# Homework 7

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### Problem 1

I will explain the algorithm. Subscript n of  $\omega_n$  denotes state of player  $n \in 1, 2$  while superscript i(j) of  $\omega^{i(j)}$  denotes level of state  $i(j) \in \{1, 2, ..., L\}$ .

• Get transition matrix  $\Pr(\omega'|\omega,q)$  (specified in setParams.m).

$$\mathbf{Pr}_{q} = \begin{bmatrix} \Pr(\omega^{1}|\omega^{1}, q) & \Pr(\omega^{2}|\omega^{1}, q) & \cdots & \Pr(\omega^{L}|\omega_{1}, q) \\ \Pr(\omega^{1}|\omega^{2}, q) & \Pr(\omega^{2}|\omega^{2}, q) & \cdots & \Pr(\omega^{L}|\omega_{2}, q) \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ \Pr(\omega^{1}|\omega^{L}, q) & \Pr(\omega^{2}|\omega^{L}, q) & \cdots & \Pr(\omega^{L}|\omega_{L}, q) \end{bmatrix}$$

with representative element  $\Pr_q(\omega^i,\omega^j) = \Pr(\omega^j|\omega^i,q)$ 

• Specify initial guess on  $p_1^{\ell}(\omega_1,\omega_2)$ . For  $\ell=0$ , I use

$$\mathbf{p}_{1}^{0} = \begin{bmatrix} \frac{c(\omega_{1}^{1}) + v}{2} & \frac{c(\omega_{1}^{1}) + v}{2} & \cdots & \frac{c(\omega_{1}^{1}) + v}{2} \\ \frac{c(\omega_{1}^{2}) + v}{2} & \frac{c(\omega_{1}^{2}) + v}{2} & \cdots & \frac{c(\omega_{1}^{2}) + v}{2} \\ \vdots & \vdots & \ddots & \vdots \\ \frac{c(\omega_{1}^{L}) + v}{2} & \frac{c(\omega_{1}^{L}) + v}{2} & \cdots & \frac{c(\omega_{1}^{L}) + v}{2} \end{bmatrix}$$

with representative ij element is  $p^0(\omega_1^i, \omega_2^j) = \frac{c(\omega_1^i) + v}{2}$ .

• Specify initial guess  $V^{\ell}(\omega_1,\omega_2)$ .

$$\mathbf{V}_{1}^{\ell} = \begin{bmatrix} \frac{p^{\ell}(\omega_{1}^{1}, \omega_{2}^{1}) - c(\omega_{1}^{1})}{1 - \beta} & \frac{p^{\ell}(\omega_{1}^{1}, \omega_{2}^{2}) - c(\omega_{1}^{1})}{1 - \beta} & \dots & \frac{p^{\ell}(\omega_{1}^{1}, \omega_{2}^{L}) - c(\omega_{1}^{1})}{1 - \beta} \\ \frac{p^{\ell}(\omega_{1}^{2}, \omega_{2}^{1}) - c(\omega_{1}^{2})}{1 - \beta} & \frac{p^{\ell}(\omega_{1}^{2}, \omega_{2}^{2}) - c(\omega_{1}^{2})}{1 - \beta} & \dots & \frac{p^{\ell}(\omega_{1}^{2}, \omega_{2}^{L}) - c(\omega_{1}^{2})}{1 - \beta} \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ \frac{p^{\ell}(\omega_{1}^{L}, \omega_{2}^{1}) - c(\omega_{1}^{L})}{1 - \beta} & \frac{p^{\ell}(\omega_{1}^{L}, \omega_{2}^{2}) - c(\omega_{1}^{L})}{1 - \beta} & \dots & \frac{p^{\ell}(\omega_{1}^{L}, \omega_{2}^{L}) - c(\omega_{1}^{L})}{1 - \beta} \end{bmatrix}$$

with representative ij element is  $V_1^\ell(\omega_1^i,\omega_2^j)=\frac{p^\ell(\omega_1^i,\omega_2^j)-c(\omega_1^i)}{1-\beta}$ .

