Machine Learning Foundations

(機器學習基石)



Lecture 9: Linear Regression

Hsuan-Tien Lin (林軒田)

htlin@csie.ntu.edu.tw

Department of Computer Science & Information Engineering

National Taiwan University (國立台灣大學資訊工程系)



Roadmap

- 1 When Can Machines Learn?
- Why Can Machines Learn?

Lecture 8: Noise and Error

learning can happen with target distribution $P(y|\mathbf{x})$ and low E_{in} w.r.t. err

3 How Can Machines Learn?

Lecture 9: Linear Regression

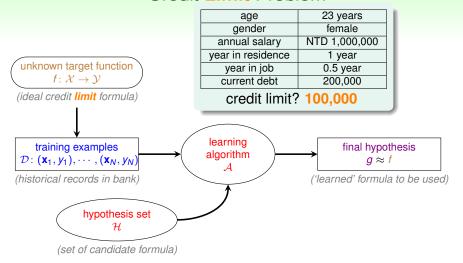
- Linear Regression Problem
- Linear Regression Algorithm
- Generalization Issue
- Linear Regression for Binary Classification
- 4 How Can Machines Learn Better?

Credit Limit Problem

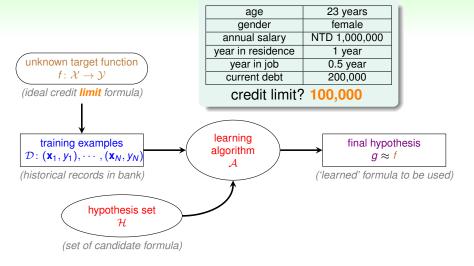
age	23 years	
gender	female	
annual salary	NTD 1,000,000	
year in residence	1 year	
year in job	0.5 year	
current debt	200,000	

credit limit? 100,000

Credit Limit Problem



Credit Limit Problem



 $\mathcal{Y} = \mathbb{R}$: regression

age	23 years
annual salary	NTD 1,000,000
year in job	0.5 year
current debt	200,000

• For $\mathbf{x} = (x_0, x_1, x_2, \dots, x_d)$ 'features of customer',

age	23 years
annual salary	NTD 1,000,000
year in job	0.5 year
current debt	200,000

• For $\mathbf{x} = (x_0, x_1, x_2, \dots, x_d)$ 'features of customer', approximate the desired credit limit with a weighted sum:

$$y \approx \sum_{i=0}^{d} \mathbf{w}_i x_i$$

age	23 years
annual salary	NTD 1,000,000
year in job	0.5 year
current debt	200,000

• For $\mathbf{x} = (x_0, x_1, x_2, \dots, x_d)$ 'features of customer', approximate the desired credit limit with a weighted sum:

$$y \approx \sum_{i=0}^{d} \mathbf{w}_{i} x_{i}$$

• linear regression hypothesis: $h(\mathbf{x}) = \mathbf{w}^T \mathbf{x}$

age	23 years
annual salary	NTD 1,000,000
year in job	0.5 year
current debt	200,000

• For $\mathbf{x} = (x_0, x_1, x_2, \dots, x_d)$ 'features of customer', approximate the desired credit limit with a weighted sum:

$$y \approx \sum_{i=0}^{d} \mathbf{w}_{i} x_{i}$$

• linear regression hypothesis: $h(\mathbf{x}) = \mathbf{w}^T \mathbf{x}$

 $h(\mathbf{x})$: like **perceptron**, but without the sign

Illustration of Linear Regression

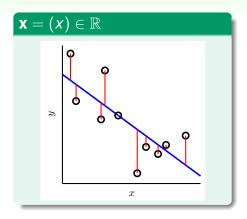
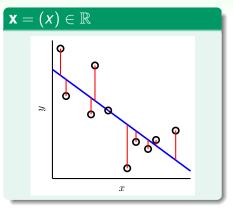


Illustration of Linear Regression



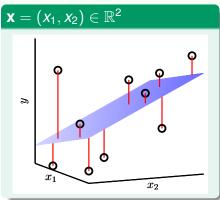
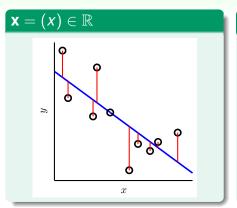
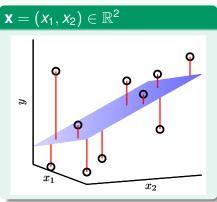


Illustration of Linear Regression





linear regression: find lines/hyperplanes with small residuals

popular/historical error measure:

squared error
$$err(\hat{y}, y) = (\hat{y} - y)^2$$

popular/historical error measure:

squared error
$$err(\hat{y}, y) = (\hat{y} - y)^2$$

in-sample

$$E_{\rm in}(h) = \frac{1}{N} \sum_{n=1}^{N} (\underline{h(\mathbf{x}_n)} - y_n)^2$$

popular/historical error measure:

squared error
$$err(\hat{y}, y) = (\hat{y} - y)^2$$

in-sample

$$E_{in}(\mathbf{w}) = \frac{1}{N} \sum_{n=1}^{N} (\underbrace{h(\mathbf{x}_n)}_{\mathbf{w}^T \mathbf{x}_n} - y_n)^2$$

popular/historical error measure:

squared error
$$err(\hat{y}, y) = (\hat{y} - y)^2$$

in-sample

$$E_{in}(\mathbf{w}) = \frac{1}{N} \sum_{n=1}^{N} (\underbrace{h(\mathbf{x}_n)}_{\mathbf{w}^T \mathbf{x}_n} - y_n)^2$$

out-of-sample

$$E_{\text{out}}(\mathbf{w}) = \underset{(\mathbf{x}, y) \sim P}{\mathcal{E}} (\mathbf{w}^T \mathbf{x} - y)^2$$

popular/historical error measure:

squared error
$$err(\hat{y}, y) = (\hat{y} - y)^2$$

in-sample

$$E_{in}(\mathbf{w}) = \frac{1}{N} \sum_{n=1}^{N} (\underbrace{h(\mathbf{x}_n)}_{\mathbf{w}^T \mathbf{x}_n} - y_n)^2$$

out-of-sample

$$E_{\text{out}}(\mathbf{w}) = \underset{(\mathbf{x}, y) \sim P}{\mathcal{E}} (\mathbf{w}^T \mathbf{x} - y)^2$$

next: how to minimize $E_{in}(\mathbf{w})$?

Fun Time

Consider using linear regression hypothesis $h(\mathbf{x}) = \mathbf{w}^T \mathbf{x}$ to predict the credit limit of customers \mathbf{x} . Which feature below shall have a positive weight in a **good** hypothesis for the task?

- birth month
- 2 monthly income
- 3 current debt
- number of credit cards owned

Fun Time

Consider using linear regression hypothesis $h(\mathbf{x}) = \mathbf{w}^T \mathbf{x}$ to predict the credit limit of customers \mathbf{x} . Which feature below shall have a positive weight in a **good** hypothesis for the task?

