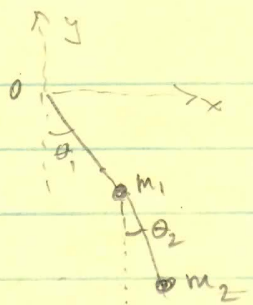


Pb. 1.



Position vectors; small

$$\vec{r}_1 = l \sin \theta_1 \hat{x} - l \cos \theta_1 \hat{y} \approx l(\theta_1 \hat{x} - \hat{y})$$

$$\vec{r}_2 = (l \sin \theta_1 + l \sin \theta_2) \hat{x} - (l \cos \theta_1 + l \cos \theta_2) \hat{y} \\ \approx l[(\theta_1 + \theta_2) \hat{x} - 2 \hat{y}]$$

⊗ For the kinetic energy

$$\frac{\partial \vec{r}_1}{\partial t} = \frac{\partial \vec{r}_2}{\partial t} = 0 \Rightarrow \dot{M}_0 = \dot{M}_j = 0$$

$$\frac{\partial \vec{r}_1}{\partial \theta_1} = l \hat{x} : \frac{\partial \vec{r}_1}{\partial \theta_2} = 0 : \frac{\partial \vec{r}_2}{\partial \theta_1} = l \hat{x} : \frac{\partial \vec{r}_2}{\partial \theta_2} = l \hat{x}$$

so

$$T = \frac{1}{2} [M_{11} \dot{\theta}_1^2 + 2M_{12} \dot{\theta}_1 \dot{\theta}_2 + M_{22} \dot{\theta}_2^2]$$

$$M_{11} = m_1 \left(\frac{\partial \vec{r}_1}{\partial \theta_1} \right)^2 + m_2 \left(\frac{\partial \vec{r}_2}{\partial \theta_1} \right)^2 = m_1 l^2 + m_2 l^2 = l^2 (m_1 + m_2)$$

$$M_{12} = m_1 \frac{\partial \vec{r}_1}{\partial \theta_1} \frac{\partial \vec{r}_1}{\partial \theta_2} + m_2 \frac{\partial \vec{r}_2}{\partial \theta_1} \frac{\partial \vec{r}_2}{\partial \theta_2} = l^2 m_2$$

$$M_{22} = m_1 \left(\frac{\partial \vec{r}_1}{\partial \theta_2} \right)^2 + m_2 \left(\frac{\partial \vec{r}_2}{\partial \theta_2} \right)^2 = m_2 l^2$$

$$T = \frac{l^2}{2} [(m_1 + m_2) \dot{\theta}_1^2 + 2m_2 \dot{\theta}_1 \dot{\theta}_2 + m_2 \dot{\theta}_2^2]$$

$$[T_{ij}] = l^2 \begin{pmatrix} m_1 + m_2 & m_2 \\ m_2 & m_2 \end{pmatrix}$$

⊗ Potential energy $V = -m_1 g y_1 - m_2 g y_2$

$$= -m_1 g l \cos \theta_1 - m_2 g l (\cos \theta_1 + \cos \theta_2)$$

(Have to keep higher order in $\cos \theta \approx 1 - \frac{\theta^2}{2}$) $\approx -g l [m_1 (1 - \frac{\theta_1^2}{2}) + m_2 (2 - \frac{\theta_1^2}{2} - \frac{\theta_2^2}{2})]$

$$V = -g l [m_1 + 2m_2 - (m_1 + m_2) \frac{\theta_1^2}{2} - m_2 \frac{\theta_2^2}{2}]$$

$$V_{ij} = \frac{\partial^2 V}{\partial \theta_i \partial \theta_j} \Rightarrow V_{11} = \frac{\partial^2 V}{\partial \theta_1^2} = g l (m_1 + m_2) : V_{12} = 0 : V_{22} = \frac{\partial^2 V}{\partial \theta_2^2} = g l m_2$$

