

Problem set 2.3 : #4, 5, 7, 8, 12 (least squares)

* should be use MATLAB for 4 & 5?

4. Gram-Schmidt orthogonalization

* from columns a_1 & a_2 of $\begin{bmatrix} 2 & 2 & 1 \\ -1 & 2 & 2 \end{bmatrix}'$, follow steps of Gram-Schmidt to create orthonormal columns q_1 & q_2 . What is R ?

$$\Rightarrow A = \begin{bmatrix} 2 & -1 \\ 2 & 2 \\ 1 & 2 \end{bmatrix} \Rightarrow \text{find } Q \text{ \& } R; A = QR.$$

(a_1) (a_2)

$$\Rightarrow Q = [v_1 \ v_2] \Rightarrow v_1 \perp v_2 \text{ form orthogonal basis for } A.$$

$$v_1 = a_1 = \begin{bmatrix} 2 \\ 2 \\ 1 \end{bmatrix}$$

$$v_2 = a_2 - \frac{a_2 \cdot v_1}{v_1 \cdot v_1} v_1 = \begin{bmatrix} -1 \\ 2 \\ 2 \end{bmatrix} - \frac{-2+4+2}{4+4+1} \begin{bmatrix} 2 \\ 2 \\ 1 \end{bmatrix} = \begin{bmatrix} -1 \\ 2 \\ 2 \end{bmatrix} - \frac{4}{9} \begin{bmatrix} 2 \\ 2 \\ 1 \end{bmatrix} = \begin{bmatrix} -17/9 \\ 10/9 \\ 14/9 \end{bmatrix} = v_2$$

$$\Rightarrow \begin{matrix} \text{columns} \\ \text{of } Q: \end{matrix} \begin{aligned} q_1 &= \frac{v_1}{\|v_1\|} = \frac{v_1}{\sqrt{4+4+1}} = \frac{1}{3} v_1 = \frac{1}{3} \begin{bmatrix} 2 \\ 2 \\ 1 \end{bmatrix} \\ q_2 &= \frac{v_2}{\|v_2\|} = \frac{v_2}{\sqrt{(-17/9)^2 + (10/9)^2 + (14/9)^2}} = \frac{1}{2.687} v_2 = \frac{1}{2.687} \begin{bmatrix} -17/9 \\ 10/9 \\ 14/9 \end{bmatrix} \end{aligned}$$

$$Q = \begin{bmatrix} q_1 & q_2 \end{bmatrix} = \begin{bmatrix} 2/3 & -.703 \\ 2/3 & .413 \\ 1/3 & .579 \end{bmatrix}$$

$$\Rightarrow A = QR \Rightarrow Q^T A = Q^T Q R; Q^T Q = I \text{ because } Q \text{ is orthonormal,}$$

$$Q^T A = R$$

$$\begin{bmatrix} 2/3 & 2/3 & 1/3 \\ -.703 & .413 & .579 \end{bmatrix} \begin{bmatrix} 2 & -1 \\ 2 & 2 \\ 1 & 2 \end{bmatrix} = \begin{bmatrix} 7/3 & 4/3 \\ 0 & 2.687 \end{bmatrix} = R$$

7. $b = (4, 1, 0, 1)$, $x = (0, 1, 2, 3)$, set up and solve the normal equation for the coefficients $\hat{u} = (C, D)$ in the nearest line $C + Dx$. (2)

line through } try to solve $Au = b$; $\begin{bmatrix} 1 & x \end{bmatrix} u = b \rightarrow \begin{matrix} C + 0D = 4 \\ C + 1D = 1 \\ C + 2D = 0 \\ C + 3D = 1 \end{matrix} \Rightarrow \begin{bmatrix} 1 & 0 \\ 1 & 1 \\ 1 & 2 \\ 1 & 3 \end{bmatrix} \begin{bmatrix} C \\ D \end{bmatrix} = \begin{bmatrix} 4 \\ 1 \\ 0 \\ 1 \end{bmatrix}$

4pts

\rightarrow minimize error; $\|b - Au\|^2 = (b - Au)^T (b - Au)$

\Rightarrow solve $A^T A \hat{u} = A^T b$ (normal eqn)

