Classification via counting

A model for the Classification task constructs a probability distribution $\hat{\mathbf{y}} = p(\mathbf{y}|\mathbf{x})$

- Given feature vector x
- ullet Construct $vector\ \hat{f y}$ (of length |C|, where C are the distinct values for the target)
- Whose elements are probabilities: $\hat{\mathbf{y}}_c$ is the probability that \mathbf{x} is in class c

Notation abuse alert:

- Subscripts of of vectors should be integers rather than class names
- ullet So technically we should write $\hat{f y}_{\#c}$ where #c is the integer index of class named c

This sounds difficult at first glance.

Let's start with something simpler: counting.

We will show to to construct this probability using nothing more than counting the features and targets of the training set!

From counting to probability

We introduce the topic by assuming all our variables (features and target) are discrete.

We will subsequently adapt this to continuous variables.

First, let's compute the distribution of target classes.

Let $\mathbf{X} = \{(\mathbf{x^{(i)}}, \mathbf{y^{(i)}}) | 1 \leq i \leq m\}$ be our m training examples.

Then

$$count_{\mathbf{y}=\mathbf{y}'} = \left| \{i \, | \, \mathbf{y^{(i)}} = \mathbf{y}'\} \right|$$

is the number of training examples with target y'.

We can easily convert this into an unconditional probability

$$p(\mathbf{y} = \mathbf{y}') = rac{count_{\mathbf{y} = \mathbf{y}'}}{m}$$

We can similarly compute the joint probability of any two features.

First we count the co-occurrences of the two variables

$$count_{\mathbf{x}_j = \mathbf{x}_j', \mathbf{x}_k = \mathbf{x}_k'} = \left| \left. \{i | \mathbf{x}_j^{(\mathbf{i})} = \mathbf{x}_j', \mathbf{x}_k^{(\mathbf{i})} = \mathbf{x}_k' \} \right|$$

And the the joint probability is

$$p(\mathbf{x}_j = \mathbf{x}_j', \mathbf{x}_k = \mathbf{x}_k') = rac{count_{\mathbf{x}_j = \mathbf{x}_j', \mathbf{x}_k = \mathbf{x}_k'}}{m}$$

Our illustration is with two features but the notation generalizes for

- Any number of variables
- Any kind of variables: feature or target

Finally, we can define *conditional* probability

$$p(\mathbf{y} = \mathbf{y}' | \mathbf{x} = \mathbf{x}') = rac{p(\mathbf{y} = \mathbf{y}', \mathbf{x} = \mathbf{x}')}{p(\mathbf{x} = \mathbf{x}')}$$

That is, the conditional probability

- Is the joint probability
- ullet As a fraction, relative to the unconditional probability of ${f x}={f x}'$

Bayes theorem

The key for converting counts (really, associated probabilities) to predictions lies in Bayes Theorem.

Bayes Theorem relates conditional and unconditional probabilities.

Bayes Theorem

$$p(\mathbf{y} = \mathbf{y}' | \mathbf{x} = \mathbf{x}') = rac{p(\mathbf{x} = \mathbf{x}' | \mathbf{y} = \mathbf{y}') * p(\mathbf{y} = \mathbf{y}')}{p(\mathbf{x} = \mathbf{x}')}$$

Let's think about Bayes Theorem in terms of our classification task:

- The left hand side is our prediction for the class probabilities, given the features
- The right hand side involves
 - The conditional probability of seeing examples with features \mathbf{x}' and target \mathbf{y}' .
 - lacktriangle The unconditional probability of seeing examples with label \mathbf{y}'
 - The unconditional probability of seeing examples with feature vector \mathbf{x}' .

All these elements can be obtained by counting (and filtering) the training set!

Hence, we can build an extremely simple classifier using nothing more than counting.

