

# Imbalanced datasets

What happens when our *training examples* are imbalanced

- some examples over-represented
- other examples under-represented

We already briefly covered this in [Loss Analysis \(Training\\_Loss.ipynb#Conditional-loss\)](#).

- Our motivation there was focusing on examples where errors occur
- Here our motivation is when the examples naturally partition into *imbalanced* subsets

We revisit this in the case of a Binary Classification task, where one class dominates.

Training loss is usually given unconditionally:

Training Example			
$\mathbf{x}^{(1)}$	$\mathbf{y}^{(1)}$	$\hat{\mathbf{y}}^{(1)}$	$\mathcal{L}_{\Theta}^{(1)}$
$\mathbf{x}^{(2)}$	$\mathbf{y}^{(2)}$	$\hat{\mathbf{y}}^{(2)}$	$\mathcal{L}_{\Theta}^{(2)}$
	$\vdots$		
$\mathbf{x}^{(i)}$	$\mathbf{y}^{(i)}$	$\hat{\mathbf{y}}^{(i)}$	$\mathcal{L}_{\Theta}^{(i)}$
	$\vdots$		
$\mathbf{x}^{(m)}$	$\mathbf{y}^{(m)}$	$\hat{\mathbf{y}}^{(m)}$	$\mathcal{L}_{\Theta}^{(m)}$
			<u><u><math>\mathcal{L}_{\Theta}</math></u></u>
			$\mathcal{L}_{\Theta}$ <b>Total Loss</b>

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But we can also partition the examples and examine the loss in each partition

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Loss analysis: conditional loss

$$\mathbf{x}^{(1)} \quad \mathbf{x}^{(1)} \quad \hat{\mathbf{y}}^{(1)} \quad \mathbf{y}^{(1)}$$

Suppose we partition the training examples into those whose class is Positive and those whose class is Negative:

$$\begin{aligned} \langle \mathbf{X}, \mathbf{y} \rangle &= [\mathbf{x}^{(i)}, \mathbf{y}^{(i)} | 1 \leq i \leq m] \\ &= [\mathbf{x}^{(i)}, \text{Positive} | 1 \leq i \leq m'] \cup [\mathbf{x}^{(i)}, \text{Negative} | 1 \leq i \leq m''] \\ &= \langle \mathbf{X}_{(\text{Positive})}, \mathbf{y}_{(\text{Positive})} \rangle \cup \langle \mathbf{X}_{(\text{Negative})}, \mathbf{y}_{(\text{Negative})} \rangle \end{aligned}$$

We can partition the training loss

$$\begin{aligned}\mathcal{L}_{\Theta} &= \frac{1}{m} \sum_{i=1}^m \mathcal{L}_{\Theta}^{(i)} \\ &= \frac{m'}{m} \frac{1}{m'} \sum_{i' \in \mathbf{X}_{(\text{Positive})}} \mathcal{L}_{\Theta}^{(i)} + \frac{m''}{m} \frac{1}{m''} \sum_{i'' \in \mathbf{X}_{(\text{Negative})}} \mathcal{L}_{\Theta}^{(i)}\end{aligned}$$

That is, the Average loss is the weighted (with weights  $\frac{m'}{m}, \frac{m''}{m}$ ) conditional losses

- $\frac{1}{m'} \sum_{i' \in \mathbf{X}_{(\text{Positive})}} \mathcal{L}_{\Theta}^{(i)}$
- $\frac{1}{m''} \sum_{i'' \in \mathbf{X}_{(\text{Negative})}} \mathcal{L}_{\Theta}^{(i)}$

As we've observed before

- As long as the majority class dominates in count (e.g.,  $m' \gg m''$ )
- It is possible for Average Loss to be low
- Even if Conditional Loss for the minority class is high

This means that training is less likely to generalize well out of sample to the minority examples.

When the set of training examples  $\langle \mathbf{X}, \mathbf{y} \rangle$  is such that

- $\mathbf{y}$  comes from set of categories  $C$
- Where the distribution of  $c \in C$  is *not* uniform

the dataset is called *imbalanced*.

This means that training is may be biased to not do as well on examples from under-represented classes.

For the Titanic survival:

- only 38% of the passengers survived, so the dataset is highly imbalanced
- a naive model that *always* predicted "Not survived" will
  - have 62% accuracy
    - be correct 100% of the time for 62% of the sample (those that didn't survive)
    - be incorrect 100% of the time for 38% of the sample (those that did survive)

The question is whether your use case requires high accuracy in *all* classes.



# Approaches to imbalanced training data

There are a number of approaches to avoid a potential bias caused by imbalanced data.