$\begin{bmatrix} 1 & 1 & 1 & 1 \\ 0 & 1 & 2 & 3 \end{bmatrix} \begin{bmatrix} C \\ D \end{bmatrix} = \begin{bmatrix} 4 \\ 1 \\ 0 \\ 1 \end{bmatrix} \Rightarrow \begin{bmatrix} 4 & 6 \\ 6 & 14 \end{bmatrix} \hat{u} = \begin{bmatrix} 4 \\ 4 \end{bmatrix} \Rightarrow \begin{bmatrix} 4C + 6D = 4 \\ 6C + 14D = 4 \end{bmatrix} \Rightarrow \begin{bmatrix} 2C + 3D = 2 \\ 3C + 7D = 2 \end{bmatrix}$

$\hat{u} = (3, -1)$, nearest line is $3 - x$

$\begin{bmatrix} 4 & 6 \\ 6 & 14 \end{bmatrix} \hat{u} = \begin{bmatrix} 4 \\ 4 \end{bmatrix} \Rightarrow \begin{matrix} 4C + 6D = 4 \\ 6C + 14D = 4 \end{matrix} \Rightarrow \begin{matrix} 2C + 3D = 2 \\ 3C + 7D = 2 \end{matrix}$

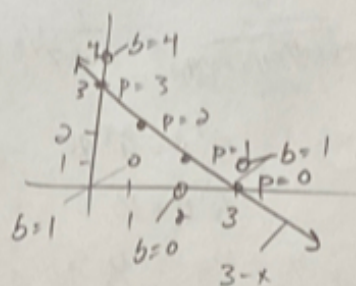
$6 - 5D = 5 \Rightarrow D = -1$

$4C + 6(-1) = 4 \Rightarrow 4C = 10 \Rightarrow C = 2.5$

8. Find projection $p = A\hat{u}$ from 7. Check these 4 values lie on $C + Dx$, compute error $e = b - p$, verify $A^T e = 0$.

$p = A\hat{u} = \begin{bmatrix} 1 & 0 \\ 1 & 1 \\ 1 & 2 \\ 1 & 3 \end{bmatrix} \begin{bmatrix} 3 \\ -1 \end{bmatrix} \Rightarrow p = \begin{bmatrix} 3 \\ 2 \\ 1 \\ 0 \end{bmatrix}$, check:

$e = b - p = \begin{bmatrix} 4 \\ 1 \\ 0 \\ 1 \end{bmatrix} - \begin{bmatrix} 3 \\ 2 \\ 1 \\ 0 \end{bmatrix} = \begin{bmatrix} 1 \\ -1 \\ -1 \\ 1 \end{bmatrix} = e$



$A^T e = \begin{bmatrix} 1 & 1 & 1 & 1 \\ 0 & 1 & 2 & 3 \end{bmatrix} \begin{bmatrix} 1 \\ -1 \\ -1 \\ 1 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \checkmark, A^T e = 0.$ Not asked for, but total error = $e^T e = 1^2 + (-1)^2 + (-1)^2 + 1^2 = 4.$

12. closest parabola $C + Dx + Ex^2$ to some 4 points, write down unsolvable eqn for $u = (C, D, E)$, $Au = b$, set up normal eqn for \hat{u} . What is \vec{e} when fitting $C + Dx + Ex^2 + Fx^3$ to these 4 pts?

$C + Dx_1 + Ex_1^2 = b_1$
 $C + Dx_2 + Ex_2^2 = b_2$
 $C + Dx_3 + Ex_3^2 = b_3$
 $C + Dx_4 + Ex_4^2 = b_4$

$A^T A \hat{u} = A^T b \Rightarrow \begin{bmatrix} 1 & x_1 & x_1^2 \\ 1 & x_2 & x_2^2 \\ 1 & x_3 & x_3^2 \\ 1 & x_4 & x_4^2 \end{bmatrix} \begin{bmatrix} C \\ D \\ E \end{bmatrix} = \begin{bmatrix} b_1 \\ b_2 \\ b_3 \\ b_4 \end{bmatrix}$

