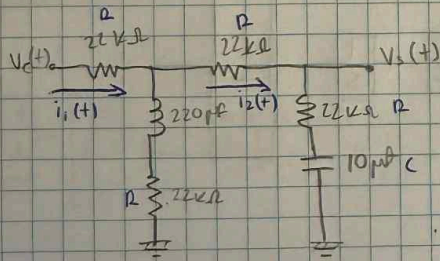
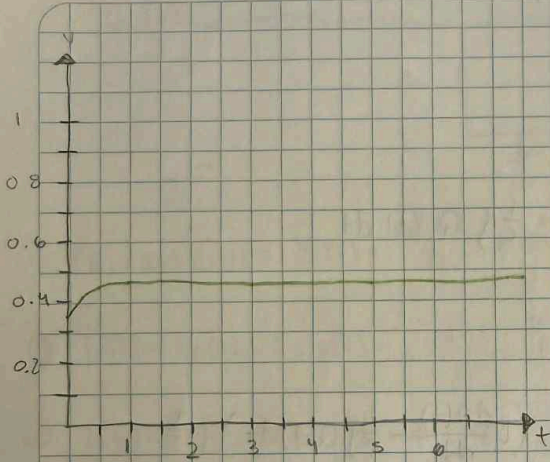


# Practica #1



## \* Ecuaciones principales

$$V_c(t) = R i_1(t) + L \frac{d(i_1(t) - i_2(t))}{dt} + R [i_1(t) - i_2(t)]$$

$$L \frac{d[i_1(t) - i_2(t)]}{dt} + R [i_1(t) - i_2(t)] = R i_2(t) + R i_2(t) + \frac{1}{C} \int i_2(t) dt$$

$$V_s(t) = R i_2(t) + \frac{1}{C} \int i_2(t) dt$$

23-sep-25

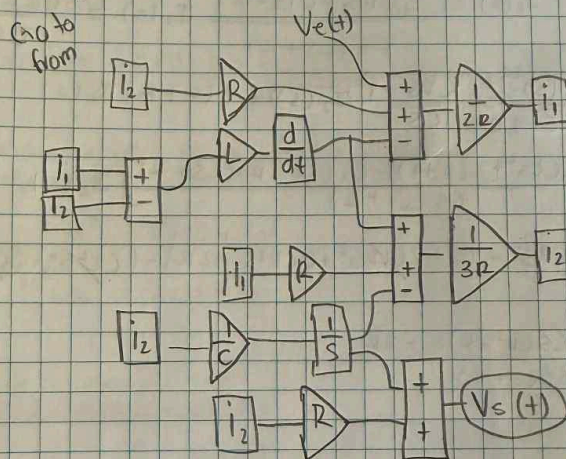
# Modelo de ecuaciones integro-diferenciales

Despeje de ec. principales

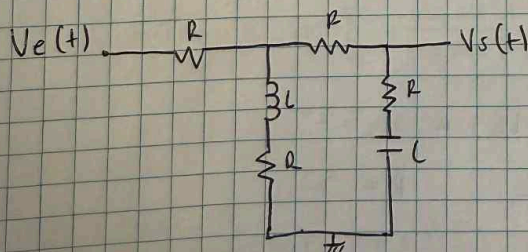
$$i_1(t) = \left[ V_e(t) - L \frac{d[i_1(t) - i_2(t)]}{dt} + R i_2(t) \right] \frac{1}{2R}$$

$$i_2(t) = \left[ L \frac{d[i_1(t) - i_2(t)]}{dt} + R i_1(t) - \frac{1}{C} \int i_2(t) dt \right] \frac{1}{3R}$$

$$V_s(t) = R i_2(t) + \frac{1}{C} \int i_2(t) dt$$



26-09-25



## Transformada de la place

función de transferencia

$$\frac{V_s(s)}{V_e(s)} = \frac{?}{?} \frac{I_2(s)}{I_2(s)}$$

$$V_e(s) = R I_1(s) + L s [I_1(s) - I_2(s)] + R [I_1(s) - I_2(s)]$$

$$L s [I_1(s) - I_2(s)] + R [I_1(s) - I_2(s)] = R I_2(s) + R I_2(s) + \frac{I_2(s)}{C s}$$

$$V_s(s) = R I_2(s) + \frac{I_2(s)}{C s} = \frac{C R s + 1}{C s} I_2(s)$$



20/9/25

20/sep/25

Nota:

no debe de haber terminos negativos!