$$[V_{ij}] = g l \begin{pmatrix} m_1 + m_2 & 0 \\ 0 & m_2 \end{pmatrix}$$

⊗ Eigenfrequencies satisfy

$$|V - \lambda T| = 0 = \begin{vmatrix} g(m_1+m_2) - l(m_1+m_2)\lambda & -l\lambda m_2 \\ -l\lambda m_2 & gm_2 - l\lambda m_2 \end{vmatrix}$$

$$m_2(m_1+m_2)(g-l\lambda)^2 - l^2 \lambda^2 m_2^2 = 0$$

$$\lambda^2 l^2 m_1 m_2 - 2gl m_2(m_1+m_2)\lambda + g^2 m_2(m_1+m_2) = 0$$

$$\boxed{\lambda_{\pm} = \frac{g}{l} \cdot \frac{1}{m_1} \left[(m_1+m_2) \pm \sqrt{m_2(m_1+m_2)} \right]} \text{ where } \lambda = \omega^2$$

⊗ Eigenvectors; use 1st row

$$M \equiv m_1 + m_2$$

$$(m_1+m_2)(g-l\lambda)a_1 - l m_2 \lambda a_2 = 0$$

$$\lambda \frac{a_2}{a_1} = \frac{M(g-l\lambda)}{l m_2} = \frac{gM}{l m_2} \left[-\frac{m_2}{m_1} \mp \frac{1}{m_1} \sqrt{m_2 M} \right] = \frac{g}{l} \frac{M}{m_2} \left[-\frac{\sqrt{M m_2}}{m_1} \mp \frac{M}{m_1} \right]$$

$$= \mp \sqrt{\frac{M}{m_2}} \cdot \frac{g}{l} \cdot \frac{1}{m_1} [M \pm \sqrt{M m_2}] = \mp \sqrt{\frac{M}{m_2}} \lambda$$

$$\boxed{a_2 = \mp a_1 \sqrt{\frac{m_1+m_2}{m_2}}} \equiv \mp a \sqrt{\frac{m_1+m_2}{m_2}} \quad a_1 \equiv a$$

Use normalization $A^T T A = 1 = l^2(a_1, a_2) \begin{pmatrix} M m_2 \\ m_2 m_2 \end{pmatrix} \begin{pmatrix} a_1 \\ a_2 \end{pmatrix}$

$$1 = l^2(a_1^2 M + 2a_1 a_2 m_2 + a_2^2 m_2) = 2l^2 a^2 (M \mp \sqrt{m_2 M})$$

$$a = \frac{1}{\sqrt{2}l} \cdot \frac{1}{\sqrt{M \mp \sqrt{m_2 M}}}$$

$$\boxed{A_{\pm} = \begin{pmatrix} a_1 \\ a_2 \end{pmatrix} = \frac{1}{\sqrt{2}l} \cdot \frac{1}{\sqrt{M \mp \sqrt{m_2 M}}} \begin{pmatrix} 1 \\ \mp \sqrt{\frac{M}{m_2}} \end{pmatrix}}$$

Note that for the high frequency mode, the motion of each mass is opposite each other.

⊗ For $m_1 = m_2$ $\lambda = \frac{g}{l} [2 \pm \sqrt{2}]$ and $A = \frac{1}{\sqrt{2}ml} \cdot \frac{1}{\sqrt{2 \mp \sqrt{2}}} \begin{pmatrix} 1 \\ \mp \sqrt{2} \end{pmatrix}$

* Beats

Define $A_{\pm} \equiv K_{\pm} \begin{pmatrix} 1 \\ \mp \beta \end{pmatrix}$ where $A_+ = \begin{pmatrix} a_{1+} \\ a_{2+} \end{pmatrix}$ and $A_- = \begin{pmatrix} a_{1-} \\ a_{2-} \end{pmatrix}$ & $\beta = \sqrt{\frac{M}{m_2}}$

So that $a_{1+} = K_-$, $a_{2+} = -K_- \beta$, $a_{1-} = K_+$, $a_{2-} = K_+ \beta$