$e_2 = b - p_2 = b - (A_2 \hat{u}) \Rightarrow * A_2 \hat{u}_2 + F \vec{x}_3 = A_3 \hat{u}_3$
 $e_3 = b - p_3 = b - (A_3 \hat{u}) \Rightarrow * e_3 = b - (A_2 \hat{u}_2 + F \vec{x}_2) \Rightarrow e_3 + F \vec{x}_3 = b - A_2 \hat{u}_2 = e_2!$

The error term \vec{e}_3 when fitting $C + Dx + Ex^2 + Fx^3$ to these 4 points will be equal to the error term of the quadratic fit, \vec{e}_2 , minus the "cubic" term Fx^3 for each point; $\vec{e}_3 = \vec{e}_2 - F \vec{x}_3$, where $\vec{x}_3 = \begin{bmatrix} x_1^3 \\ x_2^3 \\ x_3^3 \\ x_4^3 \end{bmatrix}$.

2. Show that Newton's method for $u^2 - a = 0$ finds u^{k+1} as the average of u^k and a/u^k . (connect the new error $u^{k+1} - \sqrt{a}$ to the square of the old error $u^k - \sqrt{a}$): $u^{k+1} - \sqrt{a} = \frac{1}{2}(u^k + \frac{a}{u^k}) - \sqrt{a} = (u^k - \sqrt{a})^2 / 2u^k$

Newton's method for $u^2 - a = 0$:

$$u^2 = a, \quad J(u^k) = 2u^k = g'$$

$$\rightarrow J u = -g; \quad J(u^k)(u^{k+1} - u^k) = -g(u^k)$$

$$\Rightarrow u^{k+1} = \frac{-g(u^k)}{J(u^k)} + u^k$$

$$\Rightarrow u^{k+1} = \frac{-((u^k)^2 - a)}{2u^k} + u^k$$

$$\Rightarrow u^{k+1} = \frac{-u^k + a/u^k}{2} + u^k = \boxed{\frac{u^k + a/u^k}{2}} \Rightarrow \text{this is the average of } u^k \text{ and } a/u^k.$$

* Newton squares the error at each step.

+ what are we supposed to "do"?

$u^k - \sqrt{a}$ is old error; new error = $(u^k - \sqrt{a})^2$.

$$(u^k - \sqrt{a})^2 = (u^k)^2 - 2u^k\sqrt{a} + a = u^k(u^k + \frac{a}{u^k} - 2\sqrt{a}) = 2u^k \left(\frac{u^k + \frac{a}{u^k}}{2} - \sqrt{a} \right)$$

$= 2u^k(u^{k+1} - \sqrt{a}) \rightarrow$ the new error times $2u^k$, the jacobian, is equal to the square of the old error in our case.

5. "a)" Show Newton's method converges in one step, $u' = A^{-1}b$, with $g(u) = Au - b$. (4)
 "b)" given the fixed point iteration $u^{k+1} = H(u^k) = u^k - (Au^k - b)$, has $H' = I - A$.
 Its convergence factor c is the maximum eigenvalue $|1 - \lambda(A)|$.

\Rightarrow why is $c > 1$ for $A = K = (-1, 2, -1)$ matrix, but $c < 1$ for $A = K/2$?

Newton's method: $J(u^k)(u^{k+1} - u^k) = -g(u^k) = b - Au^k$

$$J(u^k) = g' = A \quad (\text{vector differentiation})$$

$$g(u) = Au - b = 0$$

$$u = A^{-1}b \Rightarrow \text{exact solution}$$

\Rightarrow rearrange Newton's method,

$$u^{k+1} = -J(u^k)^{-1}g(u^k) + u^k; \text{ sub in } J(u^k), u^k, \text{ and } u \text{ see:}$$

$$u^{k+1} = -(A)^{-1}(Au^k - b) + u^k$$

$$u^{k+1} = -u^k + A^{-1}b + u^k$$

$$\Rightarrow \boxed{u^{k+1} = A^{-1}b}; \quad u^{k+1} - A^{-1}b = A^{-1}b - A^{-1}b = 0 \quad \checkmark \text{ error} = 0, \text{ it converges after one iteration.}$$

$\Rightarrow u^{k+1}$ doesn't rely on u^k ; it is always the same/doesn't change
 $\rightarrow \boxed{u' = A^{-1}b}, \quad u^* = A^{-1}b \dots$

"better" way to get answer they want: $u' = -(A^{-1})(Au^0 - b) + u^0$
 $u' = -u^0 + A^{-1}b + u^0 \Rightarrow \boxed{u' = A^{-1}b}$, same result.

