

Homework 7

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Problem 1

I will explain the algorithm. Subscript n of ω_n denotes state of player $n \in 1, 2$ while superscript $i(j)$ of $\omega^{i(j)}$ denotes level of state $i(j) \in \{1, 2, \dots, L\}$.

- Get transition matrix $\Pr(\omega'|\omega, q)$ (specified in `setParams.m`).

$$\mathbf{Pr}_q = \begin{bmatrix} \Pr(\omega^1|\omega^1, q) & \Pr(\omega^2|\omega^1, q) & \dots & \Pr(\omega^L|\omega^1, q) \\ \Pr(\omega^1|\omega^2, q) & \Pr(\omega^2|\omega^2, q) & \dots & \Pr(\omega^L|\omega^2, q) \\ \vdots & \vdots & \ddots & \vdots \\ \Pr(\omega^1|\omega^L, q) & \Pr(\omega^2|\omega^L, q) & \dots & \Pr(\omega^L|\omega^L, q) \end{bmatrix}$$

with representative element $\Pr_q(\omega^i, \omega^j) = \Pr(\omega^j|\omega^i, q)$

- Specify initial guess on $p_1^\ell(\omega_1, \omega_2)$. For $\ell = 0$, I use

$$\mathbf{p}_1^0 = \begin{bmatrix} \frac{c(\omega_1^1)+v}{2} & \frac{c(\omega_1^1)+v}{2} & \dots & \frac{c(\omega_1^1)+v}{2} \\ \frac{c(\omega_1^2)+v}{2} & \frac{c(\omega_1^2)+v}{2} & \dots & \frac{c(\omega_1^2)+v}{2} \\ \vdots & \vdots & \ddots & \vdots \\ \frac{c(\omega_1^L)+v}{2} & \frac{c(\omega_1^L)+v}{2} & \dots & \frac{c(\omega_1^L)+v}{2} \end{bmatrix}$$

with representative ij element is $p^0(\omega_1^i, \omega_2^j) = \frac{c(\omega_1^i)+v}{2}$.

- Specify initial guess $V^\ell(\omega_1, \omega_2)$.

$$\mathbf{V}_1^\ell = \begin{bmatrix} \frac{p^\ell(\omega_1^1, \omega_2^1)-c(\omega_1^1)}{1-\beta} & \frac{p^\ell(\omega_1^1, \omega_2^2)-c(\omega_1^1)}{1-\beta} & \dots & \frac{p^\ell(\omega_1^1, \omega_2^L)-c(\omega_1^1)}{1-\beta} \\ \frac{p^\ell(\omega_1^2, \omega_2^1)-c(\omega_1^2)}{1-\beta} & \frac{p^\ell(\omega_1^2, \omega_2^2)-c(\omega_1^2)}{1-\beta} & \dots & \frac{p^\ell(\omega_1^2, \omega_2^L)-c(\omega_1^2)}{1-\beta} \\ \vdots & \vdots & \ddots & \vdots \\ \frac{p^\ell(\omega_1^L, \omega_2^1)-c(\omega_1^L)}{1-\beta} & \frac{p^\ell(\omega_1^L, \omega_2^2)-c(\omega_1^L)}{1-\beta} & \dots & \frac{p^\ell(\omega_1^L, \omega_2^L)-c(\omega_1^L)}{1-\beta} \end{bmatrix}$$

with representative ij element is $V_1^\ell(\omega_1^i, \omega_2^j) = \frac{p^\ell(\omega_1^i, \omega_2^j) - c(\omega_1^i)}{1 - \beta}$.