The imbalanced-learn website ([https://imbalanced-learn.org/stable/user\\_guide.html](https://imbalanced-learn.org/stable/user_guide.html)) documents approaches to this topic.

# Conditional Loss

- Use conditional metrics for Loss rather than unconditional metrics
  - Metric less influenced by size
  - Combination of Precision and Recall

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Loss analysis: conditional loss

$\mathbf{x}^{(1)}$  $\mathbf{y}^{(1)}$  $\hat{\mathbf{y}}^{(1)}$  $\mathcal{L}_{\Theta}^{(1)}$

## Choose a model that is not sensitive to imbalance

Not all models are affected by Imbalanced Data.

- Decision Trees
  - branching structure can handle imbalance

# Loss sensitive training

Modify the Loss function to weight conditional probabilities

Rather than

$$\begin{aligned}\mathcal{L}_{\Theta} &= \frac{1}{m} \sum_{i=1}^m \mathcal{L}_{\Theta}^{(i)} \\ &= \frac{m'}{m} \frac{1}{m'} \sum_{i' \in \mathbf{X}_{(\text{Positive})}} \mathcal{L}_{\Theta}^{(i')} + \frac{m''}{m} \frac{1}{m''} \sum_{i'' \in \mathbf{X}_{(\text{Negative})}} \mathcal{L}_{\Theta}^{(i'')}\end{aligned}$$

adjust weights

$$\mathcal{L}_{\Theta} = C_{\text{Positive}} * \sum_{i' \in \mathbf{X}_{(\text{Positive})}} \mathcal{L}_{\Theta}^{(i')} + C_{\text{Negative}} * \sum_{i'' \in \mathbf{X}_{(\text{Negative})}} \mathcal{L}_{\Theta}^{(i'')}$$

- Equally weighted across classes:  $C_{\text{Positive}} = C_{\text{Negative}}$
- Relative importance
  - An error in one class may be more important than an error in the other

Most models in `sklearn` take an optional `class_weights` optional argument

Allows for different importance (w.r.t. Loss) of different classes

- Can be used to address imbalance
- Can be used to address increased importance (regardless of size) of a particular class

# Data Augmentation

We will describe several methods for modifying the training examples.

They usually involve adding examples in order to achieve balance across classes.

# Resampling

Re-sampling is a process of constructing a new set of training examples by drawing samples from the original.

The sampling doesn't have to be uniform and may be used such that the resampled examples are more balanced

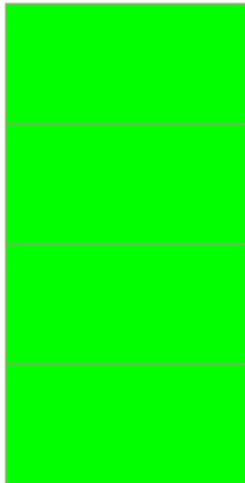
- We can oversample (draw with higher probability) the Minority class
- We can undersample (draw with lower probability) the Majority class

In the limit, weighted sampling is almost equivalent to using the original examples, but weighting the loss term for each class.

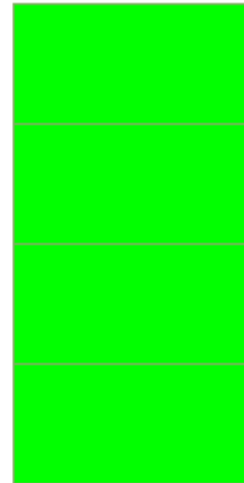


## Imbalanced data: Oversample the minority

$\langle \mathbf{X}, \mathbf{y} \rangle$



$\langle \tilde{\mathbf{X}}, \tilde{\mathbf{y}} \rangle$

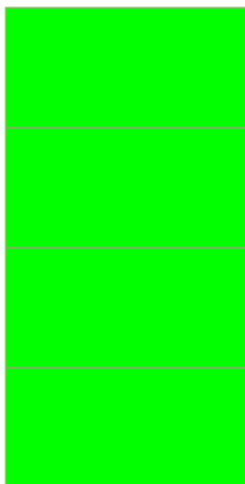


Oversampling



## Imbalanced data: Undersample the majority

$\langle \mathbf{X}, \mathbf{y} \rangle$



$\langle \tilde{\mathbf{X}}, \tilde{\mathbf{y}} \rangle$



# Synthetic examples

Oversampling merely duplicates existing examples from the Minority class.

There are techniques to generate *synthetic* examples

- SMOTE
- ADASYN

A rough description of creating a synthetic example

- Choose an example; find "close" neighboring examples of the same class (Minority)
  - Using a metric of distance between examples
- Create an example that blends/interpolates features from the neighbors into a new example

For certain data types (e.g., images)

- it is possible to perturb the features of an existing example
- such that the target/label is unchanged

This allows the creation of *new* examples

See [Creating new ships in satellite image examples](#)  
([DataAugmentation/Data\\_augmentation.ipynb#Original-image](#)).

