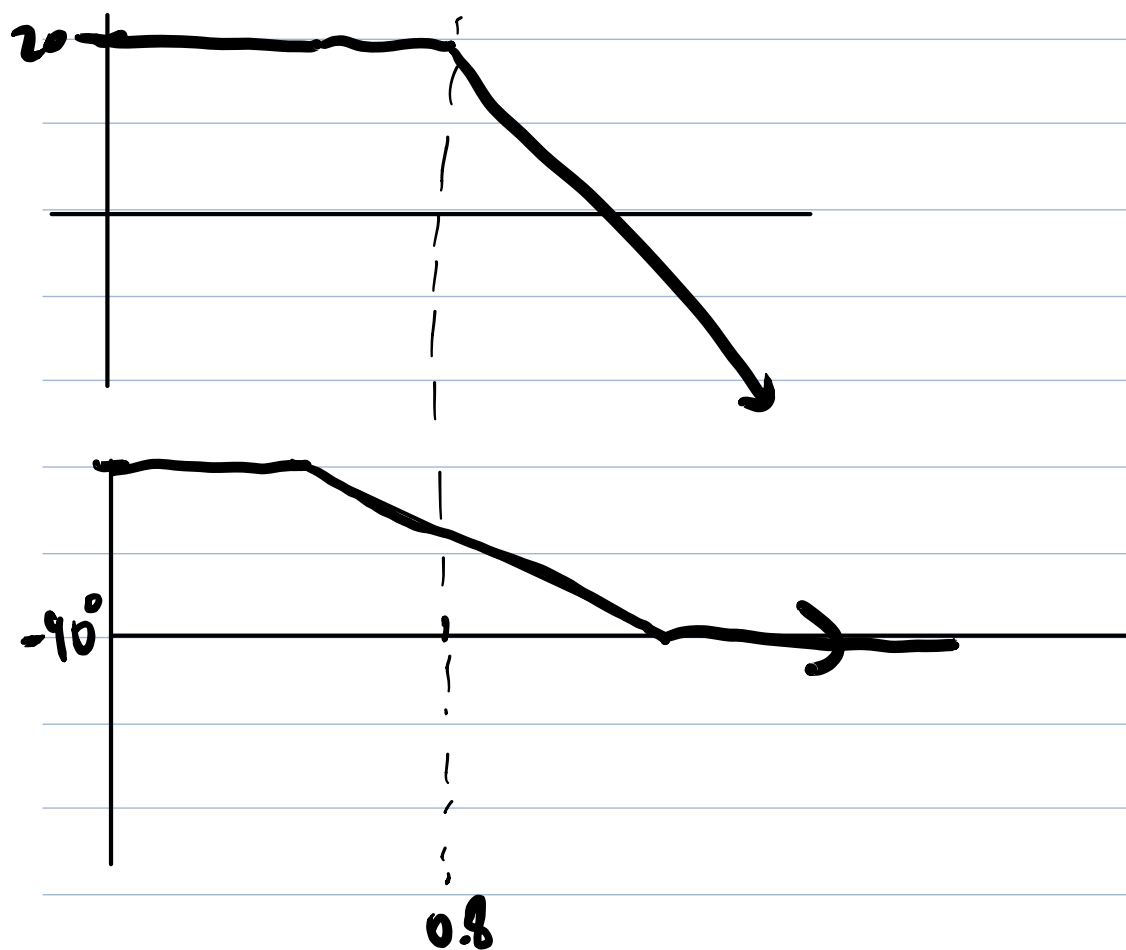


Problem 7



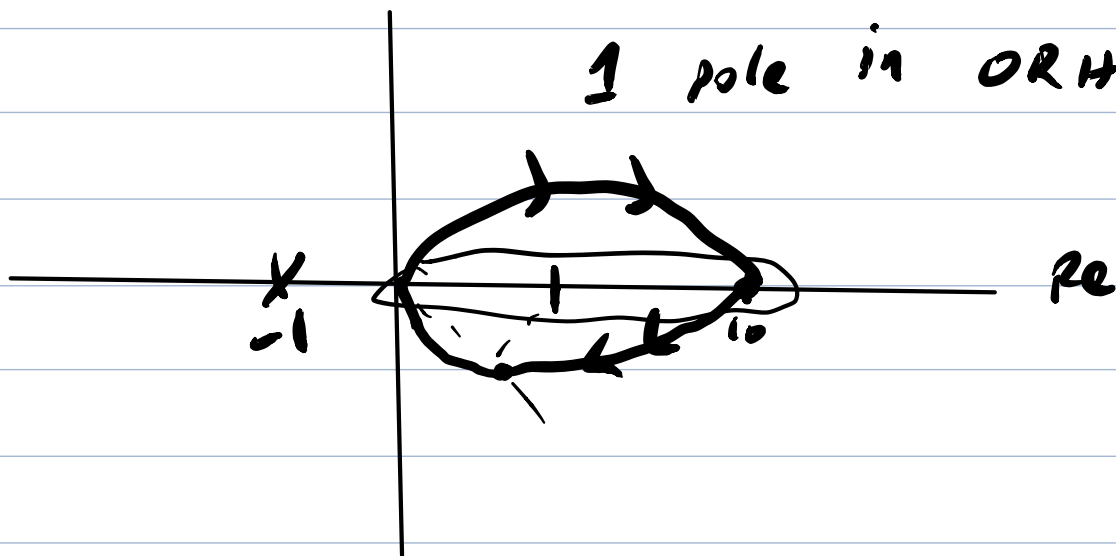
Initial $\omega = 0$

$$P(0)C(0) = 10$$

At $\omega = 0.8$

$$P(0.8j)C(0.8j) = \frac{5}{\sqrt{2}} - \frac{5}{\sqrt{2}}j$$

1 pole in ORHP



Look for ω_{gc} where $|P|_{dB} = 0$ $\omega_{gc} \approx 3$

~~$OL = \frac{1}{K} \ll 10$~~ 2 CW enc. (-1 CCW enc.) Need 1

P5

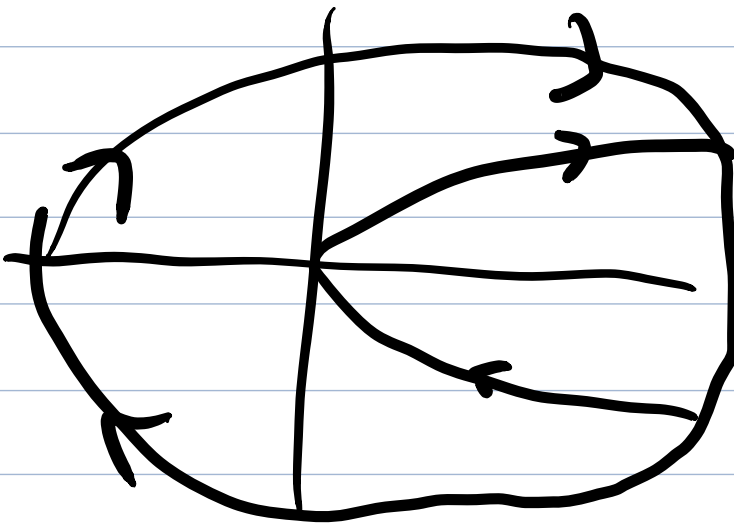
$$P(s) = \frac{s-1}{s^2} \quad C(s) = K$$

Find K for feedback stability

Note: No ORHP poles in PC.

desire no CCW encirclements!

$$P(j\omega)C(j\omega) = \frac{1}{\omega^2} - \frac{1}{\omega}j$$



$$P(z e^{j\omega}) = \frac{z e^{-j\omega} - e^{-2j\omega}}{z^2}$$