- Get $W_0^\ell(\omega_1, \omega_2)$, $W_1^\ell(\omega_1, \omega_2)$, and $W_2^\ell(\omega_1, \omega_2)$ using function `getW.m`.

$$\mathbf{W}_1^\ell = \mathbf{Pr}_{q=0} \left[\mathbf{V}_1^\ell \mathbf{Pr}_{q=0}^\top \right]$$

$$\mathbf{W}_2^\ell = \mathbf{Pr}_{q=1} \left[\mathbf{V}_1^\ell \mathbf{Pr}_{q=0}^\top \right]$$

$$\mathbf{W}_3^\ell = \mathbf{Pr}_{q=0} \left[\mathbf{V}_1^\ell \mathbf{Pr}_{q=1}^\top \right]$$

- Use built-in solver `fsolve` to solve for first order conditions. I solve function `focp.m` for price vector. Within this function, I use function `D.m` which returns demand for each player for given price matrix. The updated price matrix is denoted by $\mathbf{p}_1^{\ell+1}$.
- Use the $\mathbf{p}_1^{\ell+1}$ to get updated value function $\mathbf{V}_1^{\ell+1}$. Function `getV.m` requires the three inputs: price for player 1, price for player 2, and \mathbf{W} . For player 1's price, I use the updated price matrix $\mathbf{p}_1^{\ell+1}$. For player 2's price, I use the initial guess $[\mathbf{p}_1^\ell]^\top$.
- Use the updated matrices for price and value function, iterate the above steps until policy function and value function are converged.

Figure 1: Value function

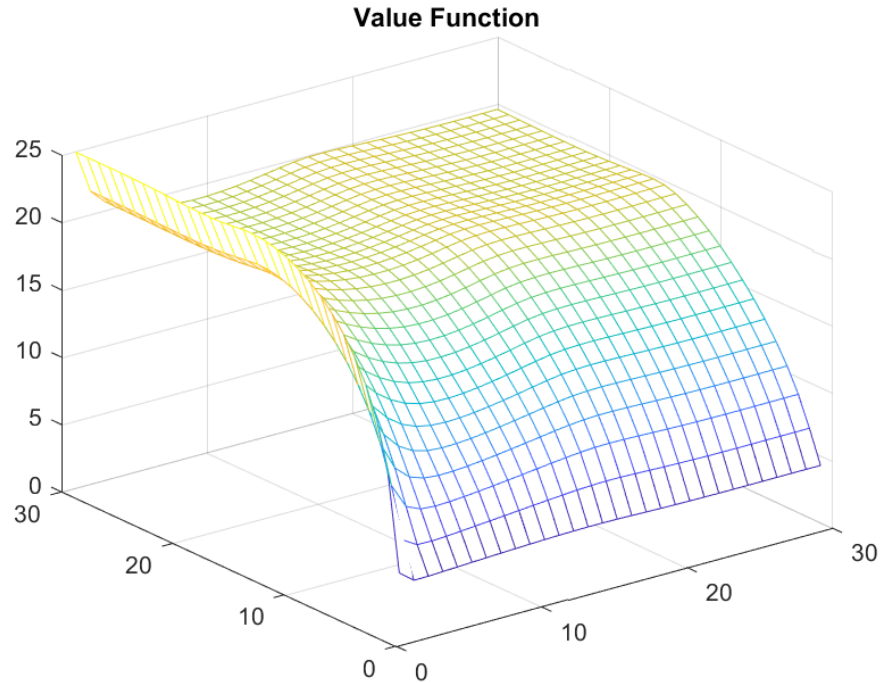
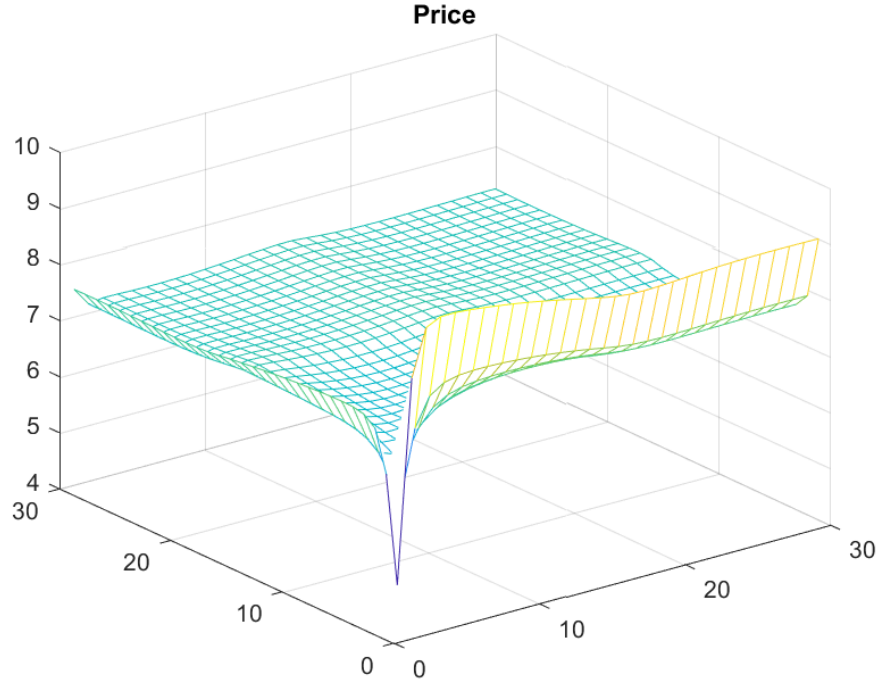


