

6/3/2020

Transfer learning: Implementing feature extraction from successful models and adding the dense/fully-connected layer.

Dataset similarity

Data set size	Similar	Different
	large	small
	Fine-tune (2)	Fine-tune / retrain (3)
	End of convNet (1)	Start of convNet (4)

Cases:

1. Adjust end of convNet

• ~~remove and replace~~ ^{no} ~~end~~ ^{4c} dense layers (add) (not remove dense)

- Randomize dense layer weights → update weights

- freeze weights in pretrained network - don't update weights

↳ prevent overfitting

3

Forward Pass: Propagation: All data travels forward through nodes to calculate the NN output

° ^{hidden} Input Layer: ~~Preprocessing~~ ^{are} non-linearity

- Equation:

* input: $X \cdot W$ ^{data} \rightarrow weight input to hidden

* output: activation function(input) \rightarrow sigmoid δ ^{are}

° ^{output} Hidden Layer: non-linearity / Linear

- Equ:

* Input: hidden output $\cdot W$ ^{output from hidden layer} \rightarrow weights from hidden to output layer
 * output: activation \leftarrow or \cdot input

Back propagation: data travels in opposite direction to fix/adjust weights & bias

° output layer:

Equ input:

Output error: $(Y - \hat{Y})$ ^{target} \rightarrow output/prediction | label - prediction

Output error term: $(Y - \hat{Y}) f'(a_k)$ | $\underbrace{\text{label - prediction}}_{(\text{error})}$ * $\underbrace{\text{derivative of activation function of output}}_{(\text{gradient})}$

hidden layer:

hidden error: $W_{jk} \delta_k$ ^{are} \rightarrow weight \leftarrow previous layer error term | $\underbrace{\text{output layer term}}_{\text{weights hidden to output}}$

hidden error term: $\sum [W_{jk} \delta_k] f'(h_j)$ | $\underbrace{\text{hidden layer error}}_{(\text{error})}$ * $\underbrace{\text{derivative of activation function of hidden output}}_{(\text{gradient})}$

