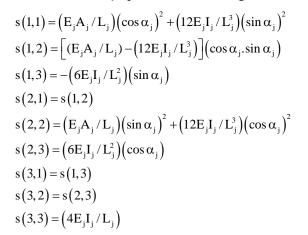
GLOBAL EKSEN TAKIMINDA ELEMAN STİFNES (RİJİTLİK) MATRİS TABLOSU

(x-y Düzlemindeki doğru eksenli prizmatik j çubuk elemanı için)

$$(s_{j}) = \begin{bmatrix} s(1,1) & s(1,2) & s(1,3) & (-) & (-) & (+) \\ s(2,1) & s(2,2) & s(2,3) & (-) & (-) & (+) \\ s(3,1) & s(3,2) & s(3,3) & (-) & (-) & \frac{1}{2}(+) \\ \hline (-) & (-) & (-) & (+) & (+) & (-) \\ (-) & (-) & (-) & (+) & (+) & (-) \\ (+) & (+) & \frac{1}{2}(+) & (-) & (-) & (+) \end{bmatrix}$$

Sol üst köşedeki tablo elemanları aşağıda tarif edilmektedir. Tabloda verilen katsayı ve işaretlerle aşağıda tarif edilen tablo elemanları çarpılarak tablonun diğer elemanları elde edilir.





 α_i = Elemanın Referan Açısı

A_i = Elemanın Dik Kesit Alanı

I_i = Elemanın Asal Atalet Momenti (z eksenine göre)

L_i = Elemanın Boyu

E_i = Elemanın Malzeme Elastisite Modülü

ÖZEL HALLER

Kiriş Elemanı $(\alpha_j = 0)$	Kolon Elemani $(\alpha_j = 90)$	Kafes Elemanı $(I_j = 0)$
(Referans noktası sol uçta)	(Referans noktası alt uçta)	(S matrisindeki tüm I _j =0)
$s(1,1) = (E_j A_j / L_j)$	$s(1,1) = \left(12E_{j}I_{j}/L_{j}^{3}\right)$	$s(1,1) = (E_j A_j / L_j) (\cos \alpha_j)^2$
s(1,2)=0	s(1,2)=0	$s(1,2) = (E_j A_j / L_j) (\cos \alpha_j . \sin \alpha_j)$
s(1,3) = 0	$s(1,3) = -(6E_iI_i/L_i^2)$	s(1,3) = 0
s(2,1)=0	s(2,1) = 0	$s(2,1) = (E_j A_j / L_j) (\cos \alpha_j . \sin \alpha_j)$
$s(2,2) = \left(12E_{j}I_{j}/L_{j}^{3}\right)$	$s(2,2) = (E_j A_j / L_j)$	$s(2,2) = (E_j A_j / L_j) (\sin \alpha_j)^2$
$s(2,3) = \left(6E_{j}I_{j}/L_{j}^{2}\right)$	s(2,3) = 0	s(2,3) = 0
s(3,1) = 0	$s(3,1) = -\left(6E_{j}I_{j}/L_{j}^{2}\right)$	s(3,1) = 0
$s(3,2) = \left(6E_{j}I_{j}/L_{j}^{2}\right)$	s(3,2) = 0	s(3,2) = 0
$s(3,3) = \left(4E_{j}I_{j}/L_{j}\right)$	$s(3,3) = \left(4E_{j}I_{j}/L_{j}\right)$	s(3,3) = 0

Eleman eksen takımındaki çubuk ucu kuvvetleri $[q_i^i]$ 'lerin, global eksen takımındaki düğüm noktası deplasmanları