Figure 2: Policy function



Problem 2

In main code, I construct 900×900 transition probability matrix which contains $\Pr(\omega'_1, \omega'_2 | \omega_1, \omega_2)$:

$\rho =$

$$\begin{bmatrix} \Pr(\omega_1^1, \omega_2^1 | \omega_1^1, \omega_2^1) & \Pr(\omega_1^1, \omega_2^2 | \omega_1^1, \omega_2^1) & \cdots & \Pr(\omega_1^1, \omega_2^L | \omega_1^1, \omega_2^1) & \Pr(\omega_1^2, \omega_2^1 | \omega_1^1, \omega_2^1) & \cdots & \Pr(\omega_1^L, \omega_2^L | \omega_1^1, \omega_2^1) \\ \Pr(\omega_1^1, \omega_2^1 | \omega_1^1, \omega_2^2) & \Pr(\omega_1^1, \omega_2^2 | \omega_1^1, \omega_2^2) & \cdots & \Pr(\omega_1^1, \omega_2^L | \omega_1^1, \omega_2^2) & \Pr(\omega_1^2, \omega_2^1 | \omega_1^1, \omega_2^2) & \cdots & \Pr(\omega_1^L, \omega_2^L | \omega_1^1, \omega_2^2) \\ \vdots & \vdots & \vdots & \vdots & \vdots & \vdots & \vdots \\ \Pr(\omega_1^1, \omega_2^1 | \omega_1^1, \omega_2^L) & \Pr(\omega_1^1, \omega_2^2 | \omega_1^1, \omega_2^L) & \cdots & \Pr(\omega_1^1, \omega_2^L | \omega_1^1, \omega_2^L) & \Pr(\omega_1^2, \omega_2^1 | \omega_1^1, \omega_2^L) & \cdots & \Pr(\omega_1^L, \omega_2^L | \omega_1^1, \omega_2^L) \\ \Pr(\omega_1^1, \omega_2^1 | \omega_1^2, \omega_2^1) & \Pr(\omega_1^1, \omega_2^2 | \omega_1^2, \omega_2^1) & \cdots & \Pr(\omega_1^1, \omega_2^L | \omega_1^2, \omega_2^1) & \Pr(\omega_1^2, \omega_2^1 | \omega_1^2, \omega_2^1) & \cdots & \Pr(\omega_1^L, \omega_2^L | \omega_1^2, \omega_2^1) \\ \vdots & \vdots & \vdots & \vdots & \vdots & \vdots & \vdots \\ \Pr(\omega_1^1, \omega_2^1 | \omega_1^L, \omega_2^L) & \Pr(\omega_1^1, \omega_2^2 | \omega_1^L, \omega_2^L) & \cdots & \Pr(\omega_1^1, \omega_2^L | \omega_1^L, \omega_2^L) & \Pr(\omega_1^2, \omega_2^1 | \omega_1^L, \omega_2^L) & \cdots & \Pr(\omega_1^L, \omega_2^L | \omega_1^L, \omega_2^L) \end{bmatrix}$$

