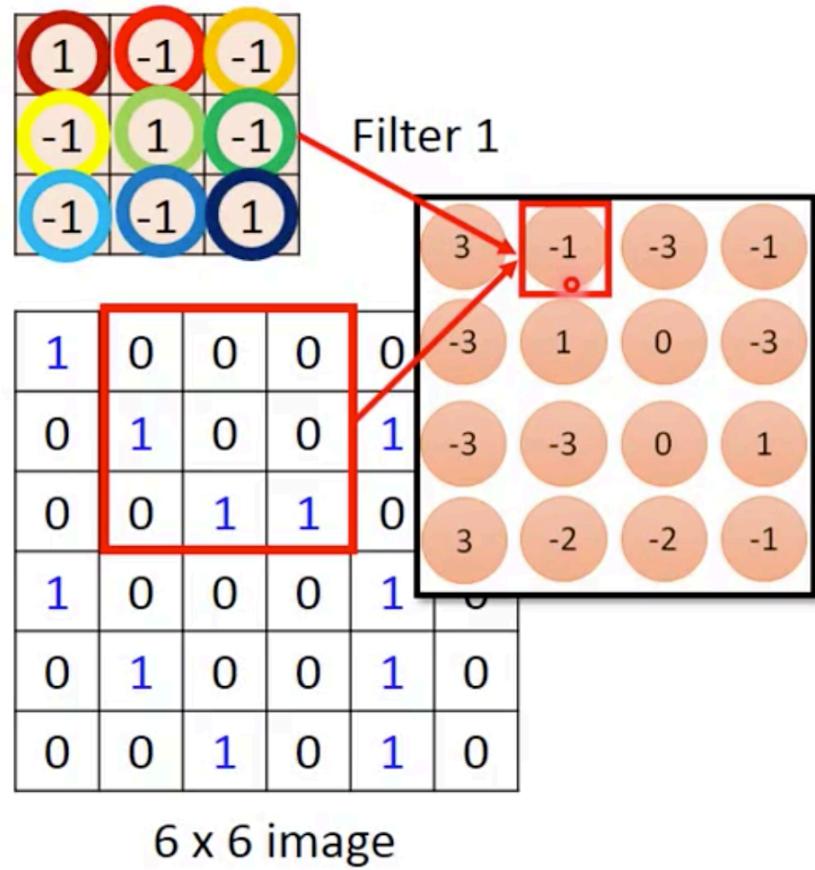




Less parameters!

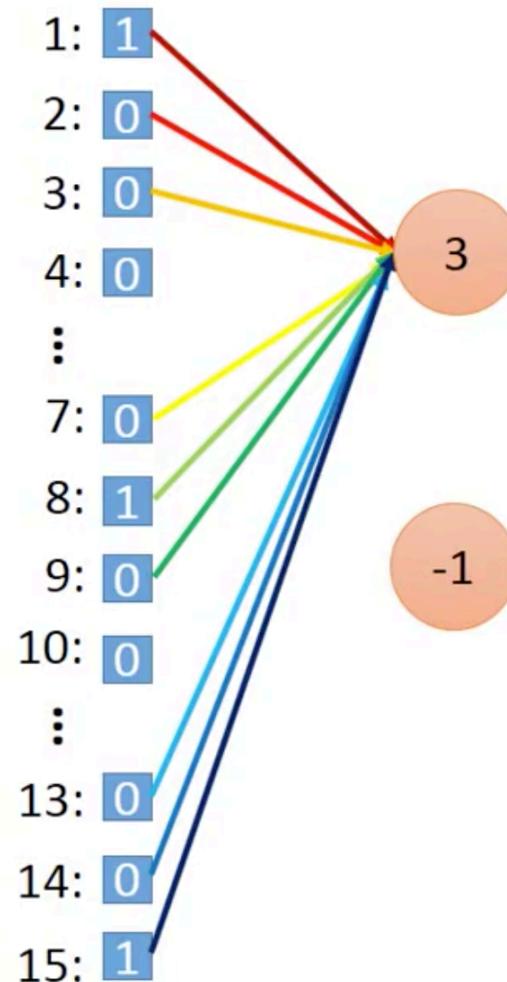
發生甚麼事呢 ?

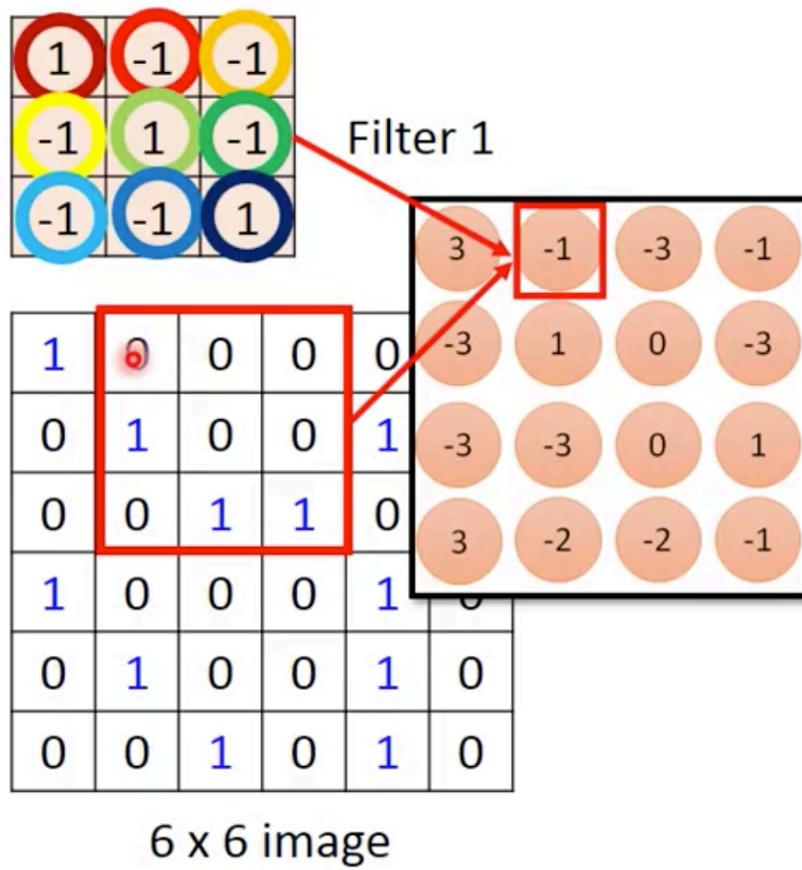




Less parameters!

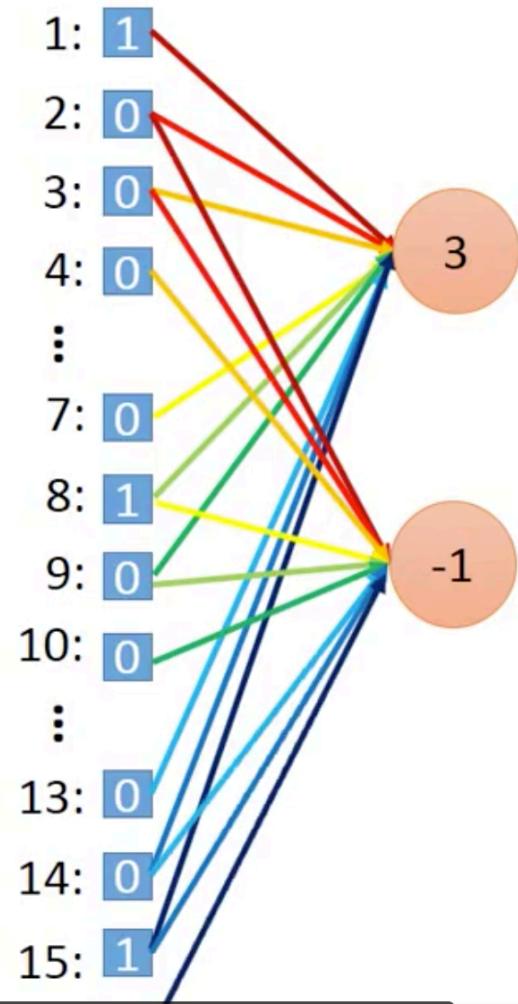
那這個 neuron 連接到哪些 input 的 weight 呢

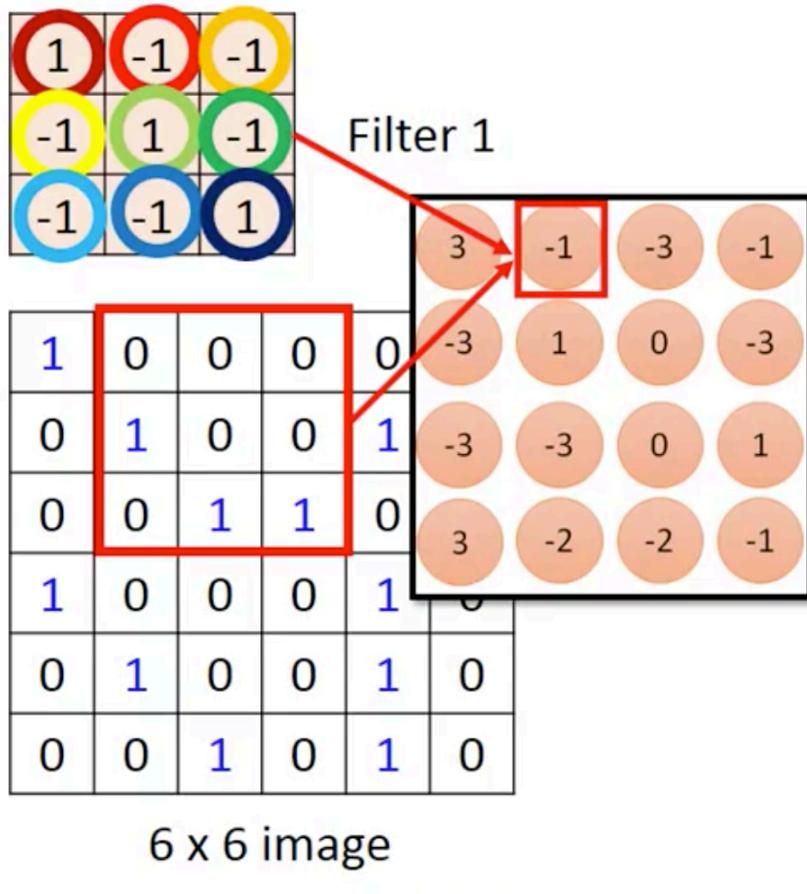




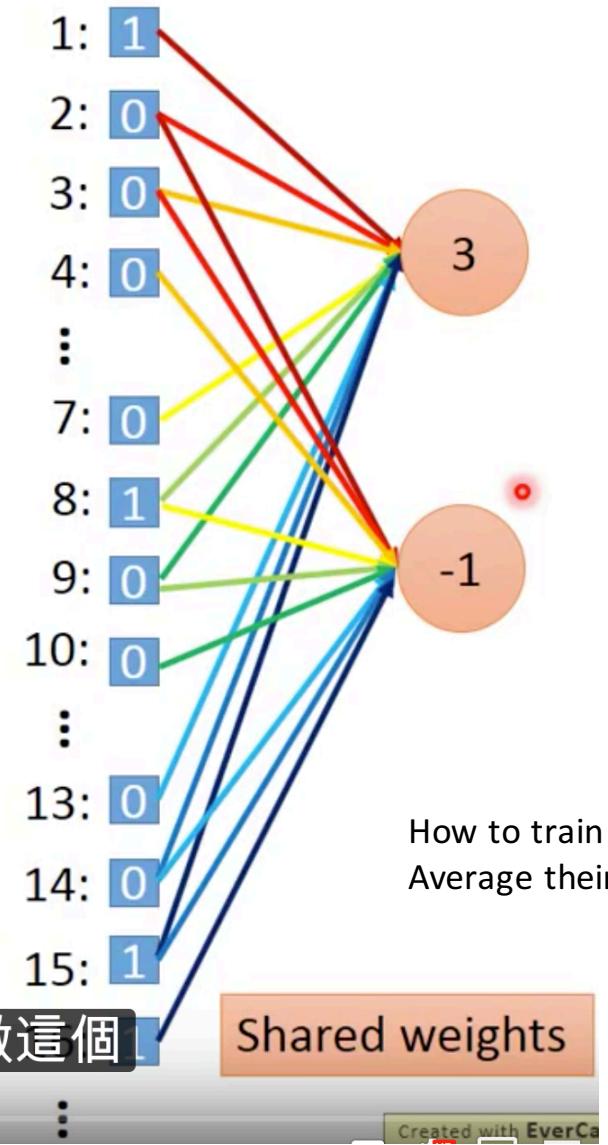
Less parameters!