Posterior, Prior Probability, Evidence

Let's break down the parts of Bayes theorem and give them some names:

- $p(\mathbf{y} = \mathbf{y}' | \mathbf{x} = \mathbf{x}')$: posterior probability
 - Our prediction
 - lacktriangleright This is the probability distribution of lacktriangleright conditional on the features being lacktriangleright
- $p(\mathbf{y} = \mathbf{y}')$: prior probability
 - lacktriangle This is the unconditional distribution of ${f y}$
- $p(\mathbf{x} = \mathbf{x}' | \mathbf{y} = \mathbf{y}')$: likelihood
 - Given that $\mathbf{y} = \mathbf{y}'$, what is the probability that $\mathbf{x} = \mathbf{x}'$?
 - This is the counting part: how often does the label y' occur when the features are x'?
- $p(\mathbf{x} = \mathbf{x}')$: evidence
 - How often do we see the features \mathbf{x}' ?

We can re-state Bayes Theorem as

$$posterior = \frac{prior*likelihood}{evidence}$$

That is:

- ullet Starting from an uninformed *prior* distribution of ${f y}$
- Derive a conditional posterior distribution (i.e., informed by evidence \mathbf{x}) by updating via the likelihood of seeing \mathbf{x} , \mathbf{y} together.

Proof of Bayes Theorem
$$p(\mathbf{y} = \mathbf{y}' | \mathbf{x} = \mathbf{x}') = \frac{p(\mathbf{y} = \mathbf{y}', \mathbf{x} = \mathbf{x}')}{p(\mathbf{x} = \mathbf{x}')} \qquad \text{(def. of conditional probabilit}$$

$$= \frac{p(\mathbf{y} = \mathbf{y}', \mathbf{x} = \mathbf{x}')}{p(\mathbf{x} = \mathbf{x}')} * \frac{\frac{1}{p(\mathbf{y} = \mathbf{y}')}}{\frac{1}{p(\mathbf{y} = \mathbf{y}')}} \qquad \text{(multiply by identity)}$$

$$= \frac{p(\mathbf{x} = \mathbf{x}' | \mathbf{y} = \mathbf{y}')}{p(\mathbf{x} = \mathbf{x}')} * \frac{1}{\frac{1}{p(\mathbf{y} = \mathbf{y}')}} \qquad \text{(def. of conditional probabilit}$$

$$= \frac{p(\mathbf{x} = \mathbf{x}' | \mathbf{y} = \mathbf{y}')}{p(\mathbf{x} = \mathbf{x}')} * p(\mathbf{y} = \mathbf{y}')$$

Length of ${\bf x}$ is ${m n}$

Remember that \mathbf{x} is a vector, so that $p(\mathbf{x} = \mathbf{x}' \,|\, \mathbf{y} = \mathbf{y}')$ is a *joint* probability of n terms $p(\mathbf{x}_1 = \mathbf{x}_1', \mathbf{x}_2 = \mathbf{x}_2', \dots, \mathbf{x}_n = \mathbf{x}_n' \,|\, \mathbf{y} = \mathbf{y}')$

We an obtain this by counting (as described above)

- Let $|\mathbf{x}_j|$ denote the number of distinct values for the j^{th} feature
- There are

$$\prod_{1 \leq j \leq n} |\mathbf{x}_j|$$

potential combinations for ${f x}$

That's a lot of counting!

More importantly, it's a lot of parameters to remember (i.e, size of Θ is big).

We need a short-cut.

The Naive part of Naive Bayes

We will assume that each feature is *conditionally* independent of one another

$$p(\mathbf{x}_j = \mathbf{x}_j', \mathbf{x}_k = \mathbf{x}_k', |\mathbf{y} = \mathbf{y}') = p(\mathbf{x}_j = \mathbf{x}_j' | \mathbf{y} = \mathbf{y}') * p(\mathbf{x}_k = \mathbf{x}_k' | \mathbf{y} = \mathbf{y}')$$

That is

- \mathbf{x}_j an \mathbf{x}_k are **not** independent unconditionally
- They **are** independent *conditional* on $\mathbf{y} = \mathbf{y}'$

Think of \mathbf{x}_j and \mathbf{x}_k being correlated through their individual relationships with \mathbf{y} .