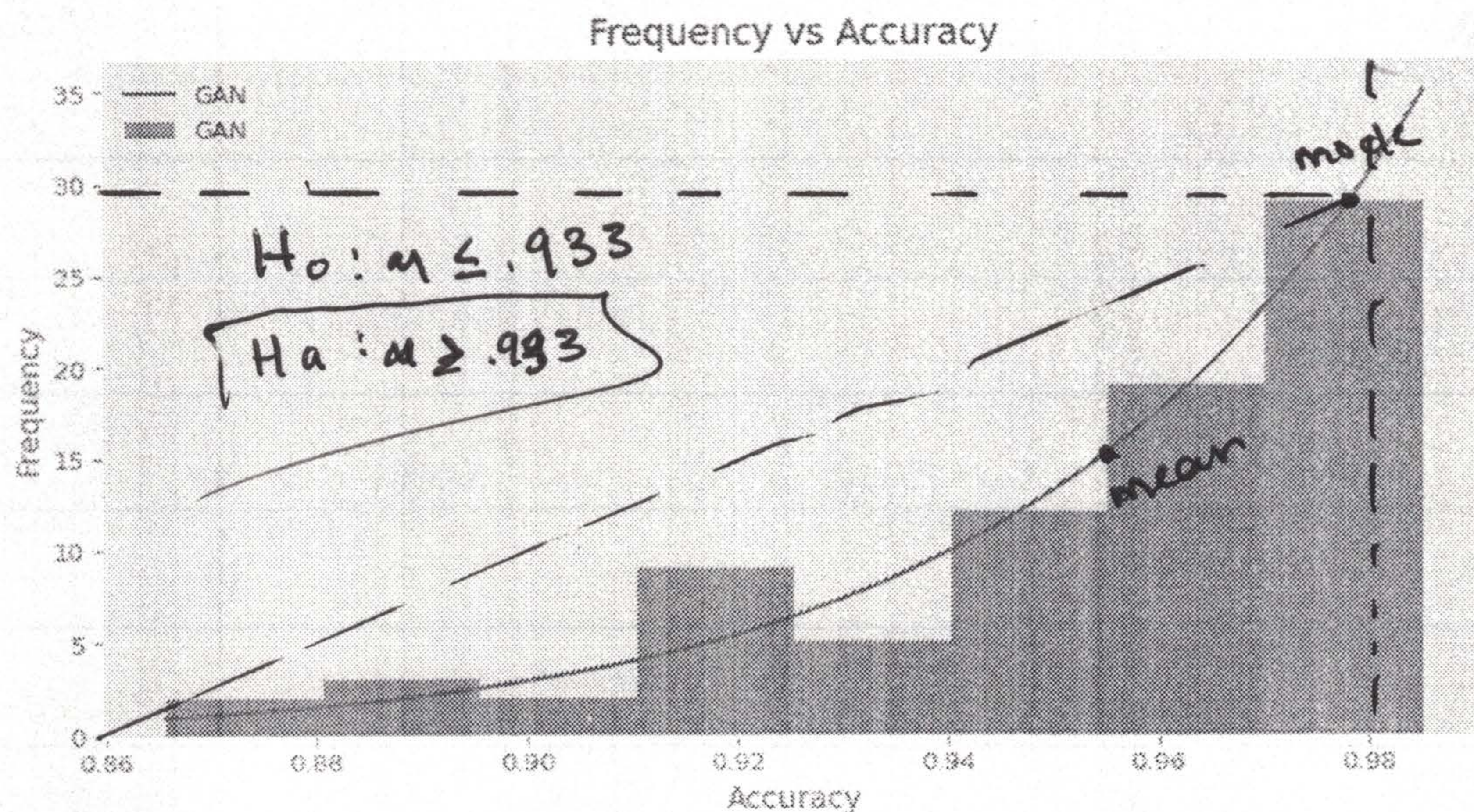
1/14/21

$$\bar{X} = 0.9498$$

$$\sigma_x = 0.0293$$

$$t = \frac{0.9498 - 0.933}{0.0293 / \sqrt{144}} = 7.0224$$