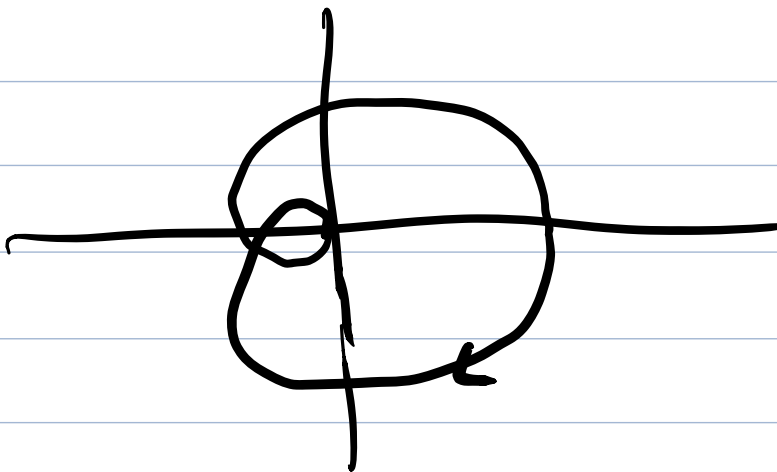
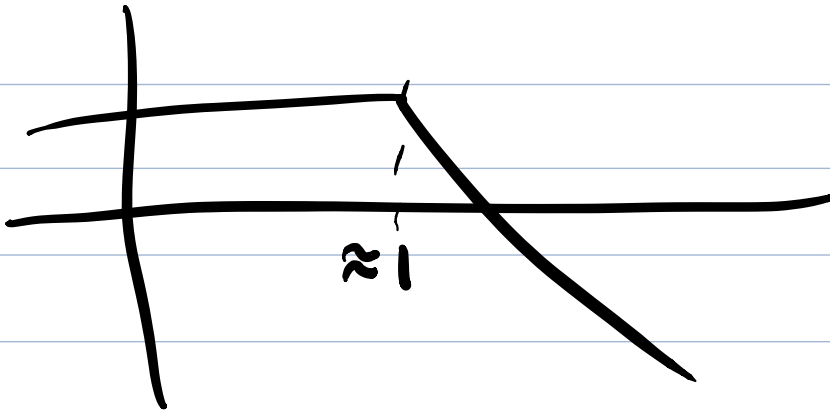
game over!

$$\approx \frac{-e^{-2j\omega}}{z^2}$$

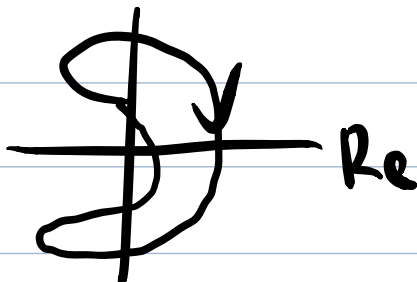
e.g. final 2017

$$P(s) = \frac{1}{(s+1)(s+2)}$$

$$C(s) = \frac{K}{s+3}$$



delay



$$P(s) = \dots e^{-j0.2s}$$

$$C(s) =$$

$$T_{\max} = \frac{\phi_{pm}}{\omega_{gc}}$$

$$s^5 + 2s^4 + 25s^3 + 50s^2 + 144s + 288$$

$$s^5 \quad 1 \quad 25 \quad 144$$

$$s^4 \quad 2 \quad 50 \quad 288$$

$$s^3 \quad 0 \quad 0^{(100)} \quad 0^{\#} \quad \text{row of zeros}$$

$$s^2$$

$$s^1$$

$$s^0$$

$$A(s) = 2s^4 + 50s^2 + 288$$

$$s^2 = \frac{-50 \pm 14}{4}$$

$$s^2 = \{-9, -16\}$$

$$s = \{3j, -3j, 4j, -4j\}$$