 $\bullet \ \ \text{Get} \ W_0^\ell(\omega_1,\omega_2)\text{, } W_1^\ell(\omega_1,\omega_2)\text{, and } W_2^\ell(\omega_1,\omega_2) \ \text{using function getW.m.}$ 

$$\begin{aligned} \mathbf{W}_1^\ell &= \mathbf{P}\mathbf{r}_{q=0} \left[ \mathbf{V}_1^\ell \mathbf{P}\mathbf{r}_{q=0}^\top \right] \\ \mathbf{W}_2^\ell &= \mathbf{P}\mathbf{r}_{q=1} \left[ \mathbf{V}_1^\ell \mathbf{P}\mathbf{r}_{q=0}^\top \right] \\ \mathbf{W}_3^\ell &= \mathbf{P}\mathbf{r}_{q=0} \left[ \mathbf{V}_1^\ell \mathbf{P}\mathbf{r}_{q=1}^\top \right] \end{aligned}$$

- Use built-in solver fsolve to solve for first order conditions. I solve function focp.m for price vector. Within this function, I use function D.m which returns demand for each player for given price matrix. The updated price matrix is denoted by  $\mathbf{p}_1^{\ell+1}$ .
- Use the  $\mathbf{p}_1^{\ell+1}$  to get updated value function  $\mathbf{V}_1^{\ell+1}$ . Function getV.m requires the three inputs: price for player 1, price for player 2, and W. For player 1's price, I use the updated price matrix  $\mathbf{p}_1^{\ell+1}$ . For player 2's price, I use the initial guess  $\left[\mathbf{p}_1^{\ell}\right]^{\top}$ .
- Use the updated matrices for price and value function, iterate the above steps until policy function and value function are converged.

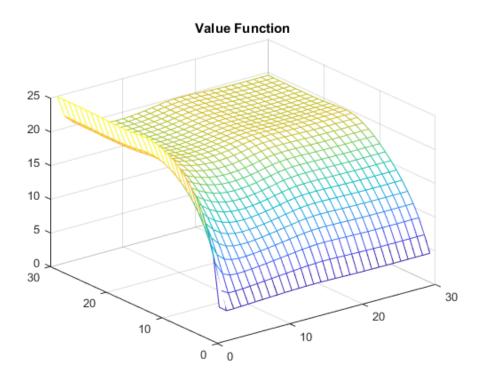


Figure 1: Value function

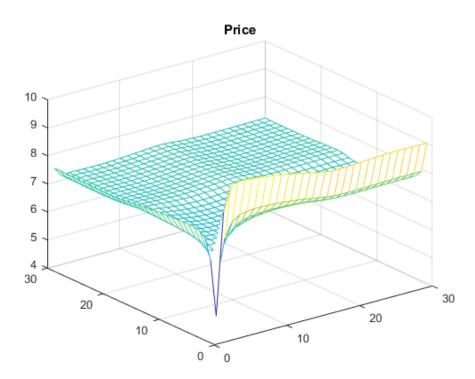


Figure 2: Policy function

## Problem 2

In main code, I construct  $900 \times 900$  transition probability matrix which contains  $\Pr(\omega_1', \omega_2' | \omega_1, \omega_2)$ :

```
 \begin{split} \rho &= \\ & \begin{bmatrix} \Pr\left(\omega_{1}^{1}, \omega_{2}^{1} | \omega_{1}^{1}, \omega_{2}^{1}\right) & \Pr\left(\omega_{1}^{1}, \omega_{2}^{2} | \omega_{1}^{1}, \omega_{2}^{1}\right) & \cdots & \Pr\left(\omega_{1}^{1}, \omega_{2}^{L} | \omega_{1}^{1}, \omega_{2}^{1}\right) & \Pr\left(\omega_{1}^{2}, \omega_{2}^{1} | \omega_{1}^{1}, \omega_{2}^{1}\right) & \cdots & \Pr\left(\omega_{1}^{L}, \omega_{2}^{L} | \omega_{1}^{1}, \omega_{2}^{2}\right) & \cdots & \Pr\left(\omega_{1}^{L}, \omega_{2}^{L} | \omega_{1}^{1}, \omega_{2}^{L}\right) & \cdots & \Pr\left(\omega_{1}^{L}, \omega_{2}^{L} | \omega_{2}^{1}, \omega_{2}^{L}\right) & \cdots & \Pr\left(\omega_{1}^{L}, \omega_{2}^{L} | \omega_{2}^{1}, \omega_{2}^{L}\right) & \cdots & \Pr\left(\omega_{1}^{L}, \omega_{2}^{L} | \omega_{2}^{2}, \omega_{2}^{L}\right) & \cdots & \Pr\left(\omega_{1}^{L}, \omega_{2}^{L} | \omega_{2}^{L}, \omega_{2}^{L}\right) & \cdots & \Pr\left(
```