這個框起來的地方，它正好就對應到 pixel 2, 3, 4



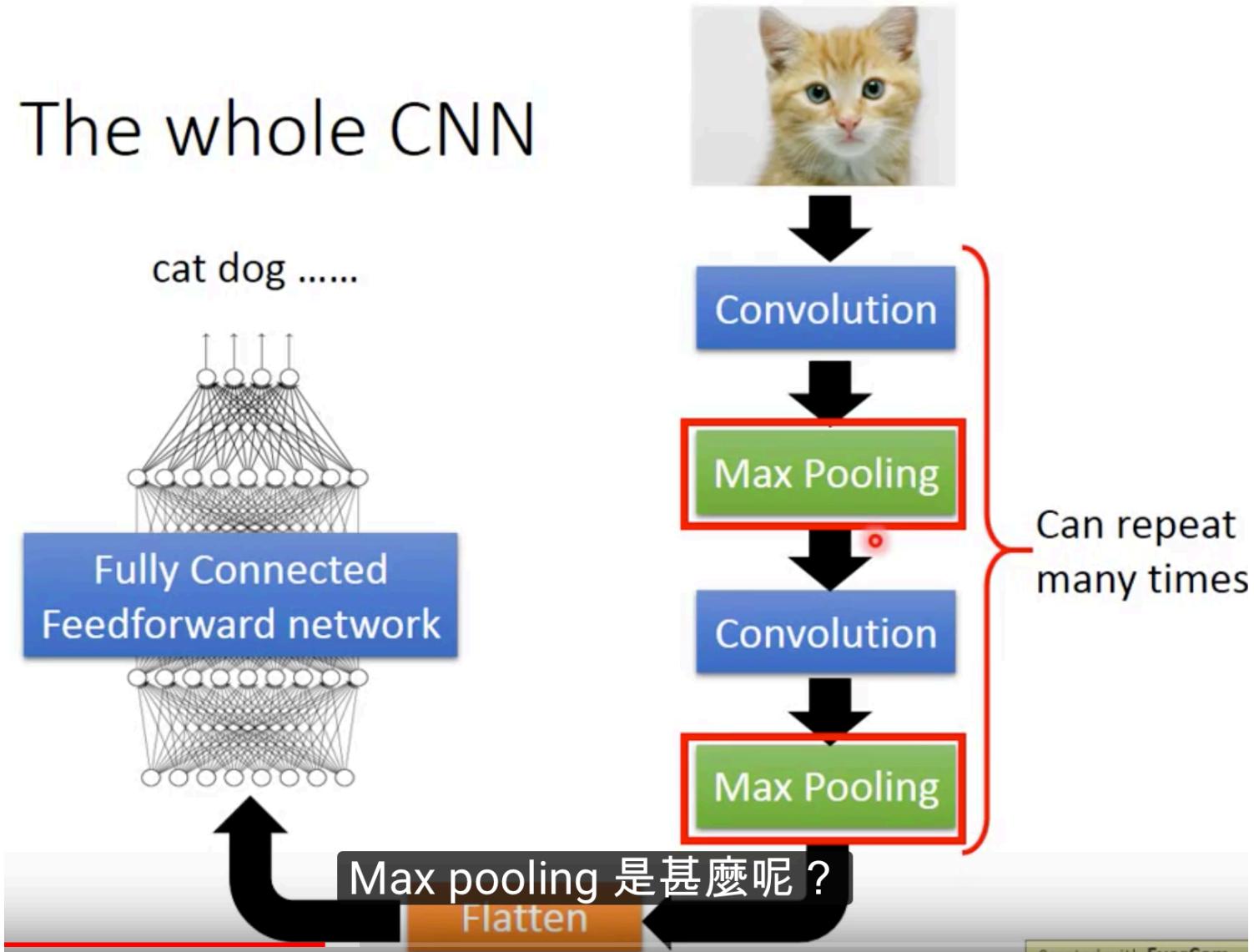


Less parameters!