Initial conditions: $\eta(0) = \begin{pmatrix} \theta_1(0) \\ \theta_2(0) \end{pmatrix} = \begin{pmatrix} \theta_0 \\ 0 \end{pmatrix}$ & $\dot{\eta}(0) = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$

$$\omega = \sqrt{\lambda}$$

General solution $\eta_i = C_k a_{ik} e^{-i\omega_k t}$

For the coefficients we know that $\text{Re } C_k = a_{jk} T_{jk} \eta_j(0)$

and $\text{Im } C_k = \frac{1}{\omega_k} a_{jk} T_{jk} \dot{\eta}_j(0) = 0$

Each one is:

$$\begin{cases} \text{Re } C_+ = a_{1+} T_{11} \eta_1(0) + a_{1+} T_{12} \eta_2(0) + a_{2+} T_{21} \eta_1(0) + a_{2+} T_{22} \eta_2(0) \\ \quad = \theta_0 l^2 (a_{1+} M + a_{2+} m_2) \end{cases}$$

$$\text{Re } C_- = \theta_0 l^2 (a_{1-} M + a_{2-} m_2)$$

$$\Delta \theta_1(t) = \text{Re} [C_+ a_{1+} e^{-i\omega_+ t} + C_- a_{1-} e^{-i\omega_- t}]$$

$$= (\text{Re } C_+) a_{1+} \cos \omega_+ t + (\text{Re } C_-) a_{1-} \cos \omega_- t$$

$$\theta_2(t) = (\text{Re } C_+) a_{2+} \cos \omega_+ t + (\text{Re } C_-) a_{2-} \cos \omega_- t$$

$$\text{Now } (\text{Re } C_+) a_{1+} = \theta_0 l^2 K_-^2 (M - \beta m_2) = \theta_0 l^2 \frac{1}{2l^2} \frac{1}{(M - \beta m_2)} (M - \beta m_2) = \theta_0 / 2$$

$$(\text{Re } C_-) a_{1-} = \theta_0 l^2 K_+^2 (M + \beta m_2) = \theta_0 / 2$$

$$\text{likewise } (\text{Re } C_+) a_{2+} = -\frac{\theta_0}{2} \beta \text{ and } (\text{Re } C_-) a_{2-} = \frac{\theta_0}{2} \beta$$

$$\Delta \theta_1(t) = \frac{\theta_0}{2} (\cos \omega_+ t + \cos \omega_- t)$$

$$\theta_2(t) = -\frac{\theta_0}{2} \beta (\cos \omega_+ t - \cos \omega_- t)$$

Defining $\bar{\omega} \equiv \frac{1}{2}(\omega_+ + \omega_-)$ and $\Delta\omega \equiv \frac{1}{2}(\omega_+ - \omega_-)$ then $\omega_{\pm} = \bar{\omega} \pm \Delta\omega$

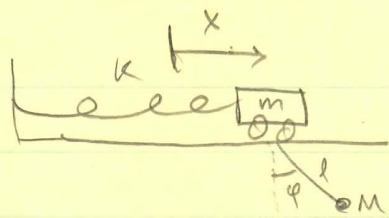
where $\bar{\omega} > \Delta\omega$. Then solutions become

$$\boxed{\theta_1(t) = \theta_0 \cos \bar{\omega} t \cos \Delta\omega t \quad \text{and} \quad \theta_2(t) = \theta_0 \beta \sin \bar{\omega} t \sin \Delta\omega t}$$

These solutions have oscillations at $\bar{\omega}$ with a periodic amplitude modulation with freq $\Delta\omega$. The modulation is 90° out of phase such that when $\theta_1(t) = 0$ at $t = (2n+1)\pi / 2\Delta\omega$, $\theta_2(t)$ is a maximum.

These form "beats".

Prob. 2.