 $\lceil d_j \rceil$ 'ler cinsinden tarifleri

$$\begin{split} q_{_{j_{1}}}^{_{1}} &= - \big(E_{_{j}} A_{_{j}} / L_{_{j}} \big) \Big[\big(d_{_{j4}} - d_{_{j1}} \big) \big(\cos \alpha_{_{j}} \big) + \big(d_{_{j5}} - d_{_{j2}} \big) \big(\sin \alpha_{_{j}} \big) \Big] \\ q_{_{j_{2}}}^{_{1}} &= \big(E_{_{j}} I_{_{j}} / L_{_{j}}^{^{2}} \big) \Bigg[6 d_{_{j3}} + 6 d_{_{j6}} - \frac{12}{L_{_{j}}} \Big[\big(d_{_{j5}} - d_{_{j2}} \big) \big(\cos \alpha_{_{j}} \big) - \big(d_{_{j4}} - d_{_{j1}} \big) \big(\sin \alpha_{_{j}} \big) \Big] \Big] \\ q_{_{j_{3}}}^{_{1}} &= \big(E_{_{j}} I_{_{j}} / L_{_{j}} \big) \Big[4 d_{_{j3}} + 2 d_{_{j6}} - \frac{6}{L_{_{j}}} \Big[\big(d_{_{j5}} - d_{_{j2}} \big) \big(\cos \alpha_{_{j}} \big) - \big(d_{_{j4}} - d_{_{j1}} \big) \big(\sin \alpha_{_{j}} \big) \Big] \Big] \\ q_{_{j_{4}}}^{_{1}} &= \big(E_{_{j}} A_{_{j}} / L_{_{j}} \big) \Big[\big(d_{_{j4}} - d_{_{j1}} \big) \big(\cos \alpha_{_{j}} \big) + \big(d_{_{j5}} - d_{_{j2}} \big) \big(\cos \alpha_{_{j}} \big) - \big(d_{_{j4}} - d_{_{j1}} \big) \big(\sin \alpha_{_{j}} \big) \Big] \Big] \\ q_{_{j_{5}}}^{_{1}} &= - \big(E_{_{j}} I_{_{j}} / L_{_{j}} \big) \Bigg[2 d_{_{j3}} + 4 d_{_{j6}} - \frac{6}{L_{_{j}}} \Big[\big(d_{_{j5}} - d_{_{j2}} \big) \big(\cos \alpha_{_{j}} \big) - \big(d_{_{j4}} - d_{_{j1}} \big) \big(\sin \alpha_{_{j}} \big) \Big] \Big] \\ q_{_{j_{6}}}^{_{1}} &= \big(E_{_{j}} I_{_{j}} / L_{_{j}} \big) \Bigg[2 d_{_{j3}} + 4 d_{_{j6}} - \frac{6}{L_{_{j}}} \Big[\big(d_{_{j5}} - d_{_{j2}} \big) \big(\cos \alpha_{_{j}} \big) - \big(d_{_{j4}} - d_{_{j1}} \big) \big(\sin \alpha_{_{j}} \big) \Big] \Big] \end{aligned}$$

ÖZEL HALLER

<u>Kiriş Elemanı</u> $(\alpha_j = 0)$

$$\begin{split} q_{_{j_{1}}}^{_{1}} &= -\Big(E_{_{j}}A_{_{j}}/L_{_{j}}\Big)\Big(d_{_{j4}}-d_{_{j1}}\Big)\\ q_{_{j_{2}}}^{_{1}} &= \Big(E_{_{j}}I_{_{j}}/L_{_{j}}^{_{2}}\Big)\Bigg[6d_{_{j3}}+6d_{_{j6}}-\frac{12}{L_{_{j}}}\Big(d_{_{j5}}-d_{_{j2}}\Big)\Bigg]\\ q_{_{j_{3}}}^{_{1}} &= \Big(E_{_{j}}I_{_{j}}/L_{_{j}}\Big)\Bigg[4d_{_{j3}}+2d_{_{j6}}-\frac{6}{L_{_{j}}}\Big(d_{_{j5}}-d_{_{j2}}\Big)\Bigg]\\ q_{_{j_{4}}}^{_{1}} &= \Big(E_{_{j}}A_{_{j}}/L_{_{j}}\Big)\Big(d_{_{j4}}-d_{_{j1}}\Big)\\ q_{_{j_{5}}}^{_{1}} &= -\Big(E_{_{j}}I_{_{j}}/L_{_{j}}^{^{2}}\Big)\Bigg[6d_{_{j3}}+6d_{_{j6}}-\frac{12}{L_{_{j}}}\Big(d_{_{j5}}-d_{_{j2}}\Big)\Bigg]\\ q_{_{j_{6}}}^{_{1}} &= \Big(E_{_{j}}I_{_{j}}/L_{_{j}}\Big)\Bigg[2d_{_{j3}}+4d_{_{j6}}-\frac{6}{L_{_{i}}}\Big(d_{_{j5}}-d_{_{j2}}\Big)\Bigg] \end{split}$$