"b)" The eigenvalues for $H(u^k)$ are equal to: $\lambda_k = 2 - 2\cos\left(\frac{k\pi}{n+1}\right)$, so $|\lambda| > 2$ because $|\cos\theta| < 1$.

The eigenvalues for $\frac{k}{2}$ are equal to $\frac{1}{2}$ those of K ; $\lambda\vec{v} = A\vec{v}$
 so $\frac{1}{2}\lambda\vec{v} = \frac{1}{2}A\vec{v}$. Hence, the eigenvalues of $\frac{1}{2}K$ are $\lambda_{k/2} = 1 - \cos\left(\frac{k\pi}{n+1}\right)$.

Given that the convergence factor c equals $|1 - \lambda_{\max}|$, it can be

shown that $c > 1$ because $0 \leq \lambda_{k/2} \leq 2$, so $|1 - \lambda_{k/2}| < 1$

for all λ , including λ_{\max} .

5. (Pset 2.3)

*Not explained well in book

5

$$a_1 = \begin{bmatrix} 3 \\ 2 \\ 1 \end{bmatrix} \Rightarrow \text{find } r_1, w_1, u_1, H_1$$

$$r_1 = \begin{bmatrix} 11 & 0 & 1 \\ 0 & 0 & 0 \end{bmatrix} = \begin{bmatrix} 3 \\ 2 \\ 1 \end{bmatrix} = r_1, \quad w_1 = a_1 - r_1 = \begin{bmatrix} 3 \\ 2 \\ 1 \end{bmatrix} - \begin{bmatrix} 3 \\ 2 \\ 1 \end{bmatrix} = \begin{bmatrix} -1 \\ 2 \\ 1 \end{bmatrix} = w_1$$

$$\|a_1\| = \sqrt{4+4+1} = 3$$

$$u_1 = \frac{w_1}{\|w_1\|} = \frac{\begin{bmatrix} -1 \\ 2 \\ 1 \end{bmatrix}}{\sqrt{1+4+1}} = \frac{1}{\sqrt{6}} \begin{bmatrix} -1 \\ 2 \\ 1 \end{bmatrix} = u_1$$

$$H = I - 2uu^T = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} - 2 \left(\frac{1}{\sqrt{6}} \begin{bmatrix} -1 \\ 2 \\ 1 \end{bmatrix} \begin{bmatrix} -1 & 2 & 1 \end{bmatrix} \right)$$

$$H = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} - \frac{1}{3} \begin{bmatrix} 1 & -2 & -1 \\ -2 & 4 & 2 \\ -1 & 2 & 1 \end{bmatrix} = \frac{1}{3} \begin{bmatrix} 2 & 2 & 1 \\ 2 & -1 & -2 \\ 1 & -2 & 2 \end{bmatrix} = H_1$$

$\hookrightarrow \frac{1}{3} \begin{bmatrix} 3 & 0 & 0 \\ 0 & 3 & 0 \\ 0 & 0 & 3 \end{bmatrix}$

\Rightarrow use $H_1 A$, below diagonal.

$$H_1 A = \frac{1}{3} \begin{bmatrix} 2 & 2 & 1 \\ 2 & -1 & -2 \\ 1 & -2 & 2 \end{bmatrix} \begin{bmatrix} 2 & -1 \\ 2 & 2 \\ 1 & 2 \end{bmatrix} = \frac{1}{3} \begin{bmatrix} 9 & 4 \\ 0 & -8 \\ 0 & -1 \end{bmatrix} = \begin{bmatrix} 3 & 4/3 \\ 0 & -8/3 \\ 0 & -1/3 \end{bmatrix} \Rightarrow a_2 = \begin{bmatrix} -8/3 \\ -1/3 \end{bmatrix}$$