Two degrees of freedom x, φ

$$\vec{r}_1 = x\hat{x} \text{ and } \vec{r}_2 = (x + l\sin\varphi)\hat{x} - l\cos\varphi\hat{y}$$

By calculating the M_{jk} and using the small angle approx

$$KE = \frac{1}{2}(m+M)\dot{x}^2 + Ml\dot{x}\dot{\varphi} + \frac{1}{2}Ml^2\dot{\varphi}^2$$

$$\Rightarrow [T_{ij}] = \begin{pmatrix} m+M & Ml \\ Ml & Ml^2 \end{pmatrix}$$

Potential energy: $V \approx \frac{1}{2}kx^2 + \frac{1}{2}Mgl\varphi^2 - Mgl \Rightarrow [V_{ij}] = \begin{pmatrix} k & 0 \\ 0 & Mgl \end{pmatrix}$

Characteristic equation

$$\begin{vmatrix} k - \lambda(m+M) & -\lambda Ml \\ -\lambda Ml & Mgl - \lambda Ml^2 \end{vmatrix} = 0 = [k - \lambda(m+M)][Mgl - \lambda Ml^2] - \lambda^2 M^2 l^2$$

$$\Rightarrow \lambda^2 ml - \lambda[(m+M)g + kl] + kg = 0$$

roots $\lambda_{\pm} = \frac{1}{2} \left[\left(1 + \frac{M}{m}\right)\omega_0^2 + \omega_1^2 \pm \sqrt{\left[\left(1 + \frac{M}{m}\right)\omega_0^2 + \omega_1^2\right]^2 - 4\omega_0^2\omega_1^2} \right]$

where $\omega_0^2 \equiv g/l$ and $\omega_1^2 \equiv k/m$ and $\omega_{\pm} = \sqrt{\lambda_{\pm}}$

For the eigenvectors, use 1st row

$$[k - \lambda(m+M)]a_1 - \lambda Mla_2 = 0$$

that have to satisfy $A^T A = 1 \Rightarrow (m+M)a_1^2 + 2Mla_1a_2 + Ml^2a_2^2 = 1$

Using algebra software $a_{1\pm} = (\lambda_{\pm}) \sqrt{\frac{M}{B_{\pm}}}$; $a_{2\pm} = \frac{-1}{Ml} (\lambda_{\pm}(m+M) - k) \sqrt{\frac{M}{B_{\pm}}}$

where $B_{\pm} \equiv \lambda_{\pm}^2 m^2 + (\lambda_{\pm}^2 M - 2\lambda_{\pm} k)m + k^2$ eigenvectors $A_{\pm} = \begin{pmatrix} a_{1\pm} \\ a_{2\pm} \end{pmatrix}$

Take the limit $\frac{M}{m} \ll 1$:

$$\lambda_{\pm} \approx \frac{1}{2} \left[\omega_0^2 + \omega_1^2 \pm \sqrt{[\omega_0^2 + \omega_1^2]^2 - 4\omega_0^2\omega_1^2} \right]$$

$$= \frac{1}{2} [\omega_0^2 + \omega_1^2 \pm (\omega_0^2 - \omega_1^2)]$$

$\left. \begin{matrix} \lambda_+ = \omega_0^2 \\ \lambda_- = \omega_1^2 \end{matrix} \right\}$ the two oscillator behave as if they were decoupled.

p6.3.

$$T = \frac{1}{2}m(\dot{x}_1^2 + \dot{x}_2^2) \quad \& \quad V = b x_1 x_2$$

$$[T_{ij}] = \begin{pmatrix} m & 0 \\ 0 & m \end{pmatrix} \quad [V_{ij}] = \begin{pmatrix} 0 & b \\ b & 0 \end{pmatrix}$$

Characteristic equation $|V - \lambda T| = 0$ $\begin{vmatrix} -\lambda m & b \\ b & -\lambda m \end{vmatrix} = 0$

$$\lambda^2 m^2 - b^2 = 0 \Rightarrow \boxed{\lambda_{\pm} = \pm b/m}$$

For eigenvectors, solve

$$-\lambda m a_1 + b a_2 = 0 \quad \text{and} \quad a_1^2 m + a_2^2 m = 1$$

$$a_1 = +b \frac{1}{\sqrt{m} \sqrt{\lambda^2 m^2 + b^2}} \quad \text{and} \quad a_2 = \frac{\lambda \sqrt{m}}{\sqrt{\lambda^2 m^2 + b^2}}$$