但是，當我們做這個

The whole CNN



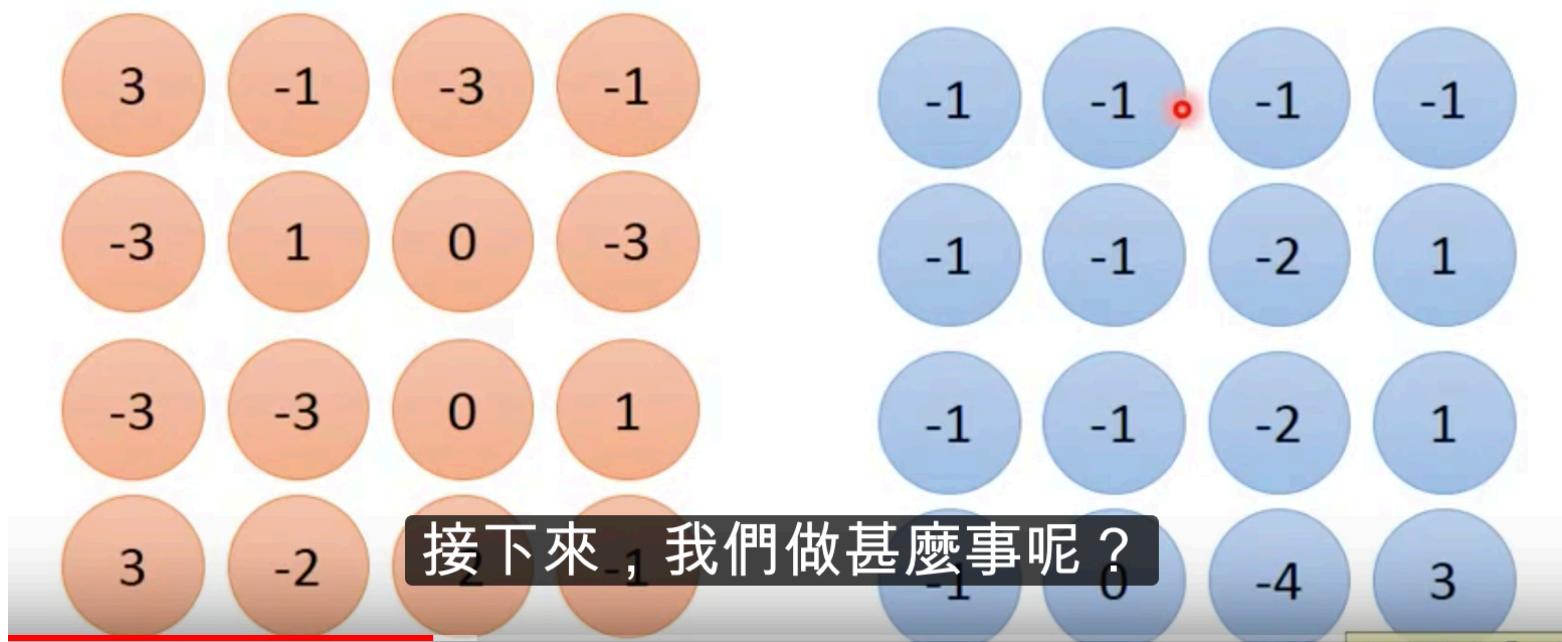
CNN – Max Pooling

1	-1	-1
-1	1	-1
-1	-1	1

Filter 1

-1	1	-1
-1	1	-1
-1	1	-1

Filter 2



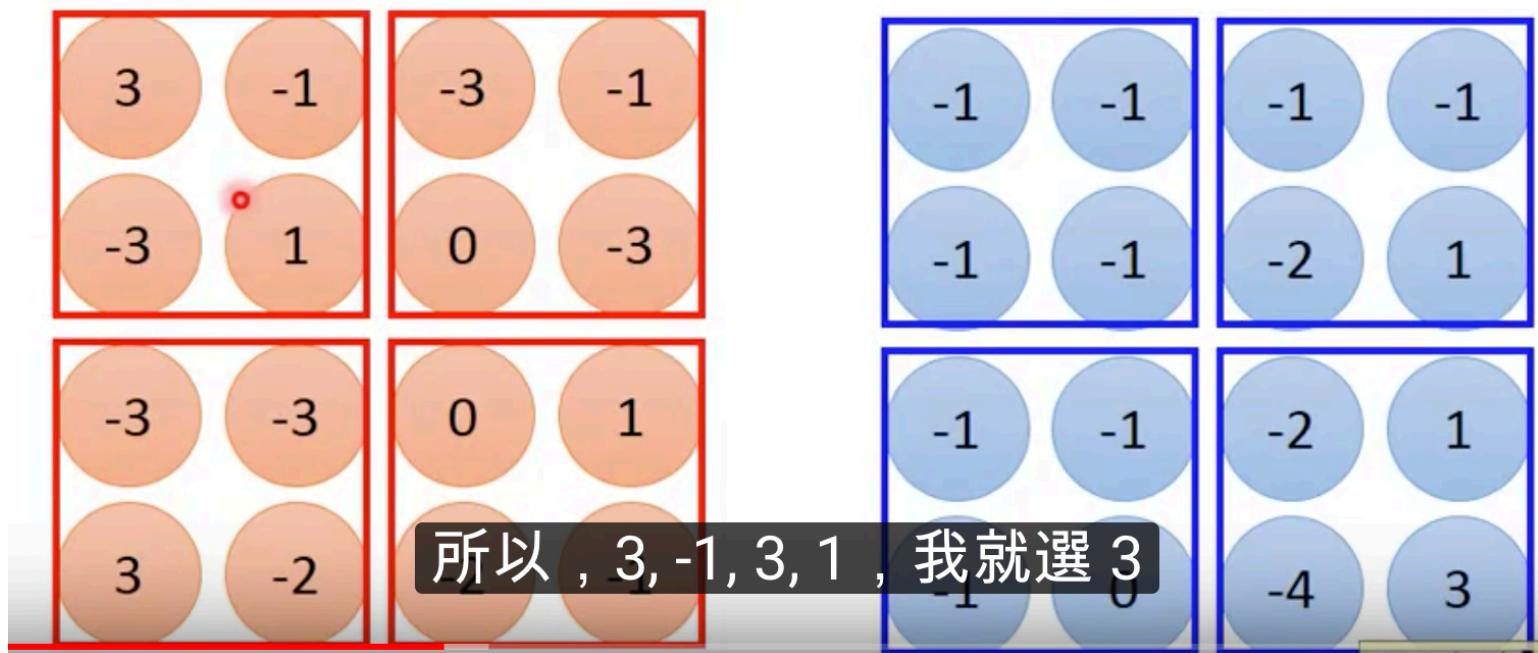
CNN – Max Pooling

1	-1	-1
-1	1	-1
-1	-1	1

Filter 1

-1	1	-1
-1	1	-1
-1	1	-1

Filter 2



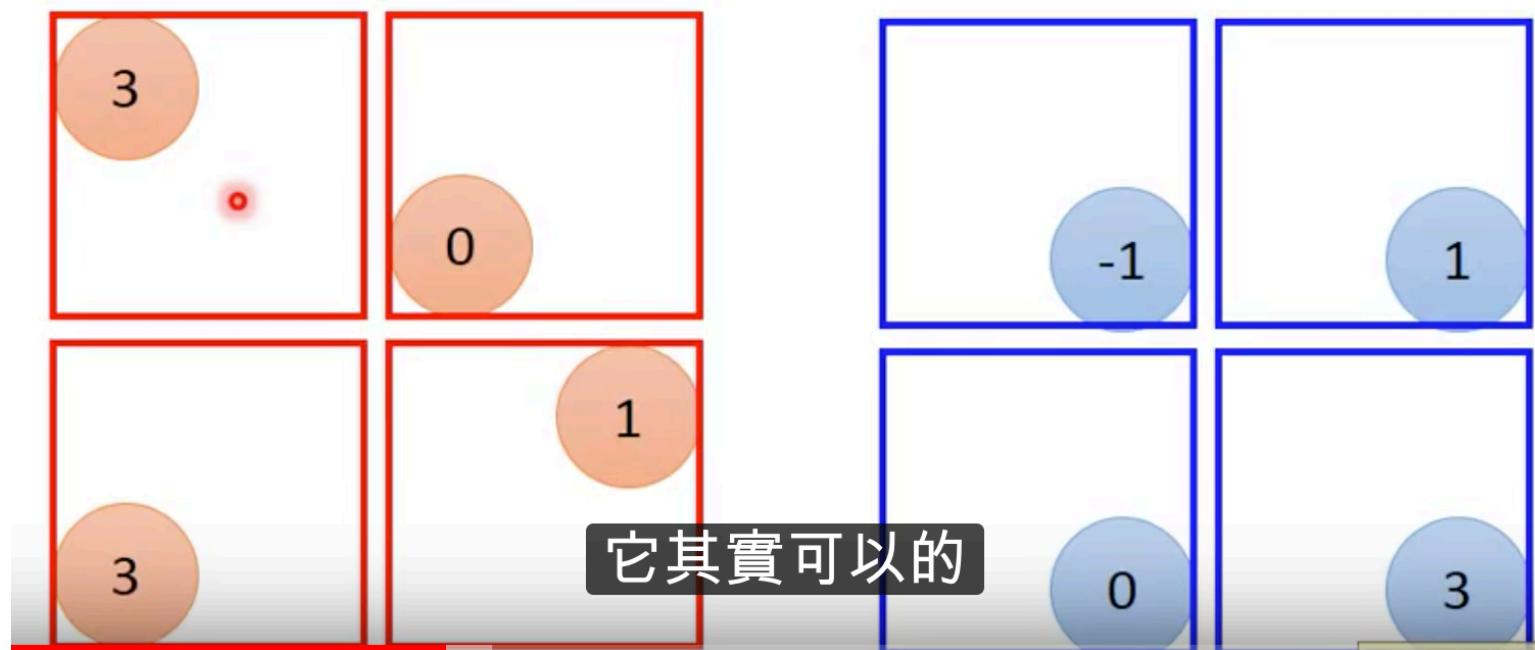
CNN – Max Pooling

1	-1	-1
-1	1	-1
-1	-1	1

Filter 1

-1	1	-1
-1	1	-1
-1	1	-1

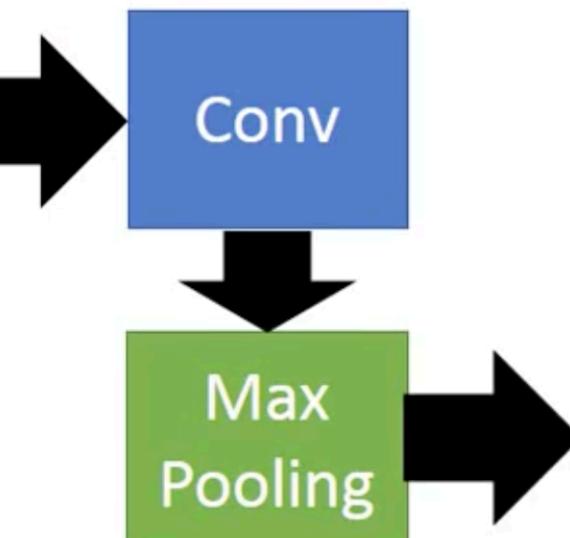
Filter 2



CNN – Max Pooling

1	0	0	0	0	1
0	1	0	0	1	0
0	0	1	1	0	0
1	0	0	0	1	0
0	1	0	0	1	0
0	0	1	0	1	0

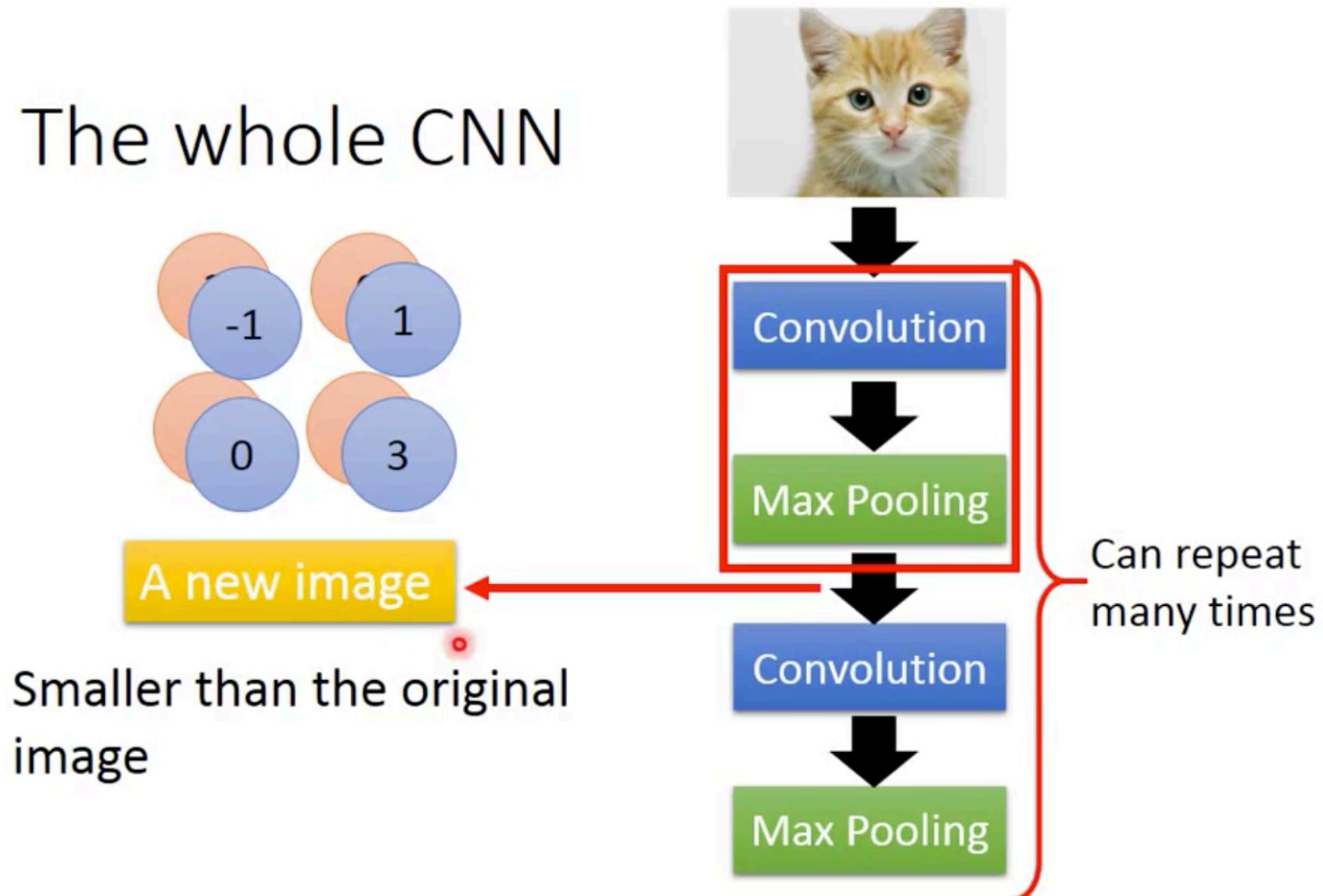
6 x 6 image



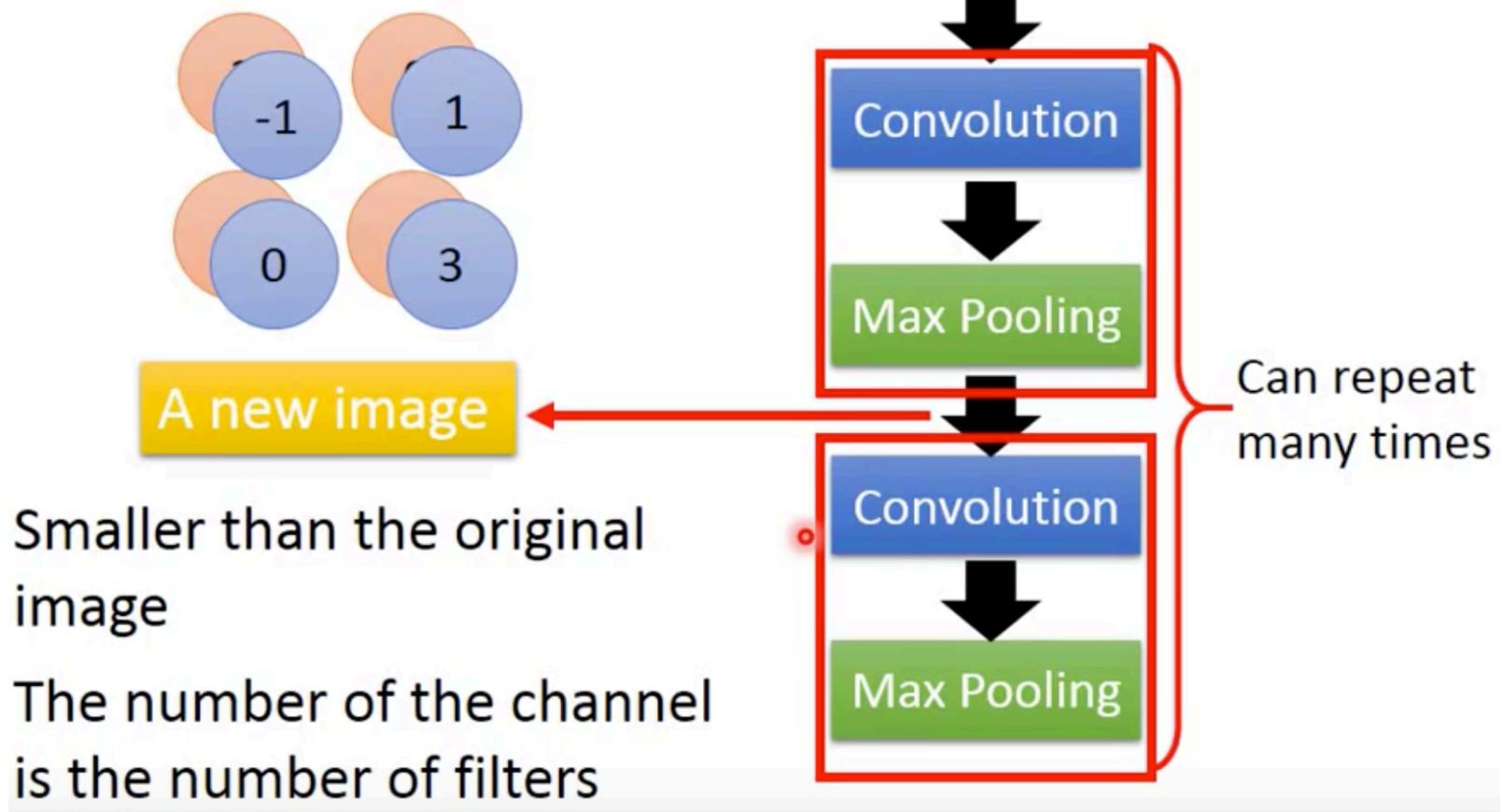
2 x 2 image

Each filter is a channel

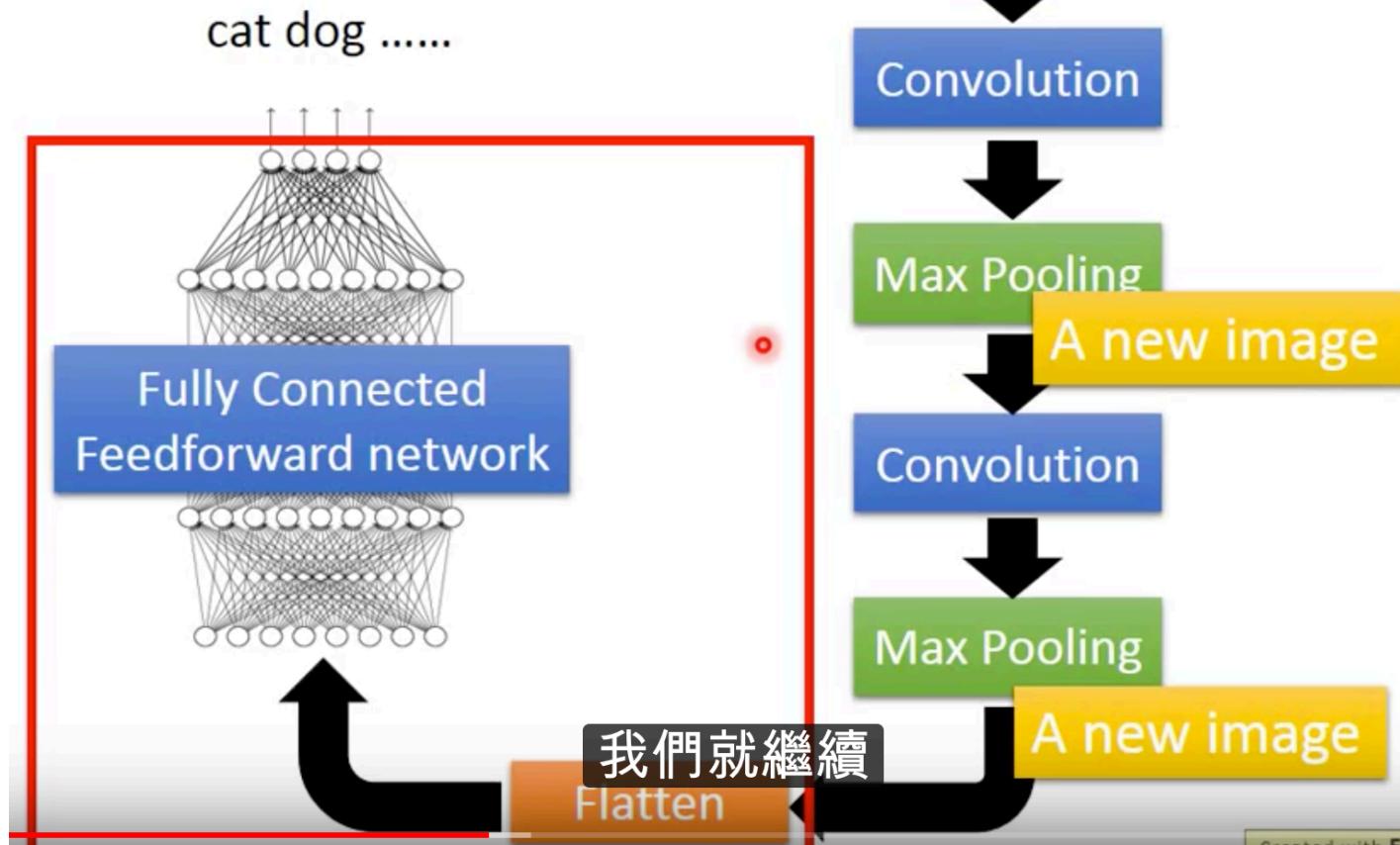
The whole CNN



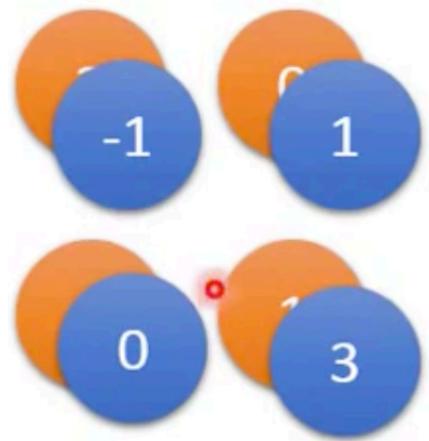
The whole CNN



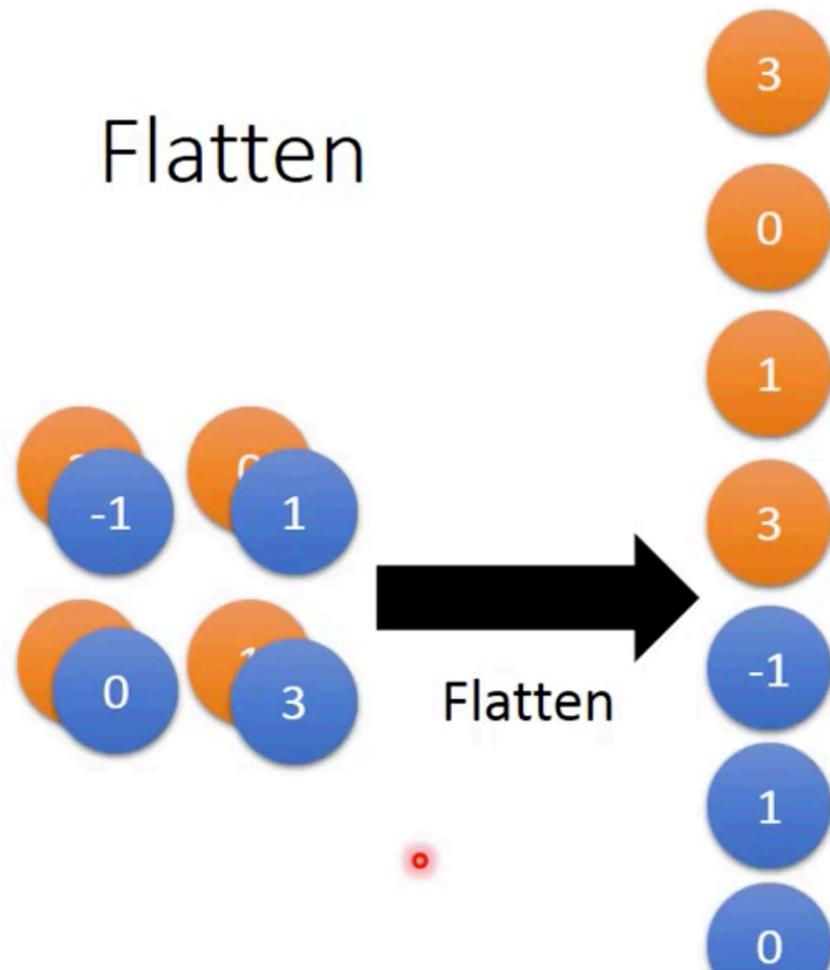
The whole CNN



Flatten

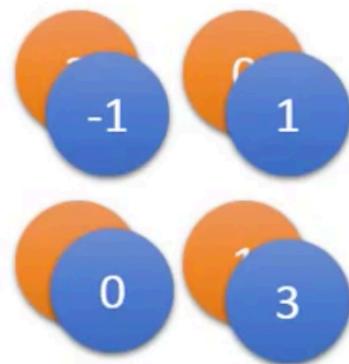


Flatten

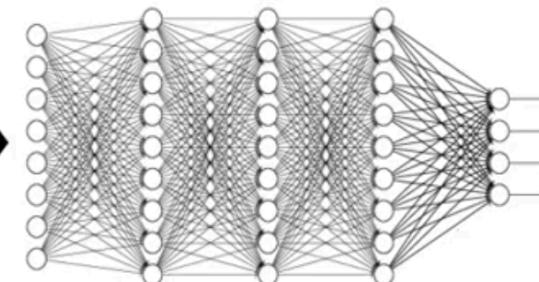


這邊完全沒有學問在

Flatten



Flatten



Fully Connected
Feedforward network

拉直以後，你就把它丟到一個 fully connected 的

CNN in Keras

Only modified the ***network structure*** and
