

Team Note of ATRI

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1 Data Structure

1.1 DSU

Usage: call init() before use

```
// ACL(Atcoder Library) Template - Disjoint set
struct dsu {
public:
    dsu() : _n(0) {}
    explicit dsu(int n) : _n(n), psz(n, -1) {}
    int merge(int a, int b) {
        int x = leader(a), y = leader(b);
        if (x == y) return x;
        if (-psz[x] < -psz[y]) swap(x, y);
        psz[x] += psz[y];
    }
};
```

```

    psz[y] = x;
    return x;
}
bool same(int a, int b) { return leader(a) == leader(b); }
int leader(int a) { return (psz[a] < 0 ? a : psz[a] = leader(psz[a])); }
int size(int a) { return -psz[leader(a)]; }
vector<vector<int>> groups() {
    vector<int> buf(_n), gsz(_n);
    for (int i = 0; i < _n; i++) {
        buf[i] = leader(i);
        gsz[buf[i]]++;
    }
    vector<vector<int>> result(_n);
    for (int i = 0; i < _n; i++) result[i].reserve(gsz[i]);
    for (int i = 0; i < _n; i++) result[buf[i]].push_back(i);
    result.erase(remove_if(result.begin(), result.end(), [&](const vector<int>& v) {
        return v.empty(); })), result.end());
    return result;
}
private:
    int _n;
    vector<int> psz;
};

```

1.2 Fenwick

```

ll fenwick[N+1];
void update(int i, ll diff) {
    while (i <= N) {
        a[i] += diff;
        i += (i & -i);
    }
}
// ex. sum
ll query(int i) {
    ll r = 0;
    while (i) {
        r += a[i];
        i -= (i & -i);
    }
    return r;
}

```

1.3 Line Container(cht)

```

// cht, MinLineContainer<ll> 처럼 사용, ax+b 꼴 점화식
enum Objective {
    MAXIMIZE = +1,
    MINIMIZE = -1,
};
template <typename T>
struct Line {
    mutable T k, m, p;
    bool operator<(const Line& o) const { return k < o.k; }
    bool operator<(T x) const { return p < x; }
};

```

```

};
template <typename T>
T lc_inf() { return numeric_limits<T>::max(); }
template <> long double lc_inf<long double>() { return 1 / .0; }
template <typename T> T lc_div(T a, T b) { return a / b - ((a ^ b) < 0 and a % b); }
template <> long double lc_div(long double a, long double b) { return a / b; };
template <typename T, Objective objective>
struct LineContainer : multiset<Line<T>, less<>> {
    using super = multiset<Line<T>, less<>>;
    using super::begin, super::end, super::insert, super::erase;
    using super::empty, super::lower_bound;
    const T inf = lc_inf<T>();
    bool insert(typename super::iterator x, typename super::iterator y) {
        if (y == end()) return x->p = inf, false;
        if (x->k == y->k) x->p = (x->m > y->m ? inf : -inf);
        else x->p = lc_div(y->m - x->m, x->k - y->k);
        return x->p >= y->p;
    }
    void add(T k, T m) {
        auto z = insert({k * objective, m * objective, 0}), y = z++, x = y;
        while (insect(y, z)) z = erase(z);
        if (x != begin() and insect(--x, y)) insect(x, y = erase(y));
        while ((y = x) != begin() and (--x)->p >= y->p) insect(x, erase(y));
    }
    T query(T x) {
        assert(!empty());
        auto l = *lower_bound(x);
        return (l.k * x + l.m) * objective;
    }
};
template <typename T>
using MinLineContainer = LineContainer<T, Objective::MINIMIZE>;
template <typename T>
using MaxLineContainer = LineContainer<T, Objective::MAXIMIZE>;

1.4 Matrix

ll n, s, e;
using Matrix = vector<vector<ll>>;
Matrix matrix;
Matrix operator* (const Matrix &op1, const Matrix &op2) {
    Matrix result(op1.size(), vector<ll>(op1[0].size()));
    for (int i = 0; i < 5*n; i++) {
        for (int j = 0; j < 5*n; j++) {
            for (int k = 0; k < 5*n; k++) {
                result[i][j] += op1[i][k] * op2[k][j];
                result[i][j] %= DIV;
            }
        }
    }
    return result;
}
Matrix matrix_pow(ll k) {
    if (k == 1) return matrix;
    else if (k % 2) return matrix_pow(k-1) * matrix;
};

```

```

    else {
        Matrix _matrix = matrix_pow(k/2);
        return _matrix * _matrix;
    }
}

int main() {
    Matrix result;
    ll k;
    scanf("%lld %lld %lld %lld", &n, &s, &e, &k);
    for (int i = 0; i < n; i++) {
        vector<ll> v;
        int x;
        for (int j = 0; j < n; j++) {
            scanf("%d", &x);
            for (int d = 5; d > 0; d--) {
                if (d == x) v.push_back(1);
                else v.push_back(0);
            }
        }
        for (int d = 0; d < 4; d++) {
            vector<ll> temp;
            for (int ti = 1; ti <= 5*n; ti++) {
                if (5*i + d + 1 == ti - 1) temp.push_back(1); else temp.push_back(0);
            }
            matrix.push_back(temp);
        }
        matrix.push_back(v);
    }
    result = matrix_pow(k);
}

```

1.5 PBDS(ordered set)

```

// 자료형만 수정, less_equal <-> less 변경시 주의
#include <ext/pb_ds/assoc_container.hpp>
#include <ext/pb_ds/tree_policy.hpp>
using namespace __gnu_pbds;
#define ordered_set tree<int, null_type, less_equal<int>,
rb_tree_tag, tree_order_statistics_node_update>
// less_equal, greater_equal 사용시 필요
void m_erase(ordered_set &os, int val){
    int idx = os.order_of_key(val);
    ordered_set::iterator it = os.find_by_order(idx);
    if(*it == val) os.erase(it);
}

```

1.6 Rope and Crope

```

__gnu_cxx::crope s; // string
__gnu_cxx::rope<int> r; // template
insert(pos, string)
substr(pos, len)
erase(pos, len)

```

1.7 Lazy Reversible BBST(Splay)

```

// ref: nachia library, like ACL seg, lazy
struct SplayTreeByIdx{
    // ACL segと ほぼ同じ
    struct S { ll l, r, ans, len; }; // affine monoid
    static S op(S l, S r) {
        ll nl = (l.l == l.len ? l.len+r.l : l.l);
        ll nr = (r.r == r.len ? r.len+l.r : r.r);
        ll len = l.len+r.len;
        return { nl, nr, max({nl, nr, l.ans, r.ans, l.r+r.l}), len };
    }
    static S e() { return { 0, 0, 0, 0 }; }
    static void reverse_prod(S& x) { swap(x.l, x.r); } // 反時に prod を更新する
    struct F { ll x; };
    static S mapping(F f, S x) { return x; }
    static F composition(F f, F x) { return x; }
    static F id() { return {0}; }
    struct Node{
        Node *l = 0, *r = 0, *p = 0;
        S a = e(); // 頂点が持つ値
        S prod = e(); // 集約( rev==1 のときでも reverse_prod 作用み)
        F f = id(); // 延(a,prod には作用み)
        int i = -1; // 配列の index
        int z = 0; // 頂点の重み ( NIL なら 0 , 普通の頂点は 1 )
        int sumz = 0; // 部分木の重み
        int rev = 0; // 反の延
    };
};

using pNode = unique_ptr<Node>;
pNode pNIL;
Node *NIL = nullptr;
vector<pNode> A;
Node *R;
SplayTreeByIdx() {
    if(!pNIL){
        pNIL = make_unique<Node>();
        NIL = pNIL.get();
        NIL->l = NIL->r = NIL->p = NIL;
        R = NIL;
    }
}

// 播
void prepareDown(Node* c){
    if(c->l != NIL) {
        // a,prod への作用を忘れずに
        c->l->a = mapping(c->f, c->l->a);
        c->l->prod = mapping(c->f, c->l->prod);
        c->l->f = composition(c->f, c->l->f);
    }
    if(c->r != NIL) {
        // a,prod への作用を忘れずに
        c->r->a = mapping(c->f, c->r->a);
        c->r->prod = mapping(c->f, c->r->prod);
        c->r->f = composition(c->f, c->r->f);
    }
}

```

```

    if(c->rev) {
        swap(c->l, c->r);
        if(c->l != NIL) {
            c->l->rev ^= 1; // 播
            reverse_prod(c->l->prod);
        }
        if(c->r != NIL) {
            c->r->rev ^= 1; // 播
            reverse_prod(c->r->prod);
        }
        c->rev = 0;
    }
    c->f = id(); // 播み
}
// 集約
void prepareUp(Node* c) {
    c->sumz = c->l->sumz + c->r->sumz + 1; // 部分木の重み
    c->prod = op(op(c->l->prod, c->a), c->r->prod); // 集約 c は播み
}
// (便利)
// p の親が、子として p を照するので、それを書き換えられるようにする
// 根の場合に張して R の照を返す。
Node*& parentchild(Node* p) {
    if(p->p == NIL) return R;
    if(p->p->l == p) return p->p->l;
    else return p->p->r;
}
// 左回
void rotL(Node* c) {
    Node* p = c->p;
    parentchild(p) = c;
    c->p = p->p;
    p->p = c;
    if(c->l != NIL) c->l->p = p; // 子が NIL かもしれない
    p->r = c->l;
    c->l = p;
}
// 右回
void rotR(Node* c) {
    Node* p = c->p;
    parentchild(p) = c;
    c->p = p->p;
    p->p = c;
    if(c->r != NIL) c->r->p = p; // 子が NIL かもしれない
    p->l = c->r;
    c->r = p;
}
// splay 後、c は播み
void splay(Node* c) {
    prepareDown(c); // ループが回らない時のために
    while(c->p != NIL) {
        Node* p = c->p;
        Node* pp = p->p;
        // 播は親から
        if (pp != NIL) prepareDown(pp);
    }
}