In order to construct $\Pr(\omega'_1, \omega'_2 | \omega_1, \omega_2)$, I use the following relationship

$$\begin{aligned} \Pr(\omega'_1, \omega'_2 | \omega_1, \omega_2) &= \Pr(\omega'_1, \omega'_2 | \omega_1, \omega_2, q_1, q_2) \Pr(q_1, q_2 | \omega_1, \omega_2) \\ &= \Pr(\omega'_1 | \omega_1, q_1) \Pr(\omega'_2 | \omega_2, q_2) \Pr(q_1, q_2 | \omega_1, \omega_2) \end{aligned}$$

and

$$\Pr(q_1, q_2 | \omega_1, \omega_2) = \begin{cases} D_0 & \text{if } q_1 = q_2 = 0 \\ D_1 & \text{if } q_1 = 1, q_2 = 0 \\ D_2 & \text{if } q_1 = 0, q_2 = 1 \end{cases}$$

Since I know $\Pr(\omega'_1 | \omega_1, q_1)$, $\Pr(\omega'_2 | \omega_2, q_2)$, and $\Pr(q_1, q_2 | \omega_1, \omega_2)$, we can construct **Trans** using the price matrix obtained in problem 1.

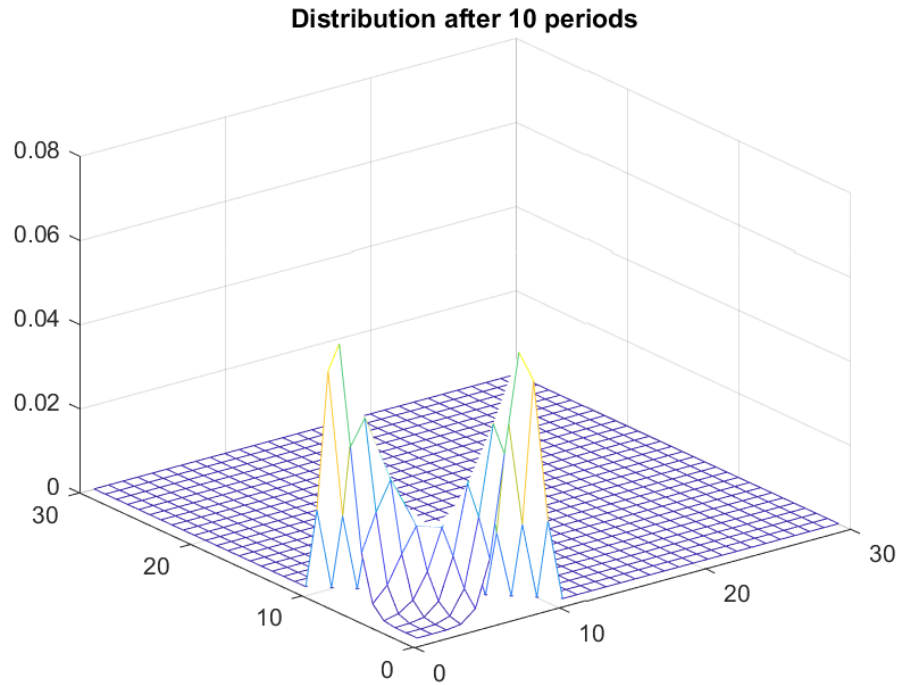
Let the state vector be $\mathbf{s} \in \mathbb{R}^{1 \times 900}$ where each element corresponds to unique pair of (ω_1, ω_2) . For example, the first element is (ω_1^1, ω_2^1) , the second element is (ω_1^1, ω_2^L) , and the last element is (ω_1^L, ω_2^L) . Since the initial state is (1,1), let $\mathbf{s}^1 = [1, 0, \dots, 0]$. The probability distribution in period 2 is