In order to construct  $\Pr(\omega_1',\omega_2'|\omega_1,\omega_2)$ , I use the following relationship

$$Pr(\omega'_{1}, \omega'_{2} | \omega_{1}, \omega_{2}) = Pr(\omega'_{1}, \omega'_{2} | \omega_{1}, \omega_{2}, q_{1}, q_{2}) Pr(q_{1}, q_{2} | \omega_{1}, \omega_{2})$$
$$= Pr(\omega'_{1} | \omega_{1}, q_{1}) Pr(\omega'_{2} | \omega_{2}, q_{2}) Pr(q_{1}, q_{2} | \omega_{1}, \omega_{2})$$

and

$$\Pr(q_1, q_2 | \omega_1, \omega_2) = \begin{cases} D_0 & \text{if } q_1 = q_2 = 0 \\ D_1 & \text{if } q_1 = 1, q_2 = 0 \\ D_2 & \text{if } q_1 = 0, q_2 = 1 \end{cases}$$

Since I know  $\Pr(\omega_1'|\omega_1, q_1)$ ,  $\Pr(\omega_2'|\omega_2, q_2)$ , and  $\Pr(q_1, q_2|\omega_1, \omega_2)$ , we can construct **Trans** using the price matrix obtained in problem 1.

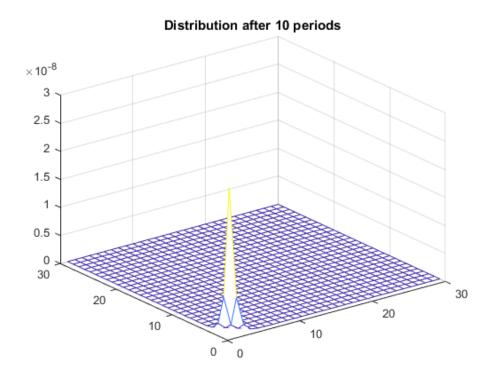
Let the state vector be  $\mathbf{s} \in \mathbb{R}^{900}$  where each element corresponds to unique pair of  $(\omega_1, \omega_2)$ . For example, the first element is  $(\omega_1^1, \omega_2^1)$ , the second element is  $(\omega_1^1, \omega_2^L)$ , and the last element is  $(\omega_1^L, \omega_2^L)$ . Since the initial state is (1,1), let  $\mathbf{s}^1 = [1, 0, \cdots, 0]^\top$ . The probability distribution in period 2 is

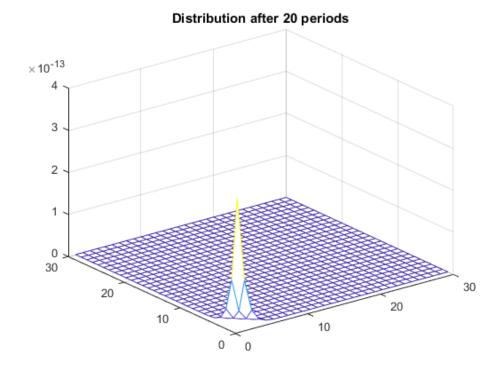
$$\mathbf{s}^2 = \boldsymbol{\rho} \mathbf{s}^1$$

We can repeat this to get the probability distribution over state in period t as

$$\mathbf{s}^t = \boldsymbol{\rho} \mathbf{s}^{t-1}$$

Following images demonstrate the probability distribution after 10, 20, and 30 periods.



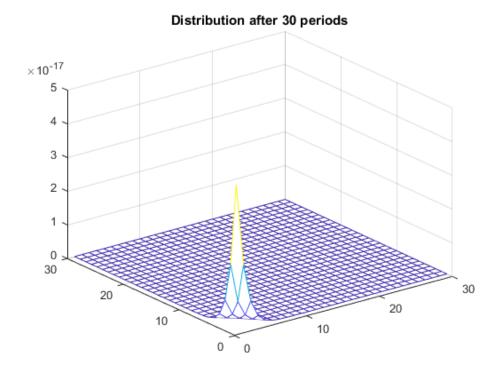


## Problem 3

Stationary distribution is obtained by iterating

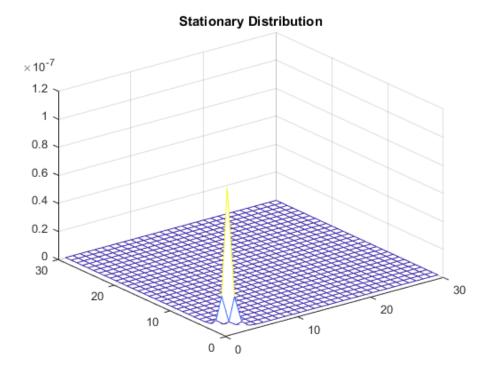
$$\mathbf{s}^t = \boldsymbol{\rho} \mathbf{s}^{t-1}$$

