

Large Network Autoregressions with Unknown Adjacency Matrix

Kenwin Maung¹

¹University of Rochester

Motivation

Economic **networks**:

- **cross-sectional dependence** and (spatial) **interactions**
- **between** economic **units** (agents) or **variables**

Motivation

Economic **networks**:

- **cross-sectional dependence** and (spatial) **interactions**
- **between** economic **units** (agents) or **variables**

Significance:

- Manifest when agents/variables interact; **encodes information about economic behavior**
- **Scale** and **type** of interconnectivity will expand: *social media, financial integration, trade liberalization etc.*
- **Applications**: asset pricing (Ahern, 2013), exchange rates (Richmond, 2019), firm growth (Allen et al, 2019), corporate finance (Gofman and Wu, 2022) etc.

Estimate networks in a large N large T framework using a Network Autoregression (Zhu et al. 2018, Chen, 2020):

$$Y_t = \beta_0 W_0 Y_t + \beta_1 W Y_{t-1} + \dots + \beta_P W Y_{t-P} + \tilde{u}_t$$

β_0 : contemporaneous network effect;

β_j : dynamic network effect;

W : $N \times N$ adjacency matrix;

W_0 : W with 0s on diagonal;

Estimate networks in a **large N large T** framework using a **Network Autoregression** (Zhu et al. 2018, Chen, 2020):

$$Y_t = \beta_0 W_0 Y_t + \beta_1 W Y_{t-1} + \dots + \beta_P W Y_{t-P} + \tilde{u}_t$$

β_0 : contemporaneous network effect;

β_j : dynamic network effect;

W : $N \times N$ adjacency matrix;

W_0 : W with 0s on diagonal;

Key contribution: Estimation without knowing W beforehand

Solution 1: Sparsity

- **Sparsity:** Assume many coefficients actually 0.
- Estimate with shrinkage (e.g. Lasso, SCAD).

Limitation

- Strong assumption in many applications. E.g. international trade networks are dense (De Benedictis and Tajoli, 2011).

Solution 2: (Weighted) Aggregation

Reduce dimension using spatial weights:

Dynamic spatial Durbin model; **Global VAR** (Pesaran et al, 2004); **Infinite-dimensional VAR** (Chudik and Pesaran, 2011); **Stochastic block VAR** (Guðmundsson and Brownlees, 2021); **Network autoregression** (Zhu et al, 2018)

Solution 2: (Weighted) Aggregation

Reduce dimension using spatial weights:

Dynamic spatial Durbin model; **Global VAR** (Pesaran et al, 2004); **Infinite-dimensional VAR** (Chudik and Pesaran, 2011); **Stochastic block VAR** (Guðmundsson and Brownlees, 2021); **Network autoregression** (Zhu et al, 2018)

Complications:

- Do all applications have natural spatial weights?
- How to specify weights? Ad-hoc?

Proposed solution

Treat adjacency matrix, W , as unknown and estimate it. But W is $N \times N$.

Focus on **centralities** (low-rank representations):

- **Position** and **influence** of nodes (units) in the network
- **Hub** and **Authority** centralities

Proposed solution

Hub and **Authority** centralities:

A node is an authority if it is linked to by hubs; it is a hub if it links to authorities.

Webpage network:

- Hub score of a node depends on the total authority score of web pages it links to;
- Authority score of a webpage depends on total hub score of the webpages it receives links from;

Proposed solution

Given adjacency matrix W , hub and authority centralities are extracted as left and right singular vectors of W .

Cai et al. (2021) model this as:

$$W = dab^{\top}$$

d : scalar; a, b : $N \times 1$ vector.

Implication: N^2 coefficients in $W \Rightarrow N + N$ coefficients.