Excluding that mutual dependence, they may be uncorrelated.

Generalizing the assumption to feature vectors \mathbf{x} of length n:

$$p(\mathbf{x} = \mathbf{x}' | \mathbf{y} = \mathbf{y}') = \prod_{i=1}^n p(\mathbf{x}_i = \mathbf{x}_i' | \mathbf{y} = \mathbf{y}')$$

That is

- ullet The joint conditional probability of the vector of length n
- Is **assumed** to be the product of the individual conditional probabilities of each element of the vector.

This assumption is probably not true but

- Makes $p(\mathbf{x} = \mathbf{x}' | \mathbf{y} = \mathbf{y}')$ very easy to compute
 - lacktriangle Don't have to compute it for possible combination of values for old x
- Uses few parameters
- May be close enough

Thus the "naive" assumption has many benefits!

What about computing the unconditional $p(\mathbf{x} = \mathbf{x}')$?

We can obtain this from conditional probabilities as well

$$p(\mathbf{x} = \mathbf{x}') = \sum_{c \in C} p(\mathbf{x} = \mathbf{x}' | \mathbf{y} = c) * p(\mathbf{y} = c)$$

That is, the unconditional probability follows from the

- Conditional probability given y
- ullet Weighted by the probability $p(\mathbf{y})$ for each possible value of \mathbf{y}

This follows from the definition of conditional probability.

What this means is that the only parameters we need to remember are

- The unconditional probabilities $p(\mathbf{y})$
 - lacktriangle Depends on number of classes |C|
- ullet Probabilities conditional on \mathbf{y} : $p(\mathbf{x}|\mathbf{y})$
 - lacktriangle Depends on length of f x: n

Example

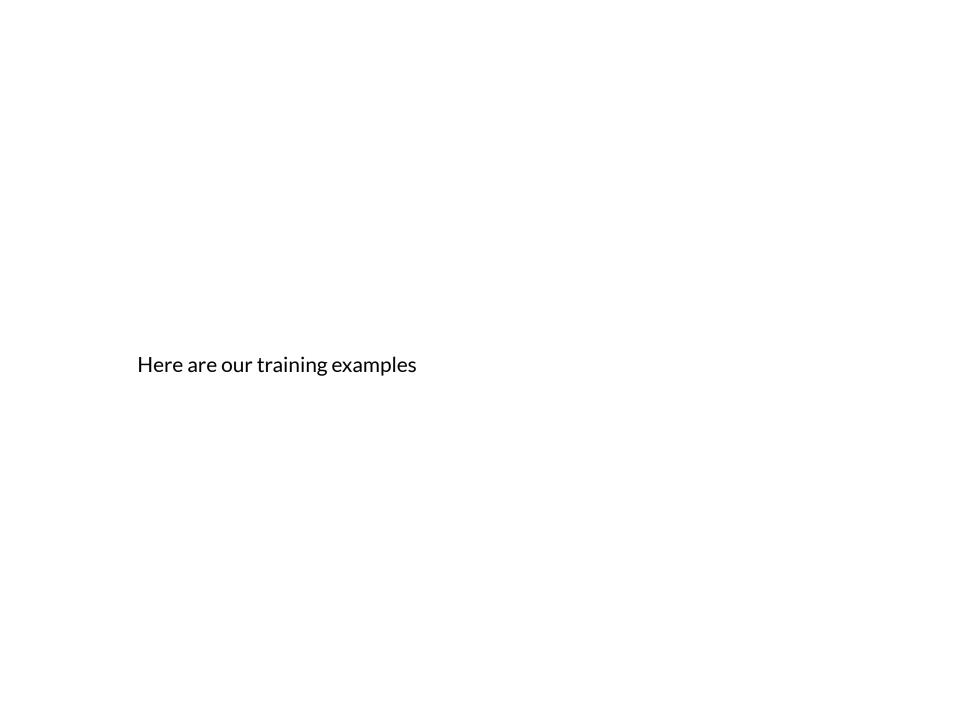
Here is a hypothetical trading example for equities

