

```
import matplotlib.pyplot as plt
import numpy as np
from keras.datasets import mnist
```

Using TensorFlow backend.

## 1 Data generation

```
(x_train,y_train),(x_test,y_test) = mnist.load_data()
x_test.shape
```

```
(10000, 28, 28)
```

Utils functions generate Bags, consist of X zeros and 100-X sevens

```
def createBags(mnistImg,mnistLb,bag_num,shaffule=True,padding=0):
    zeros=mnistImg[mnistLb==0]
    sevens=mnistImg[mnistLb==7]
    print('zeros len',len(zeros),' sevens len ',len(sevens))
    max_size=(int)((len(zeros)+len(sevens))/200)
    if bag_num>max_size:
        bag_num=max_size
    print('bags_num : ',bag_num)
    X_rate=np.random.randint(1,100,size=bag_num)
    bags=np.zeros((bag_num,100,(28+2*padding),(28+2*padding)),dtype=np.uint8)
    itzer=0
    itsev=0
    for i in range(0,bag_num):
        for j in range(0,28):
            for k in range(0,28):

                bags[i,:X_rate[i],j+padding,k+padding]=zeros[itzer:itzer+X_rate[i],j,k]

                bags[i,X_rate[i]-100:,j+padding,k+padding]=sevens[itsev:itsev+100-
X_rate[i],j,k]
                itzer+=X_rate[i]
                itsev+=100-X_rate[i]
        if shaffule:
            bags=np.random.default_rng().permutation(bags,axis=1)

    return bags,X_rate

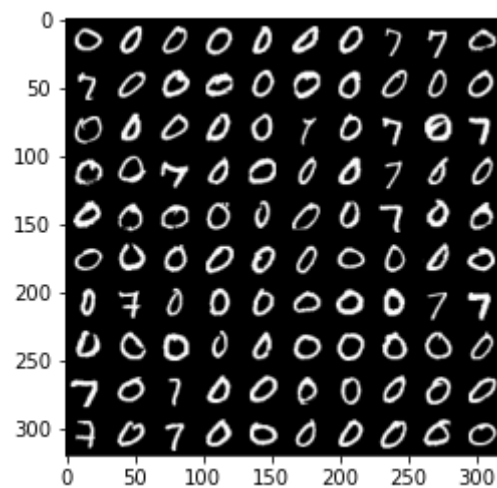
def showBags(bags,size,index=0):
    canvas=np.zeros((size*10,size*10),dtype=np.uint8)
    for i in range(0,10):
        for j in range(0,10):
            canvas[i*size:i*size+size,j*size:j*size+size]=bags[index,i*10+j]
```

```
return canvas
```

```
#train data
bags_train,label_train=createBags(x_train,y_train,100,shaffule=True,padding=2)
print('zero purity: ',label_train[5])
plt.imshow(showBags(bags_train,32,5),cmap='gray')
```

```
zeros len 5923  sevens len  6265
bags_num :   60
zero purity:  84
```

```
<matplotlib.image.AxesImage at 0x12d9aa24dc8>
```



```
#test data
bags_test,label_test=createBags(x_test,y_test,100,shaffule=True,padding=2)
```

```
zeros len 980  sevens len  1028
bags_num :   10
```

## 2 Extract features & preprocess data

```
from keras.applications import resnet
from keras.applications.vgg16 import VGG16
from keras.preprocessing import image
from keras.applications.vgg16 import preprocess_input
import keras
```

## Use pretrained VGG16 net extract features

```
bags_train3=np.concatenate([np.expand_dims(bags_train, axis=-1)]*3,axis=-1)
bags_train3.astype('float32')
bags_train3=bags_train3/255
bags_train3.shape
```

```
(60, 100, 32, 32, 3)
```

## keras pretrained VGGnet

```
featureExtractor=VGG16(weights='imagenet',include_top=False)
```

```
train_feature_data=[]
for bag in bags_train3:
    bag_features=featureExtractor.predict(preprocess_input(bag))
    train_feature_data.append(bag_features.reshape(100,512))
train_feature_data=np.array(train_feature_data)
```

```
bags_test3=np.concatenate([np.expand_dims(bags_test, axis=-1)]*3,axis=-1)
bags_test3.astype('float32')
bags_test3=bags_test3/255
test_feature_data=[]
for bag in bags_test3:
    bag_features=featureExtractor.predict(preprocess_input(bag))
    test_feature_data.append(bag_features.reshape(100,512))
test_feature_data=np.array(test_feature_data)
```

## normalize y label : purity shape(none,1)

```
label_train.astype('float32')
label_train=label_train/100
label_test.astype('float32')
label_test=label_test/100
label_train=label_train.reshape(-1,1)
label_test=label_test.reshape(-1,1)
```

