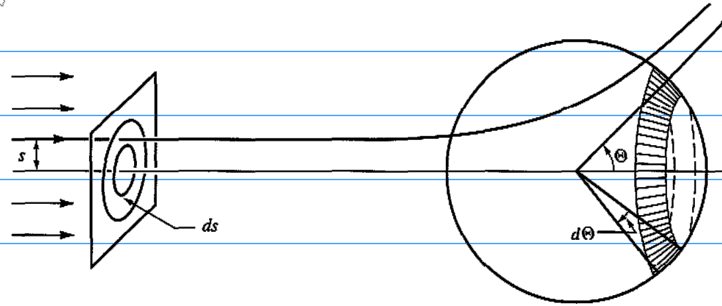


## Scattering in a central force field



$$\sigma(\vec{\Omega}) d\Omega$$

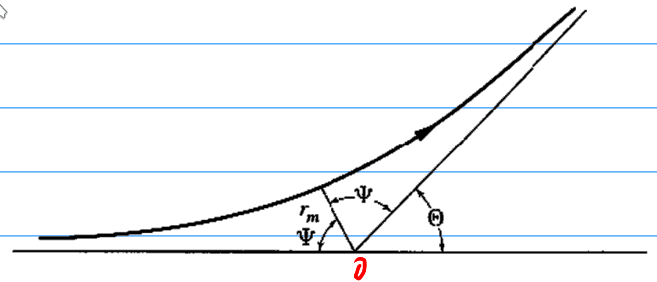
$$\underbrace{I}_{\text{Part/time}} \underbrace{2\pi s |ds|}_{\text{area ring}} = I \sigma(\vec{\Omega}) d\Omega = I \sigma(\theta) 2\pi s \sin\theta |d\theta|$$

$$\sigma(\theta) = \frac{s}{\sin\theta} \left| \frac{ds}{d\theta} \right|$$

$$s = s(\theta, E)$$

$$\theta = \pi - 2\psi$$

$$\psi = \int_{r_0}^r \frac{dr}{r^2 \sqrt{\frac{2m}{\hbar^2} (E - V) - \frac{1}{r^2}}}$$



$$l = s \sqrt{2mE}$$

$$\theta = \pi - 2 \int_{r_m}^{\infty} \frac{dr}{r^2 \sqrt{\frac{1}{s^2 E} (E - V) - \frac{1}{r^2}}}$$

$$r = 1/u$$

$$dr = -\frac{du}{u^2}$$

$$\theta = \pi - 2 \int_0^{u_m} \frac{s du}{\sqrt{1 - \frac{V}{E} - s^2 u^2}}$$

Lets look at the specific example of scattering by a Coulombic repulsive force.

scatt ctr  $Ze$

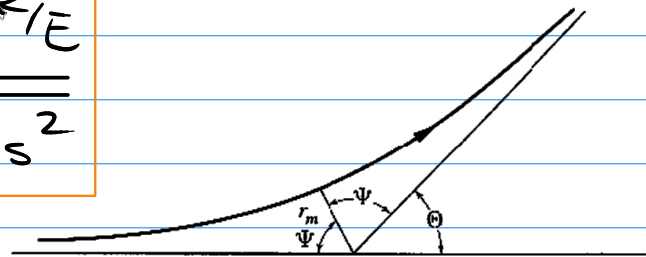
part.  $z'e$

$$f = \frac{Zz'e^2}{r^2} = Ku^2$$

$$V = \frac{K}{r} = Ku$$

$$\psi = \int_u^{u_m} \frac{s du}{\sqrt{1 - \frac{K}{E}u - s^2 u^2}}$$

$$\psi(u) = \sin^{-1} \frac{2s^2 u + K/E}{\sqrt{(K/E)^2 + 4s^2}}$$



$$\psi(u_m): E = \frac{1}{2} m \dot{r}_m^2 + \frac{1}{2} m r_m^2 \dot{\theta}^2 + \frac{K}{r_m}$$

$$m r_m^2 \dot{\theta} = L = m v_0 s = s \sqrt{2 E m} \quad // \quad E = \frac{1}{2} m v_0^2$$

$$\dot{\theta} = \frac{s}{r_m^2} \sqrt{\frac{2 E}{m}}$$

$$E = \frac{1}{2} m r_m^2 \frac{s^2}{r_m^4} \frac{2 E}{m} + \frac{K}{r_m} = \frac{s^2}{r_m^2} E + \frac{K}{r_m}$$