input format (vector -> 3-D tensor)



CNN in Keras

Only modified the ***network structure*** and
input format (vector -> 3-D tensor)

```
model2.add( Convolution2D( 25, 3, 3,  
                           input_shape=(1, 28, 28) ) )
```

1	-1	1		
-1	1	-1		
-1	-1	-1		

.....
There are 25
3x3 filters.

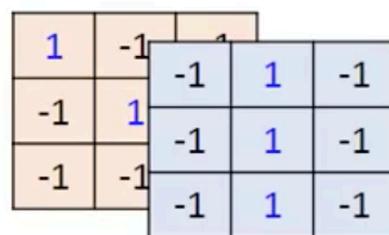
Input_shape = (1, 28, 28)
1: black/weight, 3:RGB 28 x 28 pixels



CNN in Keras

Only modified the **network structure** and
input format (vector -> 3-D tensor)

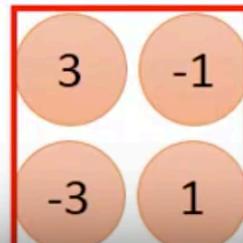
```
model2.add( Convolution2D( 25, 3, 3,  
    input_shape=(1, 28, 28) ) )
```



..... There are 25
3x3 filters.

Input_shape = (1, 28, 28)
1: black/weight, 3: RGB 28 x 28 pixels

```
model2.add(MaxPooling2D( (2, 2) ))
```



我們把 2*2 的這個

input



Convolution



Max Pooling



Convolution

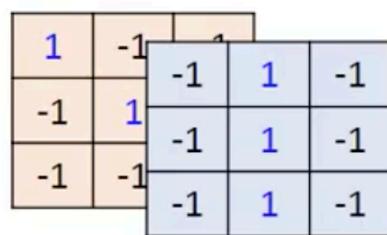


Max Pooling

CNN in Keras

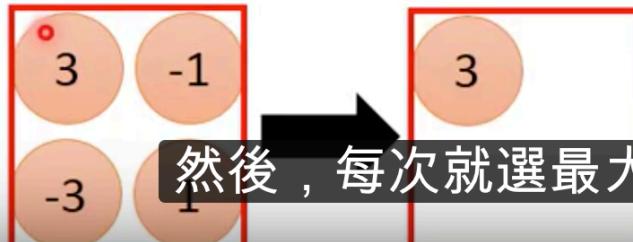
Only modified the **network structure** and
input format (vector -> 3-D tensor)

```
model2.add( Convolution2D( 25, 3, 3,  
                           input_shape=(1, 28, 28) ) )
```