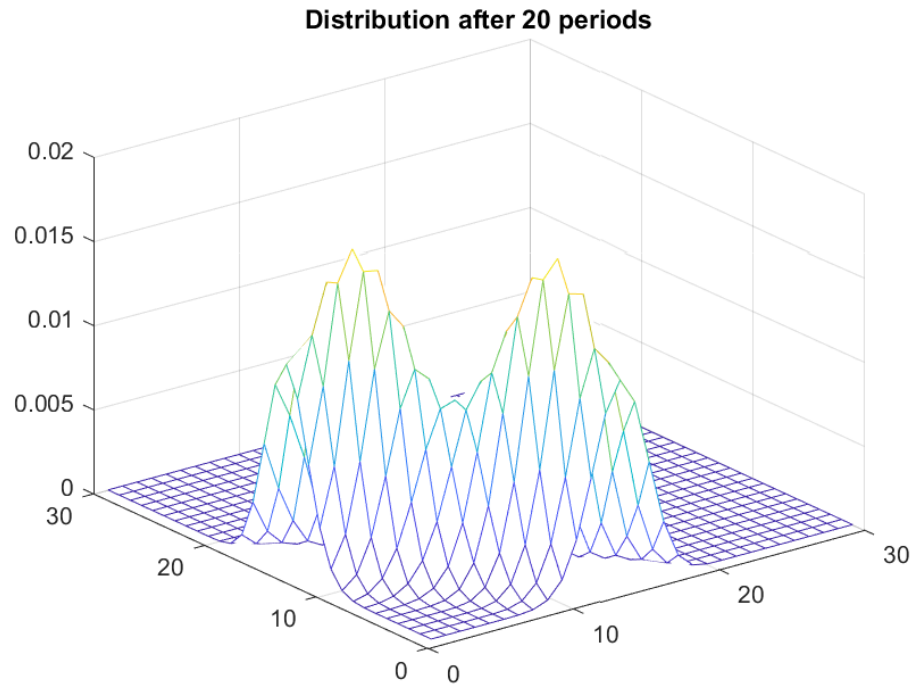
$$\mathbf{s}^2 = \boldsymbol{\rho} \mathbf{s}^1$$

We can repeat this to get the probability distribution over state in period t as

$$\mathbf{s}^t = \boldsymbol{\rho} \mathbf{s}^{t-1}$$

Following images demonstrate the probability distribution after 10, 20, and 30 periods.