$$\Rightarrow s^2 = r_m^2 \left(1 - \frac{K}{E r_m}\right) = \frac{1}{u_m^2} - \frac{K}{E} \cdot \frac{1}{u_m}$$

$$\psi(u_m) = \sin^{-1} \frac{\frac{2}{u_m} \left(1 - \frac{K}{E} u_m\right) + \frac{K}{E}}{\sqrt{\left(\frac{K}{E}\right)^2 + \frac{4}{u_m^2} \left(1 - \frac{K}{E} u_m\right)}} = \sin^{-1}(1) = \pi/2$$

$$\eta(u) = \sin^{-1} \frac{2s^2 u + \frac{k}{E}}{\sqrt{\left(\frac{k}{E}\right)^2 + 4s^2}}$$

$$\lambda = \sqrt{2mE}$$

$$s^2 = \frac{\lambda^2}{2mE}$$

$$= \sin^{-1} \frac{\frac{2}{r} \left( \frac{\lambda^2}{2mE} + \frac{k}{E} \right) \frac{E}{k}}{\sqrt{\left[ \left( \frac{k}{E} \right)^2 + \frac{4\lambda^2}{2mE} \right] \frac{E^2}{k^2}}}$$

$$= \sin^{-1} \frac{\frac{\lambda^2}{mkr} + 1}{\sqrt{1 + \frac{2\lambda^2 E}{mk^2}}}$$

$$\epsilon = \sqrt{1 + \frac{2E\lambda^2}{mk^2}}$$

$$\eta(u) = \sin^{-1} \frac{1}{\epsilon} \left( \frac{\lambda^2}{mkr} + 1 \right)$$

$$\eta(r) = \frac{\pi}{2} - \left[ \frac{\pi}{2} - \cos^{-1} \frac{1}{\epsilon} \left( \frac{\lambda^2}{mkr} + 1 \right) \right]$$

$$\frac{1}{r} = \frac{mkz'e^2}{\lambda^2} (\epsilon \cos \eta - 1)$$

$$r \rightarrow \infty : \frac{1}{r} \rightarrow 0 \Rightarrow \epsilon \cos \eta = 1$$

$$\theta = \pi - 2\eta$$

$$\cos \eta = \sin \frac{\theta}{2}$$

$$\sin \frac{\theta}{2} = \frac{1}{\epsilon}$$

$$\frac{1}{\sin^2 \frac{\theta}{2}} = \epsilon^2$$

$$\frac{1}{\sin^2 \frac{\theta}{2}} - 1 = \epsilon^2 - 1$$

$$\frac{\cos^2 \frac{\theta}{2}}{\sin^2 \frac{\theta}{2}} = \epsilon^2 - 1$$

$$\cot^2 \frac{\theta}{2} = \epsilon^2 - 1$$

$$\cot^2 \frac{\theta}{2} = \frac{2E l^2}{m k^2} = \left( \frac{2E s}{2Z' e^2} \right)^2$$

$$l = s \sqrt{2mE}$$

$$s = \frac{2Z' e^2}{2E} \cot \frac{\theta}{2}$$

$$\frac{ds}{d\theta} = \frac{2Z' e^2}{2E} \left( -\frac{1}{2} \right) \csc^2 \frac{\theta}{2}$$

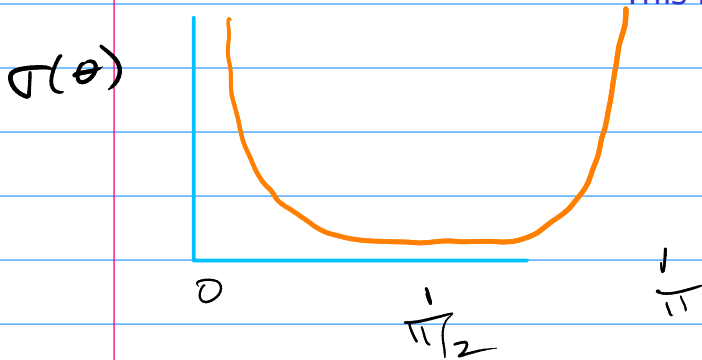
$$\sigma(\theta) = \frac{s}{\sin \theta} \left| \frac{ds}{d\theta} \right|$$

$$= \frac{s}{\sin \theta} \frac{2Z' e^2}{2E} \left( \frac{1}{2} \right) \csc^2 \frac{\theta}{2}$$