```

```

    if (p != NIL) prepareDown(p);
    prepareDown(c);
    if (p->l == c) {
        if(pp == NIL) { rotR(c); }
        else if(pp->l == p) { rotR(p); rotR(c); }
        else if(pp->r == p) { rotR(c); rotL(c); }
    }
    else {
        if(pp == NIL) { rotL(c); }
        else if(pp->r == p) { rotL(p); rotL(c); }
        else if(pp->l == p) { rotL(c); rotR(c); }
    }
    // 集約は子から
    if(pp != NIL) prepareUp(pp);
    if(p != NIL) prepareUp(p);
    prepareUp(c);
}
prepareUp(c); // ループが回らない時のために
}
Node* kth_element(int k) {
    Node* c = R;
    while(true) {
        prepareDown(c);
        if(c->l->sumz == k) break;
        if(c->l->sumz > k){ c = c->l; continue; }
        k -= c->l->sumz + 1;
        c = c->r;
    }
    prepareDown(c);
    splay(c);
    return c;
}
void insert_at(int k, S x) {
    pNode pnx = make_unique<Node>(*NIL);
    Node* nx = pnx.get();
    nx->z = nx->sumz = 1;
    nx->i = A.size();
    nx->a = nx->prod = x;
    A.emplace_back(move(pnx));
    if(k == 0) { // 左端
        nx->r = R;
        if(R != NIL) R->p = nx; // 元 0 頂点かもしれない
        R = nx;
        prepareUp(nx); // 入したら集約
        return;
    }
    if(k == R->sumz) { // 右端(左端と同)
        nx->l = R;
        if(R != NIL) R->p = nx;
        R = nx;
        prepareUp(nx);
        return;
    }
    auto p = kth_element(k);
    nx->l = p->l;
}

```

```

    nx->r = p;
    R = nx;
    p->l->p = nx;
    p->p = nx;
    p->l = NIL;
    prepareUp(p); // split/merge の影響
    prepareUp(nx); //
}
void erase_at(int k) {
    auto p = kth_element(k);
    if(k == 0) { // 左端
        R = p->r;
        if(R != NIL) R->p = NIL; // 0 頂点になるかもしれない
    }
    else if(k == R->sumz-1) { // 右端
        R = p->l;
        if(R != NIL) R->p = NIL;
    }
    else {
        auto l = p->l;
        auto r = p->r;
        r->p = NIL; // split
        R = r; //
        kth_element(0);
        r = R; // merge
        r->l = l; //
        l->p = r; //
        prepareUp(r); // split/merge の影響
    }
    swap(p->i, A.back()->i); // index が更新されるよ
    swap(A[p->i], A[A.back()->i]); // 後ろに移動して
    A.pop_back(); // 削除
}
Node* between(int l, int r) {
    if(l == 0 && r == R->sumz) return R; // 全域
    if(l == 0) return kth_element(r)->l; // 左端
    if(r == R->sumz) return kth_element(l-1)->r; // 右端
    auto rp = kth_element(r);
    auto lp = rp->l;
    R = lp; // split
    lp->p = NIL; //
    lp = kth_element(l-1);
    R = rp; // merge
    rp->l = lp; //
    lp->p = rp; //
    prepareUp(rp); // split/merge の影響
    return lp->r;
}
void reverse(int l, int r) {
    auto c = between(l, r);
    c->rev ^= 1;
    reverse_prod(c->prod);
    splay(c);
}
void apply(int l, int r, F f) {

```

```

    auto c = between(l, r);
    c->a = mapping(f, c->a);
    c->prod = mapping(f, c->prod);
    c->f = composition(f, c->f);
    splay(c);
}
S prod(int l, int r) {
    return between(l, r)->prod;
}
}; // end of struct SplayTreeByIdx
SplayTreeByIdx splay; // insert_at := i-thへデータ投入(splay node)

```

1.8 Segment Tree

```

template <class S, auto op, auto e> struct segtree {
public:
    segtree(int n = 0) : segtree(vector<S>(n, e())) {}
    segtree(const vector<S>& v) : _n(v.size()) {
        sz = 1;
        while (sz < _n) sz <= 1;
        d.assign(2 * sz, e());
        for (int i = 0; i < _n; i++) d[sz + i] = v[i];
        for (int i = sz - 1; i >= 1; i--) update(i);
    }
    void set(int p, S x) {
        p += sz;
        d[p] = x;
        for (int i = 1; i <= __builtin_ctz(sz); i++) update(p >> i);
    }
    S get(int p) { return d[p + sz]; }
    S prod(int l, int r) {
        S sml = e(), smr = e();
        l += sz;
        r += sz;
        while (l < r) {
            if (l & 1) sml = op(sml, d[l++]);
            if (r & 1) smr = op(d[--r], smr);
            l >>= 1;
            r >>= 1;
        }
        return op(sml, smr);
    }
    S all_prod() { return d[1]; }
private:
    int _n, sz;
    vector<S> d;
    void update(int k) { d[k] = op(d[2 * k], d[2 * k + 1]); }
};

```

1.9 Lazy Segment Tree

```

template <class S, auto op, auto e, class F, auto mapping, auto composition, auto id>
struct lazy_segtree {
public:
    lazy_segtree(int n = 0) : lazy_segtree(vector<S>(n, e())) {}

```

```

lazy_segtree(const vector<S>& v) : _n(v.size()) {
    sz = 1;
    while (sz < _n) sz <<= 1;
    lg = __builtin_ctz(sz);
    d.assign(2 * sz, e());
    lz.assign(sz, id());
    for (int i = 0; i < _n; i++) d[sz + i] = v[i];
    for (int i = sz - 1; i >= 1; i--) update(i);
}

void set(int p, S x) {
    p += sz;
    for (int i = lg; i >= 1; i--) push(p >> i);
    d[p] = x;
    for (int i = 1; i <= lg; i++) update(p >> i);
}

S get(int p) {
    p += sz;
    for (int i = lg; i >= 1; i--) push(p >> i);
    return d[p];
}

S prod(int l, int r) {
    if (l == r) return e();
    l += sz, r += sz;
    for (int i = lg; i >= 1; i--) {
        if (((l >> i) << i) != 1) push(l >> i);
        if (((r >> i) << i) != r) push((r - 1) >> i);
    }
    S sml = e(), smr = e();
    while (l < r) {
        if (l & 1) sml = op(sml, d[l++]);
        if (r & 1) smr = op(d[--r], smr);
        l >>= 1, r >>= 1;
    }
    return op(sml, smr);
}

S all_prod() { return d[1]; }

void apply(int p, F f) {
    p += sz;
    for (int i = lg; i >= 1; i--) push(p >> i);
    d[p] = mapping(f, d[p]);
    for (int i = 1; i <= lg; i++) update(p >> i);
}

void apply(int l, int r, F f) {
    if (l == r) return;
    l += sz, r += sz;
    for (int i = lg; i >= 1; i--) {
        if (((l >> i) << i) != 1) push(l >> i);
        if (((r >> i) << i) != r) push((r - 1) >> i);
    }
    int l2 = l, r2 = r;
    while (l < r) {
        if (l & 1) all_apply(l++, f);
        if (r & 1) all_apply(--r, f);
        l >>= 1, r >>= 1;
    }
}

```

```

    l = l2, r = r2;
    for (int i = 1; i <= lg; i++) {
        if (((l >> i) << i) != 1) update(l >> i);
        if (((r >> i) << i) != r) update((r - 1) >> i);
    }
}

private:
int _n, sz, lg;
vector<S> d;
vector<F> lz;
void update(int k) { d[k] = op(d[2 * k], d[2 * k + 1]); }
void all_apply(int k, F f) {
    d[k] = mapping(f, d[k]);
    if (k < sz) lz[k] = composition(f, lz[k]);
}
void push(int k) {
    all_apply(2 * k, lz[k]);
    all_apply(2 * k + 1, lz[k]);
    lz[k] = id();
}
};

```

2 Monoid

2.1 RMQ and RNQ

```
S op(S a, S b){ return min(a, b); } // or max
S e(){ return INF; }
S mapping(F f, S x){ return f+x; }
F composition(F f, F g){ return f+g; }
F id(){ return 0; }
```

2.2 RMQ and RUQ

```
S op(S a, S b){ return min(a, b); } // or max
S e(){ return INF; }
S mapping(F f, S x){ return (f == ID ? x : f); }
F composition(F f, F g){ return (f == ID ? g : f); }
F id(){ return ID; }
```

2.3 RSQ and RNQ

```
struct S { ll x; int sz; };
S op(S a, S b){ return {a.x+b.x, a.sz+b.sz}; }
S e(){ return {0, 0}; }
S mapping(F f, S x){ return {x.x + f*x.x, x.sz}; }
F composition(F f, F g){ return f+g; }
F id(){ return 0; }
```

2.4 RSQ and RUQ

```
struct S { ll x; int sz; };
S op(S a, S b) { return {a.x+b.x, a.sz+b.sz}; }
S e() { return {0, 0}; }
S mapping(F f, S x) { if(f != ID) x.x = f*x.sz; return x; }
F composition(F f, F g) { return (f == ID ? g : f); }
F id() { return ID; }
```

2.5 Maximum Array(Struct Segment)

```
struct S {
    bool check;
    int l, r, sum, len;
    S(int x = 0, int c = false): sum(0) { l = r = x; len = 1; check = c; }
    S(int l, int r, int sum, int len, int c): l(l), r(r), sum(sum), len(len) { check = c; }
};
using F = int;
const F ID = -1;
S op(S a, S b) {
    if (!a.check || !b.check) {
        if (!a.check && !b.check) return S();
        if (!a.check) return b;
        else if (!b.check) return a;
    }
    return S(a.l, b.r, a.sum+b.sum+(a.r==b.l), a.len+b.len, true);
}
S e() { return S(); }
S mapping(F f, S x) {
```

```
    if (f == ID) return x;
    return S(f, f, x.len-1, x.len, true);
}
F composition(F f, F g) { return (f == ID ? g : f); }
F id() { return ID; }
```

3 DP

3.1 Doubling(Sparse Table)

```
// Tree 형태에서, 어떤 값의 조상...
int n, f[200000], dp[32][200000];
void doubling() {
    for (int j = 0; j < n; j++) dp[0][j] = f[j];
    for (int i = 1; i < 31; i++) {
        for (int j = 0; j < n; j++) {
            dp[i][j] = dp[i-1][dp[i-1][j]];
        }
    }
}
```