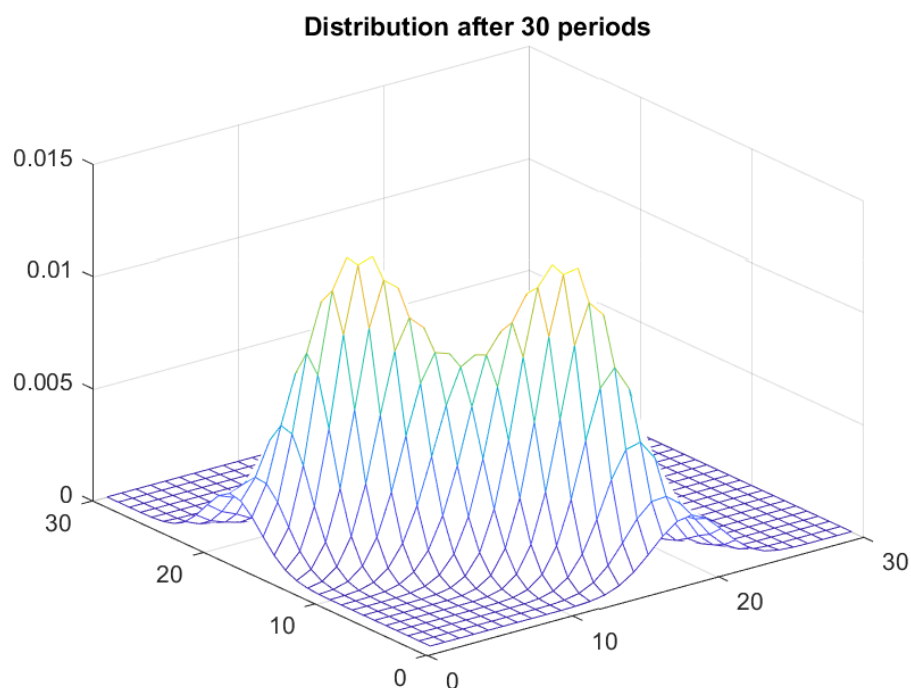


Problem 3

Stationary distribution is obtained by iterating

$$\mathbf{s}^t = \boldsymbol{\rho} \mathbf{s}^{t-1}$$

for $t = 2, 3, \dots$ until $\mathbf{s}^t = \mathbf{s}^{t+1}$

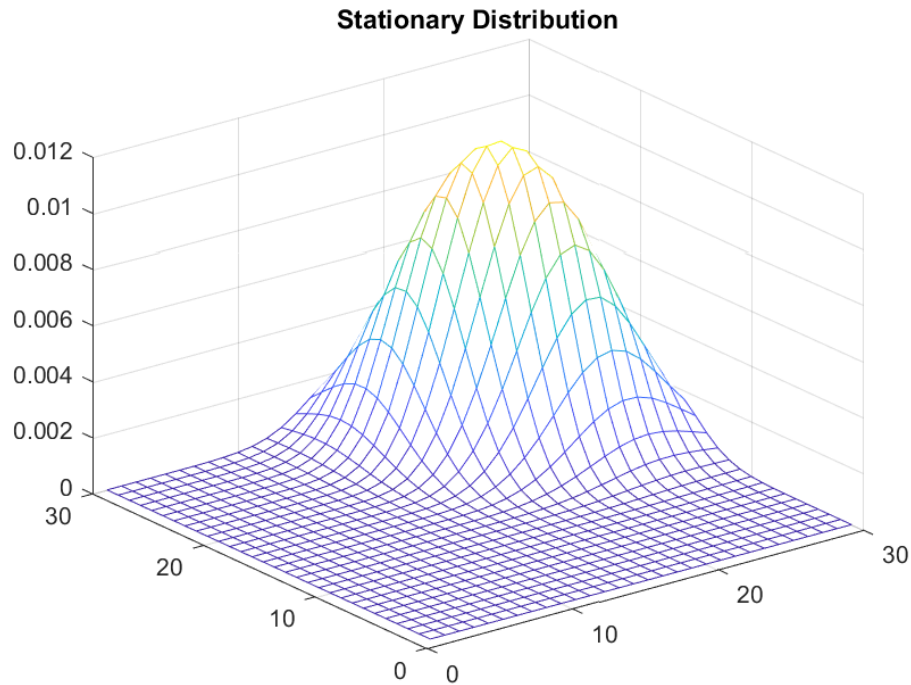


Matlab Main Code

```

1 clear;
2 tic;
3 setupParams;
4
5 %% Problem 1
6
7 % Initial guess
8 cmat = kron(c, ones(1,L));
9 p1 = (repmat(c,1,L) + v)./2;
10 V1 = (p1 - cmat)./(1-beta);
11
12 diff = 1;
13 iter=1;
14
15 load solution.mat
16 p1 = solution.price;
17 V1 = solution.value;
18
19 while diff > 1e-5 && iter < 100000;
20
21     W = getW(V1);
22
23     psol = @(p) focp(p,W);
24     p1_new = fsolve(psol, p1);
25

```



```

26  V1_new = getV(p1,p1_new,W);
27
28  diff_p = max( abs(((p1_new - p1)./(1+abs(p1_new)))) );
29  diff_V = max( abs(((V1_new - V1)./(1+abs(V1_new)))) );
30  diff = max([ diff_p , diff_V ])
31
32
33  V1 = lambda .* V1_new + (1-lambda).* V1;
34  p1 = lambda .* p1_new + (1-lambda).* p1;
35  iter = iter +1
36
37  end
38
39  solution.price = p1;
40  solution.value = V1;
41  save solution;
42
43
44  figure(1);
45  mesh(V1);
46  title('Value Function');
47  saveas(gcf,'value.png')
48
49  figure(2);
50  mesh(p1);
51  title('Price');
52  saveas(gcf,'price.png')

