NumPy_quick_tour

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```
[9]: # My standard magic ! You will see this in almost all my notebooks.

from IPython.core.interactiveshell import InteractiveShell
InteractiveShell.ast_node_interactivity = "all"

# Reload all modules imported with %aimport
%load_ext autoreload
%autoreload 1

%matplotlib inline
```

1 NumPy

VandePlas Chapter 2, Geron notebook

1.1 Python lists

Lists are *heterogeneous*: can contain elements of mixed type

```
[1]: l = list( range(0,10) )
print(1)
```

[0, 1, 2, 3, 4, 5, 6, 7, 8, 9]

```
[2]: 1[2] = "two" print(1)
```

```
[0, 1, 'two', 3, 4, 5, 6, 7, 8, 9]
```

Heterogeneity == slow - Python interpreter has to constantly examine types

1.2 NumPy ndarray

```
[3]: import numpy as np
```

NumPy n-dimensional arrays (ndarray) are homogenous - Can be faster because don't waste time examining type of each element - Can be treated as vectors - Vector arithmetic via compiled code = fast

```
[4]: 1 = list( range(0,10))

l_plus_1 = [ e+1 for e in 1]

print(l_plus_1)
```

[1, 2, 3, 4, 5, 6, 7, 8, 9, 10]

```
[5]: l_np = np.array( np.arange(0,10))
print(l_np +1)
```

[1 2 3 4 5 6 7 8 9 10]

1.2.1 Speed comparison

```
[6]: list_len = 1000
    l = list( range(0, list_len))
    %timeit [ e+1 for e in l]
```

32.9 μ s \pm 132 ns per loop (mean \pm std. dev. of 7 runs, 10000 loops each)

```
[7]: l_np = np.array( np.arange(0, list_len) )
%timeit l_np +1
```

 $1.04 \mu s \pm 6.71 \text{ ns per loop (mean } \pm \text{ std. dev. of 7 runs, } 1000000 \text{ loops each)}$

When dealing with large datasets, you need NumPy

1.3 Basics of NumPy arrays

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Vandeplas YouTube: Losing your loops - slides

The most operation on ndarrays is indexing.

• ndarray indices are 0-based (i.e, first row/col is numbered 0, not 1)

```
[10]: x = np.arange(0,6)
x
x[2]
M = np.arange(0,6).reshape(2,3)
M
M[1,1]
```

[10]: array([0, 1, 2, 3, 4, 5])

[10]: 2

```
[10]: array([[0, 1, 2],
             [3, 4, 5]])
[10]: 4
     1.3.1 Slicing
        • Python (not just NumPy) upper bound of index is NOT inclusive
[11]: print("x: ", x)
      print("x tail: ", x[2:])
      print("x head: ", x[:2])
     x: [0 1 2 3 4 5]
     x tail: [2 3 4 5]
     x head: [0 1]
     1.3.2 Strides
     x[start:stop:step]
[12]: x[1:5:2]
[12]: array([1, 3])
     1.3.3 Reshaping
[12]: grid = np.arange(1, 10).reshape((3, 3))
      print(grid)
     [[1 2 3]
      [4 \ 5 \ 6]
      [7 8 9]]
     Add dimensions
[13]: x = np.arange(0,6)
      print("x: ", x)
      print("x shape: ", x.shape)
      print("x re-shaped: ", x.reshape(1,-1))
      print("x re-shaped shape: ", x.reshape(1,-1).shape)
      print("x w/newaxis: ", x[ np.newaxis,:])
      print("x w/newaxis sja[e: ", x[ np.newaxis,:].shape)
     x: [0 1 2 3 4 5]
     x \text{ shape: } (6,)
     x re-shaped: [[0 1 2 3 4 5]]
```

```
x re-shaped shape: (1, 6)
x w/newaxis: [[0 1 2 3 4 5]]
x w/newaxis sja[e: (1, 6)
```

1.3.4 Concatentation, splitting

```
[14]: x = np.array([1, 2, 3])
y = np.array([3, 2, 1])
x
y

np.concatenate([x, y])
```

```
[14]: array([1, 2, 3])
```

[14]: array([3, 2, 1])

[14]: array([1, 2, 3, 3, 2, 1])

You can concatenate multi-dimensional ndarrays:

```
[15]: array([[1, 2, 3], [4, 5, 6]])
```

```
[15]: array([[ 7, 8, 9], [10, 11, 12]])
```

You can also specify the dimension on which to concatenate

```
[16]: M1
      M2
      np.concatenate([ M1, M2 ], axis=1)
[16]: array([[1, 2, 3],
             [4, 5, 6]])
[16]: array([[ 7, 8, 9],
             [10, 11, 12]])
[16]: array([[ 1, 2, 3, 7, 8, 9],
             [4, 5, 6, 10, 11, 12]])
     You can also use vstack (vertical stack) and hstack (horizontal stack)
[17]: x = np.array([1, 2, 3])
      grid = np.array([[9, 8, 7],
                       [6, 5, 4]])
      y = np.array([100],
                        [200]
                    ])
      х
      grid
      print("vstack:")
      # vertically stack the arrays
      np.vstack([x, grid])
      print("hstack:")
      grid
      np.hstack( [y, grid])
[17]: array([1, 2, 3])
[17]: array([[9, 8, 7],
             [6, 5, 4]])
     vstack:
[17]: array([[1, 2, 3],
             [9, 8, 7],
             [6, 5, 4]])
```

hstack:

1.4 Ufuncs

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Math

- element-wise operations
- vectorized for speed
- operator overloading