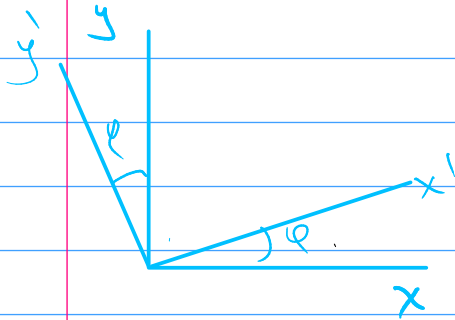
$$= \underbrace{\left( \frac{2Z' e^2}{2E} \cot \frac{\theta}{2} \right)}_s \underbrace{\frac{1}{2 \sin \frac{\theta}{2} \cos \frac{\theta}{2}} \left( \frac{2Z' e^2}{2E} \right) \frac{1}{2} \csc^2 \frac{\theta}{2}}_{1/4 \sin \theta}$$

$$\sigma(\theta) = \frac{1}{4} \left( \frac{2Z' e^2}{2E} \right)^2 \csc^4 \frac{\theta}{2}$$

This is the Rutherford scattering cross section



## Rotation of rigid bodies



$$x' = x \cos \varphi + y \sin \varphi$$

$$y' = -x \sin \varphi + y \cos \varphi$$

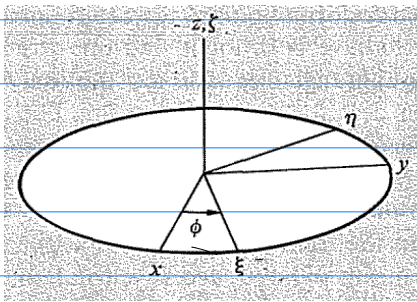
$$A = \begin{pmatrix} \cos \varphi & \sin \varphi \\ -\sin \varphi & \cos \varphi \end{pmatrix}$$

$$\begin{pmatrix} x' \\ y' \end{pmatrix} = A \begin{pmatrix} x \\ y \end{pmatrix} \Rightarrow x' = A x$$

## The Euler Angles

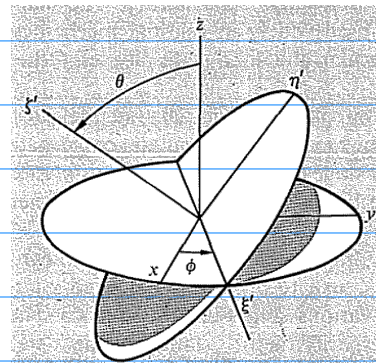
$\varphi, \theta, \psi$

(1)



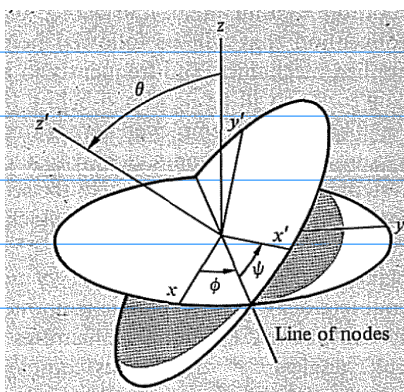
rotate by  $\varphi$  along  $z$

rotate by  $\theta$   
along  $\xi$



(2)

(3)



rotate by  $\psi$   
along  $z'$

$$(1) \xi = DX \quad (2) \xi' = C\xi \quad (3) x' = B\xi'$$

$$x' = Ax \quad \longrightarrow \quad A = BCD$$

$$D = \begin{pmatrix} \cos \varphi & \sin \varphi & 0 \\ -\sin \varphi & \cos \varphi & 0 \\ 0 & 0 & 1 \end{pmatrix} \quad \text{about } z$$

$$C = \begin{pmatrix} 1 & 0 & 0 \\ 0 & \cos \theta & \sin \theta \\ 0 & -\sin \theta & \cos \theta \end{pmatrix} \quad \text{about } \xi$$

$$B = \begin{pmatrix} \cos \psi & \sin \psi & 0 \\ -\sin \psi & \cos \psi & 0 \\ 0 & 0 & 1 \end{pmatrix} \quad \text{about } \xi'$$