- 1 birth month
- 2 monthly income
- 3 current debt
- umber of credit cards owned

Reference Answer: 2

Customers with higher monthly income should naturally be given a higher credit limit, which is captured by the positive weight on the 'monthly income' feature.

$$E_{\text{in}}(\mathbf{w}) = \frac{1}{N} \sum_{n=1}^{N} (\mathbf{w}^{T} \mathbf{x}_{n} - y_{n})^{2}$$

$$E_{\text{in}}(\mathbf{w}) = \frac{1}{N} \sum_{n=1}^{N} (\mathbf{w}^T \mathbf{x}_n - y_n)^2 = \frac{1}{N} \sum_{n=1}^{N} (y_n - y_n)^2$$

$$E_{\text{in}}(\mathbf{w}) = \frac{1}{N} \sum_{n=1}^{N} (\mathbf{w}^T \mathbf{x}_n - y_n)^2 = \frac{1}{N} \sum_{n=1}^{N} (\mathbf{x}_n^T \mathbf{w} - y_n)^2$$

$$E_{in}(\mathbf{w}) = \frac{1}{N} \sum_{n=1}^{N} (\mathbf{w}^T \mathbf{x}_n - y_n)^2 = \frac{1}{N} \sum_{n=1}^{N} (\mathbf{x}_n^T \mathbf{w} - y_n)^2$$
$$= \frac{1}{N} \left\| \right\|^2$$

$$E_{in}(\mathbf{w}) = \frac{1}{N} \sum_{n=1}^{N} (\mathbf{w}^T \mathbf{x}_n - y_n)^2 = \frac{1}{N} \sum_{n=1}^{N} (\mathbf{x}_n^T \mathbf{w} - y_n)^2$$
$$= \frac{1}{N} \begin{bmatrix} \mathbf{x}_1^T \mathbf{w} - y_1 \\ \mathbf{x}_2^T \mathbf{w} - y_2 \\ \dots \\ \mathbf{x}_N^T \mathbf{w} - y_N \end{bmatrix}^2$$

$$E_{in}(\mathbf{w}) = \frac{1}{N} \sum_{n=1}^{N} (\mathbf{w}^{T} \mathbf{x}_{n} - y_{n})^{2} = \frac{1}{N} \sum_{n=1}^{N} (\mathbf{x}_{n}^{T} \mathbf{w} - y_{n})^{2}$$

$$= \frac{1}{N} \begin{vmatrix} \mathbf{x}_{1}^{T} \mathbf{w} - y_{1} \\ \mathbf{x}_{2}^{T} \mathbf{w} - y_{2} \\ \dots \\ \mathbf{x}_{N}^{T} \mathbf{w} - y_{N} \end{vmatrix}^{2}$$

$$= \frac{1}{N} \begin{vmatrix} \mathbf{w} - \mathbf{w} \\ \mathbf{w} - \mathbf{w} \end{vmatrix}$$

$$E_{in}(\mathbf{w}) = \frac{1}{N} \sum_{n=1}^{N} (\mathbf{w}^{T} \mathbf{x}_{n} - y_{n})^{2} = \frac{1}{N} \sum_{n=1}^{N} (\mathbf{x}_{n}^{T} \mathbf{w} - y_{n})^{2}$$

$$= \frac{1}{N} \begin{vmatrix} \mathbf{x}_{1}^{T} \mathbf{w} - y_{1} \\ \mathbf{x}_{2}^{T} \mathbf{w} - y_{2} \\ \dots \\ \mathbf{x}_{N}^{T} \mathbf{w} - y_{N} \end{vmatrix}^{2}$$

$$= \frac{1}{N} \begin{vmatrix} -\mathbf{x}_{1}^{T} - - \\ -\mathbf{x}_{2}^{T} - - \\ \dots \\ -\mathbf{x}_{N}^{T} - - \end{vmatrix} \mathbf{w} - \begin{bmatrix} y_{1} \\ y_{2} \\ \dots \\ y_{N} \end{vmatrix}^{2}$$

$$E_{in}(\mathbf{w}) = \frac{1}{N} \sum_{n=1}^{N} (\mathbf{w}^{T} \mathbf{x}_{n} - y_{n})^{2} = \frac{1}{N} \sum_{n=1}^{N} (\mathbf{x}_{n}^{T} \mathbf{w} - y_{n})^{2}$$

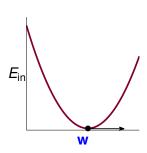
$$= \frac{1}{N} \left\| \begin{array}{c} \mathbf{x}_{1}^{T} \mathbf{w} - y_{1} \\ \mathbf{x}_{2}^{T} \mathbf{w} - y_{2} \\ \dots \\ \mathbf{x}_{N}^{T} \mathbf{w} - y_{N} \end{array} \right\|^{2}$$

$$= \frac{1}{N} \left\| \begin{bmatrix} --\mathbf{x}_{1}^{T} - - \\ --\mathbf{x}_{2}^{T} - - \\ \dots \\ --\mathbf{x}_{N}^{T} - - \end{bmatrix} \mathbf{w} - \begin{bmatrix} y_{1} \\ y_{2} \\ \dots \\ y_{N} \end{bmatrix} \right\|^{2}$$

$$= \frac{1}{N} \left\| \underbrace{\mathbf{x}}_{N \times d+1} \underbrace{\mathbf{w}}_{d+1 \times 1} - \underbrace{\mathbf{y}}_{N \times 1} \right\|^{2}$$

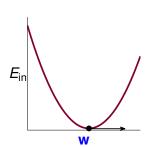
$$\min_{\mathbf{w}} E_{\text{in}}(\mathbf{w}) = \frac{1}{N} \| \mathbf{X} \mathbf{w} - \mathbf{y} \|^2$$

$$\min_{\mathbf{w}} E_{in}(\mathbf{w}) = \frac{1}{N} \|\mathbf{X}\mathbf{w} - \mathbf{y}\|^2$$



• $E_{in}(\mathbf{w})$: continuous, differentiable, **convex**

$$\min_{\mathbf{w}} E_{in}(\mathbf{w}) = \frac{1}{N} \|\mathbf{X}\mathbf{w} - \mathbf{y}\|^2$$

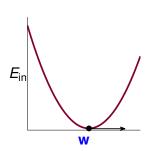


- E_{in}(w): continuous, differentiable, convex
- necessary condition of 'best' w

$$\nabla \textit{E}_{in}(\textbf{w}) \equiv \begin{bmatrix} \frac{\partial \textit{E}_{in}}{\partial \textit{w}_0}(\textbf{w}) \\ \frac{\partial \textit{E}_{in}}{\partial \textit{w}_1}(\textbf{w}) \\ \vdots \\ \frac{\partial \textit{E}_{in}}{\partial \textit{w}_d}(\textbf{w}) \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ \vdots \\ 0 \end{bmatrix}$$