Input_shape = (1, 28, 28)
1: black/weight, 3: RGB 28 x 28 pixels

```
model2.add(MaxPooling2D( (2,2) ))
```



input
↓

Convolution

↓

Max Pooling

↓

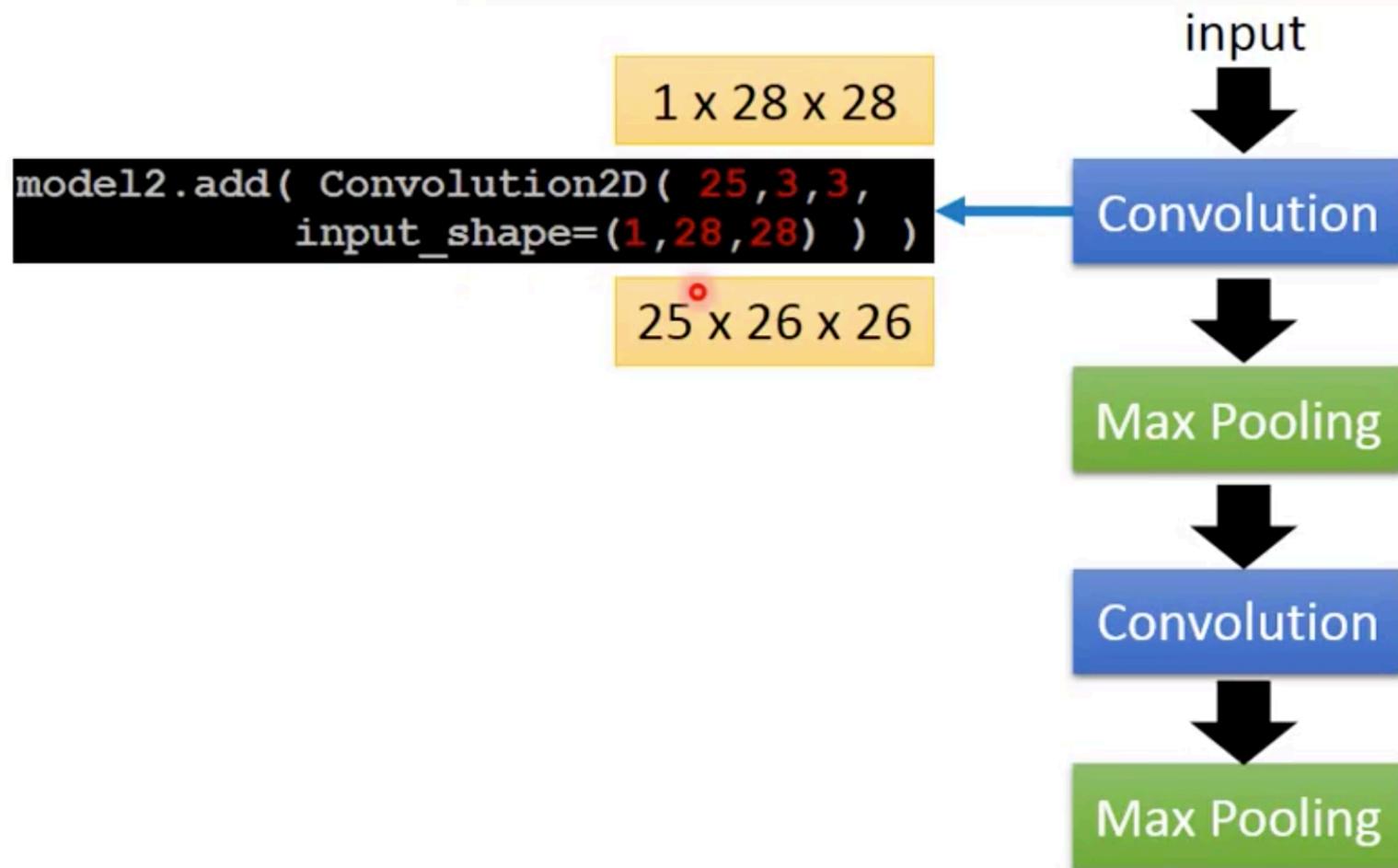
Convolution

↓

Max Pooling

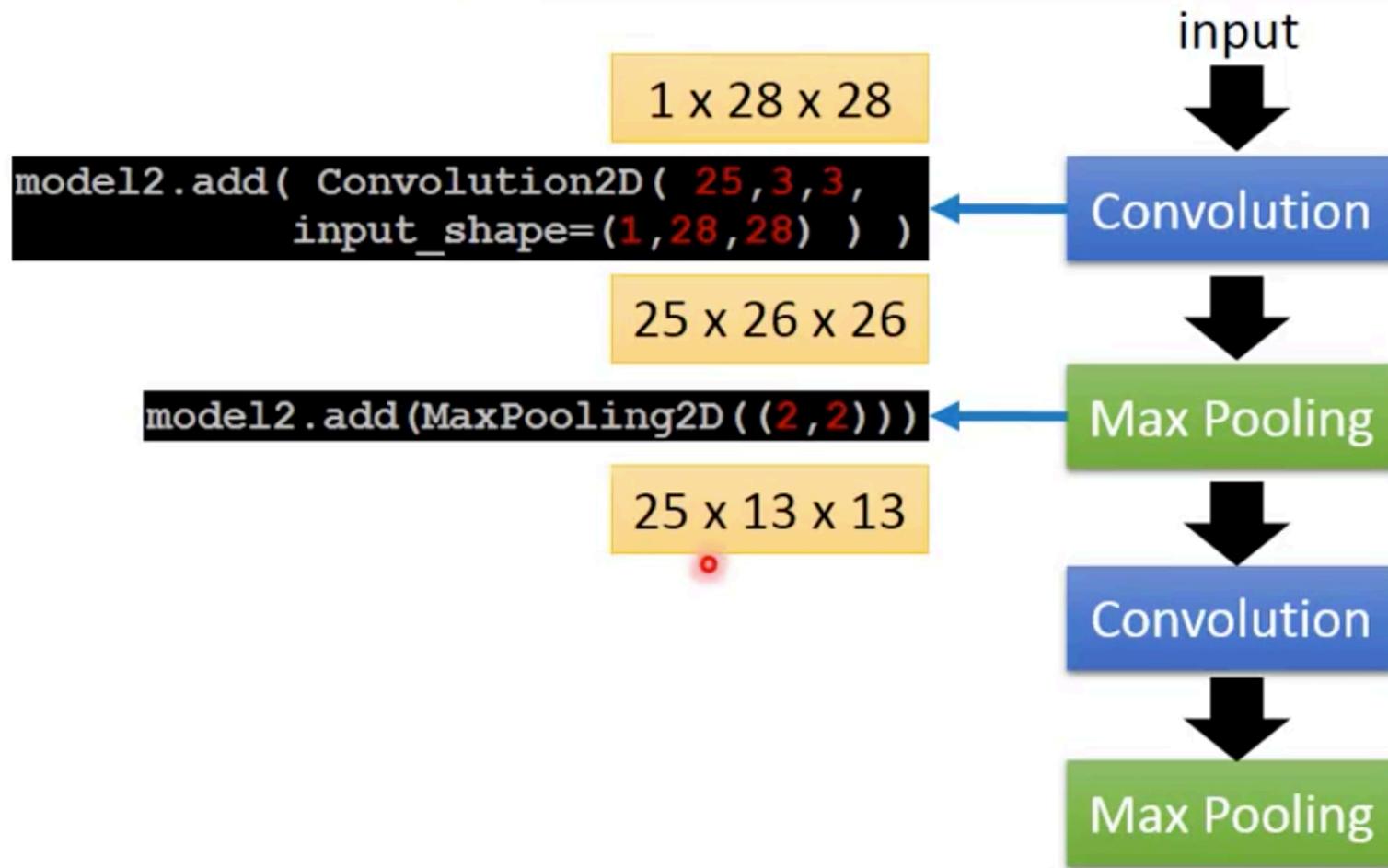
CNN in Keras

Only modified the ***network structure*** and
input format (vector -> 3-D tensor)



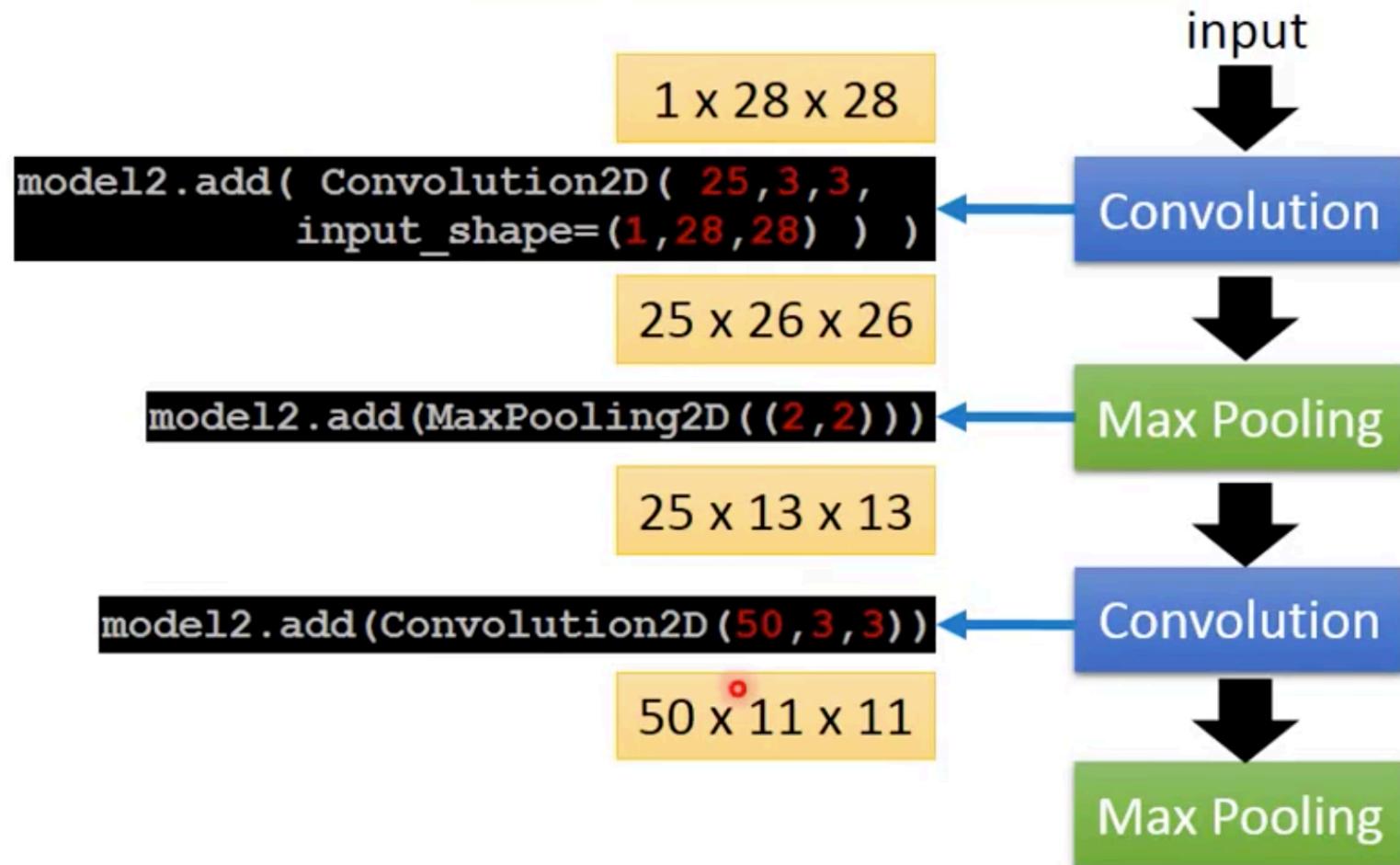
CNN in Keras

Only modified the ***network structure*** and
input format (vector -> 3-D tensor)