3.2 Streetlight(prefix sum + dp)

```
int n, m;
ll x[1002], w[1002], wsum[1002], dp[1002][1002][2];
int main() {
    cin >> n >> m;
    for (int i = 1; i <= n; i++) {
        cin >> x[i] >> w[i];
        wsum[i] = wsum[i-1] + w[i];
    }
    for (int i = 0; i <= 1001; i++) for (int j = 0; j <= 1001; j++) dp[i][j][0] = dp[i][j][1]
    = 1'000'000'000'000'000LL;
    dp[m][m][0] = dp[m][m][1] = 0;
    for (int len = 1; len <= n; len++) {
        for (int l = max(1, m-len+1); l <= m; l++) {
            int r = l+len-1;
            if (r > n) continue;
            if (l-1 >= 1) dp[l-1][r][0] = min({dp[l-1][r][0],
            dp[l][r][0]+(wsum[n]-wsum[r]+wsum[l-1])*(x[l]-x[l-1]),
            dp[l][r][1]+(wsum[n]-wsum[r]+wsum[l-1])*(x[r]-x[l-1])});
            if (r+1 <= n) dp[l][r+1][1] = min({dp[l][r+1][1],
            dp[l][r][0]+(wsum[n]-wsum[r]+wsum[l-1])*(x[r+1]-x[l]),
            dp[l][r][1]+(wsum[n]-wsum[r]+wsum[l-1])*(x[r+1]-x[r])});
        }
    }
    cout << min(dp[1][n][0], dp[1][n][1]);
}
```

4 Geometry

4.1 vector2

```
double pi = acos(-1);
template<class T>
struct vector2 {
    T x, y; // double or ll, dot, cross, fix req
    explicit vector2(T _x = 0, T _y = 0): x(_x), y(_y) {}
    vector2 operator + (const vector2 &rhs) const {
        return vector2(x + rhs.x, y + rhs.y);
    }
    vector2 operator - (const vector2 &rhs) const {
        return vector2(x - rhs.x, y - rhs.y);
    }
    vector2 operator * (const double k) const {
        return vector2(k*x, k*y);
    }
    bool operator == (const vector2 &rhs) const {
        return x == rhs.x && y == rhs.y;
    }
    bool operator < (const vector2 &rhs) const {
        return x != rhs.x ? x < rhs.x : y < rhs.y;
    }
    T dot(const vector2 &rhs) const {
        return x*rhs.x + y*rhs.y;
    }
    T cross(const vector2 &rhs) const {
        return x * rhs.y - y * rhs.x;
    }
    double norm() const {
        return hypot(x, y);
    }
    T norm2() const {
        return x*x+y*y;
    }
    vector2 basis() const {
        double d = norm(); // req T=double
        return vector2(x/d, y/d);
    }
    vector2 reverse() const {
        return vector2(-1*x, -1*y);
    }
};
int doubleCompare(double x, double y, double eps = 1e-8) {
    if (fabs(x-y) <= eps) return 0; // 0 is true
    return (x-y > 0) ? 1 : -1;
}
ll ccw(vector2 v1, vector2 v2, vector2 v3) {
    if (doubleCompare((v2-v1).cross(v3-v2), 0) == 0) return 0;
    else return (v2-v1).cross(v3-v2); // 1(>0), -1(<0)
}
bool pointYCompare(const vector2 &a, const vector2 &b) {
    return a.x != b.x ? a.x < b.x : a.y < b.y;
}
```



```

}
bool pointThetaCompare(const vector2 &a, const vector2 &b) {
    if (ccw(vector2(), a, b) == 0) return a.norm() < b.norm();
    else return ccw(vector2(), a, b) > 0;
}
double safe_acos(double a) {
    if (a <= -1.0) return pi; // req acos(-1) = pi
    else if (a >= 1.0) return 0;
    else return acos(a);
}
// like cross
double f(vector2 p1, vector2 q1, vector2 p2, vector2 q2) {
    return ((p2-p1).cross(q2-p2) / (q1-p1).cross(q2-p2));
}
double k = f(p1, q1, p2, q2); // k배
double cx = p1.x + k*(p2.x-p1.x), cy = p1.y + k*(p2.y-p1.y); // p1->p1, p2->q2 교차점

```

4.2 vector3

```

// fix vector2 -> 3, this template only v3
vector3 cross(const vector3 &rhs) const {
    return vector3(y*rhs.z-z*rhs.y, z*rhs.x-x*rhs.z, x*rhs.y-y*rhs.x);
}
double norm() const {
    return sqrt(x*x + y*y + z*z);
}

```

4.3 Line Intersection

```

// req vector2
struct line2 {
    vector2 p1, p2;

    void setLeftRight() {
        if (p2 < p1) {
            vector2 temp = p2;
            p2 = p1;
            p1 = temp;
        }
    }
};

int line_intersection(vector2 s1, vector2 e1, vector2 s2, vector2 e2) {
    if (e1 < s1) swap(s1, e1);
    if (e2 < s2) swap(s2, e2);
    int c1s = iccw(s1, e1, s2), c1e = iccw(s1, e1, e2),
        c2s = iccw(s2, e2, s1), c2e = iccw(s2, e2, e1);

    if (c1s * c1e == -1 && c2s * c2e == -1) return 2;
    else if (c1s == 0 && c1e == 0 && c2s == 0 && c2e == 0) {
        if (s1.x == e1.x) {
            // 세로 두 직선
            if (s1.y > s2.y) swap(s1, s2), swap(e1, e2);
            if (e1.y < s2.y) return 0;
            if (doubleCompare(e1.y, s2.y) == 0) return 1;
        } else {

```

```

// 가로 두 직선
            if (s1.x > s2.x) swap(s1, s2), swap(e1, e2);
            if (e1.x < s2.x) return 0;
            if (doubleCompare(e1.x, s2.x) == 0) return 1;
        }
    }
    return 3;
    if (s1.x > s2.x) swap(s1, s2), swap(e1, e2);
    if (e1.x < s2.x) return 0;
    if (s1.y > s2.y) swap(s1, s2), swap(e1, e2);
    if (e1.y < s2.y) return 0;
    if (e1.y == s2.y) return 1;
    if (s1.x > s2.x) swap(s1, s2), swap(e1, e2);
    if (e1.x == s2.x) return 1;
    return 3;
} else if (c1s * c1e * c2s * c2e == 0) {
    if ((c1s * c1e == 0 && c2s * c2e == 1)
        || (c1s * c1e == 1 && c2s * c2e == 0))
        return 0; else return 1;
} else return 0;
}
double f(vector2 p1, vector2 q1, vector2 p2, vector2 q2) {
    return ((p2-p1).cross(q2-p2) / (q1-p1).cross(q2-p2));
}
// 교차점 계산
double w = f(v[i], v[j], v[k], v[nk]);
double cx = v[i].x + w*(v[j].x-v[i].x), cy = v[i].y + w*(v[j].y-v[i].y);
// 반사
vector2 p, np, fp;
p.input();
np.input();
double k = (e-s).dot(p-s)/(e-s).get_size();
np = s + (e-s).basis()*k;
fp = p+(np-p)*2; // x1의 경우 사영
cout << fp.x << " " << fp.y << "\n";

```

4.4 Convex Hull

```

// cps: 컨헵집합, [0]이 제일 외곽, O(nlogn)
vector<vector2> p;
vector<vector<vector2>> cps;
int n, check[1050], ci = 1, cnt = 0;
double oa = 0, ia = 0;
int main () {
    cin >> n;
    p = vector<vector2>(n);
    for (int i = 0; i < n; i++) {
        check[i] = 0;
        cin >> p[i].x >> p[i].y;
        p[i].i = i;
    }
    while (p.size() >= 3) {
        sort(p.begin(), p.end(), pointYCompare);
        vector2 save = p.front();
        for (int i = 1; i < p.size(); i++) {
            p[i].x = p[i].x - p[0].x;
            p[i].y = p[i].y - p[0].y;

```

```

}
sort(next(p.begin()), p.end(), pointThetaCompare);
vector<vector2> np, cp;
p[0] = vector2();
p[0].i = save.i;
cp.push_back(p[0]);
cp.push_back(p[1]);
for (int i = 2; i < p.size(); i++) {
    while (cp.size() > 1) {
        if (ccw(cp[cp.size()-2], cp[cp.size()-1], p[i]) <= 0) {
            np.push_back(cp.back());
            cp.pop_back();
        } else break;
    }
    cp.push_back(p[i]);
}
if (cp.size() < 3) break;
for (auto &e: cp) check[e.i] = ci, e.x += save.x, e.y += save.y;
for (auto &e: np) e.x += save.x, e.y += save.y;
swap(p, np);
cps.push_back(cp);
ci++;
}
}

```

4.5 Rotating Callipers

```

// 가장 먼 두 점, 0(n)
int i2 = 1, p1, p2;
ll maxdist = 0;
for (int i1 = 0; i1 < cp.size(); i1++) {
    auto dist = (cp[i2]-cp[i1]).normll();
    if (maxdist <= dist) {
        maxdist = dist;
        p1 = i1;
        p2 = i2;
    }

    auto ccwv = ccw(cp[i1], cp[(i1+1)%cp.size()], cp[i2], cp[(i2+1)%cp.size()]);
    if (ccwv > 0) i2 = (i2+1)%cp.size();
    else i1++;
}

```

4.6 Angle Sort

```

sort(a, a+n, [&](const vector2 &a, const vector2 &b){
    if((tie(a.x, a.y) > tie(0, 0)) ^ (tie(b.x, b.y) > tie(0, 0))) return tie(a.x, a.y) >
    tie(b.x, b.y);
    if(ccw(a, b) != 0) return ccw(a, b) > 0; // ccw 잘 수정하셈
    return hypot(a) < hypot(b);
});

```

5 Graph

5.1 Floyd warshall

Time Complexity: $O(n^3)$

```

int citys[101][101];
int main() {
    int n, m;
    cin >> n >> m;
    for (int i = 1; i <= 100; i++)
        for (int j = 1; j <= 100; j++)
            citys[i][j] = 1e6 * 100;
    int a, b, c;
    for (int i = 0; i < m; i++) {
        cin >> a >> b >> c;
        citys[a][b] = min(citys[a][b], c);
    }
    for (int k = 1; k <= n; k++) {
        for (int i = 1; i <= n; i++) {
            for (int j = 1; j <= n; j++) {
                if (i != j)
                    citys[i][j] = min(citys[i][j], citys[i][k]+citys[k][j]);
            }
        }
    }
    for (int i = 1; i <= n; i++)
        for (int j = 1; j <= n; j++)
            cout << (citys[i][j] != 1e6 * 100 ? citys[i][j] : 0) << (j != n ? ' ' : '\n');
}