—not possible to 'roll down'

$$\min_{\mathbf{w}} E_{in}(\mathbf{w}) = \frac{1}{N} \|\mathbf{X}\mathbf{w} - \mathbf{y}\|^2$$



- E_{in}(w): continuous, differentiable, convex
- necessary condition of 'best' w

$$\nabla \textit{E}_{in}(\textbf{w}) \equiv \begin{bmatrix} \frac{\partial \textit{E}_{in}}{\partial \textit{w}_0}(\textbf{w}) \\ \frac{\partial \textit{E}_{in}}{\partial \textit{w}_1}(\textbf{w}) \\ \dots \\ \frac{\partial \textit{E}_{in}}{\partial \textit{w}_d}(\textbf{w}) \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ \dots \\ 0 \end{bmatrix}$$

—not possible to 'roll down'

task: find \mathbf{w}_{LIN} such that $\nabla E_{in}(\mathbf{w}_{LIN}) = \mathbf{0}$

$$E_{\text{in}}(\mathbf{w}) = \frac{1}{N} \|\mathbf{X}\mathbf{w} - \mathbf{y}\|^2 = \frac{1}{N} \left(\mathbf{w}^T - \mathbf{w} - 2\mathbf{w}^T + \mathbf{w} \right)$$

$$E_{in}(\mathbf{w}) = \frac{1}{N} \|\mathbf{X}\mathbf{w} - \mathbf{y}\|^2 = \frac{1}{N} \left(\mathbf{w}^T \mathbf{X}^T \mathbf{X} \mathbf{w} - 2 \mathbf{w}^T \mathbf{X}^T \mathbf{y} + \mathbf{y}^T \mathbf{y} \right)$$

$$E_{in}(\mathbf{w}) = \frac{1}{N} \|\mathbf{X}\mathbf{w} - \mathbf{y}\|^2 = \frac{1}{N} \left(\mathbf{w}^T \underbrace{\mathbf{X}^T \mathbf{X}}_{A} \mathbf{w} - 2 \mathbf{w}^T \underbrace{\mathbf{X}^T \mathbf{y}}_{B} + \underbrace{\mathbf{y}^T \mathbf{y}}_{C} \right)$$

$$E_{in}(\mathbf{w}) = \frac{1}{N} \|\mathbf{X}\mathbf{w} - \mathbf{y}\|^2 = \frac{1}{N} \left(\mathbf{w}^T \underbrace{\mathbf{X}^T \mathbf{X}}_{\mathbf{A}} \mathbf{w} - 2 \mathbf{w}^T \underbrace{\mathbf{X}^T \mathbf{y}}_{\mathbf{b}} + \underbrace{\mathbf{y}^T \mathbf{y}}_{\mathbf{c}} \right)$$

one w only

$$E_{\text{in}}(w) = \frac{1}{N} \left(\frac{aw^2}{aw^2} - 2bw + c \right)$$

$$E_{in}(\mathbf{w}) = \frac{1}{N} \|\mathbf{X}\mathbf{w} - \mathbf{y}\|^2 = \frac{1}{N} \left(\mathbf{w}^T \underbrace{\mathbf{X}^T \mathbf{X}}_{\mathbf{A}} \mathbf{w} - 2 \mathbf{w}^T \underbrace{\mathbf{X}^T \mathbf{y}}_{\mathbf{b}} + \underbrace{\mathbf{y}^T \mathbf{y}}_{c} \right)$$

one w only

$$E_{\rm in}(w) = \frac{1}{N} \left(aw^2 - 2bw + c \right)$$

$$\nabla E_{\text{in}}(\mathbf{w}) = \frac{1}{N} (2\mathbf{a}\mathbf{w} - 2\mathbf{b})$$

simple! :-)

The Gradient $\nabla E_{in}(\mathbf{w})$

$$E_{in}(\mathbf{w}) = \frac{1}{N} \|\mathbf{X}\mathbf{w} - \mathbf{y}\|^2 = \frac{1}{N} \left(\mathbf{w}^T \underbrace{\mathbf{X}^T \mathbf{X}}_{\mathbf{A}} \mathbf{w} - 2 \mathbf{w}^T \underbrace{\mathbf{X}^T \mathbf{y}}_{\mathbf{b}} + \underbrace{\mathbf{y}^T \mathbf{y}}_{c} \right)$$

one w only

$$E_{\rm in}(w) = \frac{1}{N} \left(aw^2 - 2bw + c \right)$$

$$\nabla E_{\rm in}(\mathbf{w}) = \frac{1}{N} \left(2 \frac{\mathsf{a} \mathsf{w}}{\mathsf{a} \mathsf{w}} - 2 \frac{\mathsf{b}}{\mathsf{b}} \right)$$

simple! :-)

vector w

$$E_{\text{in}}(\mathbf{w}) = \frac{1}{N} \left(\mathbf{w}^T \mathbf{A} \mathbf{w} - 2 \mathbf{w}^T \mathbf{b} + c \right)$$

The Gradient $\nabla E_{in}(\mathbf{w})$

$$E_{in}(\mathbf{w}) = \frac{1}{N} \|\mathbf{X}\mathbf{w} - \mathbf{y}\|^2 = \frac{1}{N} \left(\mathbf{w}^T \underbrace{\mathbf{X}^T \mathbf{X}}_{\mathbf{A}} \mathbf{w} - 2 \mathbf{w}^T \underbrace{\mathbf{X}^T \mathbf{y}}_{\mathbf{b}} + \underbrace{\mathbf{y}^T \mathbf{y}}_{c} \right)$$

one w only

$$E_{\rm in}(w) = \frac{1}{N} \left(aw^2 - 2bw + c \right)$$

$$\nabla E_{\rm in}(\mathbf{w}) = \frac{1}{N} \left(2 \frac{aw}{aw} - 2 \frac{b}{b} \right)$$

simple! :-)

vector w

$$E_{in}(\mathbf{w}) = \frac{1}{N} \left(\mathbf{w}^T \mathbf{A} \mathbf{w} - 2 \mathbf{w}^T \mathbf{b} + c \right)$$

$$\nabla E_{\text{in}}(\mathbf{w}) = \frac{1}{N} (2\mathbf{A}\mathbf{w} - 2\mathbf{b})$$

similar (derived by definition)