```

```

53
54 %% Problem 2
55 % transition matrix
56 % Row: (omega1, omega2)
57 % Column (omega1', omega2')
58 Trans = zeros(L*L,L*L);
59
60 for i = 1:L*L
61     for j = 1:L*L
62         if rem(i,30) == 0
63             i1 = fix(i/30);
64         else
65             i1 = fix(i/30) +1 ;
66         end
67         i2 = rem(i,30);
68         if i1 == 31
69             i1 = 30;
70         end
71         if i2 == 0
72             i2 = 30;
73         end
74
75         if rem(j,30) == 0
76             j1 = fix(j/30);
77         else
78             j1 = fix(j/30) +1 ;
79         end
80
81         j2 = rem(j,30);
82         if j1 == 31
83             j1 = 30;
84         end
85         if j2 == 0
86             j2 = 30;
87         end
88         [i,j];
89         ipair = [i1,i2]; % today's state for player 1 and 2
90         jpair = [j1,j2]; % future state
91
92
93         Trans(i,j) = Pr(i1,j1,1)*Pr(i2,j2,1)*(1 - D(p1(i1,i2),p1(i2,i1))-
          D(p1(i2,i1), p1(i1,i2))) ...
94             + Pr(i1,j1,2)*Pr(i2,j2,1)*(D(p1(i1,i2),p1(i2,i1))) ...
95             + Pr(i1,j1,1)*Pr(i2,j2,2)*(D(p1(i2,i1), p1(i1,i2))) );
96
97     end
98 end
99
100
101

```



```
102 clear state state_new
103
104
105 % initial state
106 state_int = zeros(1,L*L);
107 state_int(1,1) = 1;
108
109 % 10 period
110 state = state_int;
111 for t = 2:10
112     state_new = state * Trans;
113     state = state_new;
114 end
115
116 Dstrbn10 = zeros(L,L);
117 for i = 1:L
118     Dstrbn10(i,:) = (state_new((i-1)*L+1:i*L))';
119 end
120
121 % 20 period
122 state = state_int;
123 for t = 2:20
124     state_new = state * Trans;
125     state = state_new;
126 end
127
128 Dstrbn20 = zeros(L,L);
129 for i = 1:L
130     Dstrbn20(i,:) = (state_new((i-1)*L+1:i*L))';
131 end
132
133 % 30 period
134 state = state_int;
135 for t = 2:30
136     state_new = state * Trans;
137     state = state_new;
138 end
139
140 Dstrbn30 = zeros(L,L);
141 for i = 1:L
142     Dstrbn30(i,:) = (state_new((i-1)*L+1:i*L))';
143 end
144
145 figure(3);
146 mesh(Dstrbn10);
147 title('Distribution after 10 periods');
148 saveas(gcf,'10period.png')
149
150 figure(4);
151 mesh(Dstrbn20);
```

```
152 title('Distribution after 20 periods');
153 saveas(gcf,'20period.png')
154
155 figure(5);
156 mesh(Dstrbn30);
157 title('Distribution after 30 periods');
158 saveas(gcf,'30period.png')
159
160 %% Problem 3
161 % stationary distribution
162
163 state = state_int;
164 diff = 1;
165 while diff > 1e-6
166     state_new = state * Trans;
167     diff = max(abs(state - state_new))
168     state = state_new;
169 end
170
171 StDstrbn = zeros(L,L);
172 for i = 1:L
173     StDstrbn(i,:) = (state_new((i-1)*L+1:i*L))';
174 end
175
176 figure(6);
177 mesh(StDstrbn);
178 title('Stationary Distribution');
179 saveas(gcf,'stationary.png')
```