- There are two categorical features
 - Valuation: possible values {Rich, Cheap}
 - Is the current stock price expensive (Rich) or inexpensive (Cheap)?
 - Yield: possible values {High, Low}
 - Is the dividend yield of the stock desirable (High) or undesirable (Low)?
- ullet Target: An Action with possible values $\{Long, Short, Neutral\}$
 - What should our position be?

We are given a number of examples (on which to train).

Our Classification task is

- Given an equity (test example) with values for the two features Valuation and Yield
- Decide what our position (Long/Short/Neutral) should be



```
In [4]: d_df = pd.read_csv("valuation_yield_action.csv")
    target_name = "Action"
    d_df
```

Out[4]:

	Valuation	Yield	Action
0	Cheap	High	Long
1	Cheap	High	Long
2	Cheap	High	Long
3	Cheap	High	Neutral
4	Rich	Low	Short
5	Rich	Low	Short
6	Rich	Low	Short
7	Rich	Low	Short
8	Rich	Low	Neutral
9	Cheap	Low	Neutral
10	Cheap	Low	Long
11	Cheap	Low	Short
12	Cheap	Low	Neutral
13	Rich	High	Long
14	Rich	High	Short
15	Rich	High	Neutral
16	Fair	Low	Long
17	Fair	Low	Short
18	Fair	Low	Neutral
19	Fair	High	Long
20	Fair	High	Short
21	Fair	High	Neutral
22	Cheap	Low	Long
23	Fair	Low	Short
24	Fair	High	Long



```
In [5]: grouped_by_target = d_df.groupby(target_name)
    for gp in grouped_by_target.groups.keys():
        print(gp, "\n")
        print(grouped_by_target.get_group(gp).head())
        print("\n\n")
```

Long

```
Valuation Yield Action
      Cheap High
0
                    Long
      Cheap High
1
                    Long
2
      Cheap High
                    Long
10
      Cheap
             Low
                    Long
13
       Rich High
                    Long
```

Neutral

```
Valuation Yield
                     Action
3
8
       Cheap
              High
                    Neutral
        Rich
               Low
                    Neutral
9
       Cheap
               Low
                    Neutral
12
       Cheap
               Low
                    Neutral
15
        Rich
              High
                    Neutral
```

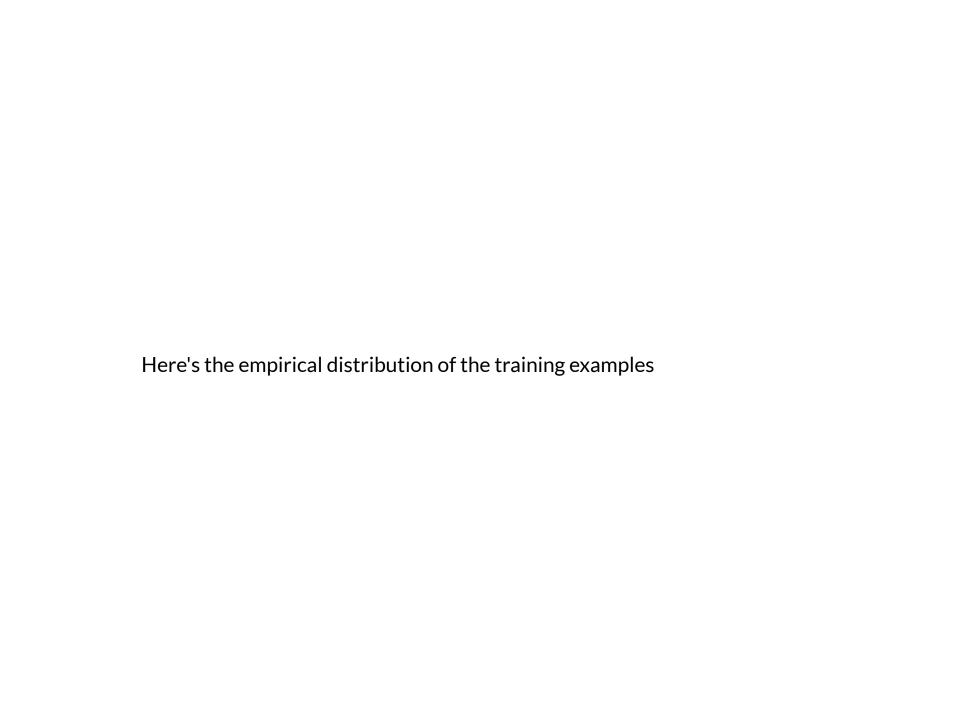
Short

```
Valuation Yield Action
4 Rich Low Short
5 Rich Low Short
6 Rich Low Short
7 Rich Low Short
11 Chean Low Short
```