```

5.2 scc

```

// 1-index, initialize: scc_graph(int size), necessary make_graph
struct scc_graph {
    int n, id = 0;
    vector<int> ids, finished;
    vector<vector<int>> path, scc;
    stack<int> stk;

    scc_graph(int _n) {
        n = _n;
        ids = finished = vector<int>(n+1);
        path = vector<vector<int>>(n+1);
    }

    void make_graph() { for (int i = 1; i <= n; i++) if (!ids[i]) dfs(i); }
    void add_edge(int u, int v) { path[u].push_back(v); }

    int dfs(int s) {
        ids[s] = ++id;
        stk.push(s);

        int parent = ids[s];
        for (auto &i: path[s]) {
            if (!ids[i]) parent = min(parent, dfs(i));
        }
    }
}

```

```

    else if (!finished[i]) parent = min(parent, ids[i]);
}

if (parent == ids[s]) {
    vector<int> findset;
    while (true) {
        auto x = stk.top();
        stk.pop();

        findset.push_back(x);
        finished[x] = 1;
        if (s == x) break;
    }
    sort(findset.begin(), findset.end());
    scc.push_back(findset);
}

return parent;
}
};

```

5.3 2-sat

```

struct csr {
    vector<int> s, el;
    csr(int n, vector<pii>& edges): s(n + 1), el(edges.size()) {
        for (auto e: edges) s[e.first+1]++;
        for (int i = 1; i <= n; i++) s[i] += s[i-1];
        auto cnt = s;
        for (auto e : edges) el[cnt[e.first]++] = e.second;
    }
};

struct scc_graph {
    scc_graph(int n) : _n(n) {}
    void add(int from, int to) { edges.push_back({from, to}); }
    pair<int, vector<int>> scc_ids() {
        auto g = csr(_n, edges);
        int cord = 0, gnum = 0;
        vector<int> vis, low(_n), ord(_n, -1), ids(_n);
        vis.reserve(_n);
        auto dfs = [&](auto self, int v) -> void {
            low[v] = ord[v] = cord++;
            vis.push_back(v);
            for (int i = g.s[v]; i < g.s[v + 1]; i++) {
                auto to = g.el[i];
                if (ord[to] == -1) {
                    self(self, to);
                    low[v] = min(low[v], low[to]);
                } else low[v] = min(low[v], ord[to]);
            }
            if (low[v] == ord[v]) {
                while (true) {
                    int u = vis.back();
                    vis.pop_back();

```

```

                    ord[u] = _n, ids[u] = gnum;
                    if (u == v) break;
                }
                gnum++;
            }
        };
        for (int i = 0; i < _n; i++) if (ord[i] == -1) dfs(dfs, i);
        for (auto& x : ids) x = gnum - 1 - x;
        return {gnum, ids};
    }

    vector<vector<int>> scc() {
        auto ids = scc_ids();
        int gnum = ids.first;
        vector<int> cnt(gnum);
        for (auto x : ids.second) cnt[x]++;
        vector<vector<int>> g(ids.first);
        for (int i = 0; i < gnum; i++) g[i].reserve(cnt[i]);
        for (int i = 0; i < _n; i++) g[ids.second[i]].push_back(i);
        return g;
    }

    int _n;
    vector<pii> edges;
};

struct two_sat {
    int n;
    vector<bool> ans;
    scc_graph scc;

    explicit two_sat(int _n): n(_n), ans(_n), scc(2*_n) {}
    void add(int i, bool f, int j, bool g) {
        scc.add(2 * i + (f ? 0 : 1), 2 * j + (g ? 1 : 0));
        scc.add(2 * j + (g ? 0 : 1), 2 * i + (f ? 1 : 0));
    }

    bool satisfiable() {
        auto id = scc.scc_ids().second;
        for (int i = 0; i < n; i++) {
            if (id[2 * i] == id[2 * i + 1]) return false;
            ans[i] = id[2 * i] < id[2 * i + 1];
        }
        return true;
    }

    vector<bool> answer() { return ans; }
};

```

5.4 hld

```

// require ACL seg
template <typename T = int>
struct Edge {
    int from, to;
    T cost;

```

```

Edge(int _to, T _cost = 1): from(-1), to(_to), cost(_cost) {} // from is array index
Edge(int _from, int _to, T _cost): from(_from), to(_to), cost(_cost) {} // only edge
save, ex) use in prim
Edge &operator= (const int &x) {
    to = x;
    return *this;
}
operator int() const { return to; }
};
// weighted graph
template <typename T>
using WeightedEdges = vector<Edge<T>>;
template <typename T>
using WeightedFIDXEdges = vector<vector<pair<int, T>>>;
using UnweightedEdges = vector<vector<int>>>;
template <typename T>
pair<WeightedEdges<T>, WeightedFIDXEdges<T>> w_fidx_graph(int n, int m = -1, bool
is_directed = false, bool is_lidx = true) {
    WeightedEdges<T> wg;
    WeightedFIDXEdges<T> g(n), c(n);
    if (m == -1) m = n-1;
    int ui = 1;
    while (m--> 0) {
        int u, v;
        T w;
        cin >> u >> v;
        // cin >> v;
        // u = ++ui;
        w=0;
        if (is_lidx) u--, v--;
        wg.emplace_back(u, v, w);
        g[u].push_back({v, w});
        if (!is_directed) g[v].push_back({u, w});
    }
    queue<pair<int,int>> q;
    q.push({0, -1});
    while (q.size()) {
        auto [v, pv] = q.front();
        q.pop();
        for (auto &[e, w]: g[v]) {
            if (e != pv) {
                c[v].emplace_back(e, w);
                q.push({e, v});
            }
        }
    }
    return {wg, c};
}
// basic HLD
template <typename T, class S, auto Sop, auto Se>
struct HeavyLightDecomposition {
    // private:
public:
    int root, eid, fid;
    vector<int> sz, d, p, top, in, out, vis, id;

```

```

vector<T> x;
WeightedFIDXEdges<T> c;
atcoder::segtree<S, Sop, Se> seg;
void dfs1(int v, int pv = -1, int cid = -1) {
    vis[v] = 1;
    sz[v] = 1;
    id[v] = cid;
    for (auto &e: c[v]) {
        if (e.first == pv) continue;
        d[e.first] = d[v]+1;
        p[e.first] = v;
        dfs1(e.first, v, cid);
        sz[v] += sz[e.first];
        if (sz[e.first] > sz[c[v][0].first]) swap(e, c[v][0]);
    }
}
void dfs2(int v, int pv = -1) {
    vis[v] = 2;
    in[v] = eid++;
    for (auto &[e, w]: c[v]) {
        if (e == pv) continue;
        top[e] = e == c[v][0].first ? top[v] : e;
        dfs2(e, v);
        x[e] = w;
    }
    out[v] = eid;
}
// public:
HeavyLightDecomposition(WeightedFIDXEdges<T> g, int _root = 0)
: c(g),
  root(_root),
  eid(0),
  fid(0),
  sz(g.size(), 0),
  d(g.size(), 0),
  x(g.size(), 0),
  in(g.size(), -1),
  out(g.size(), -1),
  vis(g.size(), 0),
  id(g.size(), 0),
  seg(atcoder::segtree<S, Sop, Se>(g.size()+1)),
  top(g.size(), root),
  p(g.size(), root) {
    for (int i = 0; i < g.size(); i++) if (vis[i] != 1) dfs1(i, -1, fid++);
    for (int i = 0; i < g.size(); i++) if (vis[i] != 2) dfs2(i);
    // init_seg();
}
void init_seg(vector<T> v) {
    assert(x.size() == v.size());
    for (int i = 0; i < x.size(); i++) seg.set(in[i], x[i] = v[i]);
}
int lca(int u, int v) {
    while (top[u] != top[v]) {

```

```

        if (d[top[u]] < d[top[v]]) swap(u, v);
        int st = top[u];
        u = p[st];
    }
    if (d[u] > d[v]) swap(u, v);
    return u;
}

S query(int u, int v, int inc_start = 0) {
    S r = Se();
    while (top[u] != top[v]) {
        if (d[top[u]] < d[top[v]]) swap(u, v);
        int st = top[u];
        r = Sop(r, seg.prod(in[st], in[u]+1));
        u = p[st];
    }
    if (d[u] > d[v]) swap(u, v);
    r = Sop(r, seg.prod(in[u]+inc_start, in[v]+1));
    return r;
}
};
// lazy hld
template <typename T, class S, auto Sop, auto Se, class F, auto mapping, auto composition,
auto id>
struct LazyHeavyLightDecomposition {
    // private:
public:
    int root, eid;
    vector<int> sz, d, p, top, in, out, vis;
    vector<T> x;
    WeightedFIDXEdges<T> c;
    atcoder::lazy_segtree<S, Sop, Se, F, mapping, composition, id> seg;
    void dfs1(int v, int pv = -1) {
        vis[v] = 1;
        sz[v] = 1;
        for (auto &e: c[v]) {
            if (e.first == pv) continue;
            d[e.first] = d[v]+1;
            p[e.first] = v;
            dfs1(e.first, v);
            sz[v] += sz[e.first];
            if (sz[e.first] > sz[c[v][0].first]) swap(e, c[v][0]);
        }
    }
    void dfs2(int v, int pv = -1) {
        vis[v] = 2;
        in[v] = eid++;
        for (auto &[e, w]: c[v]) {
            if (e == pv) continue;
            top[e] = e == c[v][0].first ? top[v] : e;
            dfs2(e, v);
            x[e] = w;
        }
        out[v] = eid;
    }
}

```

```

// public:
LazyHeavyLightDecomposition(WeightedFIDXEdges<T> g, int _root = 0)
: c(g),
  root(_root),
  eid(0),
  sz(g.size(), 0),
  d(g.size(), 0),
  x(g.size(), 0),
  in(g.size(), -1),
  out(g.size(), -1),
  vis(g.size(), 0),
  seg(atcoder::lazy_segtree<S, Sop, Se, F, mapping, composition, id>(g.size()+1)),
  top(g.size(), root),
  p(g.size(), root) {
    for (int i = 0; i < g.size(); i++) if (vis[i] != 1) dfs1(i);
    for (int i = 0; i < g.size(); i++) if (vis[i] != 2) dfs2(i);
    // init_seg();
}

void init_seg(vector<S> v) {
    assert(x.size() == v.size());
    for (int i = 0; i < x.size(); i++) seg.set(in[i], v[i]);
}

int lca(int u, int v) {
    while (top[u] != top[v]) {
        if (d[top[u]] < d[top[v]]) swap(u, v);
        int st = top[u];
        u = p[st];
    }
    if (d[u] > d[v]) swap(u, v);
    return u;
}

S query(int u, int v, int inc_start = 0) {
    S l = Se();
    S r = Se();
    while (top[u] != top[v]) {
        // if (d[top[u]] < d[top[v]]) swap(u, v);
        if (d[top[u]] > d[top[v]]) {
            int st = top[u];
            l = Sop(seg.prod(in[st], in[u]+1), l);
            u = p[st];
        } else {
            int st = top[v];
            r = Sop(seg.prod(in[st], in[v]+1), r);
            v = p[st];
        }
    }
    if (d[u] < d[v]) r = Sop(seg.prod(in[u]+inc_start, in[v]+1), r);
    else l = Sop(seg.prod(in[v]+inc_start, in[u]+1), l);
    swap(l.l, l.r);
    return Sop(l, r);
}

