Mostrix

: a rectangular array,

ex)
$$\begin{bmatrix} 1,2\\3&4 \end{bmatrix}$$
 $\begin{bmatrix} a&b&c\\d&e&f\\ \end{bmatrix}$...

4 The numbers are called entries.

10w: ->, +y, +y

Column: 1, 空, 弯

Vector: a single tow or column.

ex) [1. 2 3 47 : row vector $\begin{bmatrix} 1 \\ 2 \end{bmatrix}$: Column vector.

o mxn matrix A: m rows and n columns matrix

$$A = \begin{bmatrix} \alpha_{17} \end{bmatrix} = \begin{bmatrix} \alpha_{11} & \alpha_{12} & \cdots & \alpha_{1n} \\ \alpha_{21} & \alpha_{22} & \cdots & \alpha_{2n} \\ \vdots & \ddots & \vdots \\ \alpha_{n-1} & & \alpha_{n-1} & \alpha_{n-1} \end{bmatrix}$$

o square matrix: m=n.

morn diagonal: a,, a,, am ...

o equality of matrix

→ A,B: motrāx O A,B: mxn mottax.

 $A = [a_{ij}], B = [b_{ij}]$ $a_{ij} = b_{ij}$ for $b_{i,j}$ (is isom, is $j \le n$).

· Addrtion of mothix

* A, B: mxn matrix A+B = [agt bg].

· scalar multiplication

A: mxn motrix, a: scalar, aA = [aaz]

" Rules of matrix

(1)
$$c(A+B) = cA+cB$$

(3)
$$c(kA) = k(cA)$$

(4)
$$1 \cdot A = A$$

Matrix Multiplication

:
$$A = [a_{77}] : m \times n$$
 matrix

 $B = [b_{jk}] : m \times r$ matrix

Condition size result size

 $C = [c_{7k}] : c_{7k} = \sum_{j=1}^{n} a_{7j} b_{jk} = a_{7i}b_{ik} + a_{72}b_{2k} \cdots$
 $C = [c_{7k}] : c_{7k} = \sum_{j=1}^{n} a_{7j} b_{jk} = a_{7i}b_{ik} + a_{72}b_{2k} \cdots$

ex)
$$\begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \end{bmatrix} \cdot \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix} = \begin{bmatrix} 1+4+9 \\ 4+10+18 \end{bmatrix} = \begin{bmatrix} 14 \\ 32 \end{bmatrix}$$

· AB & BA . Rule

(A)
$$(kA)B = k(AB) = A(kB)$$

(b)
$$A(BC) = (AB)C$$

•
$$C = AB$$
, $C's$ Ith column. $\rightarrow Ab$, $C's$ with column $\rightarrow Ab$ n.
• $C's$ Ith row $\rightarrow a_1B$ $C's$ with row $\rightarrow a_1B$...

· Transposition



4 Rule

(a)
$$(A^T)^T = A$$

(b)
$$(A+B)^{T} = A^{T} + B^{T}$$

(c)
$$(cA)^T = cA^T$$

$$(AB)^T = B^TA^T$$

$$A = \begin{bmatrix} a_1 \\ \vdots \\ a_{lm} \end{bmatrix} \quad B = \begin{bmatrix} b_1 \cdots b_r \end{bmatrix} \quad AB = \begin{bmatrix} a_1b_1 \cdots a_lb_r \\ \vdots \\ a_{lm}b_1 \cdots a_{lm}b_r \end{bmatrix}$$

$$(AB)^{T} = \begin{bmatrix} a_{1}b_{1} & \cdots & a_{m}b_{r} \\ \vdots & \vdots & \vdots \\ a_{r}b_{r} & a_{m}b_{r} \end{bmatrix} = \begin{bmatrix} b_{1}a_{1} & \cdots & b_{r}a_{1m} \\ b_{r}a_{1} & \cdots & b_{r}a_{m} \end{bmatrix} = B^{T}A^{T}$$

· Gaussian

· equition → monitix form.

$$\Omega_{11} \mathcal{R}_1 + \cdots + \Omega_{1n} \mathcal{R}_1 = b_1$$

$$\Omega_{21} \mathcal{R}_1 + \cdots + \Omega_{2n} \mathcal{R}_n = b_2$$

: equation

A: Coefficient mon.
$$A\vec{x} = \vec{b}$$

4 Matrix form

homogeneous system.