Model framework

Network autoregression with P lags:

$$Y_t = \beta_0 W_0 Y_t + \beta_1 W Y_{t-1} + \dots + \beta_P W Y_{t-P} + \tilde{u}_t$$

Model framework

Network autoregression with P lags:

$$\begin{aligned}Y_t &= \beta_0 W_0 Y_t + \beta_1 W Y_{t-1} + \dots + \beta_P W Y_{t-P} + \tilde{u}_t \\(I - \beta_0 W_0) Y_t &= \beta_1 W Y_{t-1} + \dots + \beta_P W Y_{t-P} + \tilde{u}_t \\&\equiv W \mathcal{Y}_{t-P}^{t-1} \beta + \tilde{u}_t \\&= \tilde{a} \tilde{b}^\top \mathcal{Y}_{t-P}^{t-1} \beta + \tilde{u}_t\end{aligned}$$

where

$$\mathcal{Y}_{t-P}^{t-1} = [Y_{t-1}, \dots, Y_{t-P}]$$

is a $N \times P$ matrix.

Model framework

Network autoregression with P lags:

$$\begin{aligned}Y_t &= \beta_0 W_0 Y_t + \beta_1 W Y_{t-1} + \dots + \beta_P W Y_{t-P} + \tilde{u}_t \\(I - \beta_0 W_0) Y_t &= \beta_1 W Y_{t-1} + \dots + \beta_P W Y_{t-P} + \tilde{u}_t \\&\equiv W \mathcal{Y}_{t-P}^{t-1} \beta + \tilde{u}_t \\&= \tilde{a} \tilde{b}^\top \mathcal{Y}_{t-P}^{t-1} \beta + \tilde{u}_t\end{aligned}$$

where

$$\mathcal{Y}_{t-P}^{t-1} = [Y_{t-1}, \dots, Y_{t-P}]$$

is a $N \times P$ matrix.

Furthermore,

$$\tilde{u}_t = \tilde{\Lambda} f_t + \tilde{\varepsilon}_t,$$

f_t : r common shocks;

$\tilde{\varepsilon}_t$: N idiosyncratic shocks;

Two-step Estimation

Reduced form:

$$\begin{aligned} Y_t &= (I - \beta_0 W_0)^{-1} W \mathcal{Y}_{t-P}^{t-1} \beta + (I - \beta_0 W_0)^{-1} \tilde{\Lambda} f_t + (I - \beta_0 W_0)^{-1} \tilde{\varepsilon}_t \\ &\equiv A \mathcal{Y}_{t-P}^{t-1} \beta + \Lambda f_t + \varepsilon_t \\ &\equiv ab^\top \mathcal{Y}_{t-P}^{t-1} \beta + u_t \end{aligned}$$

* $\text{rank}(A) = \text{rank}(W)$ since $(I - \beta_0 W_0)^{-1}$ is fullrank.,

Identification: Normalize $\|A\|_F = \|a\|_2 \|b\|_2 = 1$.

Two-step Estimation

$$Y_t = ab^{\top} \mathcal{Y}_{t-P}^{t-1} \beta + u_t$$

* u_t is uncorrelated over time

Iterative least squares: Step 1

1. Guess $\hat{\beta}^{(m)}, \hat{b}^{(m)}$;

2. Estimate

$$\hat{a}^{(m+1)} = (\sum_t Y_t \hat{\beta}^{(m)\top} \mathcal{Y}_{t-P}^{t-1\top} \hat{b}^{(m)}) (\sum_t \hat{b}^{(m)\top} \mathcal{Y}_{t-P}^{t-1} \hat{\beta}^{(m)} \hat{\beta}^{(m)\top} \mathcal{Y}_{t-P}^{t-1\top} \hat{b}^{(m)})^{-1};$$

3. Update

$$\hat{b}^{(m+1)} = (\sum_t \hat{a}^{(m+1)\top} Y_t \hat{\beta}^{(m)\top} \mathcal{Y}_{t-P}^{t-1\top}) (\sum_t \mathcal{Y}_{t-P}^{t-1} \hat{\beta}^{(m)} \hat{\beta}^{(m)\top} \mathcal{Y}_{t-P}^{t-1\top})^{-1};$$

4. Update $\hat{\beta}^{(m+1)} =$

$$(\sum_t \mathcal{Y}_{t-P}^{t-1\top} \hat{b}^{(m+1)} \hat{a}^{(m+1)\top} \hat{a}^{(m+1)} \hat{b}^{(m+1)\top} \mathcal{Y}_{t-P}^{t-1})^{-1} (\sum_t \mathcal{Y}_{t-P}^{t-1\top} \hat{b}^{(m+1)} \hat{a}^{(m+1)\top} Y_t);$$