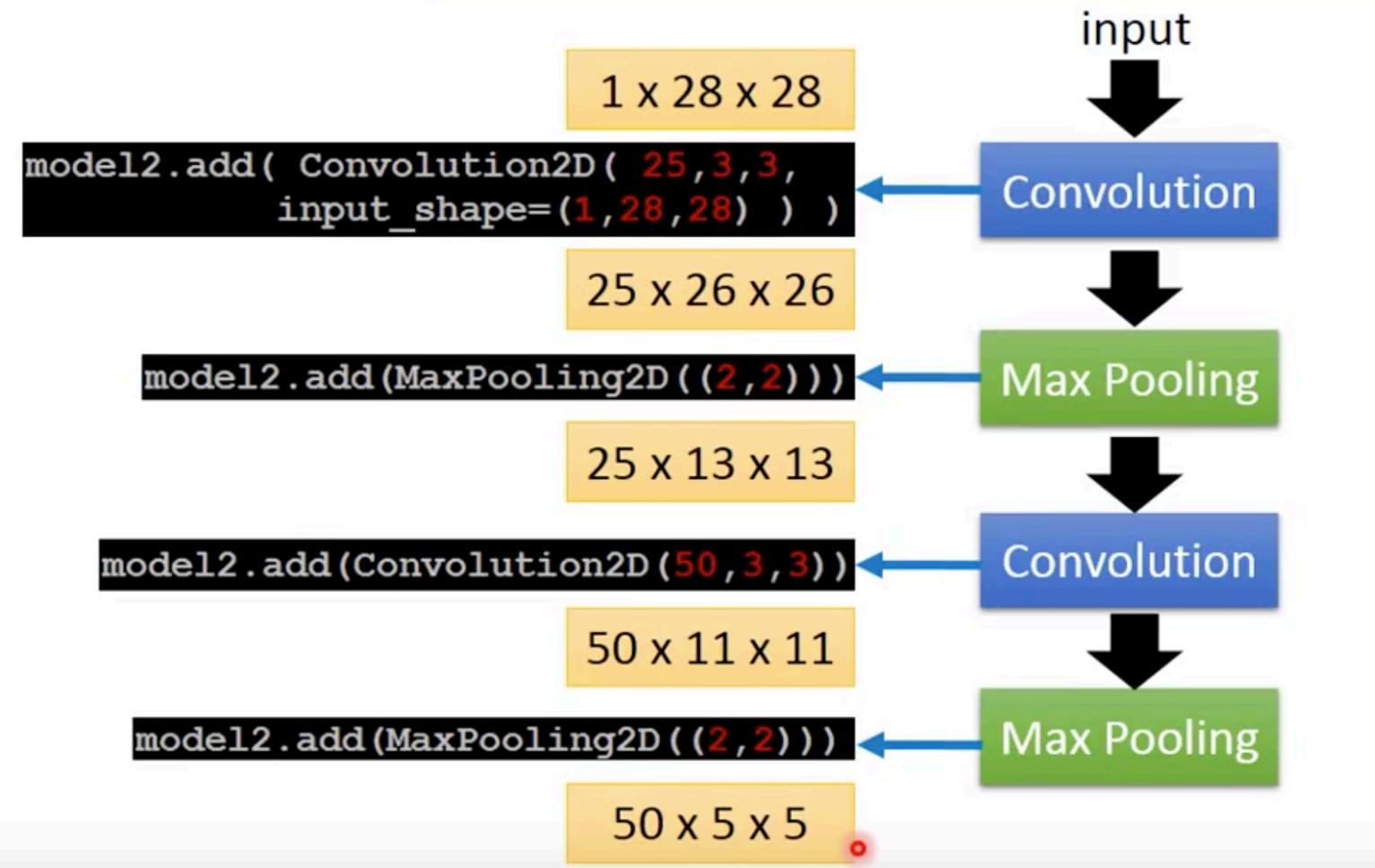
CNN in Keras

Only modified the ***network structure*** and
input format (vector -> 3-D tensor)



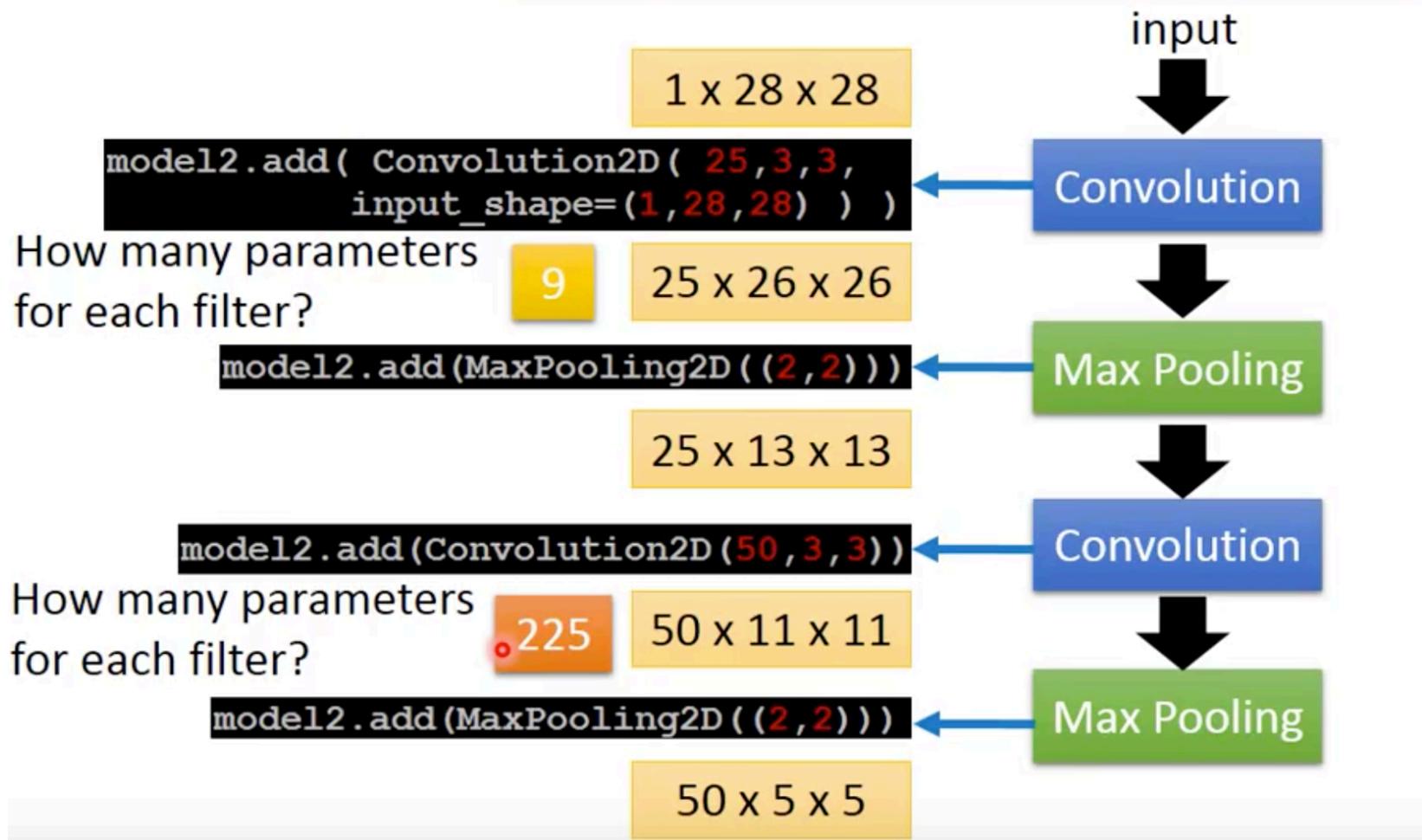
CNN in Keras

Only modified the ***network structure*** and
input format (vector -> 3-D tensor)



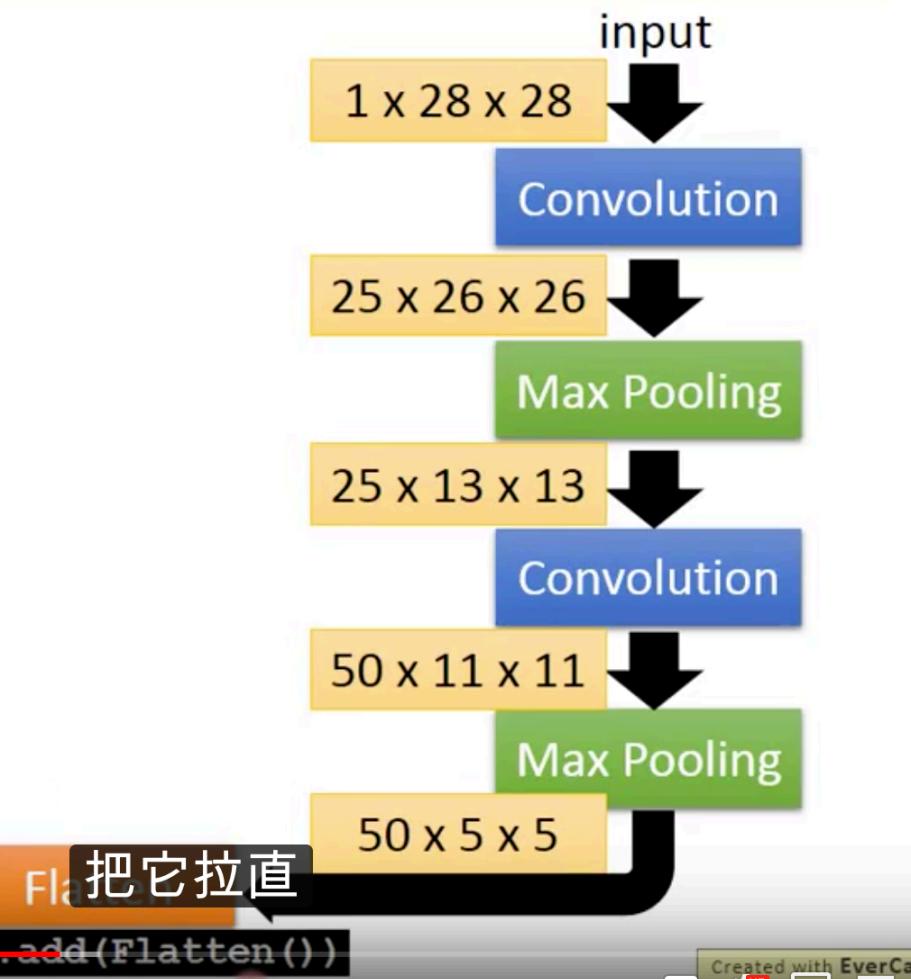
CNN in Keras

Only modified the ***network structure*** and
input format (vector -> 3-D tensor)



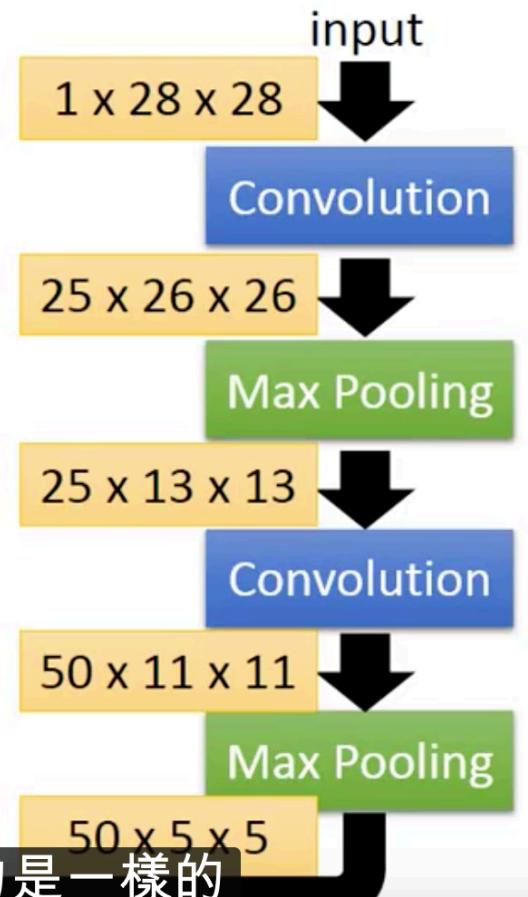
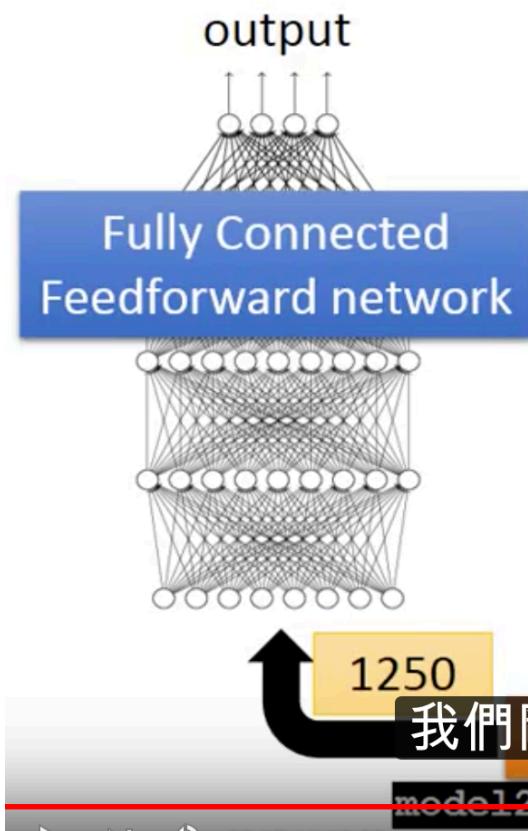
CNN in Keras