i cheap Low Shore

Looks like we

- Go Long if the stock is Cheap (Valuation) and High (Yield)
- Go Short if the stock is Rich (expensive Valuation) and Low (Yield)



Out[6]:

	count						
Valuation	Cheap)	Fair		Rich		All
Yield	High	Low	High	Low	High	Low	
Action							
Long	3.0	2.0	2.0	1.0	1.0	NaN	9
Neutral	1.0	2.0	1.0	1.0	1.0	1.0	7
Short	NaN	1.0	1.0	2.0	1.0	4.0	9
All	4.0	5.0	4.0	4.0	3.0	5.0	25

count

This gives us everything we need for the Naive Bayes algorithm

- These are counts
- We can easily turn the counts into unconditional probabilities by dividing by total number of examples
- Will leave them as counts for now

Let's parse this table:

- ullet Columns: $count_{\mathbf{y}|\mathbf{x}}$
 - A column (defined by concrete values for each of the two attributes)
 - Defines a distribution over the target (Action)
- ullet Column Sum: $count_{f x} = \sum_{a \in {
 m Action}} count_{{f x}|a}$
 - lacktriangle Total number of examples with attribute pair lacktriangle
- Rows: $count_{\mathbf{x}|\mathbf{y}}$
 - A row (defined by a concrete value for the Action)
 - Defines a distribution over the attributes pairs for which this action is taken
- ullet Row sums: $count_a = \sum_{f x} count_{{f x}|a}$
 - lacktriangleright Total number of examples with Action a

Let's simplify the table by looking at the marginal with respect to each attribute
 Distribution over a single attribute rather than the pair
First, by Valuation

```
In [7]: # Single feature (Valuation), rather than pair
d_df.drop(columns=["dummy"]).pivot_table(index=target_name, columns=["Valuation"], aggfunc=["count"],
                                          fill_value=0, margins=True)
```

Out[7]:

	count			
	Yield			
Valuation	Cheap	Fair	Rich	All
Action				
Long	5	3	1	9
Neutral	3	2	2	7
Short	1	3	5	9
All	9	8	8	25

And by Yield

```
In [8]:
```

Out[8]:

count				
	Valuation			
Yield	High Low All			
Action				
Long	6	3	9	
Neutral	3	4	7	
Short	2	7	9	
All	11	14	25	



```
In [9]: t.loc[:, idx["count","All",:]]
```

Out[9]:

	count
Valuation	All
Yield	
Action	
Long	9
Neutral	7
Short	9
All	25
Long Neutral Short	7 9



```
In [10]: num_examples = t.loc["All", idx["count","All",:]][0]
    print("There are {e:d} training examples".format(e=int(num_examples)))

# Class probabilities
t.loc[:, idx["count","All",:]]/t.loc["All", idx["count","All",:]]
```

There are 25 training examples

Out[10]:

	count
Valuation	All
Yield	
Action	
Long	0.36
Neutral	0.28
Short	0.36
All	1.00

Why not just use the empirical distribution?