for t=2,3,... until  $\mathbf{s}^t=\mathbf{s}^{t+1}$ 



### Matlab Main Code

```
1 clear;
  tic;
  setupParams;
  %% Problem 1
  % Initial guess
  cmat = kron(c, ones(1,L));
  p1 = (repmat(c,1,L) + v)./2;
  V1 = (p1 - cmat)./(1-beta);
  V1 = ones(L,L);
11
12
  diff = 1;
13
  iter=1;
15
  while diff > 1e-5 \&\& iter < 100000;
16
17
      W = getW(V1);
18
19
       psol = @(p) focp(p,W);
20
       p1_new = fsolve(psol, p1);
21
22
       V1_new = getV(p1, p1_new, W);
23
24
       diff_p = max(abs(((p1_new - p1)./(1+abs(p1_new)))));
25
```



```
diff_V = max(abs(((V1_new - V1)./(1+abs(V1_new)))));
26
       diff = max([diff_p, diff_V])
27
28
29
       V1 = lambda .* V1_new + (1-lambda).* V1;
30
       p1 = lambda .* p1_new + (1-lambda).* p1;
31
       iter = iter +1
32
33
  end
34
35
  figure(1);
36
  mesh(V1);
37
   title('Value Function');
38
39
  figure (2);
  mesh(p1);
41
   title ('Price');
42
43
44
  %% Problem 2
  % transition matrix
  % Raw: (omega1, omega2)
  % Column (omega1', omega2')
  Trans = zeros(L*L,L*L);
49
50
  for i = 1:L*L
51
       for j = 1:L*L
52
```

```
if rem(i,30) == 0
53
                 i1 = fix(i/30);
54
            else
55
                 i1 = fix(i/30) + 1;
56
            end
57
            i2 = rem(i,30);
58
            if i1 == 31
                 i1 = 30;
60
            end
61
            if i2 == 0
62
                 i2 = 30;
63
            end
64
65
            if rem(j,30) == 0
66
                 j1 = fix(j/30);
67
            else
68
                 j1 = fix(j/30) + 1;
69
            end
70
71
            j2 = rem(j,30);
72
            if j1 == 31
73
                 j1 = 30;
74
            end
75
            if j2 == 0
76
                 j2 = 30;
77
            end
78
            [i,j];
79
            ipair = [i1,i2]; % today's state for player 1 and 2
80
            jpair = [j1,j2]; % future state
81
82
83
            Trans(i,j) = Pr(i1,j1,1)*Pr(i2,j2,1)*(1 - D(p1(i1,i2),p1(i2,i1))-
84
               D(p1(i2,i1), p1(i1,i2)) ...
                          + Pr(i1, j1, 2) * Pr(i2, j2, 1) * (D(p1(i1, i2), p1(i2, i1))) ...
85
                          + Pr(i1,j1,1)*Pr(i2,j2,2)*(D(p1(i2,i1), p1(i1,i2)));
86
87
       end
   end
89
90
   clear state state_new
91
92
  % initial state
93
   state_int = zeros(L*L,1);
   state_int(1,1) = 1;
95
  % 10 period
97
   state = state_int;
98
   for t = 2:10
99
       state_new = Trans * state;
100
       state = state_new;
101
```

```
end
102
103
   Dstrbn10 = zeros(L,L);
104
   for i = 1:L
105
        Dstrbn10(i,:) = (state_new((i-1)*L+1:i*L))';
106
   end
107
108
  % 20 period
109
   state = state_int;
110
   for t = 2:20
111
        state_new = Trans * state;
112
        state = state_new;
113
   end
114
115
   Dstrbn20 = zeros(L,L);
116
   for i = 1:L
117
        Dstrbn20(i,:) = (state_new((i-1)*L+1:i*L))';
118
   end
119
120
  % 30 period
121
   state = state_int;
122
   for t = 2:30
        state_new = Trans * state;
124
125
        state = state_new;
   end
126
127
   Dstrbn30 = zeros(L,L);
128
   for i = 1:L
129
        Dstrbn30(i,:) = (state_new((i-1)*L+1:i*L))';
130
   end
131
132
   figure (3);
133
   mesh(Dstrbn10);
134
   title ('Distribution after 10 periods');
135
136
   figure (4);
137
   mesh (Dstrbn20);
138
   title ('Distribution after 20 periods');
139
140
   figure (5);
141
   mesh (Dstrbn30);
142
   title ('Distribution after 30 periods');
143
144
   % Problem 3
145
   % stationary distribution
146
147
   state = state_int;
148
   diff = 1;
149
   while diff > 1e-6
150
        state_new = Trans * state;
151
```

```
diff = max(abs(state - state_new))
152
       state = state_new;
153
   end
154
155
   StDstrbn = zeros(L,L);
156
   for i = 1:L
157
       StDstrbn(i,:) = (state_new((i-1)*L+1:i*L))';
158
   end
159
160
   figure (6);
161
   mesh(StDstrbn);
162
   title('Stationary Distribution');
163
```