Kolon Elemanı ($\alpha_i = 90$)

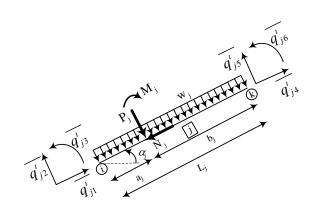
$$\begin{split} q_{_{j4}}^{_{1}} &= -\Big(E_{_{j}}A_{_{j}}/L_{_{j}}\Big)\Big(d_{_{j5}}-d_{_{j2}}\Big)\\ q_{_{j2}}^{_{1}} &= \Big(E_{_{j}}I_{_{j}}/L_{_{j}}^{_{2}}\Big)\Bigg[6d_{_{j3}}+6d_{_{j6}}+\frac{12}{L_{_{j}}}\Big(d_{_{j4}}-d_{_{j1}}\Big)\Bigg]\\ q_{_{j3}}^{_{1}} &= \Big(E_{_{j}}I_{_{j}}/L_{_{j}}\Big)\Bigg[4d_{_{j3}}+2d_{_{j6}}+\frac{6}{L_{_{j}}}\Big(d_{_{j4}}-d_{_{j1}}\Big)\Bigg]\\ q_{_{j4}}^{_{1}} &= \Big(E_{_{j}}A_{_{j}}/L_{_{j}}\Big)\Big(d_{_{j5}}-d_{_{j2}}\Big)\\ q_{_{j5}}^{_{1}} &= -\Big(E_{_{j}}I_{_{j}}/L_{_{j}}^{_{2}}\Big)\Bigg[6d_{_{j3}}+6d_{_{j6}}+\frac{12}{L_{_{j}}}\Big(d_{_{j4}}-d_{_{j1}}\Big)\Bigg]\\ q_{_{j6}}^{_{1}} &= \Big(E_{_{j}}I_{_{j}}/L_{_{j}}\Big)\Bigg[2d_{_{j3}}+4d_{_{j6}}+\frac{6}{L_{_{i}}}\Big(d_{_{j4}}-d_{_{j1}}\Big)\Bigg] \end{split}$$

Kafes Eleman $(I_i = 0)$

$$\begin{split} q_{_{j_{1}}}^{_{1}} &= -\Big(E_{_{j}}A_{_{j}}/L_{_{j}}\Big)\Big[\Big(d_{_{j4}}-d_{_{j1}}\Big)\Big(\cos\alpha_{_{j}}\Big) + \Big(d_{_{j5}}-d_{_{j2}}\Big)\Big(\sin\alpha_{_{j}}\Big)\Big]\\ q_{_{j_{2}}}^{_{1}} &= 0\\ q_{_{j_{3}}}^{_{1}} &= 0\\ q_{_{j_{4}}}^{_{1}} &= \Big(E_{_{j}}A_{_{j}}/L_{_{j}}\Big)\Big[\Big(d_{_{j4}}-d_{_{j1}}\Big)\Big(\cos\alpha_{_{j}}\Big) + \Big(d_{_{j5}}-d_{_{j2}}\Big)\Big(\sin\alpha_{_{j}}\Big)\Big]\\ q_{_{_{j5}}}^{_{1}} &= 0\\ q_{_{_{15}}}^{_{1}} &= 0 \end{split}$$

j çubuk elemanı üzerine etki eden (w_j, P_j, N_j, M_j) yüklerine bağlı eleman eksen takımındaki çubuk ucu kuvvetleri $\left\lceil \overline{q_j^l} \right\rceil$ 'lerin tarifi

