

A splitting deep Ritz method for option pricing in Lévy models

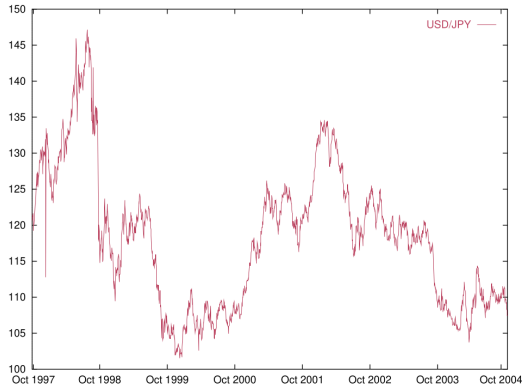
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Objectives

- ▶ Pricing options in scenarios where the underlying stock values exhibit discontinuities.
- ▶ Our focus is on options involving a large number of underlying assets.



- ▶ $\{\alpha_i\}_{i=1,\dots,d}$: weights on underlyings ($\sum_i \alpha_i = 1$)
- ▶ K : the strike price

Payoff function

$$\text{Payoff}(s) = \left(\sum_{i=1}^d \alpha_i s_i - K \right)^+$$

Moneynesses : $x_i = s_i / K$

$$\text{Payoff}(x) = \left(\sum_{i=1}^d \alpha_i x_i - 1 \right)^+$$

Using FTAP and Feynman-Kac the option price is provided by:

$$\partial_t u(t, x) + \mathcal{A}u(t, x) = 0, \quad t > 0, \quad x \in [0, \infty)^d$$

$$u(0, x) = \text{Payoff}(x), \quad x \in [0, \infty)^d$$

► \mathcal{A} : PIDE operator

$$\mathcal{A}u = - \sum_{i,j=1}^d a_{ij}(x) \frac{\partial^2 u}{\partial x_i \partial x_j} + \sum_{i=1}^d b_i(x) \frac{\partial u}{\partial x_i} + ru + g[u]$$

where $a_{ij}(x) = a_{ji}(x)$, $i, j = 1, \dots, d$ and $g[u]$ is an integral operator.

$$\mathcal{A}u = - \sum_{i,j=1}^d a_{ij}(x) \frac{\partial^2 u}{\partial x_i \partial x_j} + \sum_{i=1}^d b_i(x) \frac{\partial u}{\partial x_i} + ru + g[u]$$

We rewrite the operator as follows

$$\mathcal{A}u = - \sum_{j=1}^d \frac{\partial}{\partial x_j} \left(\sum_{i=1}^d a_{ij}(x) \frac{\partial u}{\partial x_i} \right) + \sum_{i=1}^d \left(b_i(x) + \sum_{j=1}^d \frac{\partial}{\partial x_j} a_{ij}(x) \right) \frac{\partial u}{\partial x_i} + ru + g[u]$$

$$\mathcal{A}u = \mathcal{L}u + f[u]$$

$$\mathcal{L}u = - \sum_{j=1}^d \frac{\partial}{\partial x_j} \left(\sum_{i=1}^d a_{ij}(x) \frac{\partial u}{\partial x_i} \right) + ru \quad (\text{symmetric})$$

$$f[u] = \sum_{i=1}^d \left(b_i(x) + \sum_{j=1}^d \frac{\partial}{\partial x_j} a_{ij}(x) \right) \frac{\partial u}{\partial x_i} + g[u] \quad (\text{remainder})$$

$$\mathcal{A}u = \mathcal{L}u + f[u], \quad \mathcal{E}[u] = \int_{\Omega} L(x, u, \nabla u) dx$$

$$\begin{aligned} \frac{\delta \mathcal{E}[u]}{\delta u} &= \left. \frac{d}{d\epsilon} \mathcal{E}[u + \epsilon v] \right|_{\epsilon=0} = \int_{\Omega} \sum_{k=1}^d \frac{\partial L}{\partial (\nabla u)_k} \frac{\partial v}{\partial x_k} + \frac{\partial L}{\partial u} v \, dx \\ &= \int_{\Omega} \left(- \sum_{k=1}^d \frac{\partial}{\partial x_k} \left(\frac{\partial L}{\partial (\nabla u)_k} \right) + \frac{\partial L}{\partial u} \right) v \, dx. \end{aligned}$$

$$\frac{\delta \mathcal{E}[u]}{\delta u} = 0 \Leftrightarrow - \sum_{k=1}^d \frac{\partial}{\partial x_k} \left(\frac{\partial L}{\partial (\nabla u)_k} \right) + \frac{\partial L}{\partial u} = 0 \quad (\text{Euler-Lagrange})$$