The Gradient $\nabla E_{in}(\mathbf{w})$

$$E_{in}(\mathbf{w}) = \frac{1}{N} \|\mathbf{X}\mathbf{w} - \mathbf{y}\|^2 = \frac{1}{N} \left(\mathbf{w}^T \underbrace{\mathbf{X}^T \mathbf{X}}_{\mathbf{A}} \mathbf{w} - 2 \mathbf{w}^T \underbrace{\mathbf{X}^T \mathbf{y}}_{\mathbf{b}} + \underbrace{\mathbf{y}^T \mathbf{y}}_{c} \right)$$

one w only

$$E_{in}(w) = \frac{1}{N} \left(aw^2 - 2bw + c \right)$$
$$\nabla E_{in}(w) = \frac{1}{N} \left(2aw - 2b \right)$$

simple! :-)

vector w

$$E_{\text{in}}(\mathbf{w}) = \frac{1}{N} \left(\mathbf{w}^T \mathbf{A} \mathbf{w} - 2 \mathbf{w}^T \mathbf{b} + c \right)$$

$$\nabla E_{\rm in}(\mathbf{w}) = \frac{1}{N} (2\mathbf{A}\mathbf{w} - 2\mathbf{b})$$

similar (derived by definition)

$$\nabla E_{\mathsf{in}}(\mathbf{w}) = \frac{2}{N} \left(\mathbf{X}^\mathsf{T} \mathbf{X} \mathbf{w} - \mathbf{X}^\mathsf{T} \mathbf{y} \right)$$

task: find \mathbf{w}_{LIN} such that $\frac{2}{N} \left(\mathbf{X}^T \mathbf{X} \mathbf{w} - \mathbf{X}^T \mathbf{y} \right) = \nabla E_{in}(\mathbf{w}) = \mathbf{0}$

task: find
$$\mathbf{w}_{LIN}$$
 such that $\frac{2}{N} \left(\mathbf{X}^T \mathbf{X} \mathbf{w} - \mathbf{X}^T \mathbf{y} \right) = \nabla E_{in}(\mathbf{w}) = \mathbf{0}$

invertible X^TX

• easy! unique solution

$$\mathbf{w}_{\mathsf{LIN}} = \left(\mathbf{X}^{\mathsf{T}}\mathbf{X}\right)^{-1}\mathbf{X}^{\mathsf{T}} \quad \mathbf{y}$$

task: find
$$\mathbf{w}_{LIN}$$
 such that $\frac{2}{N} (\mathbf{X}^T \mathbf{X} \mathbf{w} - \mathbf{X}^T \mathbf{y}) = \nabla E_{in}(\mathbf{w}) = \mathbf{0}$

invertible X^TX

• easy! unique solution

$$\mathbf{w}_{LIN} = \underbrace{\left(\mathbf{X}^{T}\mathbf{X}\right)^{-1}\mathbf{X}^{T}}_{pseudo-inverse} \mathbf{x}^{\dagger}$$

task: find
$$\mathbf{w}_{LIN}$$
 such that $\frac{2}{N} (\mathbf{X}^T \mathbf{X} \mathbf{w} - \mathbf{X}^T \mathbf{y}) = \nabla E_{in}(\mathbf{w}) = \mathbf{0}$

invertible X^TX

easy! unique solution

$$\mathbf{w}_{LIN} = \underbrace{\left(\mathbf{X}^{T}\mathbf{X}\right)^{-1}\mathbf{X}^{T}}_{pseudo-inverse} \mathbf{x}^{\dagger}$$

• often the case because $N \gg d + 1$

task: find
$$\mathbf{w}_{LIN}$$
 such that $\frac{2}{N} (\mathbf{X}^T \mathbf{X} \mathbf{w} - \mathbf{X}^T \mathbf{y}) = \nabla E_{in}(\mathbf{w}) = \mathbf{0}$

invertible X^TX

easy! unique solution

$$\mathbf{w}_{LIN} = \underbrace{\left(\mathbf{X}^{T}\mathbf{X}\right)^{-1}\mathbf{X}^{T}}_{pseudo-inverse} \mathbf{x}^{\dagger}$$

• often the case because $N \gg d + 1$

singular X^TX

· many optimal solutions

task: find
$$\mathbf{w}_{LIN}$$
 such that $\frac{2}{N} \left(\mathbf{X}^T \mathbf{X} \mathbf{w} - \mathbf{X}^T \mathbf{y} \right) = \nabla E_{in}(\mathbf{w}) = \mathbf{0}$

invertible X^TX

easy! unique solution

$$\mathbf{w}_{LIN} = \underbrace{\left(\mathbf{X}^{T}\mathbf{X}\right)^{-1}\mathbf{X}^{T}}_{pseudo-inverse} \mathbf{x}^{\dagger}$$

• often the case because $N \gg d + 1$

singular X^TX

- many optimal solutions
- one of the solutions

$$\mathbf{w}_{\mathsf{LIN}} = \mathbf{X}^{\dagger} \mathbf{y}$$

by defining X[†] in other ways

task: find
$$\mathbf{w}_{LIN}$$
 such that $\frac{2}{N} (\mathbf{X}^T \mathbf{X} \mathbf{w} - \mathbf{X}^T \mathbf{y}) = \nabla E_{in}(\mathbf{w}) = \mathbf{0}$

invertible X^TX

easy! unique solution

$$\mathbf{w}_{\mathsf{LIN}} = \underbrace{\left(\mathbf{X}^{\mathsf{T}}\mathbf{X}\right)^{-1}\mathbf{X}^{\mathsf{T}}}_{\mathsf{pseudo-inverse}} \mathbf{x}^{\dagger}$$

• often the case because $N \gg d + 1$

singular X^TX

- many optimal solutions
- · one of the solutions

$$\mathbf{w}_{\mathsf{LIN}} = \mathbf{X}^{\dagger} \mathbf{y}$$

by defining X^{\dagger} in other ways

practical suggestion:

 $\label{eq:continuous} \text{use } \frac{\text{well-implemented}}{\text{instead of}} \frac{\dagger}{\left(X^T X\right)^{-1}} \frac{\dagger}{X^T} \\ \text{for numerical stability when } \frac{\dagger}{\text{almost-singular}}$

1 from \mathcal{D} , construct input matrix X and output vector y by

$$X = \underbrace{\begin{bmatrix} --\mathbf{x}_{1}^{T} - - \\ --\mathbf{x}_{2}^{T} - - \\ \cdots \\ --\mathbf{x}_{N}^{T} - - \end{bmatrix}}_{N \times (d+1)} \quad \mathbf{y} = \underbrace{\begin{bmatrix} y_{1} \\ y_{2} \\ \cdots \\ y_{N} \end{bmatrix}}_{N \times 1}$$

1 from \mathcal{D} , construct input matrix \mathbf{X} and output vector \mathbf{y} by

$$X = \underbrace{\begin{bmatrix} --\mathbf{x}_{1}^{T} - - \\ --\mathbf{x}_{2}^{T} - - \\ \cdots \\ --\mathbf{x}_{N}^{T} - - \end{bmatrix}}_{N \times (d+1)} \quad \mathbf{y} = \underbrace{\begin{bmatrix} y_{1} \\ y_{2} \\ \cdots \\ y_{N} \end{bmatrix}}_{N \times 1}$$