$$\begin{split} &\overline{q_{jl}^{i}} = \frac{b_{j}N_{j}}{L_{j}} \\ &\overline{q_{j2}^{i}} = \frac{w_{j}L_{j}}{2} + \frac{P_{j}b_{j}^{2}\left(3a_{j} + b_{j}\right)}{L_{j}^{3}} - \frac{6M_{j}a_{j}b_{j}}{L_{j}^{3}} \\ &\overline{q_{j3}^{i}} = \frac{w_{j}L_{j}^{2}}{12} + \frac{P_{j}b_{j}^{2}a_{j}}{L_{j}^{2}} + \frac{M_{j}b_{j}\left(b_{j} - 2a_{j}\right)}{L_{j}^{2}} \\ &\overline{q_{j4}^{i}} = \frac{a_{j}N_{j}}{L_{j}} \\ &\overline{q_{j5}^{i}} = \frac{w_{j}L_{j}}{2} + \frac{P_{j}a_{j}^{2}\left(3b_{j} + a_{j}\right)}{L_{j}^{3}} + \frac{6M_{j}a_{j}b_{j}}{L_{j}^{3}} \\ &\overline{q_{j6}^{i}} = -\frac{w_{j}L_{j}^{2}}{12} - \frac{P_{j}a_{j}^{2}b_{j}}{L_{j}^{2}} + \frac{M_{j}a_{j}\left(a_{j} - 2b_{j}\right)}{L_{j}^{2}} \end{split}$$



Global eksen takımındaki çubuk ucu kuvvetleri $\left[\overline{q_{i}}\right]$ 'lerin yukarıda tarif edilen $\left[\overline{q_{i}^{i}}\right]$ 'ler cinsinden ifadeleri

Genel Elemanı	<u>Kiriş Elemanı</u> $(\alpha_j = 0)$	Kolon Elemani ($\alpha_j = 90$)
$\overline{q_{jl}} = \overline{q_{jl}^{\iota}} \Big(\cos \alpha_{j} \Big) - \overline{q_{j2}^{\iota}} \Big(\sin \alpha_{j} \Big)$	$\overline{q_{jl}} = \overline{q_{jl}^i}$	$\overline{\mathbf{q}_{j1}} = -\overline{\mathbf{q}_{j2}^{1}}$
$\overline{q_{j2}} = \overline{q_{jl}^{\iota}} \left(\sin \alpha_{j} \right) + \overline{q_{j2}^{\iota}} \left(\cos \alpha_{j} \right)$	$\overline{q_{j2}} = \overline{q_{j2}^{i}}$	$\overline{\mathbf{q}_{j2}} = \overline{\mathbf{q}_{jl}^{\scriptscriptstyle{\mathrm{l}}}}$
$\overline{q_{j3}} = \overline{q_{j3}^{\iota}}$	$\overline{q_{j3}} = \overline{q_{j3}^{\iota}}$	$\overline{\mathbf{q}_{j3}} = \overline{\mathbf{q}_{j3}^{\scriptscriptstyle{\mathrm{I}}}}$
$\overline{q_{j4}} = \overline{q_{j4}^{\iota}} \left(\cos \alpha_{j} \right) - \overline{q_{j5}^{\iota}} \left(\sin \alpha_{j} \right)$	$\overline{q_{j4}} = \overline{q_{j4}^{\scriptscriptstyle 1}}$	$\overline{\mathbf{q}_{\mathtt{j}4}} = -\overline{\mathbf{q}_{\mathtt{j}5}^{\mathtt{l}}}$
$\overline{q_{j5}} = \overline{q_{j4}^{\iota}} \left(\sin \alpha_{j} \right) + \overline{q_{j5}^{\iota}} \left(\cos \alpha_{j} \right)$	$\overline{q_{j5}} = \overline{q_{j5}^{1}}$	$\overline{\mathbf{q}_{\mathtt{j5}}} = \overline{\mathbf{q}_{\mathtt{j4}}^{\mathtt{l}}}$
$\overline{q_{j6}} = \overline{q_{j6}^{i}}$	$\overline{q_{j6}} = \overline{q_{j6}^{\scriptscriptstyle 1}}$	$\overline{\mathbf{q}_{j6}} = \overline{\mathbf{q}_{j6}^{\scriptscriptstyle{\mathrm{1}}}}$