Algorithms

All algorithms can be distributed hogwild-style using the lab's unified API.

- SARSA, DQN, DDQN, DuelingDQN
- Prioritized Exp. Replay, CER
- REINFORCE, A2C, A3C, PPO, DPPO
- · Self-Imitation Learning on A2C, PPO

Network

Auto-infers input/output dims; supports (Hydra) multi-head/tail.

- MLPNet, HydraMLPNet
- RecurrentNet, ConvNet
- DuelingMLPNet, DuelingConvNet

Memory

- Off-policy Replay, ConcatReplay, AtariReplay, PrioritizedReplay, AtariPrioritizedReplay, ...
- On-Policy OnPolicyReplay, OnPolicySeqReplay, OnPolicyAtariReplay...

Env

- OpenAl Gym & Unity ML-agents
- more to come using standard API

Fitness Metric

Introduces a richer vectorial fitness metric to measure agent's performance.

fitness = [strength, speed, stability, consistency]

Benchmark

- CartPole, LunarLander, ..., soon Atari
- in-progress: check Github for results

SLM Lab: modular deep RL framework

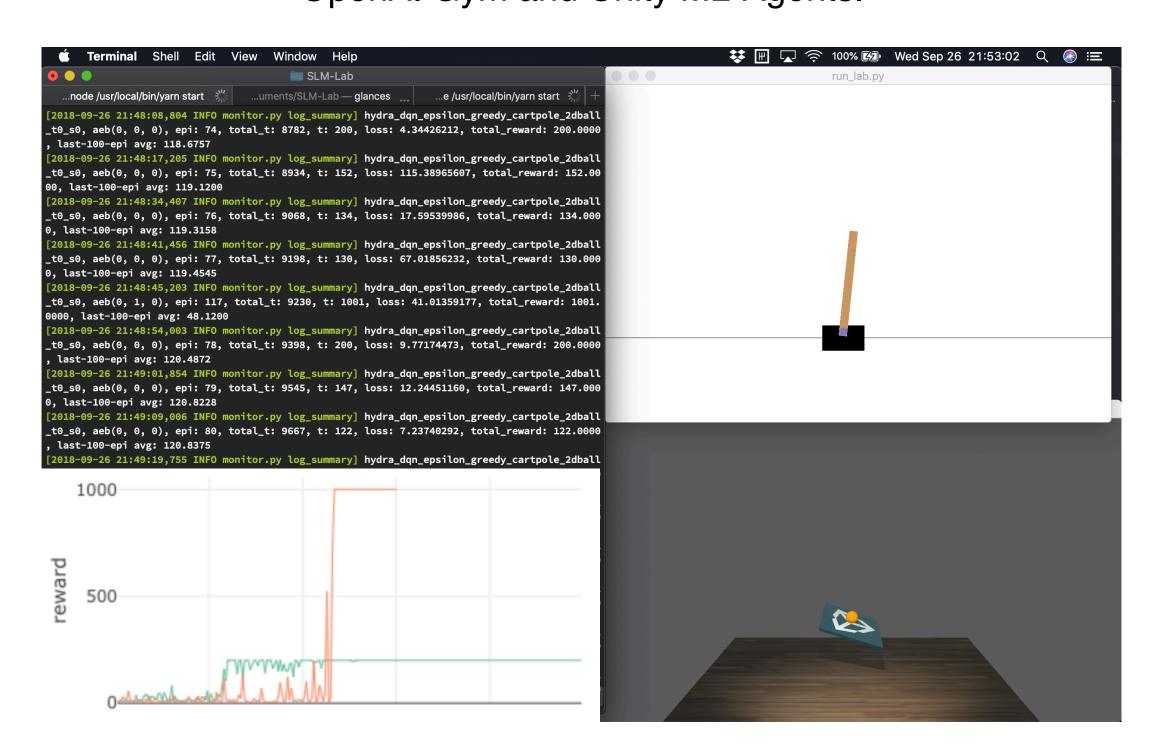
github.com/kengz/SLM-Lab

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SLM Lab is a modular deep reinforcement learning framework in PyTorch. It implements a number of canonical algorithms using modular and reusable components, provides an automated experiment and analytics framework focusing on reproducibility, introduces a multi-dimensional fitness metric, and integrates with OpenAI Gym and Unity ML-Agents.