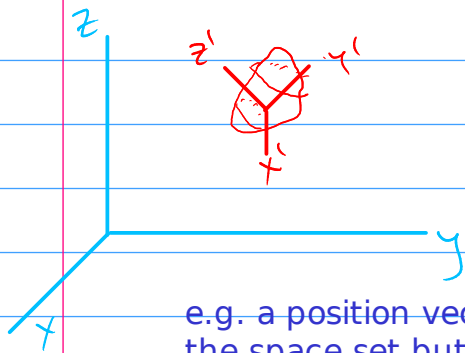
$$A = BCD$$

$$A = \begin{bmatrix} \cos \psi \cos \phi - \cos \theta \sin \phi \sin \psi & \cos \psi \sin \phi + \cos \theta \cos \phi \sin \psi & \sin \psi \sin \theta \\ -\sin \psi \cos \phi - \cos \theta \sin \phi \cos \psi & -\sin \psi \sin \phi + \cos \theta \cos \phi \cos \psi & \cos \psi \sin \theta \\ \sin \theta \sin \phi & -\sin \theta \cos \phi & \cos \theta \end{bmatrix}$$

$$x' = Ax$$

$$x = A^{-1} x' = A^T x'$$

## Rate of change of a vector



$x, y, z$

space set of axes

$x', y', z'$

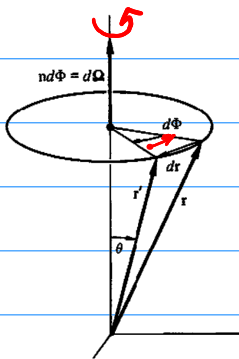
body set of axes

e.g. a position vector relative to the body set will change relative to the space set but not to the body set.

The time-rate of change of the components will be different depending on the axes of reference.

$\bar{G}$

$$\left( \frac{d\bar{G}}{dt} \right)_{\text{space}} = \left( \frac{d\bar{G}}{dt} \right)_{\text{body}} + \left( \frac{d\bar{G}}{dt} \right)_{\text{rot}}$$



$$\frac{d\bar{G}}{dt}_{\text{rot}} = \frac{d\bar{\Omega}}{dt} \times \bar{G}$$

$$\left( \frac{d\bar{G}}{dt} \right)_{\text{space}} = \left( \frac{d\bar{G}}{dt} \right)_{\text{body}} + \frac{d\bar{\Omega}}{dt} \times \bar{G}$$

$$\left( \frac{d\bar{G}}{dt} \right)_s = \left( \frac{d\bar{G}}{dt} \right)_r + \bar{\omega} \times \bar{G}$$

$$\bar{\omega} dt = d\bar{\Omega}$$

$$\left( \frac{d}{dt} \right)_s = \left( \frac{d}{dt} \right)_r + \bar{\omega} \times$$

## The Coriolis Effect

$$\bar{G} = \bar{r}$$

$$\left( \frac{d}{dt} \bar{r} \right)_s = \left( \frac{d}{dt} \bar{r} \right)_r + \bar{\omega} \times \bar{r}$$

$$\bar{v}_s = \bar{v}_r + \bar{\omega} \times \bar{r}$$

velocity rel.  
to space set

vel. rel.  
body set

angular velocity

$$\begin{aligned}
 \left( \frac{d\vec{v}_s}{dt} \right)_s &= \left( \frac{d\vec{v}_s}{dt} \right)_r + \vec{\omega} \times \vec{v}_s \\
 &= \left( \frac{d}{dt} (\vec{v}_r + \vec{\omega} \times \vec{r}) \right)_r + \vec{\omega} \times ( \quad ) \\
 &= \vec{a}_r + 2\vec{\omega} \times \vec{v}_r + \vec{\omega} \times (\vec{\omega} \times \vec{r})
 \end{aligned}$$

$$\vec{F} = m\vec{a}_s$$

$$m\vec{a}_r = \vec{F} - 2m\vec{\omega} \times \vec{v}_r - m\vec{\omega} \times (\vec{\omega} \times \vec{r})$$

$$\vec{F}_{\text{eff}} =$$

$\underbrace{\hspace{10em}}$   
Coriolis eff

$\underbrace{\hspace{10em}}$   
centrifugal  
force

$$\omega \sim 7 \times 10^{-5}$$