→ Procedimiento algebraico

$$\Rightarrow \underline{V_e(s)} = (R + Ls + R) I_1(s) - (Ls + R) I_2(s) \\ = (Ls + 2R) I_1(s) - (Ls + R) I_2(s)$$

$$\Rightarrow \underline{Ls I_1(s)} - Ls I_2(s) + R I_1(s) - R I_2(s) = 2R I_2(s) + \frac{I_2(s)}{Cs} \\ Ls I_1(s) + R I_1(s) = 3R I_2(s) + Ls I_2(s) + \frac{I_2(s)}{Cs}$$

$$(Ls + R) I_1(s) = \left( 3R + Ls + \frac{1}{Cs} \right) I_2(s)$$

$$I_1(s) = \frac{3CRs + Cs^2 + 1}{Cs(Ls + R)} I_2(s) = \frac{(Ls^2 + 3CRs + 1)}{Cs(Ls + R)} I_2(s)$$

$$\Rightarrow \underline{V_e(s)} = \frac{(Ls + 2R)(Ls^2 + 3CRs + 1)}{Cs(Ls + R)} I_2(s) - (Ls + R) I_2(s)$$

$$V_e(s) = \left[ \frac{(Ls + 2R)(Ls^2 + 3CRs + 1) - (Ls + R)(Ls + R)}{Cs(Ls + R)} \right] I_2(s)$$

$$(\cancel{CLs^3} + 3CLR s^2 + Ls + \cancel{2CR s^2} + 6CR^2 s + 2R) - (\cancel{CLs^3} - 2\cancel{CLR s^2} - CR^2 s)$$

$$\underline{V_e(s)} = \frac{3CLR s^2 + (5CR^2 + L)s + 2R}{Cs(Ls + R)}$$

$$V_s(s) = \frac{(Rs + 1)}{Cs} I_2(s) \\ \frac{3CLR s^2 + (5CR^2 + L)s + 2R}{Cs(Ls + R)} I_2(s)$$

$$\underline{V_s(s)} = (Rs + 1)(Ls + R) = CLR s^2 + CR^2 s + Ls + R$$

$$\frac{V_s(s)}{V_e(s)} = \frac{CLR s^2 + (CR^2 + L)s + R}{3CLR s^2 + (5CR^2 + L)s + 2R}$$

$$R = 22$$

$$C = 22$$

$$L = 2$$

02-oct-25

## Estabilidad en lazo abierto

Calcular los polos de la función de transferencia

$$\frac{V_s(s)}{V_e(s)} = \frac{CLs^2 + (CR^2 + L)s + R}{3(LRs^2 + (SCR^2 + L)s + 2R)}$$

$$\text{den} = [3 * C * L * R, 5 * C * R * L + L, 2 * R]$$

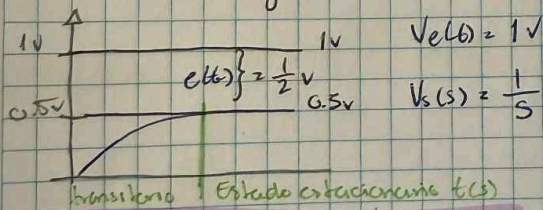
$$l = \text{np.roots}(\text{den})$$

fprint: las raíces  $\{l[0]\}$  y  $\{l[1]\}$

$$\lambda_1 = -1.6666666666666667$$

$$\lambda_2 = -1.818181818181818$$

El sistema presenta una respuesta estable y sobre amortiguada.



Error en estado estacionario

$$e(s) = \lim_{s \rightarrow 0} s V_e(s) \left[ 1 - \frac{V_s(s)}{V_e(s)} \right]$$

$$= \lim_{s \rightarrow 0} s - \frac{1}{s} \left[ 1 - \frac{CLs^2 + (CR^2 + L)s + R}{3CLR s^2 + (SCR^2 + L)s + 2R} \right]$$

$$= \frac{R}{2R}$$

$$e(t) = \frac{1}{2} V$$