5. Repeat until convergence.

Two-step Estimation

$$Y_t = ab^\top \mathcal{Y}_{t-P}^{t-1} \beta + u_t$$

* u_t is uncorrelated over time

Principal components analysis: Step 2

1. Define $\hat{Y}_t = Y_t - \hat{a}\hat{b}^\top \mathcal{Y}_{t-P}^{t-1} \hat{\beta}$ and we have a pure factor model:

$$\begin{aligned}\hat{Y}_t &= u_t \\ &= \Lambda f_t + \varepsilon_t\end{aligned}$$

2. Let $\hat{Y} = [\hat{Y}_{P+1}, \dots, \hat{Y}_T]^\top$,

estimator of $F \left(= [f_{P+1}^\top, \dots, f_T^\top] \right) = r$ eigenvectors of $\frac{\hat{Y}^\top \hat{Y}}{(T-P)}$;

3. Estimate

$$\hat{\Lambda} = \frac{\hat{Y}^\top \hat{F}}{T-P}.$$

Asymptotic theory: Assumptions (1)

Assumption 1 (Composite errors) (i) f_t is a zero mean stationary white noise processes; (ii) $\|\varepsilon_t\| = O(\sqrt{N})$ almost surely; (iii) $f_t \perp \varepsilon_t$.

Assumption 2 (Factor structure) Normalize $F^\top F / T = I_r$ where $F = [f_1, \dots, f_T]^\top$ and let $\Lambda^\top \Lambda$ be a diagonal matrix. Assume

- (i) $E\|f_t\|^4 \leq C_f < \infty$, $\frac{1}{T} \sum_{t=1}^T f_t f_t^\top \rightarrow^p \Sigma_f > 0$ as $T \rightarrow \infty$ for some $r \times r$ matrix Σ_f ,
- (ii) $\|\lambda_i\| \leq C_\lambda < \infty$ where λ_i is the i^{th} row of Λ , $\frac{1}{N} \Lambda^\top \Lambda \rightarrow \Sigma_\lambda > 0$ as $N \rightarrow \infty$ for some $r \times r$ matrix Σ_λ .

Asymptotic theory: Assumptions (2)

Assumption 3 (Stationarity) Normalize $\|A\|_F = 1$ and define β_j to be the j -th element of β . Assume the following stability condition holds for $P \geq 1$: The roots of the P -th order polynomial equation

$$z^P - |\beta_1|z^{P-1} - |\beta_2|z^{P-2} - \dots - |\beta_{P-1}|z^1 - |\beta_P| = 0$$

lie inside the unit circle.

Assumption 4 (Rates) Let $N, T, P \rightarrow \infty$ and assume that

$$\frac{N \log N}{T - P} \rightarrow 0.$$

Proposition

Under Assumptions 1-3, the (reduced form) model is stable.

Theorem

Under Assumptions 1-3, and with $A = ab^\top$, we have:

$$\left\| \hat{\beta}^\top \otimes \hat{a}\hat{b}^\top - \beta^\top \otimes ab^\top \right\|_S \rightarrow^P 0;$$

Alternatively, without assuming $A = ab^\top$ instead, we get:

$$\left\| \hat{\beta}^\top \otimes \hat{A} - \beta^\top \otimes A \right\|_S \rightarrow^P 0,$$

where $\|\cdot\|_S$ refers to the spectral norm of a matrix.

Theorem

Let $L_{N,P}$ be a $q \times (2N + P)$ non-stochastic matrix such that $L_{N,P} L_{N,P}^\top \rightarrow L$ where L is some $q \times q$ non-negative symmetric matrix, for a finite q . Define $\hat{\theta} = (\hat{a}, \hat{b}, \hat{\beta}^\top)^\top$. Given Assumptions 1-4 and $A = ab^\top$, we have:

$$L_{N,P} \Omega^{-1/2} \sqrt{(T - P)/N} (\hat{\theta} - \theta) \rightarrow^d N(0, L),$$

where $\Omega = H^{-1} E[G_t \Sigma G_t^\top] H^{-1\top}$, $\Sigma = \text{Var}(u_t)$.