```

```

void apply(int u, int v, F x, int inc_start = 0) {
    while (top[u] != top[v]) {
        if (d[top[u]] < d[top[v]]) swap(u, v);
        int st = top[u];
        seg.apply(in[st], in[u]+1, x);
        u = p[st];
    }
    if (d[u] > d[v]) swap(u, v);
    seg.apply(in[u]+inc_start, in[v]+1, x);
}
};

```

5.5 Bellman Ford

```

// require HLD-WeightedEdges,
template <typename T = int>
vector<T> bellman_ford(int n, kENN3N::WeightedEdges<T> edges, int sv = 0, int ev = -1) {
    T MAX = numeric_limits<T>::max() / 2;
    vector<T> d(n, MAX);
    d[sv] = 0;
    for (int i = 0; i < n; i++) {
        bool upd = false;
        for (auto &e: edges) {
            if (d[e.from] == MAX) continue;
            if (d[e.to] > d[e.from] + e.cost) upd = true, d[e.to] = d[e.from] + e.cost;
        }
        if (!upd) return d;
    }
    if (ev == -1) return vector<T>();
    vector<bool> nega(n, false);
    for (int i = 0; i < n; i++) {
        for (auto &e: edges) {
            if (d[e.from] == MAX) continue;
            if (d[e.to] > d[e.from] + e.cost) nega[e.to] = true, d[e.to] = d[e.from] + e.cost;
            if (nega[e.from]) nega[e.to] = true;
        }
    }
    if (nega[ev]) return vector<T>();
    else return d;
}
/*
벨만 포드 부등식
방법은, xj - xi <= T일때, i -> j로 가는 가중치 T의 간선을 만들어주는 것이다.
이러한 일련의 작업이 끝났다면, 임의의 정점 i에서 벨만 포드를 돌렸을 때, xj = xi + ShortestPath(i, j) 라는 값을 대입했을 때 저것을 만족함을 보장할 수 있다.
*/
WeightedEdges<ll> g;
for (int i = 0; i < q; i++) {
    int a, b, x;
    string op;
    cin >> a >> b >> op >> x;
    // a--, b--;
    if (op == "<=") g.push_back(Edge<ll>(b+n, a, x));
    else g.push_back(Edge<ll>(a, b+n, -x));
}

```

```

for (int i = 1; i <= n+m; i++) g.push_back(Edge<ll>(0, i, 0));
auto y = bellman_ford(n+m+1, g);
cout << (y.size() ? "Possible" : "Impossible") << "\n";

```

5.6 Maxflow

Time Complexity: $O(n+m)\sqrt{n}$, $O(n^2m)$

```

template <class Cap> struct mf_graph {
    mf_graph(int n = 0) : _n(n), g(n) {}
    void add_edge(int from, int to, Cap cap) {
        int from_id = g[from].size();
        int to_id = g[to].size();
        g[from].push_back({to, to_id, cap});
        g[to].push_back({from, from_id, 0});
    }
    Cap flow(int s, int t, Cap limit = numeric_limits<Cap>::max()) {
        Cap flow = 0;
        vector<int> level(_n), iter(_n);
        auto bfs = [&]() {
            fill(level.begin(), level.end(), -1);
            level[s] = 0;
            queue<int> q;
            q.push(s);
            while (!q.empty()) {
                int v = q.front();
                q.pop();
                for (auto& e : g[v]) {
                    if (e.cap > 0 && level[e.to] < 0) {
                        level[e.to] = level[v] + 1;
                        q.push(e.to);
                    }
                }
            }
        };
        return level[t] != -1;
    };
    auto dfs = [&](auto self, int v, Cap up) -> Cap {
        if (v == t) return up;
        Cap res = 0;
        for (int& i = iter[v]; i < g[v].size(); i++) {
            _edge &e = g[v][i], &re = g[e.to][e.rev];
            if (e.cap > 0 && level[v] < level[e.to]) {
                Cap d = self(self, e.to, min(up - res, e.cap));
                if (d > 0) {
                    e.cap -= d;
                    re.cap += d;
                    res += d;
                    if (res == up) break;
                }
            }
            iter[v]++;
        }
        return res;
    };
    while (flow < limit && bfs()) {
        fill(iter.begin(), iter.end(), 0);
    }
}

```

```

    Cap f = dfs(dfs, s, limit - flow);
    if (!f) break;
    flow += f;
}
return flow;
}

private:
struct _edge { int to, rev; Cap cap; };
int _n;
vector<vector<_edge>> g;
};
mf_graph<int> mf;

```

5.7 Min cost Max Flow

Time Complexity: $O(F(n + m)\log(n + m))$

```

template <class Cap, class Cost> struct mcf_graph {
public:
    mcf_graph(int n = 0) : _n(n), g(n) {}
    void add_edge(int from, int to, Cap cap, Cost cost) {
        g[from].push_back({to, (int)g[to].size(), cap, cost});
        g[to].push_back({from, (int)g[from].size() - 1, 0, -cost});
    }
    pair<Cap, Cost> flow(int s, int t, Cap flow_limit = numeric_limits<Cap>::max()) {
        Cap flow = 0;
        Cost cost = 0;
        vector<Cost> h(_n, 0);
        vector<int> prev_v(_n), prev_e(_n);

        while (flow < flow_limit) {
            vector<Cost> dist(_n, numeric_limits<Cost>::max());
            dist[s] = 0;
            priority_queue<pair<Cost, int>, vector<pair<Cost, int>>, greater<pair<Cost, int>>>
            que;
            que.push({0, s});

            while (!que.empty()) {
                auto [d, v] = que.top();
                que.pop();
                if (dist[v] < d) continue;
                for (int i = 0; i < g[v].size(); i++) {
                    _edge& e = g[v][i];
                    if (e.cap > 0 && dist[e.to] > dist[v] + e.cost + h[v] - h[e.to]) {
                        dist[e.to] = dist[v] + e.cost + h[v] - h[e.to];
                        prev_v[e.to] = v;
                        prev_e[e.to] = i;
                        que.push({dist[e.to], e.to});
                    }
                }
            }

            if (dist[t] == numeric_limits<Cost>::max()) break;
            for (int i = 0; i < _n; i++) h[i] += dist[i];

```

```

        Cap d = flow_limit - flow;
        for (int v = t; v != s; v = prev_v[v]) d = min(d, g[prev_v[v]][prev_e[v]].cap);
        flow += d;
        cost += d * h[t];
        for (int v = t; v != s; v = prev_v[v]) {
            _edge& e = g[prev_v[v]][prev_e[v]];
            e.cap -= d;
            g[v][e.rev].cap += d;
        }
        return {flow, cost};
    }
private:
    struct _edge { int to, rev; Cap cap; Cost cost; };
    int _n;
    vector<vector<_edge>> g;
};

```

6 Math

6.1 Combination

```
// ncr
struct Combination {
    const ll MAX, MOD;
    vector<ll> inv, fac, fi;
    Combination(ll max, ll mod): MAX(max), MOD(mod) {
        inv = vector<ll>(max+1);
        fac = vector<ll>(max+1);
        fi = vector<ll>(max+1);
        fac[1] = inv[1] = fi[1] = 1;
        for (ll i = 2; i <= max; i++) {
            fac[i] = (fac[i-1]*i) % mod;
            inv[i] = (mod - mod/i) * inv[mod%i] % mod;
            fi[i] = fi[i-1]*inv[i] % mod;
        }
    }
    ll ncr(ll n, ll r) {
        if (r == 0 || n == r) return 1;
        return (fac[n]*fi[r]%MOD)*fi[n-r]%MOD;
    }
};
```