$$\Rightarrow \begin{bmatrix} a_{i1} & \cdots & a_{in} & b_{i} \\ \vdots & \vdots & \vdots & \vdots \\ a_{in} & \cdots & a_{inn} & b_{in} \end{bmatrix} : augmented matrix (mx(n+1) matrix)$$

o Gauss Elimination & Back Substitution.

$$\begin{bmatrix}
1 & -1 & 1 & 0 & 0 \\
-1 & 1 & -1 & 0 & 0 \\
0 & 10 & 25 & 90 & 80
\end{bmatrix}
\rightarrow
\begin{bmatrix}
1 & -1 & 1 & 0 & 0 \\
0 & 0 & 0 & 0 & 0 \\
0 & 2 & 5 & 16 & 0
\end{bmatrix}
\rightarrow
\begin{bmatrix}
1 & -1 & 1 & 0 & 0 \\
2 & 1 & 0 & 0 & 0 \\
0 & 2 & 5 & 16 & 0
\end{bmatrix}
\rightarrow
\begin{bmatrix}
1 & -1 & 1 & 0 & 0 \\
2 & 1 & 0 & 0 & 0 \\
0 & 2 & 5 & 16 & 0
\end{bmatrix}
\rightarrow
\begin{bmatrix}
1 & -1 & 1 & 0 & 0 \\
0 & 3 & -2 & 6 & 18 \\
0 & 0 & 0 & 0 & 0
\end{bmatrix}$$

$$\Rightarrow \begin{bmatrix} 1 & -1 & 1 & 0 \\ 0 & 3 & -2 & 6 \\ 0 & 0 & 19 & 38 \\ 0 & 0 & 0 & 0 \end{bmatrix} z=2, y=4. x=2$$

- 1 Interchange of two rous/equations.
- a Addition of a constant multiple of one row to another row
- @ Multiplication of row by a nonzero constant c.

o The Three possible Coves

- 1) a unique solution X
- 2) Infinitely many dution / consistant system
- 3) no solution / Inconstance system
 - \Rightarrow Every homogeneous linear system is consistant. ($\cancel{R} = 0$, thivial solution)
 - → 2), free column: 设定 建物程 EIR.

· Row Echelon Form

if... 0 in each non-zero row, the first non-zero entry is in a column to the left of any leading entries below it. = upper-triangular form.

- o Reduced Row Echelon Form
 - och column containing leading 1 has zeros everywher else.
- o tank (A) = #(nonzero tows of A)

[unknowns] =
$$n$$
. (i) $r = m \rightarrow a$ unique sol.

Linear Independence, Rank of a matrix

Let $\vec{\alpha}_1$, $\vec{\alpha_2}$, $\vec{\alpha_3}$... $\vec{\alpha_{un}} \in \mathbb{R}^n$ be vectors.

o linear combination

o Linearly independent

if
$$C_{\alpha} \overline{\Omega_1} + \cdots + C_{m} \overline{\Omega_m} = \overline{C} \iff C_1 = \cdots = C_m = 0$$
,
 $C_{\alpha} \overline{\Omega_2} + \cdots = C_m = 0$ are theory independent

· Linearly dependent

나 설년 하나의 벡터가 다른 벡터로 표현이 가능함

$$\frac{p\ell}{C_1 \, \vec{\alpha_1} + \cdots + C_m \, \vec{\alpha_m}} = \vec{\delta} \quad \text{for some nonzero } C_i,$$

$$C_1 \neq 0. \quad \times \frac{1}{C_1}, \quad \vec{\delta_1} + \frac{C_2}{C_1} \, \vec{\delta_2} + \cdots + \frac{C_m}{C_4} \, \vec{\alpha_m} = \vec{\delta}, \quad \Rightarrow \quad -\vec{\delta} = \frac{1}{C_1} \left(C_2 \, \vec{\delta_2} + \cdots + C_m \, \vec{\delta_m} \right)$$

4 zero vector-7+ others some trinearly dependent

· Rank of A

4 max # (trinearly rudependent vector/row)

Thm.

Let
$$A = \begin{bmatrix} \vec{a}_1 \\ \vdots \\ \vec{a}_m \end{bmatrix}$$
 $B = \begin{bmatrix} \vec{a}_1 \\ \cdots \\ \vec{a}_m \end{bmatrix}$ A^T) Then $\vec{a}_1 \cdots \vec{a}_m$ are linearly independent if rank(A) = rank(B) = m : $f \cdot n < m$, then vectors are linearly dependent $f \cdot n = m$.