2 calculate pseudo-inverse X^{\dagger}

1 from \mathcal{D} , construct input matrix \mathbf{X} and output vector \mathbf{y} by

$$X = \underbrace{\begin{bmatrix} --\mathbf{x}_{1}^{T} - - \\ --\mathbf{x}_{2}^{T} - - \\ \cdots \\ --\mathbf{x}_{N}^{T} - - \end{bmatrix}}_{N \times (d+1)} \quad \mathbf{y} = \underbrace{\begin{bmatrix} y_{1} \\ y_{2} \\ \cdots \\ y_{N} \end{bmatrix}}_{N \times 1}$$

- 2 calculate pseudo-inverse X^{\dagger} $(d+1)\times N$

1 from \mathcal{D} , construct input matrix \mathbf{X} and output vector \mathbf{y} by

$$X = \underbrace{\begin{bmatrix} --\mathbf{x}_{1}^{T} - - \\ --\mathbf{x}_{2}^{T} - - \\ \cdots \\ --\mathbf{x}_{N}^{T} - - \end{bmatrix}}_{N \times (d+1)} \quad \mathbf{y} = \underbrace{\begin{bmatrix} y_{1} \\ y_{2} \\ \cdots \\ y_{N} \end{bmatrix}}_{N \times 1}$$

- 2 calculate pseudo-inverse X^{\dagger} $(d+1)\times N$
- 3 return $\underbrace{\mathbf{w}_{LIN}}_{(d+1)\times 1} = \mathbf{X}^{\dagger}\mathbf{y}$

simple and efficient with good † routine

Fun Time

After getting \mathbf{w}_{LIN} , we can calculate the predictions $\hat{y}_n = \mathbf{w}_{LIN}^T \mathbf{x}_n$. If all \hat{y}_n are collected in a vector $\hat{\mathbf{y}}$ similar to how we form \mathbf{y} , what is the matrix formula of $\hat{\mathbf{y}}$?

- **1** y
- $2 XX^T y$
- 3 XX[†]y
- $\mathbf{4} \mathbf{X} \mathbf{X}^{\dagger} \mathbf{X} \mathbf{X}^{T} \mathbf{y}$

Fun Time

After getting \mathbf{w}_{LIN} , we can calculate the predictions $\hat{y}_n = \mathbf{w}_{LIN}^T \mathbf{x}_n$. If all \hat{y}_n are collected in a vector $\hat{\mathbf{y}}$ similar to how we form \mathbf{y} , what is the matrix formula of $\hat{\mathbf{y}}$?

- **1** y
- $2 XX^T y$
- 3 XX[†]y
- $\mathbf{4} \mathbf{X} \mathbf{X}^{\dagger} \mathbf{X} \mathbf{X}^{T} \mathbf{y}$

Reference Answer: (3)

Note that $\hat{\mathbf{y}} = \mathbf{X}\mathbf{w}_{LIN}$. Then, a simple substitution of \mathbf{w}_{LIN} reveals the answer.

$$\mathbf{w}_{\mathsf{LIN}} = \mathbf{X}^{\dagger} \mathbf{y}$$

$$\boldsymbol{w}_{\text{LIN}} = \boldsymbol{X}^{\dagger}\boldsymbol{y}$$

No!

 analytic (closed-form) solution, 'instantaneous'

$$\mathbf{w}_{\mathsf{LIN}} = \mathbf{X}^{\dagger} \mathbf{y}$$

No!

- analytic (closed-form) solution, 'instantaneous'
- not improving E_{in} nor E_{out} iteratively

$$\mathbf{w}_{\mathsf{LIN}} = \mathbf{X}^{\dagger} \mathbf{y}$$

No!

- analytic (closed-form) solution, 'instantaneous'
- not improving E_{in} nor Eout iteratively

Yes!

• good *E*_{in}? yes, optimal!

$$\mathbf{w}_{\mathsf{LIN}} = \mathbf{X}^{\dagger} \mathbf{y}$$

No!

- analytic (closed-form) solution, 'instantaneous'
- not improving E_{in} nor E_{out} iteratively

Yes!

- good E_{in}?yes, optimal!
- good E_{out}?
 yes, finite d_{VC} like perceptrons

$$\mathbf{w}_{\mathsf{LIN}} = \mathbf{X}^{\dagger} \mathbf{y}$$

No!

- analytic (closed-form) solution, 'instantaneous'
- not improving E_{in} nor E_{out} iteratively

Yes!

- good E_{in}?yes, optimal!
- good E_{out}?
 yes, finite d_{VC} like perceptrons
- improving iteratively?
 somewhat, within an iterative pseudo-inverse routine

$$\mathbf{w}_{\mathsf{LIN}} = \mathbf{X}^{\dagger} \mathbf{y}$$

No!

- analytic (closed-form) solution, 'instantaneous'
- not improving E_{in} nor E_{out} iteratively

Yes!

- good E_{in}?yes, optimal!
- good E_{out}?
 yes, finite d_{VC} like perceptrons
- improving iteratively?
 somewhat, within an iterative pseudo-inverse routine

if $E_{out}(\mathbf{w}_{LIN})$ is good, learning 'happened'!

$$\overline{E_{\text{in}}} \ = \ \underset{\mathcal{D} \sim P^N}{\mathcal{E}} \Big\{ E_{\text{in}}(\mathbf{w}_{\text{LIN}} \text{ w.r.t. } \mathcal{D}) \Big\}$$

$$\overline{E_{\text{in}}} = \underset{\mathcal{D} \sim P^N}{\mathcal{E}} \Big\{ E_{\text{in}}(\mathbf{w}_{\text{LIN}} \text{ w.r.t. } \mathcal{D}) \Big\} \stackrel{\text{to be shown}}{=} \text{noise level} \cdot \left(1 - \frac{d+1}{N}\right)$$

$$\overline{E_{\text{in}}} = \underset{\mathcal{D} \sim P^N}{\mathcal{E}} \Big\{ E_{\text{in}}(\mathbf{w}_{\text{LIN}} \text{ w.r.t. } \mathcal{D}) \Big\} \overset{\text{to be shown}}{=} \text{noise level} \cdot (1 - \frac{d+1}{N})$$

$$E_{\text{in}}(\mathbf{w}_{\text{LIN}}) = \frac{1}{N} \|\mathbf{y} - \hat{\mathbf{y}}\|^2$$

predictions

$$\overline{E_{\text{in}}} = \underset{\mathcal{D} \sim P^N}{\mathcal{E}} \Big\{ E_{\text{in}}(\mathbf{w}_{\text{LIN}} \text{ w.r.t. } \mathcal{D}) \Big\} \overset{\text{to be shown}}{=} \text{noise level} \cdot \left(1 - \frac{d+1}{N}\right)$$

$$E_{\text{in}}(\mathbf{w}_{\text{LIN}}) = \frac{1}{N} \|\mathbf{y} - \hat{\mathbf{y}}_{\text{predictions}}\|^2 = \frac{1}{N} \|\mathbf{y} - \mathbf{X} \mathbf{X}^{\dagger} \mathbf{y}\|^2$$

$$\overline{E_{\text{in}}} = \underbrace{\mathcal{E}_{\mathcal{D} \sim P^N}}_{\mathcal{D} \sim P^N} \left\{ E_{\text{in}}(\mathbf{w}_{\text{LIN}} \ \mathbf{w.r.t.} \ \mathcal{D}) \right\}^{\text{to be shown}} \text{ noise level} \cdot \left(1 - \frac{d+1}{N}\right)$$

$$E_{\text{in}}(\mathbf{w}_{\text{LIN}}) = \frac{1}{N} \|\mathbf{y} - \underbrace{\hat{\mathbf{y}}}_{\text{predictions}}\|^2 = \frac{1}{N} \|\mathbf{y} - \underbrace{\mathbf{X}^{\dagger} \mathbf{y}}_{\mathbf{w}_{\text{LIN}}}\|^2$$