$$P = 1.03 e^{-10}$$



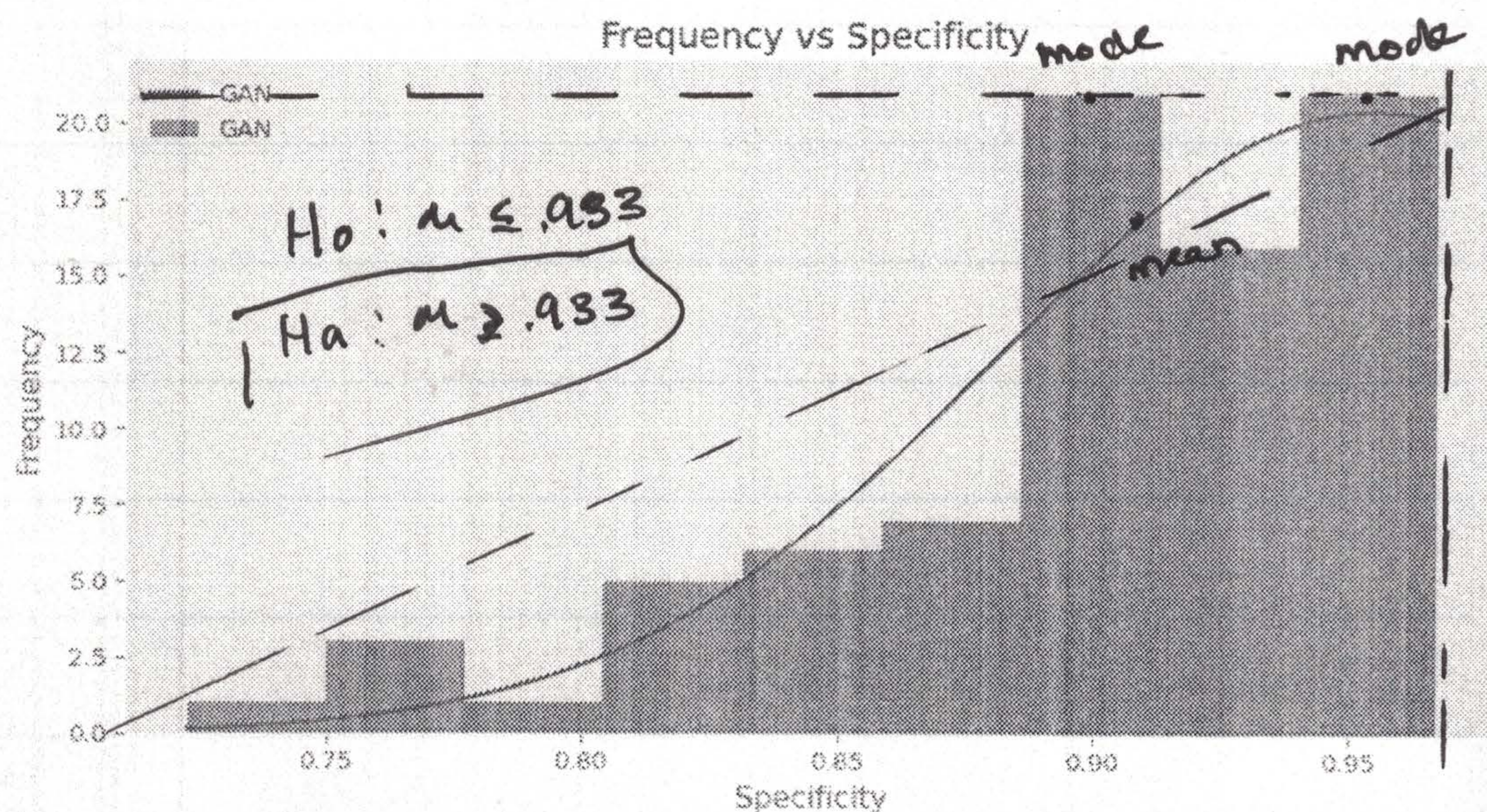
The distributions are skewed to the left, could mean that it is stable in performance.

