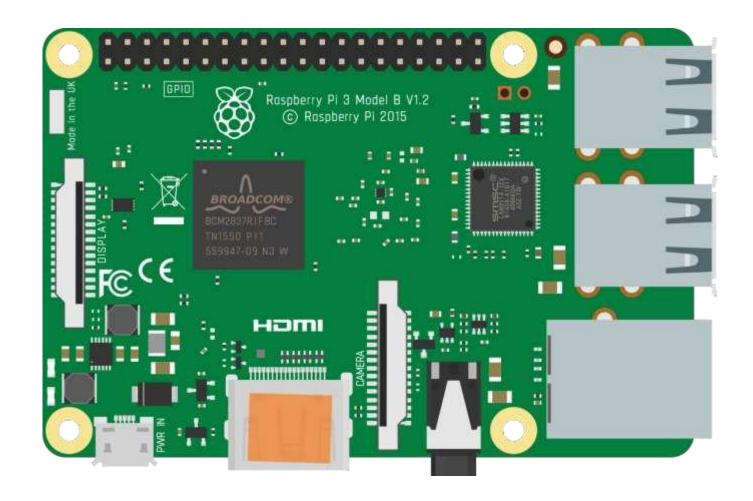
# CAST Robot Wiring Guide

# CAST Bot Contains one CPU

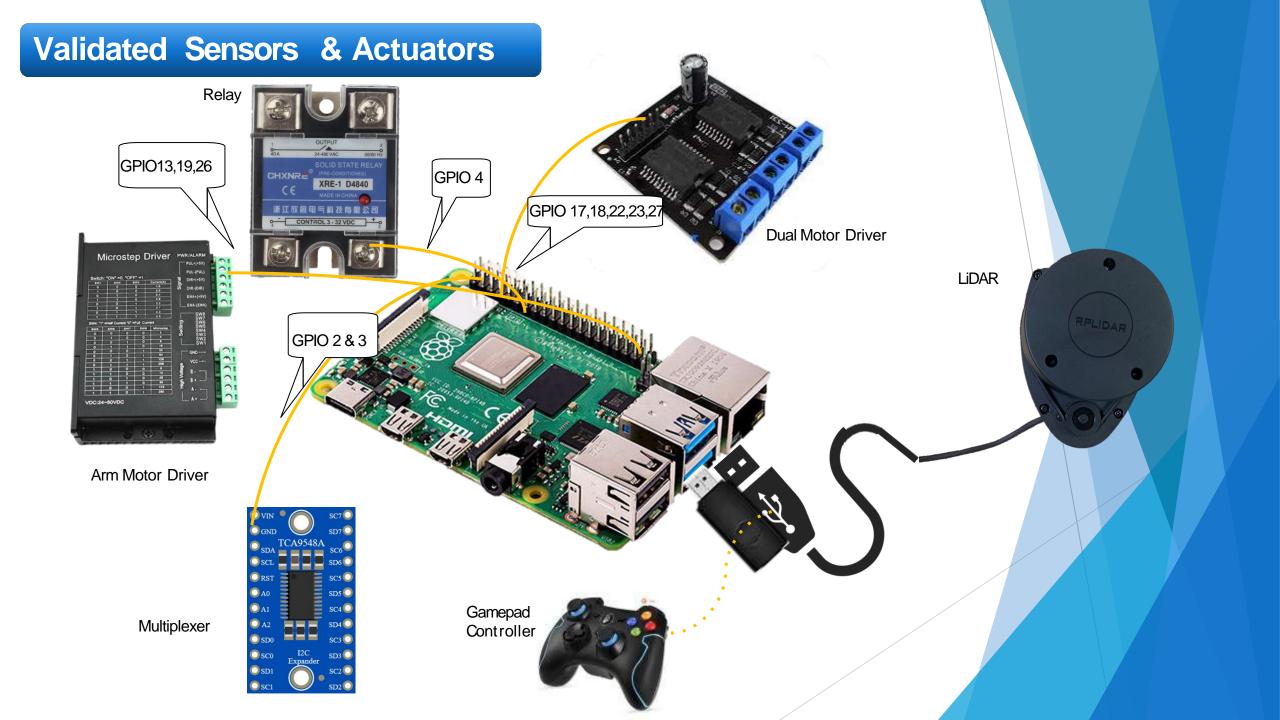




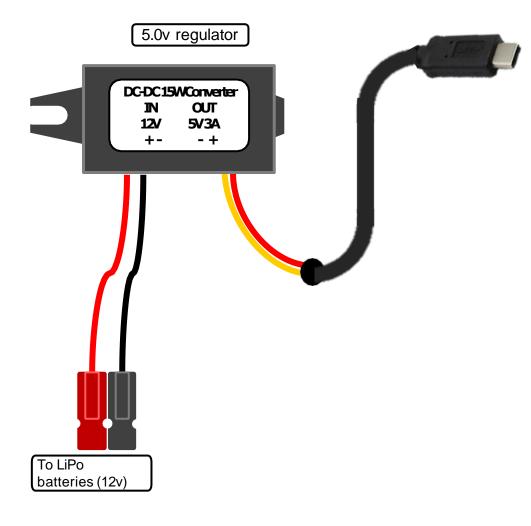
# CAST Wiring For Raspberry Pi 4

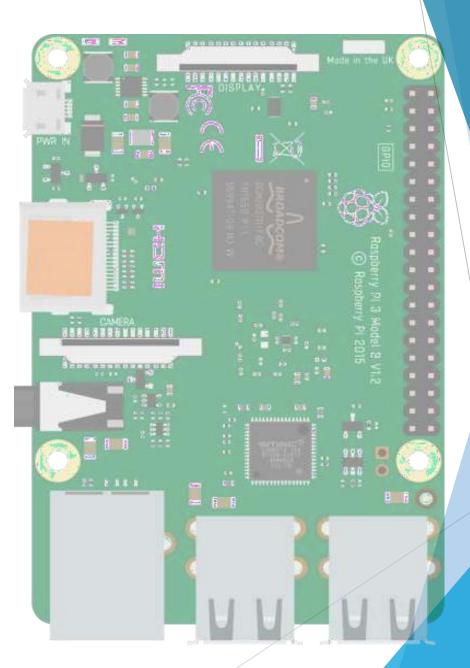






# Pi - Power Supply







### Pi - Motor Driver Signals

Keepthe wires bonded to each other, if possible.

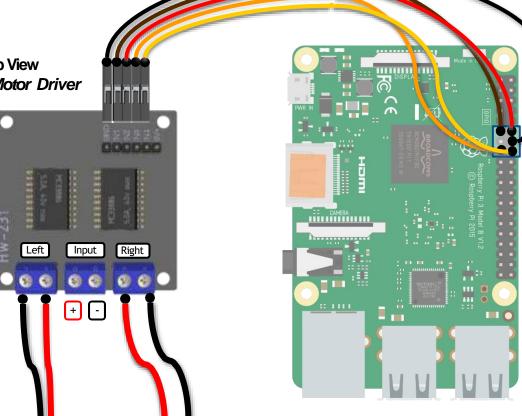




Left

Mot or

Ground is optional if the Pi and Motor Driver have a commonground to the battery pack.