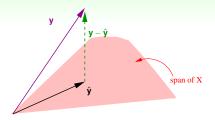
$$= \frac{1}{N} \|(\underbrace{\mathbf{I}}_{\text{identity}} - \mathbf{X} \mathbf{X}^{\dagger}) \mathbf{y}\|^2$$

$$\overline{E_{\text{in}}} = \underbrace{\mathcal{E}}_{\mathcal{D} \sim P^N} \left\{ E_{\text{in}}(\mathbf{w}_{\text{LIN}} \text{ w.r.t. } \mathcal{D}) \right\}^{\text{to be shown}} \text{ noise level} \cdot \left(1 - \frac{d+1}{N}\right)$$

$$E_{\text{in}}(\mathbf{w}_{\text{LIN}}) = \frac{1}{N} \|\mathbf{y} - \underbrace{\hat{\mathbf{y}}}_{\text{predictions}}\|^2 = \frac{1}{N} \|\mathbf{y} - \mathbf{X} \underbrace{\mathbf{X}^{\dagger} \mathbf{y}}_{\mathbf{w}_{\text{LIN}}}\|^2$$

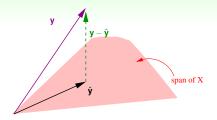
$$= \frac{1}{N} \|(\underbrace{\mathbf{I}}_{\text{identity}} - \mathbf{X} \mathbf{X}^{\dagger}) \mathbf{y}\|^2$$

call XX^{\dagger} the hat matrix H because it puts \wedge on y



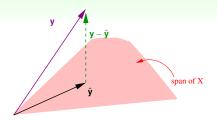
in \mathbb{R}^N

• $\hat{\mathbf{y}} = \mathbf{X}\mathbf{w}_{\mathsf{LIN}}$ within the span of X columns



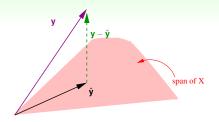
in \mathbb{R}^N

- $\hat{\mathbf{y}} = \mathbf{X}\mathbf{w}_{\mathsf{LIN}}$ within the span of X columns
- $\mathbf{y} \hat{\mathbf{y}}$ smallest: $\mathbf{y} \hat{\mathbf{y}} \perp \mathbf{span}$



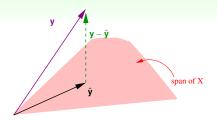
in \mathbb{R}^N

- $\hat{\mathbf{y}} = \mathbf{X}\mathbf{w}_{LIN}$ within the span of X columns
- $\mathbf{y} \hat{\mathbf{y}}$ smallest: $\mathbf{y} \hat{\mathbf{y}} \perp \mathbf{span}$
- H: project y to ŷ ∈ span



in \mathbb{R}^N

- $\hat{\mathbf{y}} = \mathbf{X}\mathbf{w}_{LIN}$ within the span of X columns
- $\mathbf{y} \hat{\mathbf{y}}$ smallest: $\mathbf{y} \hat{\mathbf{y}} \perp \mathbf{span}$
- H: project y to ŷ ∈ span
- I H: transform y to y $\hat{y} \perp span$

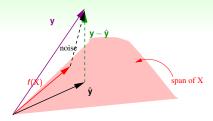


in \mathbb{R}^N

- $\hat{\mathbf{y}} = \mathbf{X}\mathbf{w}_{\mathsf{LIN}}$ within the span of X columns
- $\mathbf{y} \hat{\mathbf{y}}$ smallest: $\mathbf{y} \hat{\mathbf{y}} \perp \mathbf{span}$
- H: project y to ŷ ∈ span
- I H: transform y to y $\hat{y} \perp span$

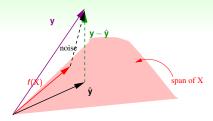
claim: trace(I - H) = N - (d + 1). Why? :-)

An Illustrative 'Proof'

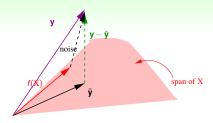


• if y comes from some ideal $f(X) \in \text{span}$ plus noise

An Illustrative 'Proof'

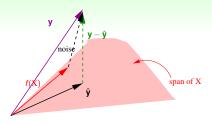


- if y comes from some ideal $f(X) \in \text{span}$ plus **noise**
- **noise** transformed by I H to be $y \hat{y}$



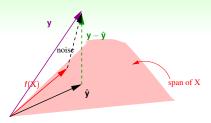
- if y comes from some ideal $f(X) \in \text{span}$ plus noise
- **noise** transformed by I H to be $y \hat{y}$

$$E_{\text{in}}(\mathbf{w}_{\text{LIN}}) = \frac{1}{N} \|\mathbf{y} - \hat{\mathbf{y}}\|^2 = \frac{1}{N} \|(\mathbf{I} - \mathbf{H}) \mathbf{noise}\|^2$$



- if y comes from some ideal $f(X) \in \text{span}$ plus noise
- **noise** transformed by I H to be $y \hat{y}$

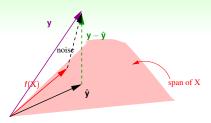
$$\begin{split} E_{\text{in}}(\mathbf{w}_{\text{LIN}}) &= \frac{1}{N} \|\mathbf{y} - \hat{\mathbf{y}}\|^2 &= \frac{1}{N} \|(\mathbf{I} - \mathbf{H}) \mathbf{noise}\|^2 \\ &= \frac{1}{N} (N - (d+1)) \|\mathbf{noise}\|^2 \end{split}$$



- if y comes from some ideal $f(X) \in \text{span}$ plus **noise**
- **noise** transformed by I H to be $y \hat{y}$

$$\begin{split} E_{\text{in}}(\mathbf{w}_{\text{LIN}}) &= \frac{1}{N} \|\mathbf{y} - \hat{\mathbf{y}}\|^2 &= \frac{1}{N} \|(\mathbf{I} - \mathbf{H}) \mathbf{noise}\|^2 \\ &= \frac{1}{N} (N - (d+1)) \|\mathbf{noise}\|^2 \end{split}$$

$$\overline{E_{\text{in}}} = \text{noise} \ \text{level} \cdot \left(1 - \frac{d+1}{N}\right)$$



