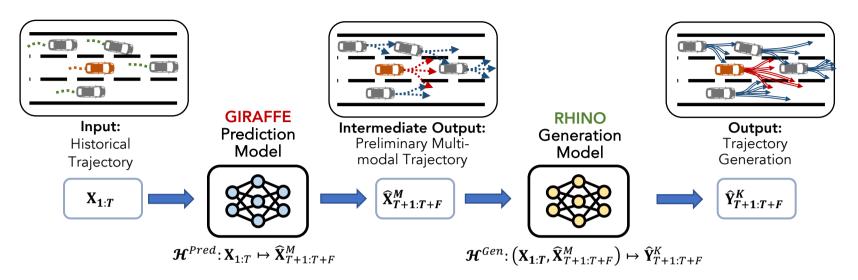
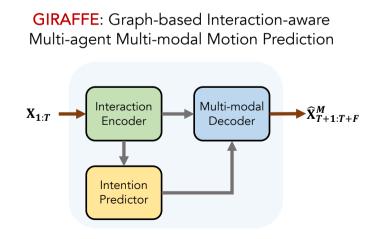
Motion Generation Framework Architecture





Reasoning for Motion Generation Future Hypergraph $\widehat{\mathbf{X}}_{T+1:T+F}^{M}$ Relational Encoder Posterior Motion $\triangleright \widehat{\mathbf{Y}}_{T+1:T+F}^K$ Distribution Generator Learner Historical Hypergraph Relational Encoder

RHINO: Hypergraph-based Interaction Relational