Right

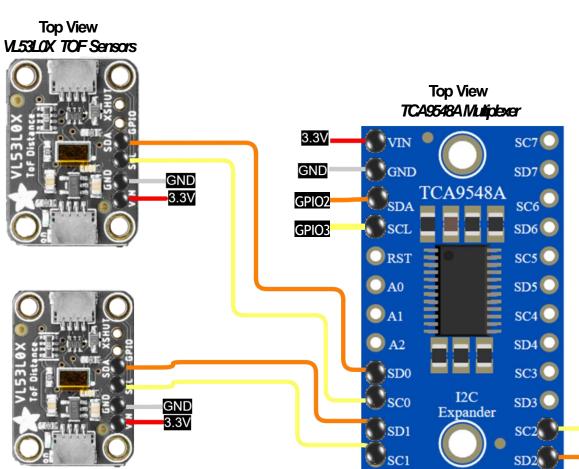
**Not** or

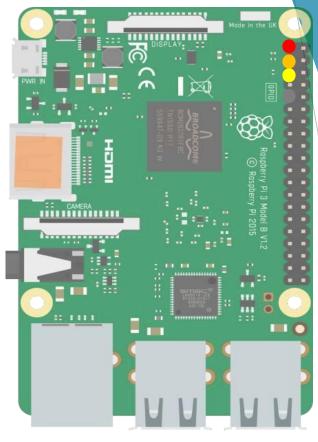
#### Pins on RasPi

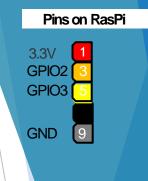


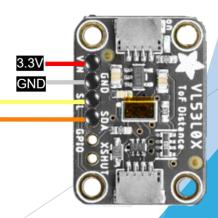
#### PI - Stepper Driver - ST-M5045 Pins on RasPi **GPIO13** 35 37 39 **GPIO19 Top View** GPIO26 **Short by** STN5045 Motor Driver GND solder Keepthe wires bonded Microstep Driver to each other, if possible. LAMERA PUL-(PUL) Switch: "ON" =0, "OFF" =1 D(R+(+5V) DIR-(DIR) 24 ENA+[+5V] ENA-(ENA) SW8 SW7 SW6 SW5 SW4 SW3 SW3 SW3 VDC:24~50VDC The order on the motor may not be the same.

# PI - Multiplexer - TCA9548A



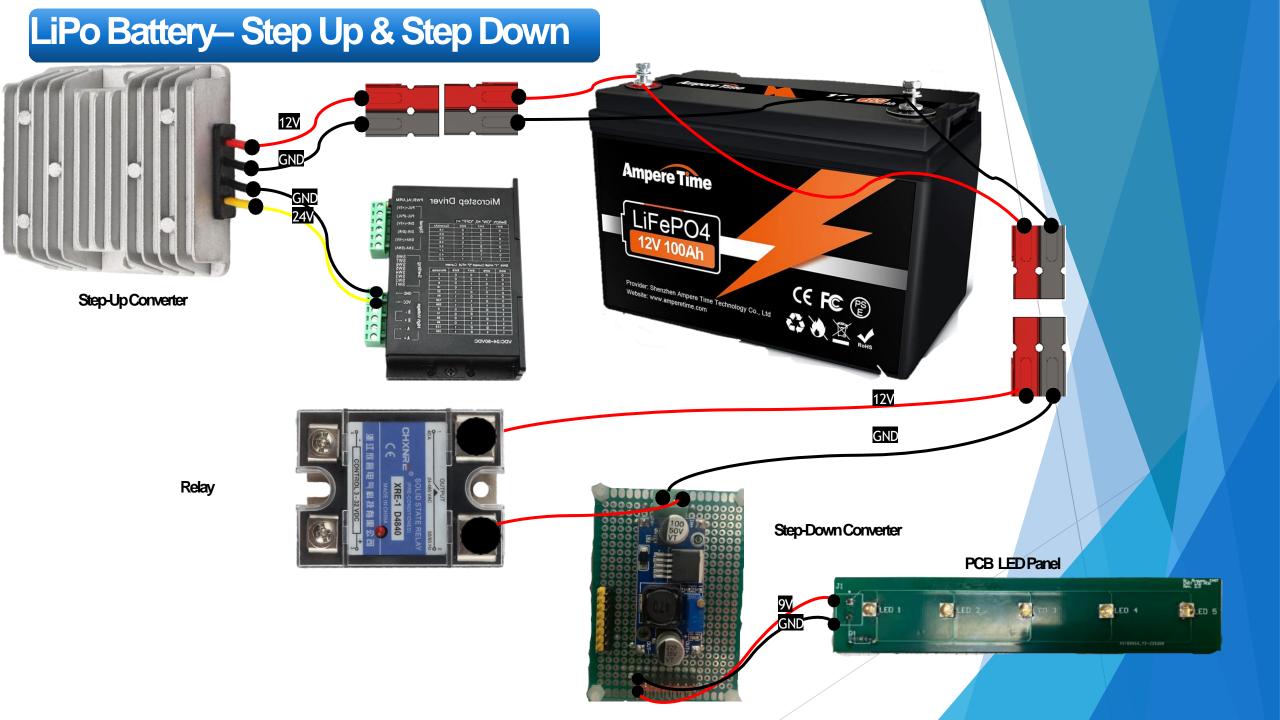






# PI - RPLiDAR and Gamepad

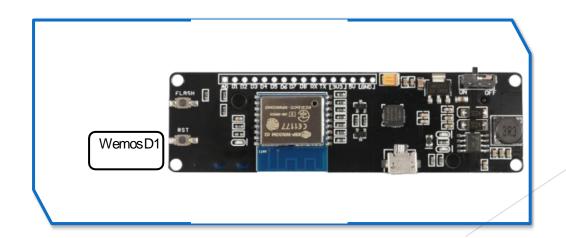




# Bacteria Killed Indicator Wiring Guide

# Bacteria Killed Indicator Contains one CPU





# Wemos D1-Wiring