# Technical Issues with augmenting the training examples

We have described several techniques for augmenting the training examples.

- The goal is to make the Loss calculation more sensitive to the under-represented class

We could achieve the same effect by using a weighted Loss function (Loss sensitive training)

- Setting  $C_{\text{Positive}} = C_{\text{Negative}}$  will give equal weight to both classes, regardless of the size of each

From a mathematical perspective (w.r.t., Loss) these are equivalent.

**But** there are important practical differences

Let

- $p_{\text{data}}$  denote the true but potentially imbalanced distribution.
- $p_{\text{augment}}$  denote the augmented distribution created by either
  - re-sampling from  $p_{\text{data}}$
  - create synthetic examples

The following two methods of evaluating the Loss Function should be equivalent

- measured with respect to the augmented training distribution  $p_{\text{augment}}$
- measured as a weighted Loss Function using the weights of Loss Sensitive Training

**However:** the Performance Metric should always be evaluated using the true distribution  $p_{\text{data}}$

- assumed to be representative of the out of sample examples to be seen in the future



One therefore must be careful in using  $p_{\text{augment}}$  when fitting a model

- the out of sample test dataset must be created *before* augmentation
  - so that it comes from  $p_{\text{data}}$  rather than  $p_{\text{augment}}$
- the multiple out of sample proxy datasets created by Cross Validation will be from
  - $p_{\text{data}}$  if we train on  $p_{\text{data}}$  and use Loss Sensitive Training to compute a weighted Loss
  - $p_{\text{augment}}$  if we train on  $p_{\text{augment}}$ 
    - not representative of the true out of sample distribution against which the Performance Metric is computed
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So, from a practical perspective

- Modifying the Loss function (loss-sensitive training)
- May avoid "side-effects" that can easily arise if we immediately augment

# Imbalanced example

Here's an unbalanced dataset with 2 classes, and the associated predictions of some model.

```
In [4]: y_true = np.array([0, 1, 0, 0, 1, 0])  
        y_pred = np.array([0, 1, 0, 0, 0, 1])
```

And the regular and class balanced accuracy

```
In [5]: print("Accuracy={a:3.3f}".format(a=accuracy_score(y_true, y_pred)))  
        print("Class balanced Accuracy={a:3.3f}".format(a=balanced_accuracy_score(y_true, y_pred)))
```

Accuracy=0.667

Class balanced Accuracy=0.625

Here's the math behind the two accuracy computations

- "Regular accuracy": per class conditional accuracy, weight by class fraction as percent of total
- "Balanced accuracy": simple average of per class conditional accuracy





```

In [6]: # Enumerate the classes
classes = [0,1]

accs, weights = [], []

# Compute per class accuracy and fraction
for c in classes:
    # Filter examples and predictions, conditional on class == c
    cond = y_true == c
    y_true_cond, y_pred_cond = y_true[cond], y_pred[cond]

    # Compute fraction of total examples in class c
    fraction = y_true_cond.shape[0]/y_true.shape[0]

    # Compute accuracy on this single class
    acc_cond = accuracy_score(y_true_cond, y_pred_cond)

    print("Accuracy conditional on class={c:d} ({p:.2%} of examples) = {a:3.3f}"
          .format(c=c,
                  p=fraction,
                  a=acc_cond
                  )
          )

    accs.append(acc_cond)
    weights.append(fraction)

# Manual computation of accuracy, to show the math
acc = np.dot( np.array(accs), np.array(weights) )
acc_bal = np.average( np.array(accs) )

eqn_elts = [ "{p:.2%} * {a:3.3f}" .format(p=fraction, a=acc_cond) for fraction, a

```

```
cc_cond in zip(weights, accs) ]  
eqn_bal = " + ".join( eqn_elts )
```

```
eqn = "average( {elts:s})".format(elts=", ".join([ str(a) for a in accs ]))  
print("\n")  
print("Computed Accuracy={a:3.3f} ( {e:s} )".format(a=acc, e=eqn_bal))  
print("Computed Balanced Accuracy={a:3.3f} ( {e:s} )".format(a=acc_bal, e=eqn) )
```

Accuracy conditional on class=0 (66.67% of examples) = 0.750  
Accuracy conditional on class=1 (33.33% of examples) = 0.500

Computed Accuracy=0.667 ( 66.67% \* 0.750 + 33.33% \* 0.500 )  
Computed Balanced Accuracy=0.625 ( average( 0.75, 0.5) )

In [7]: `print("Done")`

Done