SLM Lab allows multi-task learning with arbitrary set of environments: HydraDQN simultaneously solves Gym-CartPole and Unity-2DBall

Modularity focus from component reuse, hence less code, more tests, and fewer bugs

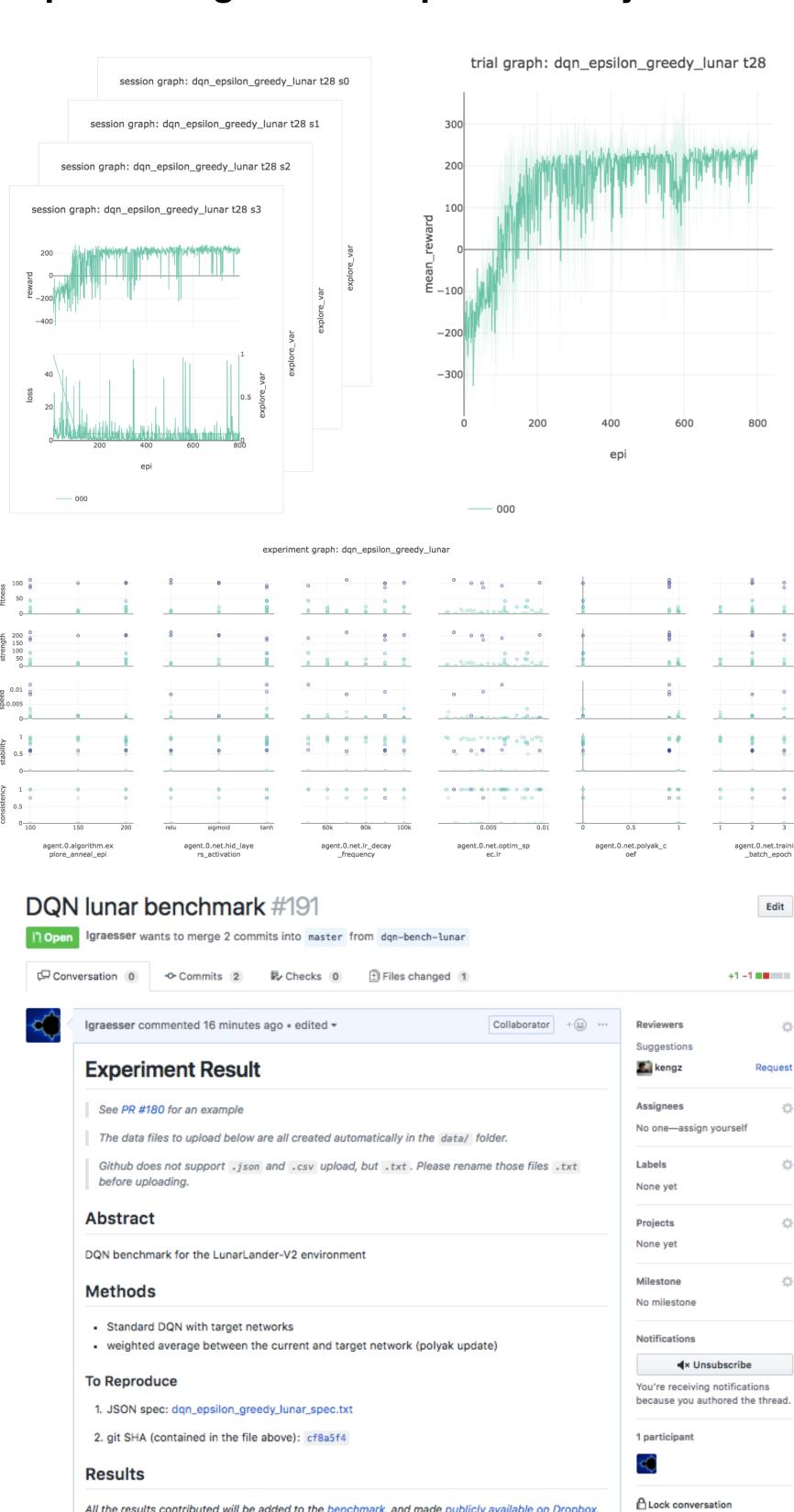
Simplicity component design closely corresponds to how papers discuss RL

Analytical clarity hyperparameter search: results automatically analyzed by Session, Trial, Experiment

Reproducibility only the *spec file* and a git SHA are needed to fully reproduce an experiment. Data is open-access.

Experiments

- distributed hyperparam. search: Ray Tune
- replication with multiple random seeds
- graphs and fitness metric
- Pull Request with scientific report format
- spec file + git SHA = reproducibility



1. full experiment data zip: (please find our contact in README and request a "Dropbox file