- if y comes from some ideal $f(X) \in \text{span}$ plus **noise**
- **noise** transformed by I H to be $y \hat{y}$

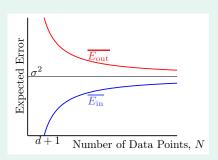
$$\begin{split} E_{\text{in}}(\mathbf{w}_{\text{LIN}}) &= \frac{1}{N} \|\mathbf{y} - \hat{\mathbf{y}}\|^2 &= \frac{1}{N} \|(\mathbf{I} - \mathbf{H}) \mathbf{noise}\|^2 \\ &= \frac{1}{N} (N - (d+1)) \|\mathbf{noise}\|^2 \end{split}$$

$$\overline{E_{\text{in}}} = \text{noise level} \cdot \left(1 - \frac{d+1}{N}\right)$$

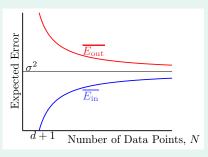
$$\overline{E_{\text{out}}} = \text{noise level} \cdot \left(1 + \frac{d+1}{N}\right) \text{(complicated!)}$$

$$\overline{\underline{E}_{\text{out}}} = \text{noise level} \cdot \left(1 + \frac{d+1}{N}\right)$$

$$\overline{\underline{E}_{\text{in}}} = \text{noise level} \cdot \left(1 - \frac{d+1}{N}\right)$$



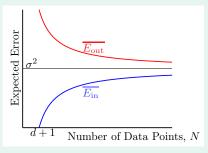
$$\overline{E_{\text{out}}} = \text{noise level} \cdot \left(1 + \frac{d+1}{N}\right)$$
 $\overline{E_{\text{in}}} = \text{noise level} \cdot \left(1 - \frac{d+1}{N}\right)$



• both converge to σ^2 (**noise** level) for $N \to \infty$

$$\overline{E_{\text{out}}} = \text{noise level} \cdot \left(1 + \frac{d+1}{N}\right)$$

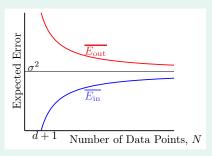
$$\overline{E_{\text{in}}} = \text{noise level} \cdot \left(1 - \frac{d+1}{N}\right)$$



- both converge to σ^2 (**noise** level) for $N \to \infty$
- expected generalization error: ^{2(d+1)}/_N
 —similar to worst-case quarantee from VC

$$\overline{E_{\text{out}}} = \text{noise level} \cdot \left(1 + \frac{d+1}{N}\right)$$

 $\overline{E_{\text{in}}} = \text{noise level} \cdot \left(1 - \frac{d+1}{N}\right)$



- both converge to σ^2 (**noise** level) for $N \to \infty$
- expected generalization error: ^{2(d+1)}/_N
 —similar to worst-case quarantee from VC

linear regression (LinReg): learning 'happened'!

Fun Time

Which of the following property about H is not true?

- 1 H is symmetric
- $2 H^2 = H$ (double projection = single one)
- (3) $(I H)^2 = I H$ (double residual transform = single one)
- 4 none of the above

Fun Time

Which of the following property about H is not true?

- 1 H is symmetric
- 2 $H^2 = H$ (double projection = single one)
- (3) $(I H)^2 = I H$ (double residual transform = single one)
- 4 none of the above

Reference Answer: (4)

You can conclude that (2) and (3) are true by their physical meanings! :-)

Linear Classification

$$\mathcal{Y} = \{-1, +1\}$$

 $h(\mathbf{x}) = \text{sign}(\mathbf{w}^T \mathbf{x})$
 $\text{err}(\hat{y}, y) = [\hat{y} \neq y]$

NP-hard to solve in general

Linear Classification

$$\mathcal{Y} = \{-1, +1\}$$

$$h(\mathbf{x}) = \operatorname{sign}(\mathbf{w}^{T}\mathbf{x})$$

$$\operatorname{err}(\hat{y}, y) = [\hat{y} \neq y]$$

NP-hard to solve in general

Linear Regression

$$\mathcal{Y} = \mathbb{R}
h(\mathbf{x}) = \mathbf{w}^T \mathbf{x}
\operatorname{err}(\hat{y}, y) = (\hat{y} - y)^2$$

efficient analytic solution

Linear Classification

$$\mathcal{Y} = \{-1, +1\}$$

$$h(\mathbf{x}) = \operatorname{sign}(\mathbf{w}^T \mathbf{x})$$

$$\operatorname{err}(\hat{y}, y) = [[\hat{y} \neq y]]$$

NP-hard to solve in general

Linear Regression

$$\mathcal{Y} = \mathbb{R}$$

$$h(\mathbf{x}) = \mathbf{w}^T \mathbf{x}$$

$$\operatorname{err}(\hat{y}, y) = (\hat{y} - y)^2$$

efficient analytic solution

$$\{-1,+1\}\subset\mathbb{R}$$

Linear Classification

$$\mathcal{Y} = \{-1, +1\}$$

$$h(\mathbf{x}) = \operatorname{sign}(\mathbf{w}^T \mathbf{x})$$

$$\operatorname{err}(\hat{y}, y) = [[\hat{y} \neq y]]$$

NP-hard to solve in general

Linear Regression

$$\mathcal{Y} = \mathbb{R}$$

$$h(\mathbf{x}) = \mathbf{w}^T \mathbf{x}$$

$$\operatorname{err}(\hat{y}, y) = (\hat{y} - y)^2$$

efficient analytic solution

 $\{-1, +1\} \subset \mathbb{R}$: linear regression for classification?

Linear Classification

$$\mathcal{Y} = \{-1, +1\}$$

$$h(\mathbf{x}) = \operatorname{sign}(\mathbf{w}^T \mathbf{x})$$

$$\operatorname{err}(\hat{y}, y) = [[\hat{y} \neq y]]$$

NP-hard to solve in general

Linear Regression

$$\mathcal{Y} = \mathbb{R}$$

$$h(\mathbf{x}) = \mathbf{w}^T \mathbf{x}$$

$$\operatorname{err}(\hat{y}, y) = (\hat{y} - y)^2$$

efficient analytic solution

$$\{-1, +1\} \subset \mathbb{R}$$
: linear regression for classification?

 \bigcirc run LinReg on binary classification data \mathcal{D} (efficient)

Linear Classification

$$\mathcal{Y} = \{-1, +1\}$$

$$h(\mathbf{x}) = \operatorname{sign}(\mathbf{w}^T \mathbf{x})$$

$$\operatorname{err}(\hat{y}, y) = [[\hat{y} \neq y]]$$

NP-hard to solve in general

Linear Regression

$$\mathcal{Y} = \mathbb{R}$$

$$h(\mathbf{x}) = \mathbf{w}^T \mathbf{x}$$

$$err(\hat{y}, y) = (\hat{y} - y)^2$$

efficient analytic solution

 $\{-1,+1\} \subset \mathbb{R}$: linear regression for classification?