$$\bar{X} = 0.9030$$

$$\sigma_x = 0.0547$$

$$t = \frac{0.903 - 0.933}{0.0547 / \sqrt{144}} = -6.69$$

$$P = 1.05 e^{-10}$$



Sensitive to maximize

b/c we want to have

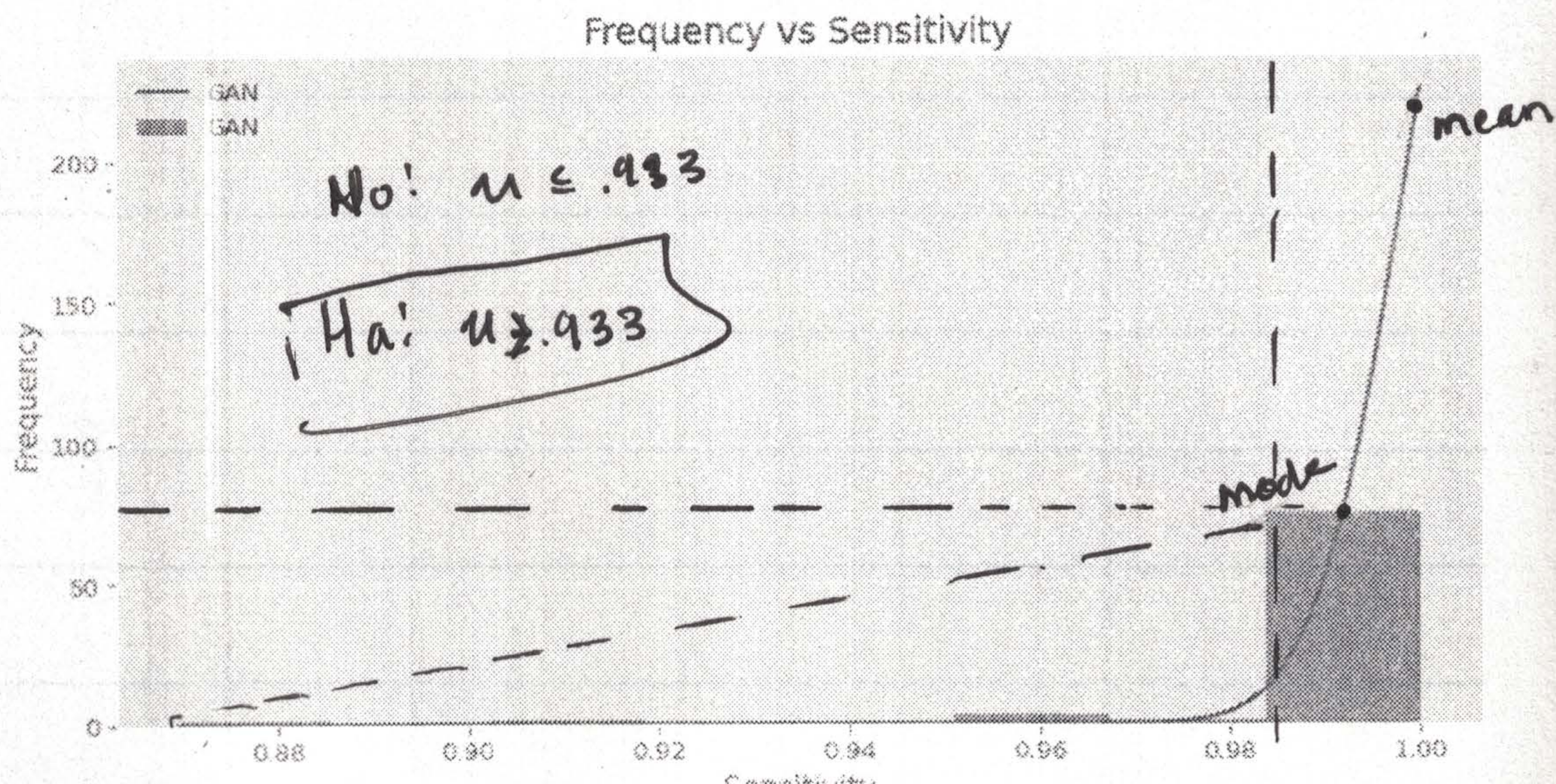
all potential anomalies detected

$$\bar{X} = 0.9952$$

$$\sigma_x = 0.0197$$

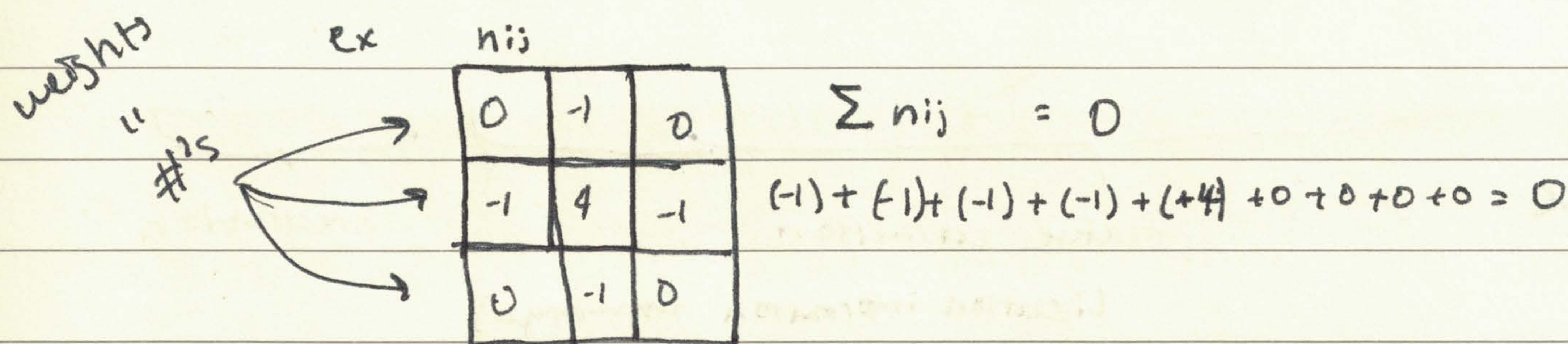
$$t = \frac{0.9952 - 0.933}{0.0197 / \sqrt{144}} = 38.5$$

$$P = 1.54 e^{-17}$$



Filters & Edges in CNNs:

- low pass filters: block high frequencies (vice versa)
- using high pass filters - can block low pass freqs in image
 - o used for edge detection
- convolutional kernel: edge detection filter



process \Downarrow

Kernel \Rightarrow

0	-1	0
-1	4	-1
0	-1	0

Image data \Rightarrow

3	4	7
8	5	6
9	11	10

$*$
 \nearrow
Convolution
(astrik)

* main same volume data

numbers multiplied

Final \Rightarrow

3	-4	0
-8	20	-6
0	-11	0

$$\sum n_{ij} = -9$$

$$(-4) + (-8) + (-11) + 20 = -9$$

Convolution Layer:

- applies many convolutional kernels
- strike the distance from pixel to pixel

- 9 becomes center pixel value (5) in data image

Max pooling - used for decreasing complexity & overfitting

Avg Pooling

* Capsel network