At this point, it's fair to ask:

- Given a test example $\mathbf{x} = \mathbf{x}'$
- ullet We can read $p(\mathbf{y}=\mathbf{y}'|\mathbf{x}=\mathbf{x}')$ directly from the table

Why do we need Naive Bayes?

Answer: Because the table can be big!

• One entry for every possible combination of features

The "naive" conditional independence assumption allows us

- ullet To have a single vector for each feature ${f x}_1,{f x}_2$ individually: total $|{f x}_1|+|{f x}_2|$
- Rather than *combinations* of features $\mathbf{x}_1, \mathbf{x}_2$: total $|\mathbf{x}_1| * |\mathbf{x}_2|$
 - lacksquare In this case n=2 but in general: total $\prod_{j=0}^n |\mathbf{x}_j|$

This is usually much smaller.

Moreover:

- There may be ${\bf no}$ training examples for some combination of features ${\bf x}'$ that shows up as a test example
- The Naive Bayes method allows us to interpolate for such a text example

Drawbacks

The zero frequency problem

In order for Naive Bayes to work we must have

$$p(\mathbf{x}_j = \mathbf{x}_j' | \mathbf{y} = \mathbf{y}')$$

for all possible values of \mathbf{x}_i' that we will encounter during inference (test) time.

There is no guarantee that we will see each of these values in the training set.

Especially when the training set is small

If we don't, the probability is 0, which is not only probably wrong but can cause problems

Note

The Zero Frequency problem is different than the issue in the previous section

- Here, the issue is: Not seeing a particular value for a single feature
- Previous: the issue was not seeing a particular value for the entire vector in training

Additive smoothing

additive smoothing (https://en.wikipedia.org/wiki/Additive_smoothing)

There is a simple solution to the zero frequency problem

• Artificially inflate all counts by some parameter α .

This eliminates zero counts at the cost of biasing all counts.

Note that when converting counts to probabilities

- ullet We have increased the count of each of the |C| classes by lpha
- ullet So the total count for the denominator is m+|C|*lpha

Replace empirical distributions by functional forms

Another way to address the zero frequency problem is to avoid the empirical distribution of training data (the counts)

- assume the features come from a parameterized distribution
 - Bernoulli distribution for binary variables
 - Multinomial distribution for variables with more than two classes

This also has the advantage of fewer parameters: one parameter per feature.

Assumption of conditional independence

This is a questionable assumption.

In its defense:

- If *n* (the number of features) is very large
 - The conditional independence assumption is more likely to hold.

Advantages

- Very simple: just counting!
 - Easy and powerful Baseline Model to use in your Recipe for Machine Learning

Continuous variables for features

The above discussion was limited to features that could take on discrete values.

We now discuss how to include features that are continuous variables.

Discretizing continuous variables

The simplest way to deal with a continuous feature \mathbf{x}_j is to turn it into one or more discrete variables.

- Define a threshold t_i and replace the continuous \mathbf{x}_i with a binary variable
 - \blacksquare Is_{$\mathbf{x}_j < t_j$}
- Define multiple intervals on the range of \mathbf{x}_j and create a binary variable per interval
 - $lacksquare \mathbf{Is}_{t_{j,l-1} \leq \mathbf{x}_j \leq t_{j,l}}$
- The thresholds are a hyper-parameter: can search for optimal

Unfortunately the ordering relationship between continuous values is lost

We have made them categorical

We see this same technique used in Decision Trees, so it's worth mentioning.

Replacing empirical distributions by functional forms for continous variables

Another technique for continuous variables

- Replace the discrete empirical distribution by a functional form
 - Gaussian

This has the advantage that many distributions are characterized by a small number of parameters

• Gaussian: 2 per feature -- a mean and standard deviation

This also deals with the zero frequency problem by eliminating the empirical distribution.

```
In [11]: print("Done")
```

Done