- \bigcirc run LinReg on binary classification data \mathcal{D} (efficient)
- 2 return $g(\mathbf{x}) = \text{sign}(\mathbf{w}_{\text{LIN}}^T \mathbf{x})$

Linear Classification

$$\mathcal{Y} = \{-1, +1\}$$

 $h(\mathbf{x}) = \text{sign}(\mathbf{w}^T \mathbf{x})$
 $\text{err}(\hat{y}, y) = [\hat{y} \neq y]$

NP-hard to solve in general

Linear Regression

$$\mathcal{Y} = \mathbb{R}$$

$$h(\mathbf{x}) = \mathbf{w}^T \mathbf{x}$$

$$\operatorname{err}(\hat{y}, y) = (\hat{y} - y)^2$$

efficient analytic solution

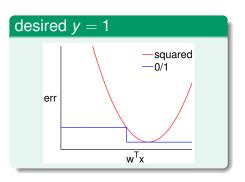
$$\{-1,+1\}\subset\mathbb{R}$$
: linear regression for classification?

- 1 run LinReg on binary classification data \mathcal{D} (efficient)
- 2 return $g(\mathbf{x}) = \text{sign}(\mathbf{w}_{11N}^T \mathbf{x})$

but explanation of this heuristic?

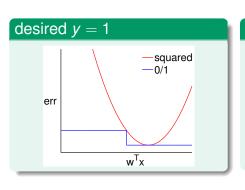
$$\operatorname{err}_{0/1} = \left[\operatorname{sign}(\mathbf{w}^T \mathbf{x}) \neq y \right] \quad \operatorname{err}_{\operatorname{sqr}} = \left(\mathbf{w}^T \mathbf{x} - y \right)^2$$

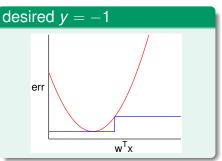
$$\operatorname{err}_{0/1} = \left[\operatorname{sign}(\mathbf{w}^T \mathbf{x}) \neq y \right] \quad \operatorname{err}_{\operatorname{sqr}} = \left(\mathbf{w}^T \mathbf{x} - y \right)^2$$



$$\operatorname{err}_{0/1} = \left[\operatorname{sign}(\mathbf{w}^T \mathbf{x}) \neq y \right] \quad \operatorname{err}_{\operatorname{sqr}} = \left(\mathbf{w}^T \mathbf{x} - y \right)^2$$

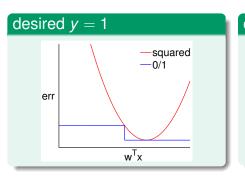
$$\operatorname{err}_{\mathsf{sqr}} = \left(\mathbf{w}^\mathsf{T}\mathbf{x} - y\right)^2$$

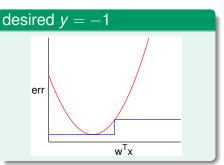




$$\operatorname{err}_{0/1} = \left[\operatorname{sign}(\mathbf{w}^T\mathbf{x}) \neq y\right] \quad \operatorname{err}_{\operatorname{sqr}} = \left(\mathbf{w}^T\mathbf{x} - y\right)^2$$

$$\operatorname{err}_{\mathsf{sqr}} = \left(\mathbf{w}^\mathsf{T}\mathbf{x} - y\right)^2$$





$$err_{0/1} \leq err_{sqr}$$

 $err_{0/1} \le err_{sqr}$

$$err_{0/1} \le err_{sqr}$$

classification
$$E_{out}(\mathbf{w}) \stackrel{VC}{\leq} classification $E_{in}(\mathbf{w}) + \sqrt{\dots}$$$

$$err_{0/1} \le err_{sqr}$$

classification
$$E_{out}(\mathbf{w}) \stackrel{VC}{\leq} classification $E_{in}(\mathbf{w}) + \sqrt{\dots}$
 $\leq regression E_{in}(\mathbf{w}) + \sqrt{\dots}$$$

$$err_{0/1} \le err_{sqr}$$

classification
$$E_{out}(\mathbf{w}) \stackrel{VC}{\leq} classification $E_{in}(\mathbf{w}) + \sqrt{\dots}$
 $\leq regression E_{in}(\mathbf{w}) + \sqrt{\dots}$$$

(loose) upper bound err_{sqr} as err to approximate err_{0/1}

$$err_{0/1} \le err_{sqr}$$

```
classification E_{out}(\mathbf{w}) \stackrel{VC}{\leq} classification <math>E_{in}(\mathbf{w}) + \sqrt{\dots}
\leq regression E_{in}(\mathbf{w}) + \sqrt{\dots}
```

- (loose) upper bound errsqr as err to approximate err_{0/1}
- trade bound tightness for efficiency

$$err_{0/1} \le err_{sqr}$$

```
classification E_{out}(\mathbf{w}) \stackrel{VC}{\leq} classification <math>E_{in}(\mathbf{w}) + \sqrt{\dots}
\leq regression E_{in}(\mathbf{w}) + \sqrt{\dots}
```

- (loose) upper bound err_{sqr} as err to approximate err_{0/1}
- trade bound tightness for efficiency

w_{LIN}: useful baseline classifier, or as **initial PLA/pocket vector**

Fun Time

Which of the following functions are upper bounds of the pointwise 0/1 error $\|\operatorname{sign}(\mathbf{w}^T\mathbf{x}) \neq y\|$ for $y \in \{-1, +1\}$?

- $\mathbf{0} \exp(-y\mathbf{w}^T\mathbf{x})$
- **2** $\max(0, 1 y \mathbf{w}^T \mathbf{x})$
- 4 all of the above

Fun Time

Which of the following functions are upper bounds of the pointwise 0/1 error $\llbracket \text{sign}(\mathbf{w}^T\mathbf{x}) \neq y \rrbracket$ for $y \in \{-1, +1\}$?

- $\mathbf{0} \exp(-y\mathbf{w}^T\mathbf{x})$
- **2** $\max(0, 1 y \mathbf{w}^T \mathbf{x})$
- 3 $\log_2(1 + \exp(-y\mathbf{w}^T\mathbf{x}))$
- 4 all of the above

Reference Answer: 4

Plot the curves and you'll see. Thus, all three can be used for binary classification. In fact, all three functions connect to very important algorithms in machine learning and we will discuss one of them soon in the next lecture.

Stay tuned.:-)

Summary

- When Can Machines Learn?
- 2 Why Can Machines Learn?

Lecture 8: Noise and Error

3 How Can Machines Learn?

Lecture 9: Linear Regression

- Linear Regression Problem
 use hyperplanes to approximate real values
- Linear Regression Algorithm
 analytic solution with pseudo-inverse
- Generalization Issue

$$E_{\rm out} - E_{\rm in} \approx \frac{2(d+1)}{N}$$
 on average

- Linear Regression for Binary Classification
 - 0/1 error \leq squared error
- next: binary classification, regression, and then?
- 4 How Can Machines Learn Better?