$$L_{\mathcal{L}} = \frac{1}{2} \sum_{i,j=1}^d a_{ij}(x) \frac{\partial u}{\partial x_i} \frac{\partial u}{\partial x_j} + \frac{1}{2} r u^2 \quad (\text{Lagrangian}) \Rightarrow - \sum_{k=1}^d \frac{\partial}{\partial x_k} \left(\frac{\partial L_{\mathcal{L}}}{\partial (\nabla u)_k} \right) + \frac{\partial L_{\mathcal{L}}}{\partial u} = \mathcal{L}u = 0$$

Suppose we would like to estimate the solution of the following equation:

$$\begin{aligned}\partial_t u(t, x) + \mathcal{L}u(t, x) + f[u(t, x)] &= 0, \quad x \in [0, x_{\max}]^d = \Omega, \quad t \in [0, T] \\ u(0, x) &= \text{Payoff}(x)\end{aligned}$$

We consider a time subdivision of the time interval $[0, T]$

$$\tau = T/n, \quad t_k = k\tau, \quad k = 0, \dots, n$$

$$u^k(x) \doteq u(t_k, x)$$

BDF-2 method (implicit - explicit)

$$\frac{u^k - 4/3u^{k-1} + 1/3u^{k-2}}{\tau} + \frac{2}{3}\mathcal{L}u^k + \frac{2}{3}(2f[u^{k-1}] - f[u^{k-2}]) = 0$$

BDF-2 method (implicit - explicit)

- Approximate u^1, u^2 using the implicit-explicit Euler method

$$u - \frac{4}{3}u^{k-1} + \frac{1}{3}u^{k-2} + \frac{2}{3}\tau\mathcal{L}u + \frac{2}{3}\tau(2f[u^{k-1}] - f[u^{k-2}]) = 0, \quad u^{k-2}, u^{k-1} \text{ given, } k \geq 3$$

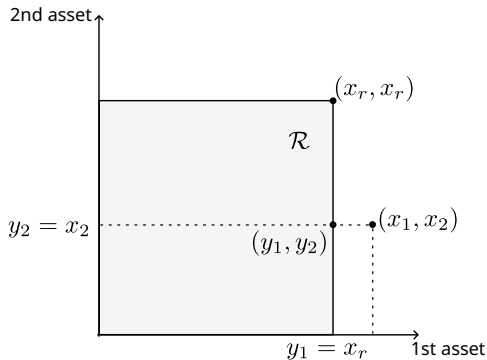
Lagrangian (BDF-2)

$$L = \frac{1}{2} \left(u - \frac{4}{3}u^{k-1} + \frac{1}{3}u^{k-2} \right)^2 + \frac{2}{3}\tau L_{\mathcal{L}}(u) + \frac{2}{3}\tau(2f[u^{k-1}] - f[u^{k-2}])u$$

Minimization Problem

$$\mathcal{C}(\theta; \theta^{k-2}, \theta^{k-1}) \doteq \frac{1}{2} \left\| u - \frac{4}{3}u^{k-1} + \frac{1}{3}u^{k-2} \right\|_{L^2(\Omega)}^2 + \frac{2}{3}\tau\mathcal{E}_{\mathcal{L}}[u] + \frac{2}{3}\tau \int_{\Omega} (2f[u^{k-1}] - f[u^{k-2}])u \, dx,$$

$$\theta^k \rightarrow \min_{\theta} \mathcal{C}(\theta; \theta^{k-2}, \theta^{k-1}), \quad k \in \{3, \dots, n\}$$



Choose $x_r \leq x_{\max}$

Let \mathcal{R} be a rectangle of \mathbb{R}^d such that

$$\mathcal{R} \doteq \{y \in \mathbb{R}^d : y_i \in [0, x_r]\}$$

For $x \in \mathbb{R}_+^d$ we define $y \in \mathcal{R}$ such that

$$y_i = \min\{x_i, x_r\}, \quad i = 1, 2, \dots, d$$

The approach : Taking into account the asymptotic behaviour of the solution

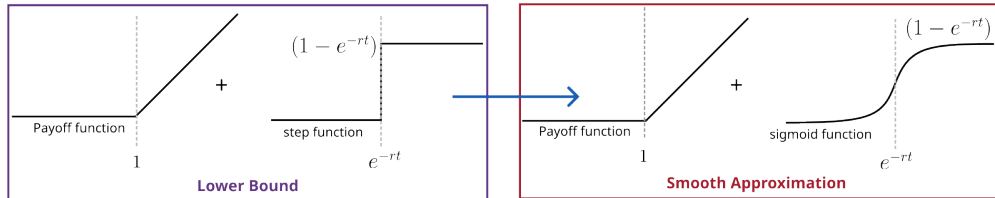
$$u(t, x) \doteq u(t, y) + \sum_{i=1}^d \alpha_i (x_i - y_i), \quad x \in \mathbb{R}_+^d$$

$$\forall x \in \mathbb{R}_+^d \quad x \rightarrow y = y(x) \rightarrow u(t, y) \rightarrow u(t, x)$$