Only modified the ***network structure*** and
input format (vector -> 3-D tensor)



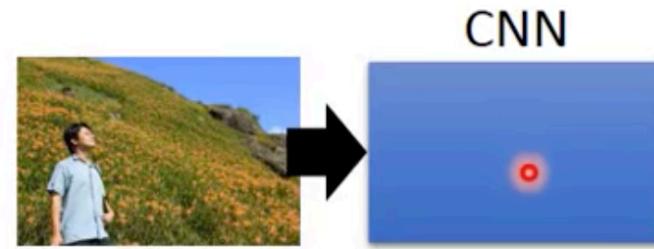
CNN in Keras

Only modified the ***network structure*** and
input format (vector -> 3-D tensor)



Created with EverC

Deep Dream



- Given a photo, machine adds what it sees



Deep Dream

- Given a photo, machine adds what it sees



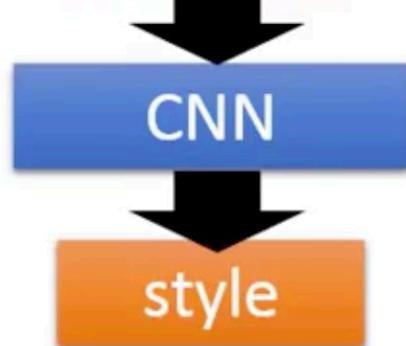
那 Deep Dream 還有一個進階的版本

Deep Style

- Given a photo, make its style like famous paintings



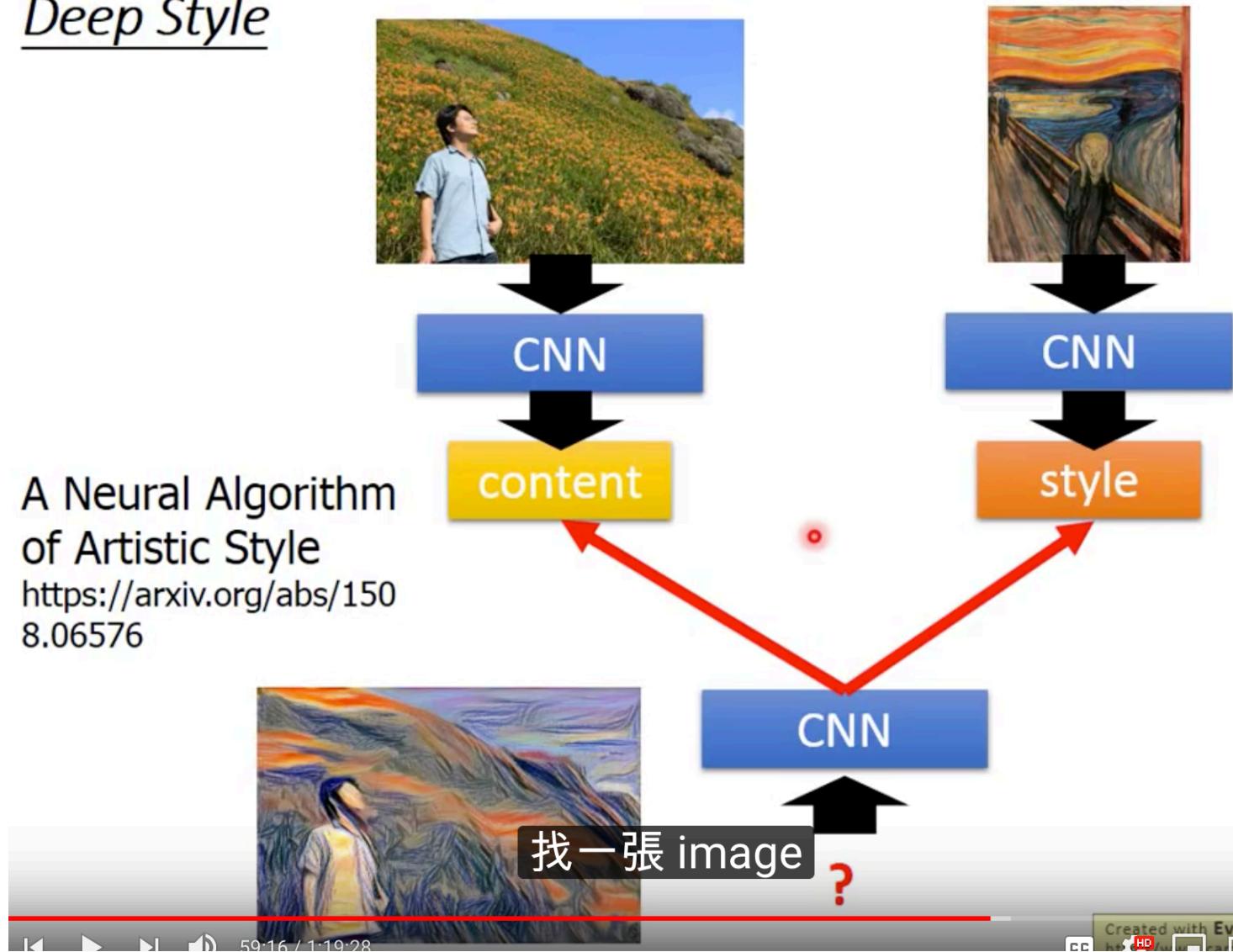
Deep Style



A Neural Algorithm
of Artistic Style
<https://arxiv.org/abs/1508.06576>

Deep Style

A Neural Algorithm
of Artistic Style
<https://arxiv.org/abs/1508.06576>

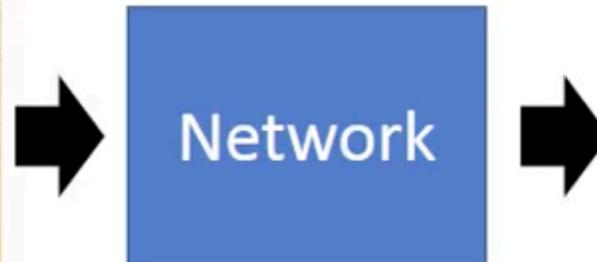


More Application: Playing Go



19 x 19 vector

Black: 1
white: -1



Next move
(19 x 19
positions)

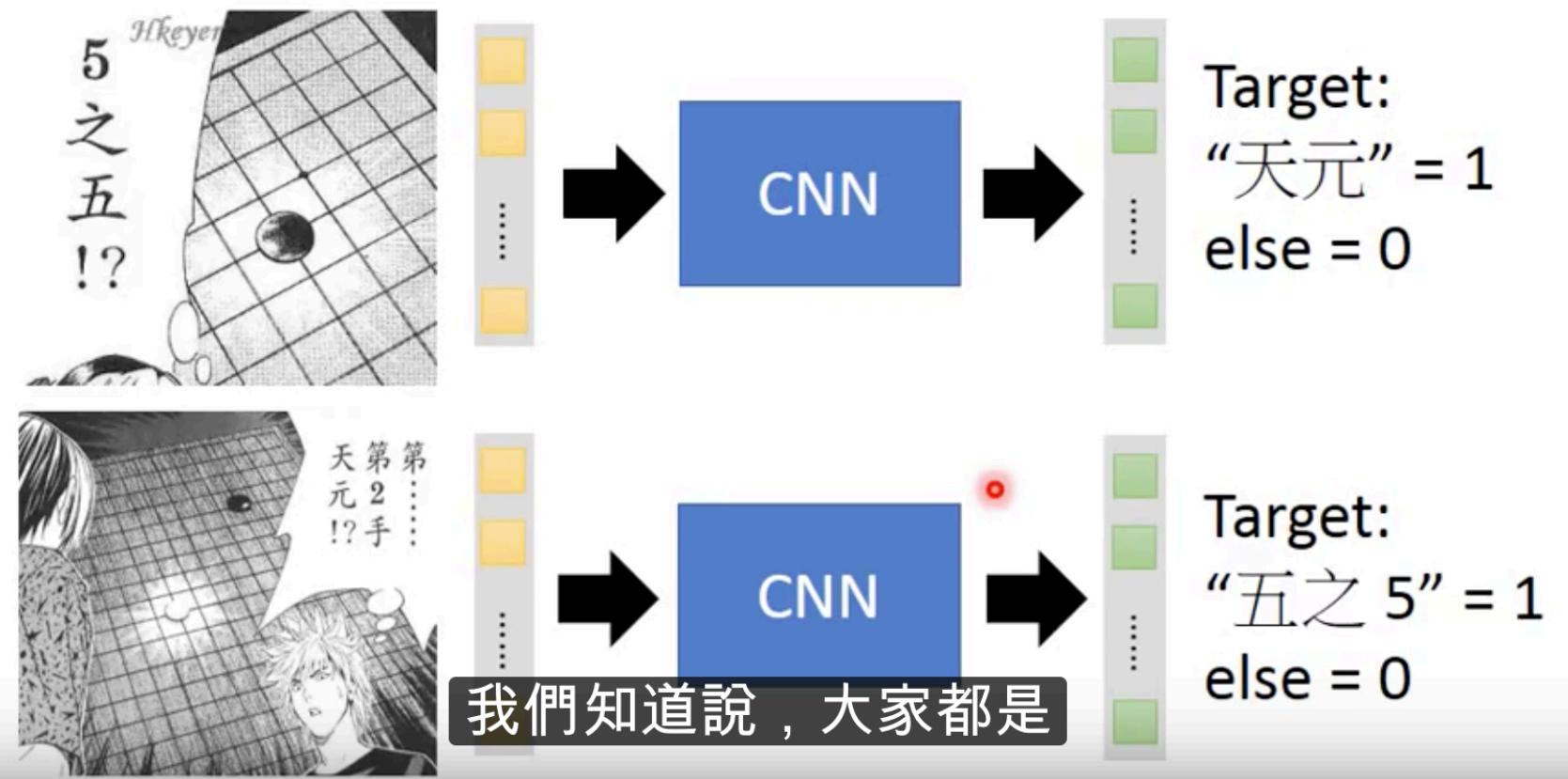
19 x 19 vector

Fully-connected feedforward
network can be used

But CNN performs much better.

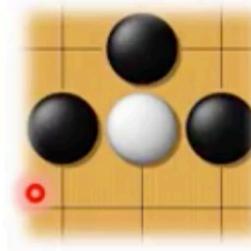
More Application: Playing Go

Training: record of previous plays 黑: 5之五 → 白: 天元 → 黑: 五之5 ...



Why CNN for playing Go?

- Some patterns are much smaller than the whole image

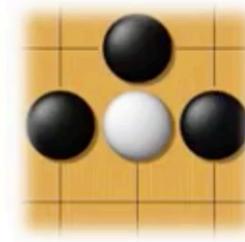


- The same patterns appear in different regions.

Why CNN for playing Go?

- Some patterns are much smaller than the whole image

Alpha Go uses 5 x 5 for first layer



- The same patterns appear in different regions.



在圍棋上，也可能有同樣的現象

Why CNN for playing Go?

- Subsampling the pixels will not change the object
- Max Pooling How to explain this???

Why CNN for playing Go?

- Subsampling the pixels will not change the object



Max Pooling

How to explain this???

Neural network architecture. The input to the policy network is a $19 \times 19 \times 48$ image stack consisting of 48 feature planes. The first hidden layer zero pads the input into a 23×23 image, then convolves k filters of kernel size 5×5 with stride 1 with the input image and applies a rectifier nonlinearity. Each of the subsequent hidden layers 2 to 12 zero pads the respective previous hidden layer into a 21×21 image, then convolves k filters of kernel size 3×3 with stride 1, again followed by a rectifier nonlinearity. The final layer convolves 1 filter of kernel size 1×1 with stride 1, with a different bias for each position, and applies a softmax function. The match version of AlphaGo used $k = 192$ filters; Fig. 2b and Extended Data Table 3 additionally show the results of training with $k = 128, 256$ and 384 filters.

叫吃的狀態呢，等等

Why CNN for playing Go?

- Subsampling the pixels will not change the object



Max Pooling

How to explain this???

