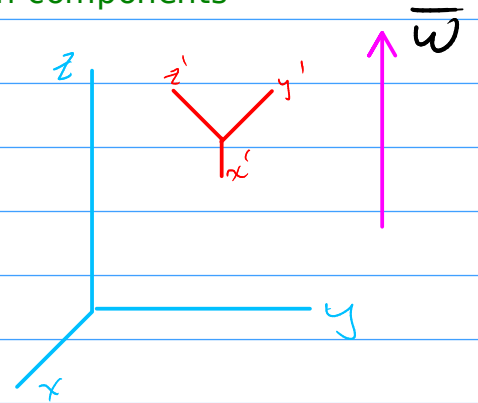


## Expressing the angular velocity in terms of Cartesian components

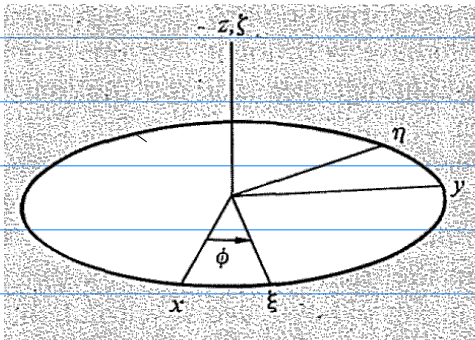
Time rate change of vectors on a rotating axis

$$\left(\frac{d}{dt}\right)_s = \left(\frac{d}{dt}\right)_r + \bar{\omega} \times$$



$$\bar{\omega} \rightarrow \omega_\varphi = \dot{\varphi} \quad \omega_\psi = \dot{\psi}$$

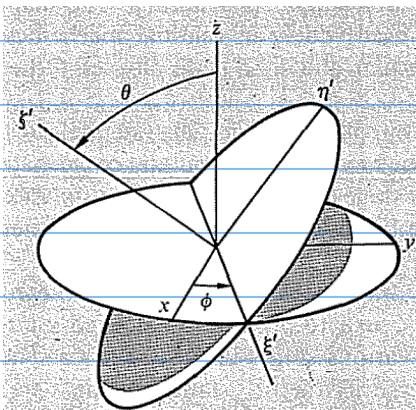
$$\omega_\theta = \dot{\theta}$$



$$\varphi: \omega_\varphi^x = 0$$

$$\omega_\varphi^y = 0$$

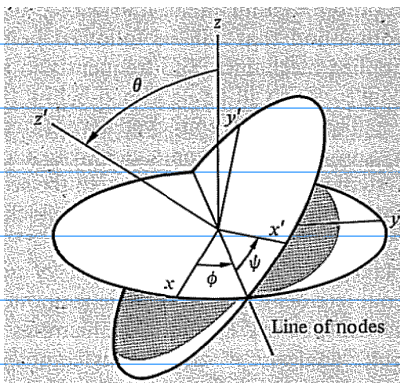
$$\omega_\varphi^z = \dot{\varphi}$$



$$\theta: \omega_\theta^{\xi'} = \dot{\theta}$$

$$\omega_\theta^{\eta'} = 0$$

$$\omega_\theta^{\zeta'} = 0$$



$$\psi: \omega_\psi^{\xi'} = 0$$

$$\omega_\psi^{\eta'} = 0$$

$$\omega_\psi^{\zeta'} = \dot{\psi}$$

$$\psi: \omega_{\psi}^{x'} = 0 \quad \omega_{\psi}^{y'} = 0 \quad \omega_{\psi}^{z'} = \dot{\psi}$$

$$\theta: \begin{pmatrix} \omega_{\theta}^{x'} \\ \omega_{\theta}^{y'} \\ \omega_{\theta}^{z'} \end{pmatrix} = \underbrace{\begin{pmatrix} \cos \psi & \sin \psi & 0 \\ -\sin \psi & \cos \psi & 0 \\ 0 & 0 & 1 \end{pmatrix}}_B \begin{pmatrix} \omega_{\theta}^{x''} \\ \omega_{\theta}^{y''} \\ \omega_{\theta}^{z''} \end{pmatrix}$$

$$= \begin{pmatrix} \cos \psi & \sin \psi & 0 \\ -\sin \psi & \cos \psi & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} \dot{\theta} \\ 0 \\ 0 \end{pmatrix}$$

$$\omega_{\theta}^{x'} = \dot{\theta} \cos \psi$$

$$\omega_{\theta}^{y'} = -\dot{\theta} \sin \psi$$

$$\omega_{\theta}^{z'} = 0$$

$$\varphi: \begin{pmatrix} \omega_{\varphi}^{x'} \\ \omega_{\varphi}^{y'} \\ \omega_{\varphi}^{z'} \end{pmatrix} = A \begin{pmatrix} 0 \\ 0 \\ \dot{\varphi} \end{pmatrix}$$

$$A = BCD$$

$$\omega_{\varphi}^{x'} = \dot{\varphi} \sin \psi \sin \theta$$

$$\omega_{\varphi}^{z'} = \dot{\varphi} \cos \theta$$

$$\omega_{\varphi}^{y'} = \dot{\varphi} \cos \psi \sin \theta$$

$$\omega_{x'} = \dot{\varphi} \sin \psi \sin \theta + \dot{\theta} \cos \psi$$

$$\omega_{y'} = \dot{\varphi} \cos \psi \sin \theta - \dot{\theta} \sin \psi$$

$$\omega_{z'} = \dot{\varphi} \cos \theta + \dot{\psi}$$