Simulation set-up

Experiment 1

$$A = \left[\frac{1}{N} \right]_{N \times N}$$

and

$$a = (1/\sqrt{N}, \dots, 1/\sqrt{N})^\top, b = (1/\sqrt{N}, \dots, 1/\sqrt{N})^\top.$$

Experiment 2 (Two-neighbor model; Chudik and Pesaran, 2011)

$$A = \begin{bmatrix} 0.8 & -0.2 & 0 & \dots & \dots & 0 \\ -0.2 & 0.8 & -0.2 & 0 & \dots & 0 \\ 0 & -0.2 & 0.8 & -0.2 & \dots & 0 \\ \vdots & \ddots & \ddots & \ddots & \ddots & \vdots \\ 0 & \dots & \dots & -0.2 & 0.8 & -0.2 \\ 0 & \dots & \dots & \dots & -0.2 & 0.8 \end{bmatrix}.$$

Simulation set-up

- $P = 4$
- $\beta = (0.8, -0.4, 0.2, 0.1)$
- Number of common shocks = 1, i.i.d standard normal
- $\Lambda = (\underbrace{1, \dots, 1}_{N/2}, \underbrace{0.5, \dots, 0.5}_{N/2})$
- ε_t follows $N(0, \Sigma)$, $\Sigma_{(i,j)} = 0.5^{|i-j|}$

Simulation result

Table 1: Simulation results from experiment 1 and 2

| Experiment 1 | | N | | | |
|--------------|--|----------------------------|-----------------|-----------------------------------|-----------------|
| | | Reduced-rank (algorithm 1) | | | |
| | | 10 | 50 | 100 | |
| T | | | | | |
| 300 | | 1.22 (0.4) | 3.36 (0.58) | 6.41 (1.03) | |
| 400 | | 1.02 (0.31) | 2.78 (0.46) | 4.80 (0.71) | |
| 500 | | 0.85 (0.25) | 2.31 (0.34) | 3.88 (0.44) | |
| | | | | | |
| Experiment 2 | | N | | | |
| | | Reduced-rank (algorithm 1) | | Arbitrary structure (algorithm 2) | |
| | | 10 | 20 | 10 | 20 |
| T | | | | | |
| 500 | | 1.11 (0.085) | 1.24 (0.109) | 0.66 (0.072) | 1.32 (0.083) |
| 600 | | 1.08 (0.076) | 1.21 (0.087) | 0.59 (0.066) | 1.20 (0.075) |
| 700 | | 1.08 (0.07) | 1.17 (0.076) | 0.55 (0.06) | 1.10 (0.069) |

Recovering structural form

Structural VAR:

$$Y_t = (I - \beta_0 W_0)^{-1} W \mathcal{Y}_{t-P}^{t-1} \beta + (I - \beta_0 W_0)^{-1} \tilde{\Lambda} f_t + (I - \beta_0 W_0)^{-1} \tilde{\varepsilon}_t$$

Reduced form:

$$Y_t = A W \mathcal{Y}_{t-P}^{t-1} \beta + \Lambda f_t + \varepsilon_t$$

Estimate (over-identified) nonlinear system:

$$\hat{A} = \hat{a} \hat{b}^\top = (I - \beta_0 W_0)^{-1} W$$

$$\text{Var}(\hat{\varepsilon}_t) = (I - \beta_0 W_0)^{-1} (I - \beta_0 W_0)^{-1\top}$$

subject to $W = \tilde{a} \tilde{b}^\top$; $\|\tilde{a}\|_2 = \|\tilde{b}\|_2 = 1$.

Empirical application: Linkages in the US stock market

- Study a network of large-cap (monthly) stock returns;
- Greater degree of co-movement of asset prices may pose systemic stability issues;
- Adverse idiosyncratic shocks may more readily spillover to other stocks;
- Portfolios, ETFs, indices that include these stocks take on large correlated exposures;
- Increases the likelihood of simultaneous losses for investors.