## 3 MIL Modeling

```

from keras.layers import Input, Subtract, Multiply, BatchNormalization,
MaxPooling1D
from keras.layers.core import Dropout, Flatten, Dense, Reshape, Lambda
from keras.models import Model
from keras import backend as K
from keras.engine.topology import Layer
from keras.activations import relu
import math

```

## sample point layer, used in Bag lever representation

```

def expandDims(x):
    x1=K.expand_dims(x, -1)
    return x1

class samplePoint(Layer):
    def __init__(self, num_instances, num_features, num_bins, **wkargs):
        self.num_instances=num_instances
        self.num_features=num_features
        self.num_bins=num_bins
        super(samplePoint, self).__init__()
        self.output_dim=(num_instances, num_features, num_bins)
        self.sample_point=np.linspace(0, 1, num_bins, dtype=np.float32)
        self.sample_points=np.tile(self.sample_point,
(num_instances, num_features, 1))
        def build(self, input_shape):
            self.kernal=self.add_weight(name='sample_point',
                                        shape=(0, 0),
                                        initializer='uniform',
                                        trainable=False
                                        )
            super(samplePoint, self).build(input_shape)
        def call(self, x):
            return Subtract()([x, K.constant([self.sample_points])])
        def compute_output_shape(self, input_shape):
            return
            (input_shape[0], self.num_instances, self.num_features, self.num_bins)

```

```

def
MILModel(num_instances=100, num_features=512, num_classes=1, num_bins=21, sigma=0.01
67, batch_size=5):
    alfa = 1/math.sqrt(2*math.pi*(sigma**2))
    beta = -1/(2*(sigma**2))
    splayer=samplePoint(num_instances, num_features, num_bins)

    X=Input(shape=(num_instances, num_features))

    ##----- Distribution pooling filter-----
    , num_instances, num_features = X.shape
    x=Lambda(expandDims)(X)

```

```

#x=MaxPooling1D(pool_size=3)(x)
diff=spLayer(x)
diff2=Lambda(lambda x :x**2)(diff)

exp=Lambda(lambda x:K.exp(x))
cox=Lambda(lambda x:x*beta)
result=cox(exp(diff2))

out_unnormalized = Lambda(lambda x:K.sum(x,axis=1))(result)
norm_coeff = Lambda(lambda x:K.sum(x, axis=2, keepdims=True))
(out_unnormalized)
out=Multiply()([out_unnormalized,Lambda(lambda x:1/x)(norm_coeff)])

##-----Representation transform
out=MaxPooling1D(3,2)(out)
x=Flatten()(out)

x=Dense(384,activation='relu')(x)
x=BatchNormalization()(x)
x=Dense(192)(x)
x=Dense(192,use_bias=True)(x)
out1=Dense(num_classes)(x)

model=Model(inputs=[X],outputs=out1)
return model

```

```
Mil_model=MILModel(num_classes=1)
```

```
Mil_model.summary()
```

```
Model: "model_1"
```

Layer (type)	Output Shape	Param #	Connected to
=====			
input_2 (InputLayer)	(None, 100, 512)	0	
=====			
lambda_1 (Lambda)	(None, 100, 512, 1)	0	input_2[0][0]
=====			
sample_point_1 (samplePoint)	(None, 100, 512, 21)	0	lambda_1[0][0]
=====			
lambda_2 (Lambda)	(None, 100, 512, 21)	0	sample_point_1[0][0]
=====			

lambda_3 (Lambda)	(None, 100, 512, 21) 0	lambda_2[0][0]
lambda_4 (Lambda)	(None, 100, 512, 21) 0	lambda_3[0][0]
lambda_5 (Lambda)	(None, 512, 21) 0	lambda_4[0][0]
lambda_6 (Lambda)	(None, 512, 1) 0	lambda_5[0][0]
lambda_7 (Lambda)	(None, 512, 1) 0	lambda_6[0][0]
multiply_1 (Multiply)	(None, 512, 21) 0	lambda_5[0][0] lambda_7[0][0]
max_pooling1d_1 (MaxPooling1D)	(None, 255, 21) 0	multiply_1[0][0]
flatten_1 (Flatten) max_pooling1d_1[0][0]	(None, 5355) 0	
dense_1 (Dense)	(None, 384) 2056704	flatten_1[0][0]
batch_normalization_1 (BatchNormalizatio	(None, 384) 1536	dense_1[0][0]
dense_2 (Dense) batch_normalization_1[0][0]	(None, 192) 73920	
dense_3 (Dense)	(None, 192) 37056	dense_2[0][0]
dense_4 (Dense)	(None, 1) 193	dense_3[0][0]
=====		
Total params: 2,169,409		
Trainable params: 2,168,641		
Non-trainable params: 768		