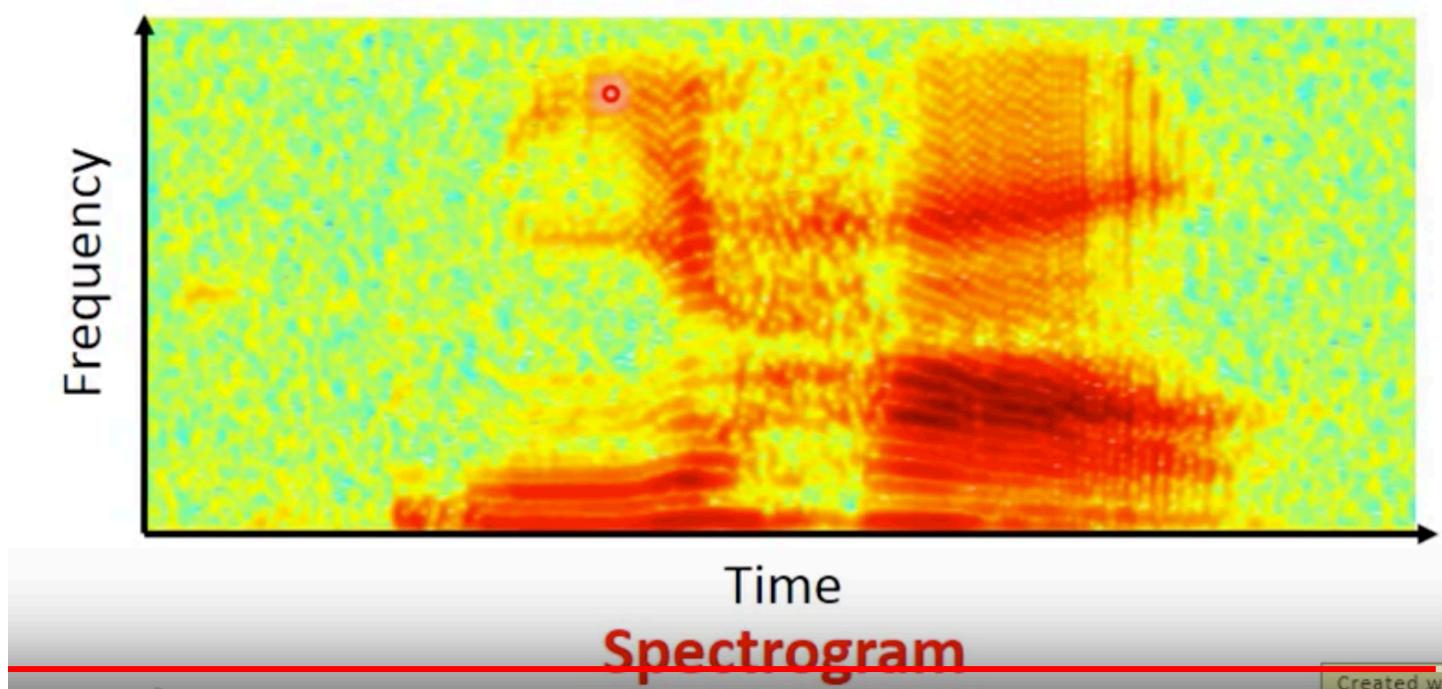
Neural network architecture. The input to the policy network is a $19 \times 19 \times 48$ image stack consisting of 48 feature planes. The first hidden layer zero pads the input into a 23×23 image, then convolves k filters of kernel size 5×5 with stride 1 with the input image and applies a rectifier nonlinearity. Each of the subsequent hidden layers 2 to 12 zero pads the respective previous hidden layer into a 21×21 image, then convolves k filters of kernel size 3×3 with stride 1, again followed by a rectifier nonlinearity. The final layer convolves 1 filter of kernel size 1×1 with stride 1 with a different bias for each position, and applies a softmax function. The Alpha Go does not use Max Pooling Extended Data Table 3 additionally show the results of training with $k = 128, 256$ and 384 filters.



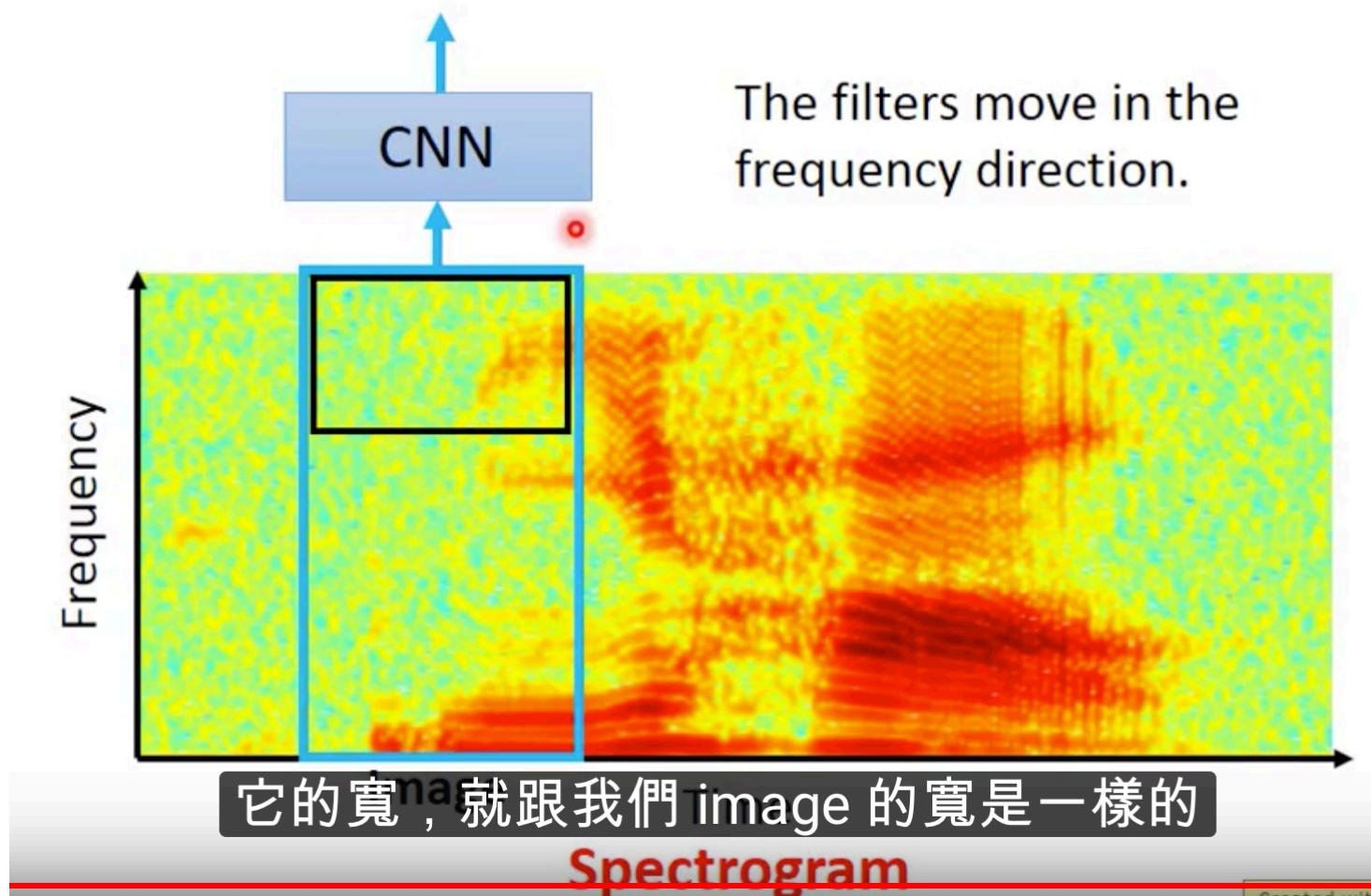
1:09:17 / 1:19:28

Created with EverCam
http://www.evercam.com

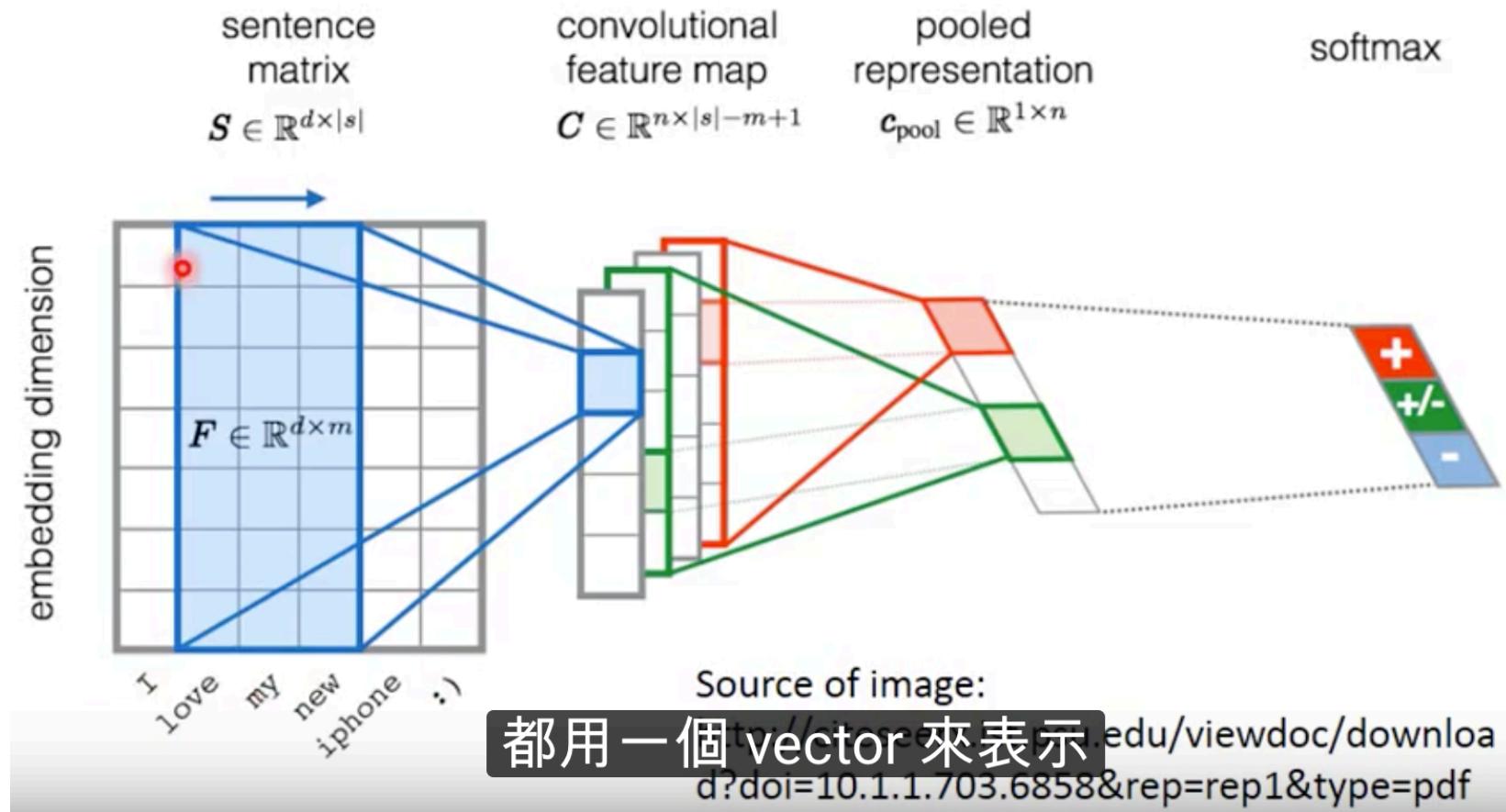
More Application: Speech



More Application: Speech



More Application: Text



To learn more

- The methods of visualization in these slides
 - <https://blog.keras.io/how-convolutional-neural-networks-see-the-world.html>
- More about visualization
 - <http://cs231n.github.io/understanding-cnn/>
- Very cool CNN visualization toolkit
 - <http://yosinski.com/deepvis>
 - <http://scs.ryerson.ca/~aharley/vis/conv/>