$$\Rightarrow r_2 = \begin{bmatrix} 11 & 0 & 1 \\ 0 & 0 & 0 \end{bmatrix} = \begin{bmatrix} \frac{\sqrt{65}}{3} \\ 0 \end{bmatrix} = r_2, \quad w_2 = a_2 - r_2 = \begin{bmatrix} -8/3 \\ -1/3 \end{bmatrix} - \begin{bmatrix} \sqrt{65}/3 \\ 0 \end{bmatrix} = \begin{bmatrix} \frac{-8-\sqrt{65}}{3} \\ -1/3 \end{bmatrix} = w_2$$

$$u_2 = \frac{w_2}{\|w_2\|} = \frac{w_2}{5.36} \Rightarrow u_2 = \begin{bmatrix} -.998 \\ -.062 \end{bmatrix}$$

$$H_2 = I - 2u_2 u_2^T = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} - 2 \begin{bmatrix} -.998 \\ -.062 \end{bmatrix} \begin{bmatrix} -.998 & -.062 \end{bmatrix} = \begin{bmatrix} .1006 & .0 & .0 \\ 0 & .992 & .124 \\ 0 & .124 & .992 \end{bmatrix}$$

only operate on this "square"

$$H_2 H_1 A = \begin{pmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 0 & .992 & .124 \\ 0 & .124 & .992 \end{bmatrix} \frac{1}{3} \begin{bmatrix} 2 & 2 & 1 \\ 2 & -1 & -2 \\ 1 & -2 & 2 \end{bmatrix} \end{pmatrix} \begin{bmatrix} 2 & -1 \\ 2 & 2 \\ 1 & 2 \end{bmatrix} \approx \begin{bmatrix} 3 & 4/3 \\ 0 & 2.687 \\ 0 & 0 \end{bmatrix} = R$$

* seems wrong as R is not square, but followed the steps where $H_1 = I - u_1 u_1^T$ & $H_2 = \begin{bmatrix} 1 & \dots & 0 \\ 0 & I - u_2 u_2^T \end{bmatrix}$.
But, R is upper triangular.

* there is a jacobian function in MATLAB, will compare answers.

$$\left. \begin{aligned} g_1 &= u_1 + u_2^4 u_3 = 0 \\ g_2 &= -u_1 u_2 + 2u_2 + u_3^2 u_4 = 0 \\ g_3 &= -2u_1^2 + 4u_3 - u_4 = 0 \\ g_4 &= 2u_3^2 + 4u_4 = 0 \end{aligned} \right\} J = \begin{bmatrix} \frac{\partial g_1}{\partial u_1} & \frac{\partial g_1}{\partial u_2} & \frac{\partial g_1}{\partial u_3} & \frac{\partial g_1}{\partial u_4} \\ \frac{\partial g_2}{\partial u_1} & \frac{\partial g_2}{\partial u_2} & \frac{\partial g_2}{\partial u_3} & \frac{\partial g_2}{\partial u_4} \\ \frac{\partial g_3}{\partial u_1} & \frac{\partial g_3}{\partial u_2} & \frac{\partial g_3}{\partial u_3} & \frac{\partial g_3}{\partial u_4} \\ \frac{\partial g_4}{\partial u_1} & \frac{\partial g_4}{\partial u_2} & \frac{\partial g_4}{\partial u_3} & \frac{\partial g_4}{\partial u_4} \end{bmatrix}$$

$$\Rightarrow J = \begin{bmatrix} 1 & 4u_2^3 u_3 & u_2^4 & 0 \\ -u_2 & -u_1 + 2 & 2u_3^2 u_4 & u_3^2 \\ -4u_1 & 0 & 4 & -1 \\ 0 & 0 & 4u_3 & 4 \end{bmatrix}$$

(I think) ✓

(matches w/ matlab code)

* might want to have this as a function...
(loop do)

* need to check error @ each step to see ~~if it~~ if it is below given tolerance.

* Note: a different number of iterations is reported for the second guess, when using $\text{inv}(A)^*b$ vs. $A \setminus b$. This is because the Jacobian $J(u)$ becomes ill-conditioned through the iterations,