6.2 FFT - int

```
using pll = pair<ll, ll>;
using ull = unsigned long long;
// X.v 와 같이 접근해야함. int 범위 내 NTT 전용
namespace NTT {
    constexpr int MOD = 998244353;
    constexpr int G = 3; // Primitive root for MOD
    struct mint {
        int v;
        mint(ll x = 0) : v(x % MOD) { if (v < 0) v += MOD; }
        mint& operator+=(const mint& o) { v += o.v; if (v >= MOD) v -= MOD; return *this; }
        mint& operator-=(const mint& o) { v -= o.v; if (v < 0) v += MOD; return *this; }
        mint& operator*=(const mint& o) { v = (int)((ll)v * o.v % MOD); return *this; }
        mint operator+(const mint& o) const { return mint(*this) += o; }
        mint operator-(const mint& o) const { return mint(*this) -= o; }
        mint operator*(const mint& o) const { return mint(*this) *= o; }
        mint pow(ll n) const {
            mint res = 1, x = *this;
            while (n > 0) {
                if (n & 1) res *= x;
                x *= x;
                n >>= 1;
            }
            return res;
        }
        mint inv() const { return pow(MOD - 2); }
    };
    int ceil_pow2(int n) {
        int x = 0;
```

```
while ((1U << x) < (unsigned int)(n)) x++;
        return x;
    }
    int bsf(unsigned int n) { return __builtin_ctz(n); }
    void butterfly(vector<mint>& a) {
        int n = a.size();
        int h = ceil_pow2(n);
        static bool first = true;
        static vector<mint> sum_e;
        if (first) {
            first = false;
            sum_e.resize(30);
            mint es[30], ies[30];
            int cnt2 = bsf(MOD - 1);
            mint e = mint(G).pow((MOD - 1) >> cnt2), ie = e.inv();
            for (int i = cnt2; i >= 2; i--) {
                es[i - 2] = e;
                ies[i - 2] = ie;
                e *= e;
                ie *= ie;
            }
            mint now = 1;
            for (int i = 0; i < cnt2 - 2; i++) {
                sum_e[i] = es[i] * now;
                now *= ies[i];
            }
        }
        for (int ph = 1; ph <= h; ph++) {
            int w = 1 << (ph - 1), p = 1 << (h - ph);
            mint now = 1;
            for (int s = 0; s < w; s++) {
                int offset = s << (h - ph + 1);
                for (int i = 0; i < p; i++) {
                    auto l = a[i + offset];
                    auto r = a[i + offset + p] * now;
                    a[i + offset] = l + r;
                    a[i + offset + p] = l - r;
                }
                now *= sum_e[bsf(~(unsigned int)(s))];
            }
        }
    }
    void butterfly_inv(vector<mint>& a) {
        int n = a.size();
        int h = ceil_pow2(n);
        static bool first = true;
        static vector<mint> sum_ie;
        if (first) {
            first = false;
            sum_ie.resize(30);
            mint es[30], ies[30];
            int cnt2 = bsf(MOD - 1);
            mint e = mint(G).pow((MOD - 1) >> cnt2), ie = e.inv();
            for (int i = cnt2; i >= 2; i--) {
                es[i - 2] = e; ies[i - 2] = ie;
```



```

    e *= e; ie *= ie;
}
mint now = 1;
for (int i = 0; i < cnt2 - 2; i++) { sum_ie[i] = ies[i] * now; now *= es[i]; }
}
for (int ph = h; ph >= 1; ph--) {
    int w = 1 << (ph - 1), p = 1 << (h - ph);
    mint inow = 1;
    for (int s = 0; s < w; s++) {
        int offset = s << (h - ph + 1);
        for (int i = 0; i < p; i++) {
            auto l = a[i + offset];
            auto r = a[i + offset + p];
            a[i + offset] = l + r;
            a[i + offset + p] = (l - r) * inow;
        }
        inow *= sum_ie[bsf(~(unsigned int)(s))];
    }
}
}
vector<mint> convolution(vector<mint> a, vector<mint> b) {
    int n = a.size(), m = b.size();
    if (!n || !m) return {};
    if (min(n, m) <= 60) {
        if (n < m) { swap(n, m); swap(a, b); }
        vector<mint> ans(n + m - 1);
        for (int i = 0; i < n; i++) for (int j = 0; j < m; j++) ans[i + j] += a[i] * b[j];
        return ans;
    }
    int z = 1 << ceil_pow2(n + m - 1);
    a.resize(z); b.resize(z);
    butterfly(a); butterfly(b);
    for (int i = 0; i < z; i++) a[i] *= b[i];
    butterfly_inv(a);
    a.resize(n + m - 1);
    mint iz = mint(z).inv();
    for (int i = 0; i < n + m - 1; i++) a[i] *= iz;
    return a;
}
} // namespace NTT
vector<NTT::mint> a;

```

6.3 FFT - ll (Dnc + CRT)

```

using ull = unsigned long long;
// fft ll = DnC + CRT
// ===== AtCoder Convolution Library =====
namespace atcoder {
namespace internal {
    int ceil_pow2(int n) { int x = 0; while ((1U << x) < (ui)(n)) x++; return x; }
    int bsf(ui n) { return __builtin_ctz(n); }
    constexpr ll safe_mod(ll x, ll m) { x %= m; if (x < 0) x += m; return x; }
    constexpr pair<ll, ll> inv_gcd(ll a, ll b) {
        a = safe_mod(a, b);
        if (a == 0) return {b, 0};
    }

```

```

    ll s = b, t = a;
    ll m0 = 0, m1 = 1;
    while (t) {
        ll u = s / t;
        s -= t * u;
        m0 -= m1 * u;
        auto tmp = s; s = t; t = tmp;
        tmp = m0; m0 = m1; m1 = tmp;
    }
    if (m0 < 0) m0 += b / s;
    return {s, m0};
}
constexpr ll pow_mod(ll x, ll n, int m) {
    if (m == 1) return 0;
    ui _m = (ui)(m);
    ull r = 1, y = safe_mod(x, m);
    while (n) { if (n & 1) r = (r * y) % _m; y = (y * y) % _m; n >>= 1; }
    return r;
}
constexpr bool is_prime(int n) {
    if (n <= 1) return false;
    if (n == 2 || n == 7 || n == 61) return true;
    if (n % 2 == 0) return false;
    ll d = n - 1;
    while (d % 2 == 0) d /= 2;
    constexpr ll bases[3] = {2, 7, 61};
    for (ll a : bases) {
        ll t = d, y = pow_mod(a, t, n);
        while (t != n - 1 && y != 1 && y != n - 1) { y = y * y % n; t <<= 1; }
        if (y != n - 1 && t % 2 == 0) return false;
    }
    return true;
}
constexpr int primitive_root(int m) {
    if (m == 998244353) return 3;
    if (m == 2) return 1;
    int divs[20] = {2}, cnt = 1;
    int x = (m - 1) / 2;
    while (x % 2 == 0) x /= 2;
    for (int i = 3; (1ll)(i) * i <= x; i += 2) {
        if (x % i == 0) { divs[cnt++] = i; while (x % i == 0) x /= i; }
    }
    if (x > 1) divs[cnt++] = x;
    for (int g = 2; ; g++) {
        bool ok = true;
        for (int i = 0; i < cnt; i++) {
            if (pow_mod(g, (m - 1) / divs[i], m) == 1) { ok = false; break; }
        }
        if (ok) return g;
    }
}
template <class T> using is_integral = typename std::is_integral<T>;
} // namespace internal
template <int m>
struct static_modint {

```

```

using mint = static_modint;
static constexpr int mod() { return m; }
int v;
static_modint(ll x = 0) : v(x % m) { if (v < 0) v += m; }
mint& operator+=(const mint& o) { v += o.v; if (v >= m) v -= m; return *this; }
mint& operator-=(const mint& o) { v -= o.v; if (v < 0) v += m; return *this; }
mint& operator*=(const mint& o) { v = (int)((ll)v * o.v % m); return *this; }
mint& operator/=(const mint& o) { return *this = *this * o.inv(); }
mint operator+(const mint& o) const { return mint(*this) += o; }
mint operator-(const mint& o) const { return mint(*this) -= o; }
mint operator*(const mint& o) const { return mint(*this) *= o; }
mint operator/(const mint& o) const { return mint(*this) /= o; }
mint pow(ll n) const {
    mint res = 1, x = *this;
    while (n > 0) { if (n & 1) res *= x; x *= x; n >>= 1; }
    return res;
}
mint inv() const {
    if (prime) { assert(v); return pow(m - 2); }
    else { auto eg = internal::inv_gcd(v, m); assert(eg.first == 1); return eg.second; }
}
static constexpr bool prime = internal::is_prime(m);
};
namespace internal {
template <class mint> void butterfly(vector<mint>& a) {
    constexpr int g = primitive_root(mint::mod());
    int n = a.size(), h = ceil_pow2(n);
    static vector<mint> sum_e;
    if (sum_e.empty()) {
        sum_e.resize(30);
        mint es[30], ies[30];
        int cnt2 = bsf(mint::mod() - 1);
        mint e = mint(g).pow((mint::mod() - 1) >> cnt2), ie = e.inv();
        for (int i = cnt2; i >= 2; i--) {
            es[i - 2] = e; ies[i - 2] = ie; e *= e; ie *= ie;
        }
        mint now = 1;
        for (int i = 0; i < cnt2 - 2; i++) {
            sum_e[i] = es[i] * now; now *= es[i];
        }
    }
    for (int ph = 1; ph <= h; ph++) {
        int w = 1 << (ph - 1), p = 1 << (h - ph);
        mint now = 1;
        for (int s = 0; s < w; s++) {
            int offset = s << (h - ph + 1);
            for (int i = 0; i < p; i++) {
                auto l = a[i + offset], r = a[i + offset + p] * now;
                a[i + offset] = l + r; a[i + offset + p] = l - r;
            }
            now *= sum_e[bsf(~(ui)(s))];
        }
    }
}
template <class mint> void butterfly_inv(vector<mint>& a) {

```

```

constexpr int g = primitive_root(mint::mod());
int n = a.size(), h = ceil_pow2(n);
static vector<mint> sum_ie;
if (sum_ie.empty()) {
    sum_ie.resize(30);
    mint es[30], ies[30];
    int cnt2 = bsf(mint::mod() - 1);
    mint e = mint(g).pow((mint::mod() - 1) >> cnt2), ie = e.inv();
    for (int i = cnt2; i >= 2; i--) {
        es[i - 2] = e; ies[i - 2] = ie; e *= e; ie *= ie;
    }
    mint now = 1;
    for (int i = 0; i < cnt2 - 2; i++) {
        sum_ie[i] = ies[i] * now; now *= es[i];
    }
}
for (int ph = h; ph >= 1; ph--) {
    int w = 1 << (ph - 1), p = 1 << (h - ph);
    mint inow = 1;
    for (int s = 0; s < w; s++) {
        int offset = s << (h - ph + 1);
        for (int i = 0; i < p; i++) {
            auto l = a[i + offset], r = a[i + offset + p];
            a[i + offset] = l + r; a[i + offset + p] = (l - r) * inow;
        }
        inow *= sum_ie[bsf(~(ui)(s))];
    }
}
} // namespace internal
template <class mint>
vector<mint> convolution(vector<mint> a, vector<mint> b) {
    int n = a.size(), m = b.size();
    if (!n || !m) return {};
    int z = 1 << internal::ceil_pow2(n + m - 1);
    a.resize(z); b.resize(z);
    internal::butterfly(a); internal::butterfly(b);
    for (int i = 0; i < z; i++) a[i] *= b[i];
    internal::butterfly_inv(a);
    a.resize(n + m - 1);
    mint iz = mint(z).inv();
    for (int i = 0; i < n + m - 1; i++) a[i] *= iz;
    return a;
}
template <ui mod = 998244353, class T, enable_if_t<internal::is_integral<T>::value>* =
nullptr>
vector<T> convolution_int(const vector<T>& a, const vector<T>& b) {
    int n = a.size(), m = b.size();
    if (!n || !m) return {};
    using mint = static_modint<mod>;
    vector<mint> a2(n), b2(m);
    for (int i = 0; i < n; i++) a2[i] = mint(a[i]);
    for (int i = 0; i < m; i++) b2[i] = mint(b[i]);
    auto c2 = convolution(move(a2), move(b2));
    vector<T> c(n + m - 1);