* For $\lambda_+ = b/m$ $a_1 = \frac{1}{\sqrt{2m}}$ $a_2 = \frac{1}{\sqrt{2m}}$

* For $\lambda_- = -b/m$ $a_1 = \frac{1}{\sqrt{2m}}$ $a_2 = -\frac{1}{\sqrt{2m}}$

$$\boxed{A_+ = \frac{1}{\sqrt{2m}} \begin{pmatrix} 1 \\ 1 \end{pmatrix} \quad A_- = \frac{1}{\sqrt{2m}} \begin{pmatrix} 1 \\ -1 \end{pmatrix}}$$

* General Solution $\eta_i = c_k a_{ik} e^{-i\omega_k t}$

$$X_1(t) = c_+ a_{1+} e^{-i\omega_+ t} + c_- a_{1-} e^{-i\omega_- t}$$

$$X_2(t) = c_+ a_{2+} e^{-i\omega_+ t} + c_- a_{2-} e^{-i\omega_- t}$$

Now $\omega_{\pm} = \sqrt{\lambda_{\pm}} = \sqrt{\pm b/m} \rightarrow \omega_+ = \gamma, \omega_- = i\gamma$ $\gamma = \sqrt{b/m}$

$$\boxed{X_1(t) = \frac{1}{\sqrt{2m}} [c_+ e^{-i\gamma t} + c_- e^{\gamma t}]}$$

$$\boxed{X_2(t) = \frac{1}{\sqrt{2m}} [c_+ e^{-i\gamma t} - c_- e^{\gamma t}]}$$

Solutions are the real part of these expressions.

* Find normal coordinates from $\tilde{z} = A^{-1} \eta$

$$A = \frac{1}{\sqrt{2m}} \begin{pmatrix} 1 & 1 \\ 1 & -1 \end{pmatrix} \Rightarrow A^{-1} = \sqrt{\frac{m}{2}} \begin{pmatrix} 1 & 1 \\ 1 & -1 \end{pmatrix}$$

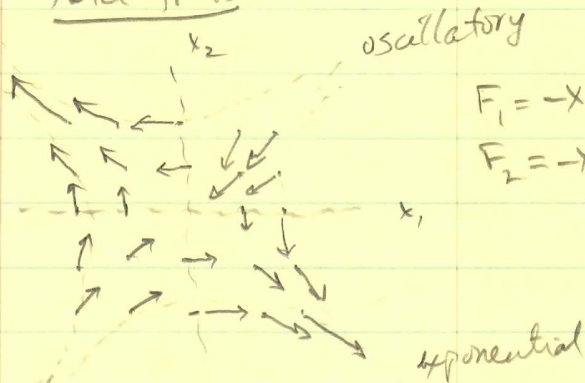
$$\begin{pmatrix} \tilde{z}_1 \\ \tilde{z}_2 \end{pmatrix} = \sqrt{\frac{m}{2}} \begin{pmatrix} 1 & 1 \\ 1 & -1 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \sqrt{\frac{m}{2}} \begin{pmatrix} x_1 + x_2 \\ x_1 - x_2 \end{pmatrix}$$

$$\Rightarrow \boxed{\tilde{z}_1(t) = c_+ e^{-i\gamma t} \quad \tilde{z}_2(t) = c_- e^{\gamma t}}$$

oscillatory

exponential growth

the solution can be understood by looking at the Force field



$$\left. \begin{array}{l} F_1 = -x_2 \\ F_2 = -x_1 \end{array} \right\} \text{ forces } \vec{F} = (-x_2, -x_1)$$

the particle will perform oscillatory motion in the $x_1 = -x_2$ line and go to infinity on the

$x_1 = -x_2$ line. But the purely oscillatory motion is unstable as any perturbation away from $x_1 = -x_2$ will push the particle to $\pm\infty$.

Note that the normal coordinates are a 45° rotation of the $x_1 - x_2$ axis. the A matrix rotates the coordinates

