

# Recommender Systems: Pseudo SVD

There is another interesting use of Matrix Factorization that we will briefly review.

It will show both a case study and interesting extension of SVD.

## Netflix Prize competition

- Predict user ratings for movies
- Dataset
  - Ratings assigned by users to movies: 1 to 5 stars
  - 480K users, 18K movies; 100MM ratings total
- \$1MM prize
- Awarded to team that beat Netflix existing prediction system by at least 10 percentage points

# User preference matrix

We will try to use same language as PCA (examples, features, synthetic features)

- But map them to Netflix terms
  - Examples: Viewers
  - Features: Movies ("items")

Matrix  $\mathbf{X}$ : user rating of movies

$\mathbf{X}_j^{(i)}$  is  $i^{\text{th}}$  user's rating of movie  $j$

**X** is huge:  $m * n$

- $m = .5$  million viewers
- $n = 18,000$  items (movies).

About 9 billion entries for a full matrix !

## Idea: Linking Viewer to Movies via concepts

- Come up with your own "concepts" (synthetic features)
  - Concept = attribute of a movie
    - Map user preference to concept
    - Map movie style to concept
    - Supply and demand:
      - User demands concept, Movie provides concept

## Human defined concepts

- Style: Action, Adventure, Comedy, Sci-fi
- Actor
- Typical audience segment

## Making recommendations based on concepts

- Create user profile  $P$ : maps user to concept
- Create item profile  $Q$ : maps movies (features, items) to concept
- $\mathbf{X} = PQ^T$

To "recommend" a movie to a new user

- Given a sparse feature vector for the new user
- Obtain a dense vector
  - By mapping the sparse vector to concept space (synthetic features)
  - Finding a cluster of similar synthetic feature vectors, summarizing
  - Inverse transformation back to original features

The original features (movies) newly populated in the formerly sparse vector are the recommendations



One advantage of the  $\mathbf{X} = PQ^T$  approach is a big space reduction.

With  $k \leq n$  concepts:

- $\mathbf{X}$  is  $m \times n$
- $P$  is  $m \times k$
- $Q$  is  $n \times k$

## SVD to discover concepts

Why let a human guess concepts when Machine Learning can discover them ?

- Factor  $\mathbf{X}$  by SVD !
  - Let SVD discovers the  $k$  "best" synthetic features, rather than leaving it to a human

Here's how to use SVD to discover  $P, Q$ :

$$\begin{aligned}\mathbf{X} &= U\Sigma V^T && \text{SVD of } \mathbf{X} \\ &= (U\Sigma)V^T \\ &= PQ && \text{Letting } P = U\Sigma, Q = V^T\end{aligned}$$

Anyone spot the problem(s) ?

The matrix  $\mathbf{X}$  with 9 billion entries is a handful !

But the problem is more acute than one of size.

Each row  $\mathbf{X}^{(i)}$  is *sparse*

- Any single user views only a fraction of the  $n$  movies

How can we perform SVD on a matrix with missing values ?

Missing value imputation is not attractive

- Of the 9 billion potential entries in  $\mathbf{X}$ , only 100 million are defined
- Would impute more missing values than actual values

What can we do ?

## The ML mantra

- It's all about the Loss function
- The essence of ML is finding a Loss function that describes a solution to your problem
- Gradient Descent is the "Swiss Army Knife" used for optimization of Loss functions

We will use "Pseudo SVD", a form of matrix decomposition based on minimizing a Loss.

# Pseudo SVD Loss function

The Frobenius Norm

- Used in PCA as a metric with which to find the "best" low rank approximation
- Is modified to exclude missing values

$$\mathcal{L}(\mathbf{X}', \mathbf{X}) = \sum_{\substack{1 \leq i \leq m, \\ 1 \leq j \leq n \\ \mathbf{X}_j^{(i)} \text{ defined}}} \left( \mathbf{X}_j^{(i)} - \mathbf{X}'_j^{(i)} \right)^2$$

That is: the loss is computed *only for the defined entries* of  $\mathbf{X}$ .

We can interpret the loss as a Reconstruction Error



Note that  $\mathcal{L}(\mathbf{X}', \mathbf{X})$  is parameterized by  $P, Q$

$$\begin{aligned}
 \mathcal{L}(\mathbf{X}', \mathbf{X}) &= \sum_{\substack{1 \leq i \leq m, \\ 1 \leq j \leq n \\ \mathbf{X}_j^{(i)} \text{ defined}}} \left( \mathbf{X}_j^{(i)} - \mathbf{X}'_j^{(i)} \right)^2 \\
 &= \sum_{\substack{1 \leq i \leq m, \\ 1 \leq j \leq n \\ \mathbf{X}_j^{(i)} \text{ defined}}} \left( \mathbf{X}_j^{(i)} - (PQ^T)_j^{(i)} \right)^2 \quad \text{since } \mathbf{X}' = PQ^T
 \end{aligned}$$

$P, Q$  are our *parameters* (e.g.,  $\Theta$ )

So we search for the  $P^*, Q^*$  that minimize  $\mathcal{L}(\mathbf{X}', \mathbf{X})$

$$P^*, Q^* = \underset{P, Q}{\operatorname{argmin}} \mathcal{L}(\mathbf{X}', \mathbf{X})$$

How ? Gradient Descent !

## Pseudo SVD algorithm

- Define  $\mathbf{X}' = PQ^T$
- Initialize elements of  $P, Q$  randomly.
- Take analytic derivatives of  $\mathcal{L}(\mathbf{X}', \mathbf{X})$  with respect to
  - $P_j^{(i)}$  for  $1 \leq i \leq m, 1 \leq j \leq k$
  - $Q_j^{(i)}$  for  $1 \leq i \leq m, 1 \leq j \leq k$
- Use Gradient Descent to solve for optimal entries of  $P, Q$ .
  - Find entries of  $P, Q$  such that product matches non-empty part of  $\mathbf{X}$

## Note

- No guarantee that the  $P, Q$  obtained are
  - Orthonormal, etc. (which SVD would give you)

But SVD won't work for  $\mathbf{X}$  with missing values.

## Filling in missing values

Once you have  $P, Q$

- to predict a missing rating for user  $i$  movie  $j$ :

$$\hat{r}_{j,i} = q^{(i)} \cdot p_j^T$$

- $q^{(i)}$  is row  $i$  of  $Q$
- $p_j$  is column  $j$  of  $P^T$

## Some intuition

The rating vector of a user may have missing entries.

But we can still project to synthetic feature space based on the non-empty entries.

The projection winds up in a "neighborhood" of concepts.

Inverse transformation

- Gets us to a completely non-empty rating vector that is a resident of this neighborhood.

## Example

User rates

- Sci-Fi movies A and B very highly
- Does not rate Sci-Fi movie C.

Since A,B, C express same concept (Sci-Fi) they will be close in synthetic feature space.

Hence, the implied rating of User for movie C will be close to what other users rate C.

In [3]: `print("Done")`

Done