```

```

    for (int i = 0; i < n + m - 1; i++) c[i] = c2[i].v;
    return c;
}
vector<ll> convolution_ll(const vector<ll>& a, const vector<ll>& b) {
    int n = a.size(), m = b.size();
    if (!n || !m) return {};
    static constexpr ui MOD1 = 754974721; // 2^24 * 45 + 1
    static constexpr ui MOD2 = 167772161; // 2^25 * 5 + 1
    static constexpr ui MOD3 = 469762049; // 2^26 * 7 + 1
    auto c1 = convolution_int<MOD1>(a, b);
    auto c2 = convolution_int<MOD2>(a, b);
    auto c3 = convolution_int<MOD3>(a, b);
    ll m1_m2 = (ll)MOD1 * MOD2;
    ll m1_inv_m2 = internal::inv_gcd(MOD1, MOD2).second;
    ll m1_m2_inv_m3 = internal::inv_gcd(m1_m2, MOD3).second;
    vector<ll> c(n + m - 1);
    for (int i = 0; i < n + m - 1; i++) {
        ll v1 = c1[i], v2 = c2[i], v3 = c3[i];
        ll x = v1;
        ll y = (v2 - x) * m1_inv_m2 % MOD2;
        if (y < 0) y += MOD2;
        x += y * MOD1;
        ll z = (v3 - x % MOD3) * m1_m2_inv_m3 % MOD3;
        if (z < 0) z += MOD3;
        c[i] = x + z * m1_m2;
    }
    return c;
}
} // namespace atcoder

```

6.4 Pollard Rho (with fast prime check)

```

// time: O(n^(1/4))
using i64 = __int128_t;
i64 my_abs(i64 x) { return (x < 0 ? -1*x : x); }
i64 primes[] = { 2, 3, 5, 7, 11, 13, 17, 19, 23, 29, 31, 37, 41 };
// i64 primes[] = { 2, 7, 61 }; // int only
i64 f(i64 x, i64 p, i64 mod) {
    i64 r = 1;
    x %= mod;
    while (p) {
        if (p%2) r *= x, r %= mod;
        p /= 2, x *= x, x %= mod;
    }
    return r;
}
// a is test number, a^d = 1 (MOD N), a^(d*2^r) = -1 (MOD N), d is odd
bool miller_rabin(i64 n, i64 a) {
    if (n == a) return true;
    if (a % n == 0) return false;
    i64 k = n-1;
    while (true) {
        i64 t = f(a, k, n);
        if (t == n-1) return true;
        if (k%2) return (t == 1 || t == n-1);
        k /= 2;
    }
}

```

```

    }
}
bool isp(i64 x) {
    bool p = true;
    for (auto &e: primes) {
        p &= miller_rabin(x, e);
        if (!p) return false;
    }
    return true;
}
void g(i64 x, vector<i64> &v) {
    if (x == 1) return;
    if (x%2 == 0) { v.push_back(2); g(x/2, v); return; }
    if (isp(x)) { v.push_back(x); return; }
    i64 a, b, c, w = x;
    auto h = [&](i64 y) { return (c + y*y%x) % x; };
    do {
        if (w == x) a = b = rand()%(x-2) + 2, c = rand() % 20 + 1;
        a = h(a), b = h(h(b)), w = __gcd(my_abs(a-b), x);
    } while (w == 1);
    g(w, v);
    g(x/w, v);
}
// source: jinhan, factorize code
vector<pair<i64, int>> pollard_rho(i64 x) {
    vector<i64> v;
    vector<pair<i64, int>> r;
    g(x, v);
    sort(v.begin(), v.end());
    for (auto e: v) {
        if (r.size() && r.back().first == e) r.back().second++;
        else r.push_back({ e, 1 });
    }
    return r;
}
int main() {
    ll x;
    while (cin >> x) {
        ll r = 1;
        for (auto [e, c]: pollard_rho(x)) r *= (c+1);
        cout << r << "\n";
    }
}

```

6.5 Permutation and Combination

'''

중복 순열

서로 다른 n개의 원소 중에서 중복을 허용하면서 r개를 순서있게 뽑는 방법의 수 즉, 한 원소를 여러번 뽑을 수 있고, 뽑은 순서를 고려함

print(n**r)

=====

중복 조합

서로 다른 n 개의 원소 중에서 중복을 허용하면서 r 개를 순서 없이 뽑는 방법의 수 즉, 한 원소를 여러번 뽑을 수 있지만, 순서는 고려하지 않음

```
math.comb(n+r-1, r)
```

중복 원소가 있는 순열

동일한 원소가 여러 번 있는 집합(예: AAB)에서 원소들을 모두 사용하여 순열을 만드는 방법의 수 전체 원소의 개수가 n 이고, 중복된 원소의 개수가 n_1, n_2, \dots, n_k 일 때

```
math.factorial(n) / (math.factorial(n1) * math.factorial(n2) * ...)
```

완전 순열

순열의 일종으로, 일렬로 배열한 대상들의 위치를 재조정했을 때, 모든 대상이 자기 위치에 있지 않도록 하는 배열 방법

```
D[n] = (n-1)(D[n-1]+D[n-2])
```

```
D[0] = 1
D[1] = 0
D[2] = 1
D[3] = 2
D[4] = 9
D[5] = 44
'''
```

6.6 Pairwise Product Sum

```
# 모든 i<j에 대해 arr[i]*arr[j]의 합
# 1*2 + 1*3 + 1*4 + 2*3 + 2*4 + 3*4
arr = [1,2,3,4]
```

```
S = sum(arr)
sum_sq = sum(x*x for x in arr)
```

```
result = (S*S - sum_sq) // 2
print(result) # 35
```

6.7 Modular Divide

```
# (a/b)%M => (a%M * pow(b,M-2,M)) % M
```

```
M = 1000000007
a=7
b=3
print((a%M * pow(b,M-2,M)) % M)
```

7 String

7.1 KMP

```
vector<int> get_pi(string p) {
    vector<int> pi(p.length(), 0);

    for (int i = 1, j = 0; i < p.length(); i++) {
        while (j && p[i] != p[j]) j = pi[j-1];
        if (p[i] == p[j]) pi[i] = ++j;
    }
    return pi;
}

int kmp(string s, string p) {
    auto pi = get_pi(p);
    int lj = 0;

    for (int i = 0, j = 0; i < s.length(); i++) {
        lj = j;
        while (j && s[i] != p[j]) j = pi[j-1];
        if (s[i] == p[j]) {
            if (j == p.length() - 1) {
                // result.push_back(i-p.length()+1); if want result string
                j = pi[j];
            } else j++;
        }
    }
    return lj;
}
```

7.2 Z

```
// 접미사와 문자열전체접두사와 가장 긴 공통접두사
template <class T> vector<int> z_algorithm(const vector<T>& s) {
    int n = int(s.size());
    if (n == 0) return {};
    vector<int> z(n);
    z[0] = 0;
    for (int i = 1, j = 0; i < n; i++) {
        int& k = z[i];
        k = (j + z[j] <= i) ? 0 : std::min(j + z[j] - i, z[i - j]);
        while (i + k < n && s[k] == s[i + k]) k++;
        if (j + z[j] < i + z[i]) j = i;
    }
    z[0] = n;
    return z;
}

vector<int> z_algorithm(const string& s) {
    int n = int(s.size());
    vector<int> s2(n);
    for (int i = 0; i < n; i++) s2[i] = s[i];
    return z_algorithm(s2);
}
```

7.3 Trie and Ahocorasick

```
// include Trie
struct Trie {
    map<char, Trie*> ch;
    Trie* fail;
    bool end;
    Trie() { end = false; }
    ~Trie() {
        for (auto trie: ch) delete trie.second;
        ch.clear();
    }
    void insert(string s, int i = 0) {
        if (i == s.length()) {
            this->end = true;
            return;
        }
        if (!ch[s[i]]) ch[s[i]] = new Trie();
        ch[s[i]]->insert(s, i+1);
    }
};

Trie trie;
void set_fail() {
    queue<Trie*> q;
    trie.fail = &trie;
    q.push(&trie);
    while (q.size()) {
        Trie* cur = q.front();
        q.pop();
        for (auto [c, nxt]: cur->ch) {
            if (cur == &trie) nxt->fail = &trie;
            else {
                auto dest = cur->fail;
                while (dest != &trie && dest->ch.find(c) == dest->ch.cend()) dest = dest->fail;
                if (dest->ch.find(c) != dest->ch.cend()) dest = dest->ch[c];
                nxt->fail = dest;
            }
            if (nxt->fail->end) nxt->end = true;
            q.push(nxt);
        }
    }
}

int main() {
    // put all string to trie
    set_fail();
    cin >> n;
    while (n--) {
        cin >> s;
        bool result = false;
        Trie* cur = &trie;
        for (auto c: s) {
            while (cur != &trie && cur->ch.find(c) == cur->ch.cend()) cur = cur->fail;
            if (cur->ch.find(c) != cur->ch.cend()) cur = cur->ch[c];
            if (cur->end) result = true;
        }
    }
}
```

```
    cout << (result ? "YES" : "NO") << (n ? "\n" : "");
}
}
```