Empirical application: Linkages in the US stock market

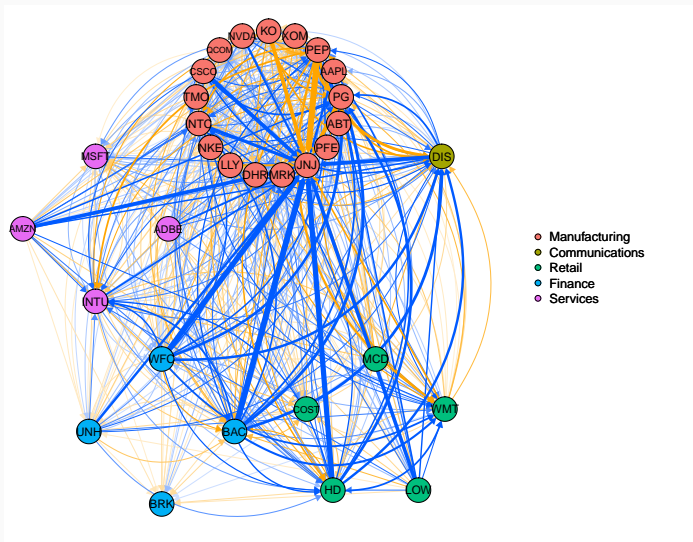
Data: Large-cap firms (top 31 holdings in Vanguard Large-cap ETF, VV)

Sample period: Jan 2010 - Dec 2019;

$N = 31$, $T = 108 \Rightarrow$ Unrestricted estimation of W **not feasible**;

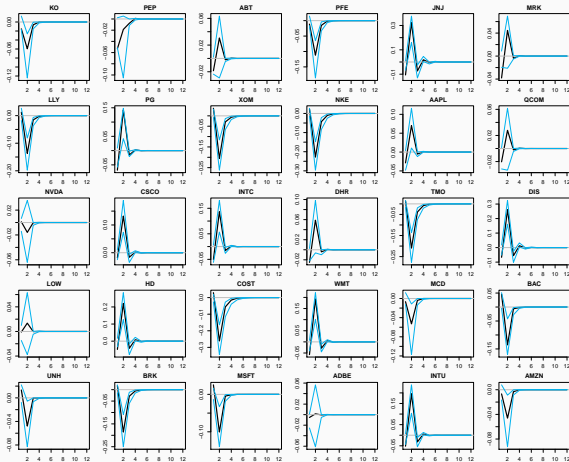
Empirical application: Linkages in the US stock market

Figure 1: Estimated adjacency matrix, W_0 .



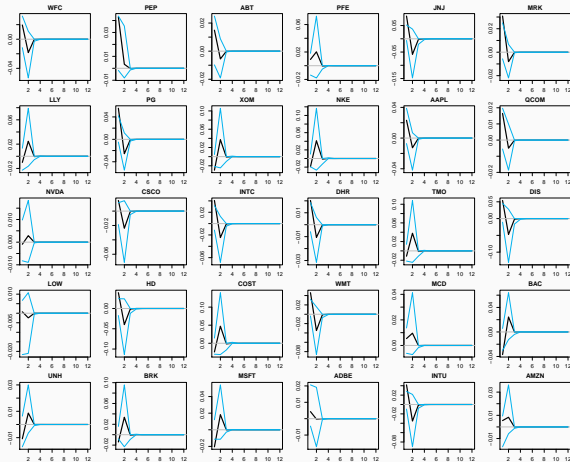
Empirical application: Linkages in the US stock market

Figure 2: Impulse response to a 1 s.d. negative shock to WFC.



Empirical application: Linkages in the US stock market

Figure 3: Impulse response to a 1 s.d. negative shock to KO.



Concluding remarks

- Proposed a novel SVAR methodology to handle large networks observed over time with **unknown adjacency matrices**;
- Reduced-form estimation is **consistent** and **asymptotically normal**;
- Numerical experiments show that the proposed iterated least squares algorithms can handle large network autoregressions well;
- Empirical application highlights the ability of the SVAR to isolate idiosyncratic impacts from common shocks;
- Provided **a tool to identify systemically important actors** in a network;