```
- +, -, *, /
- <, ==, >
```

- provides natural syntax

```
* 1 + 1
* 'np.add(l,1)
```

```
[18]: x = np.array( np.arange(0,10))
    print("x: ", x)
    print("+1: ", x + 1)
    print("+1 verbose: ", np.add(x,1))
    print("-1: ", x -1)
```

```
x: [0 1 2 3 4 5 6 7 8 9]
+1: [1 2 3 4 5 6 7 8 9 10]
+1 verbose: [1 2 3 4 5 6 7 8 9 10]
-1: [-1 0 1 2 3 4 5 6 7 8]
```

1.4.1 Aggregates

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Aggregation: taking a one-dimensional slice of an ndarray and reducing it to a scalar
 also known as reduce

Best illustrated with an example

```
[19]: x = np.arange(1, 6)
    print("x: ", x)
    print("x reduced by add: ",np.add.reduce(x))

# Less verbose synonym
    print("x reduced by add, via sum", x.sum())
```

```
x: [1 2 3 4 5]
x reduced by add: 15
x reduced by add, via sum 15
```

1.4.2 Aggregates on multi-dimensional ndarray: choose your dimension

```
[20]: x = np.arange(1,7).reshape(2,3)
    print("x: ", x)

print("x reduced on first dimension: ", x.sum(axis=0))

print("x reduced on second dimension: ", x.sum(axis=1))

x: [[1 2 3]
    [4 5 6]]
    x reduced on first dimension: [5 7 9]
    x reduced on second dimension: [6 15]
```

1.4.3 Cumulative

Closely related to reduce: accumulate - running operations, e.g, running sum

```
[21]: print("x: ", x)
print("x running sum: ", np.add.accumulate(x)) # NOTE: not a method ON x; x is

→ a parameter

# Less verbose synonym. n.b., WITHOUT an axis arg,, it will flatten x before

→ summing
print("x running sum via cumsum: ", x.cumsum(axis=0))
```

```
x: [[1 2 3]
  [4 5 6]]
x running sum: [[1 2 3]
  [5 7 9]]
x running sum via cumsum: [[1 2 3]
  [5 7 9]]
```

1.5 Broadcasting

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You hopefully intuitively understand what NumPy does when a binary operator is applied to 2 identically-shaped arguments

```
[22]: a = np.array([0, 1, 2])
b = np.array([5, 5, 5])
a + b
```

```
[22]: array([5, 6, 7])
```

But what happens if the two arguments have different shape? Simplest case: one argument is dimension 0 or 1:

```
[23]: print("a: ", a) print("a + 1: ", a+1)

a: [0 1 2]
```

Next case: what if one argument is identical to the other EXCEPT is missing a dimension:

```
[24]: M = np.arange(1,10).reshape(3,3)

print("a shape (", a.shape, "): ", a)
   print("M shape (", M.shape, "):\n", M)
   print("a + M shape(", (a+M).shape, "):\n", a + M)

a shape ( (3,) ): [0 1 2]
   M shape ( (3, 3) ):
   [[1 2 3]
```

a + M shape((3, 3)):
[[1 3 5]
[4 6 8]
[7 9 11]]

[4 5 6] [7 8 9]]

a + 1: [1 2 3]

NumPy took a one dimensional ndarray a and treated it like a 2-d ndarray by repeated it's rows

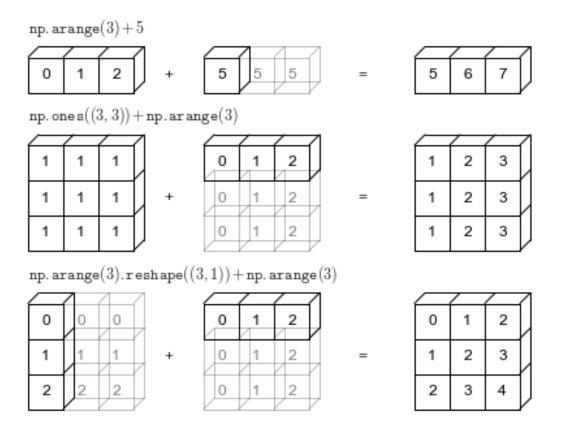
This is called **broadcasting**

Broadcasting follows some simple rules (quoted from Vanderplass):

Rule 1: If the two arrays differ in their number of dimensions, the shape of the one with fewer dimensions is padded with ones on its leading (left) side.

Rule 2: If the shape of the two arrays does not match in any dimension, the array with shape equal to 1 in that dimension is stretched to match the other shape.

Rule 3: If in any dimension the sizes disagree and neither is equal to 1, an error is raised.



1.6 Boolean arrays and masks

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In discussing ufuncs, we stated that logical operators work on ndarrays

```
[25]: x = np.array([1, 2, 3, 4, 5])
x < 3
```

[25]: array([True, True, False, False, False])

What happens if you use a logical array to index into an ndarray? It serves as a mask

```
[26]: x[x < 3]
```

[26]: array([1, 2])

What happens when you apply a mask to a higher dimensional ndarray? Notice what happens to the shape

```
[27]: rng = np.random.RandomState(0)
x = np.arange(0,12).reshape(3,4)
print("x:\n", x)
```

```
print("x masked shape: ", x[ x < 3 ].shape)
print("x masked:\n", x[ x < 3 ])</pre>
```

```
x:

[[0 1 2 3]

[4 5 6 7]

[8 9 10 11]]

x masked shape: (3,)

x masked:

[0 1 2]
```

The shape of the result is the shape of the indexing array.

1.7 Fancy indexing

1.7.1 Fancy indexing

```
[28]: print("Done")
```

Done