7.4 Suffix Automaton

```
struct Suffix_Automaton {
    struct Node {
        int len, link, last, cnt = 1;
        int minpos = 0, maxpos = 0;
        // bool isleaf = true;
        map<int, int> nxt;
        // int nxt[26];
        Node(int len = 0, int link = 0, int last = 0): len(len), link(link), last(last) {}
    };
    vector<Node> v;
    vector<pii> sv; // len / original i
    int total;
    // ll substr_cnt = 0;
    Suffix_Automaton() { total = 0; v.push_back(Node(0, -1)); }
    void add(int c, int last = 0) {
        // int c = _c - 'A';
        v.push_back(Node(v[total].len+1, 0, last));
        int p = total;
        v[p].minpos = v[p].maxpos = v[p].len-1;
        total = v.size()-1;
        // cout << "[debug]" << (char)c << ": " << v[p].len << ", " << v[p].link << ", " <<
        v[p].minpos << ", " << v[p].maxpos << "\n";
        while (p != -1 && v[p].nxt.find(c) == v[p].nxt.cend()) {
            v[p].nxt.insert({c, total});
            // v[p].nxt[c] = total;
            // if (v[p].link != -1) substr_cnt += v[p].len-v[v[p].link].len;
            // else substr_cnt++;
            p = v[p].link;
        }
        if (p != -1) {
            int q = v[p].nxt[c];
            int upd = q;
            if (v[p].len+1 < v[q].len) {
                upd = v.size();
                Node clone = v[q];
                clone.len = v[p].len + 1;
                clone.cnt = 0;
                v.push_back(clone);
                v[q].link = upd;
                for (int j = p; j != -1 && v[j].nxt[c] == q; j = v[j].link) v[j].nxt[c] = upd;
            }
            v[total].link = upd;
        }
    }
    // len, i
    pii lcs(string s) {
        int cur = 0;
        Node x = v[0];
        int l = 0, rl = 0, ri = 0;
    }
}
```

```

for (int i = 0; i < s.length(); i++) {
    x = v[cur];
    // cout << i << ": " << x.len << ", " << x.link << "\n";
    // cout << i << "(" << s[i] << "): " << x.len << " " << x.link << " => ";
    int idx = s[i] - 'a';
    // for (auto e: x.nxt) cout << e << " "; cout << " => ";
    while (x.len && x.nxt[idx] == -1) {
        // l -= (x.len - v[x.link].len);
        l = v[x.link].len;
        cur = x.link;
        x = v[x.link];
    }
    if (x.nxt[idx] != -1) cur = v[cur].nxt[idx], l++;
    if (l > rl) rl = l, ri = i;
    // cout << x.len << " " << x.link << "\n";
}
return { rl, ri };
}

void clear() {
    total = 0;
    v.clear();
    v.push_back(Node(0, -1, 0));
}

// vector<int> search(string t) {
//     vector<int> pos;
//     int cur = 0, l = 0;
//     for (int i = 0; i < t.length(); i++) {
//         while (v[cur].len && v[cur].nxt.find(t[i]) == v[cur].nxt.cend()) {
//             cur = v[cur].link;
//             l = v[cur].len;
//         }
//         if (v[cur].nxt.find(t[i]) != v[cur].nxt.cend()) cur = v[cur].nxt[t[i]], l++;
//         if (t.length() == l) pos.push_back(i-l+2);
//     }
//     return pos;
// }

// bool search(string t) {
//     int cur = 0, l = 0;
//     for (int i = 0; i < t.length(); i++) {
//         while (v[cur].len && v[cur].nxt.find(t[i]) == v[cur].nxt.cend()) {
//             cur = v[cur].link;
//             l = v[cur].len;
//         }
//         if (v[cur].nxt.find(t[i]) != v[cur].nxt.cend()) cur = v[cur].nxt[t[i]], l++;
//         if (t.length() == l) pos.push_back(i-l+2);
//     }
//     return pos;
// }

void sort() {
    sv = vector<pii>(v.size());
    for (int i = 0; i < v.size(); i++) sv[i] = { v[i].len, i };
    auto comp = [](pii a, pii b) -> bool {
        return a.first > b.first;
    };

```

```

        std::sort(sv.begin(), sv.end(), comp);
    }
};
Suffix_Automaton sa;

```

8 etc

8.1 Deque Trick

```
int n, l;
deque<pii> dq;
cin >> n >> l;
for (int i = 0; i < n; i++) {
    int x;
    cin >> x;
    while (dq.size() && dq.back().first >= x) dq.pop_back();
    dq.push_back({x, i});
    while (dq.size() && dq.front().second <= i-l) dq.pop_front();
    cout << dq.front().first << " ";
}
```

8.2 imos rectangle and diamond

```
const int FIX = 5, DIV = 1e9;
int ty, px, py, qx, qy, r;
for (int i = 0; i < k; i++) {
    cin >> ty;
    if (ty == 1) {
        cin >> px >> py >> qx >> qy;
        px += FIX;
        py += FIX;
        qx += FIX;
        qy += FIX;
        rect[py][px] += 1;
        rect[qy+1][px] -= 1;
        rect[py][qx+1] -= 1;
        rect[qy+1][qx+1] += 1;
    } else {
        cin >> px >> py >> r;
        px += FIX;
        py += FIX;
        dia[py-r][px] += 1;
        dia[py-r+1][px] += 1;
        dia[py+1][px-r-1] -= 1;
        dia[py+1][px-r] -= 1;
        dia[py+1][px+r+1] -= 1;
        dia[py+1][px+r] -= 1;
        dia[py+r+1][px] += 1;
        dia[py+r+2][px] -= 1;
    }
}
for (int i = 0; i < h+FIX; i++) for (int j = 1; j < w+FIX; j++) rect[i][j] += rect[i][j-1];
for (int i = 0; i < w+FIX; i++) for (int j = 1; j < h+FIX; j++) rect[j][i] += rect[j-1][i];
for (int i = 1; i < h+FIX; i++) for (int j = 1; j < w+FIX; j++) dia[i][j] += dia[i-1][j-1];
for (int i = 1; i < h+FIX; i++) for (int j = 0; j < w-1+FIX; j++) dia[i][j] +=
dia[i-1][j+1];
for (int i = 0+FIX; i < h+FIX; i++) {
    for (int j = 0+FIX; j < w+FIX; j++) {
        if ((rect[i][j] + dia[i][j]) % 2) cout << "#";
        else cout << ".";
    }
}
```

```
}
cout << "\n";
}
```

8.3 imos triangle

int x, y, s; // (x, y), (x+s, y), (x+s, y+s)를 정점으로 하는 삼각형

```
for (int i = 0; i < m; i++) {
    cin >> x >> y >> s;
    pos[x][y]++;
    pos[x][y+1]--;
    pos[x+s+1][y]--;
    pos[x+s+2][y+1]++;
    pos[x+s+1][y+s+2]++;
    pos[x+s+2][y+s+2]--;
}
for (int i = 1; i <= n; i++) for (int j = 1; j <= n; j++) pos[i][j] += pos[i][j-1];
for (int i = 1; i <= n; i++) for (int j = 1; j <= n; j++) pos[i][j] += pos[i-1][j];
for (int i = 1; i <= n; i++) for (int j = 1; j <= n; j++) pos[i][j] += pos[i-1][j-1];
int cnt = 0;
for (int i = 1; i <= n; i++) for (int j = 1; j <= i; j++) if (pos[i][j] > 0) cnt++;
```

8.4 mo's algorithm

```
// O(nsqrt(n))
struct Query {
    ll l, r;
    int i;
};
ll n, m, cnt[100001], cntn[100001], ans[100001], sqrtn, a[100001];
Query query[100000];
int main() {
    cin >> n;
    for (int i = 1; i <= n; i++)
        cin >> a[i];
    cin >> m;
    for (int i = 0; i < m; i++) {
        cin >> query[i].l >> query[i].r;
        query[i].i = i;
    }
    sqrtn = sqrt(n);
    sort(query, query+m, [](Query q1, Query q2){
        if (q1.l/sqrtn == q2.l/sqrtn) return q1.r < q2.r;
        else return q1.l/sqrtn < q2.l/sqrtn;
    });

    cntn[0] = n;

    ll mcnt = 0, s = query[0].l, e = query[0].r;
    for (int i = s; i <= e; i++) {
        cntn[cnt[a[i]]]--;
        cnt[a[i]]++;
        cntn[cnt[a[i]]]++;
        mcnt = max(mcnt, cnt[a[i]]);
    }
```

```

ans[query[0].i] = mcnt;

int temp;
for (int i = 1; i < m; i++) {
    while (s < query[i].l) {
        cntn[cnt[a[s]]]--;
        cnt[a[s]]--;
        cntn[cnt[a[s]]]++;
        s++;
        while (cntn[mcnt] == 0) mcnt--;
    }
    while (query[i].l < s) {
        s--;
        cntn[cnt[a[s]]]--;
        if (cnt[a[s]] == mcnt) mcnt++;
        cnt[a[s]]++;
        cntn[cnt[a[s]]]++;
    }
    while (e < query[i].r) {
        e++;
        cntn[cnt[a[e]]]--;
        if (cnt[a[e]] == mcnt) mcnt++;
        cnt[a[e]]++;
        cntn[cnt[a[e]]]++;
    }
    while (query[i].r < e) {
        cntn[cnt[a[e]]]--;
        cnt[a[e]]--;
        cntn[cnt[a[e]]]++;
        e--;
        while (cntn[mcnt] == 0) mcnt--;
    }
    ans[query[i].i] = mcnt;
}
}

```

8.5 random generator

```

// init
random_device rd;
mt19937 gen(rd());
uniform_int_distribution<int> dis(0, n);
// use
int x = dis(gen);

```

9 Note and Checklist

9.1 etc formular

```

// Area = I + B/2 - 1, B: 경계격자점, I: 내부격자점
// C^2 = A^2 + B^2 - 2ABcos
// 카탈란수: Cn = { 1/(n+1) } * (2n C n)

```

9.2 pisano

```

// 주기의 길이를 P라고 하면 N번째 피보나치 수를 M으로 나눈 나머지는 N%P번째 피보나치 수를 M으로 나눈
// 나머지와 같다.
// 주기는 M = 10^k (k>2)일때, 항상 15 * 10^(k-1)이다.

```

9.3 Ternary Search

```

/*
while (l+2 < r)로 해두고
i = l ~ r까지 순회해서 찾기
*/

```

9.4 문제 풀이 체크리스트

- 비슷한 문제를 풀어본 적이 있던가?
- 단순한 방법에서 시작할 수 있을까? (Brute Force)
- 내가 문제를 푸는 과정을 수식화할 수 있을까? (예제를 직접 해결해보면서)
- 문제를 단순화할 수 없을까?
- 그림으로 그려볼 수 있을까?
- 수식으로 표현할 수 있을까?
- 문제를 분해할 수 있을까?
- 뒤에서부터 생각해서 풀 수 있을까?
- 순서를 강제할 수 있을까?
- 특정 형태의 답만을 고려할 수 있을까? (정규화)
- 구간을 통째로 가져간다 : 플로우 + 적당한 자료구조 $(i, i + 1, k, 0), (s, e, 1, w), (N, T, k, 0)$
- $a = b$: a만 움직이기, b만 움직이기, 두 개 동시에 움직이기, 반대로 움직이기
- 말도 안 되는 것들을 한 번은 생각해보기 / "당연하다고 생각한 것" 다시 생각해보기
- 확률 : DP, 이분 탐색(NYPC 2019 Finals C)
- 최대/최소 : 이분 탐색, 그리디(Prefix 고정, Exchange Argument), DP(순서 고정)