## 4 Training

```
from keras.optimizers import Adam,SGD
from keras import losses
```

```
def myloss(y_true, y_pred):
    loss1 =losses.mean_absolute_error(y_true, y_pred)
    return loss1
```

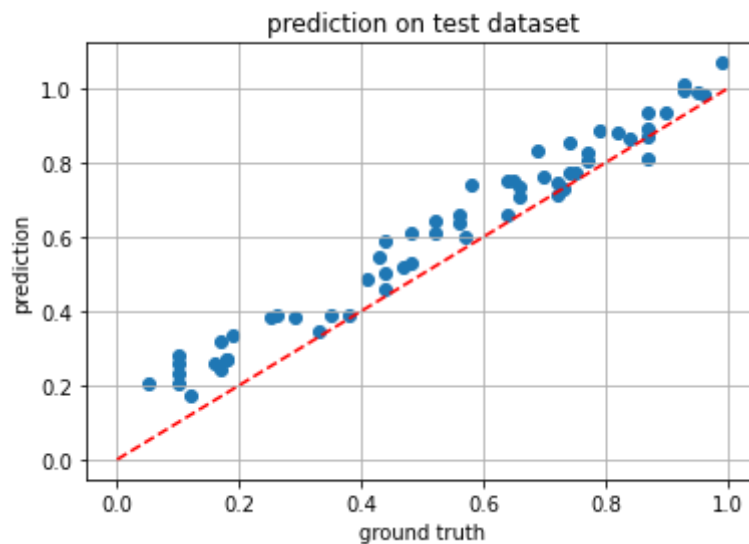
```
Mil_model.compile(optimizer=SGD(0.01),
                  loss=myloss)
```

```
history=Mil_model.fit(train_feature_data,label_train,epochs=200,batch_size=10,verbose=0)
```

```
Mil_model.save('MIL200_10.h5')
```

## 5 Evaluating

```
y_scatter=Mil_model.predict(train_feature_data)
line=np.linspace(0,1,20)
plt.ylabel('prediction')
plt.xlabel('ground truth')
plt.scatter(label_train,y_scatter)
plt.plot(line,line,color='r',linestyle='--')
plt.title("prediction on test dataset")
plt.grid()
```



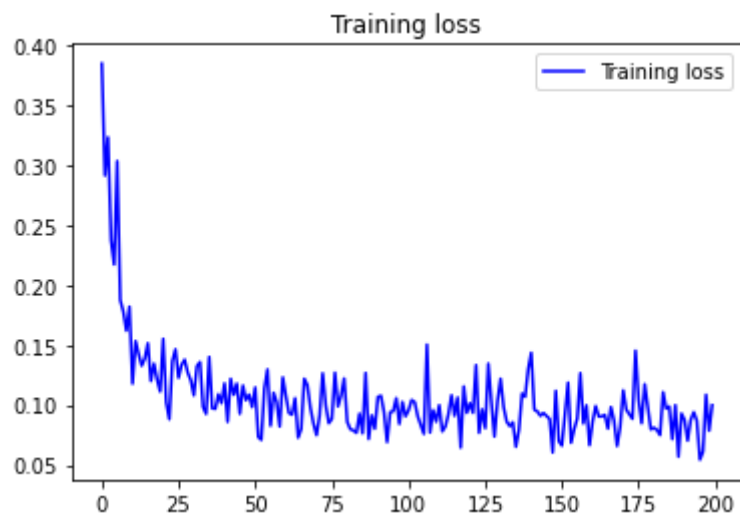
```
print('loss on test ',Mil_model.evaluate(test_feature_data,label_test))
print('loss on train ',Mil_model.evaluate(train_feature_data,label_train))
```

```
10/10 [=====] - 0s 4ms/step
loss on test  0.08194070309400558
60/60 [=====] - 0s 416us/step
loss on train  0.07673474897940953
```

## loss plot

```
epochs=range(len(history.history['loss']))
plt.plot(epochs,history.history['loss'],'b',label='Training loss')
plt.title('Training loss')
plt.legend()
```

```
<matplotlib.legend.Legend at 0x12d9b858e88>
```



## 6 reference

- [1]<https://github.com/onermustafaumit/SRTPMs>
- [2]<https://medium.com/swlh/multiple-instance-learning-c49bd21f5620>
- [3]<https://www.p-chao.com/2017-01-19/%E7%9B%AE%E6%A0%87%E8%B7%9F%E8%B8%AA%EF%BC%88%E4%B8%80%E5%AE%9E%E4%BE%8B%E5%9C%A8%E7%BA%BF%E5%AD%A6%E4%B9%A0/>