(Solution at time t_k) = (Lower Bound at time t_k) + (positive function)

$$u(t_k, y) = \tilde{u}_{\text{LB}}(t_k, y) + w^k(y, \theta^k)$$

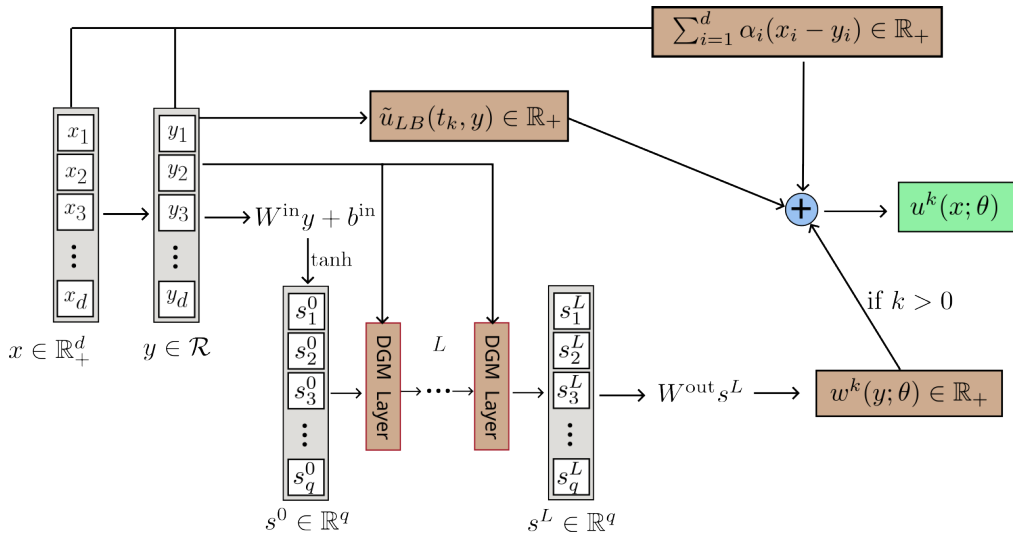
Lower bound at each time-step



$$\tilde{u}_{\text{LB}}(t, x; \gamma) = \text{Payoff}(x) + (1 - e^{-rt}) \text{Sigmoid}\left(\sum_{i=1}^d \alpha_i x_i - e^{-rt/2}; \gamma\right), \gamma > 0$$

$$\text{Sigmoid}(x; \gamma) = \frac{1}{1 + e^{-\gamma x}}.$$

Model : Neural Network



$$w^k(y; \theta) = \text{Softplus}(W^{\text{out}} s^L; \delta)$$

$$\text{Output : } u^k(x; \theta) = (1 - \delta_{k0})w^k(y; \theta) + \tilde{u}_{\text{LB}}(t_k, y) + \sum_{i=1}^d \alpha_i(x_i - y_i),$$

We sample N points in the interval $[0, x_{\max}]^d$. By applying Monte-Carlo to approximate the integrals of the cost functional, we get:

$$\begin{aligned} \mathcal{C}(\theta; \theta^{k-2}, \theta^{k-1}) &\approx \frac{(x_{\max})^d}{N} \sum_{i=1}^N \left[(u(x_i; \theta) - \frac{4}{3}u^{k-1}(x_i) + \frac{1}{3}u^{k-2}(x_i))^2 \right. \\ &\quad \left. + \frac{2}{3}\tau \left(L(x_i) + (2f[u^{k-1}(x_i)] - f[u^{k-2}(x_i)])u(x_i; \theta) \right) \right] \end{aligned}$$

Merton model

$$\mathcal{A}u = - \sum_{i,j=1}^d a_{ij}(x) \frac{\partial^2 u}{\partial x_i \partial x_j} + \sum_{i=1}^d b_i(x) \frac{\partial u}{\partial x_i} + ru + g[u]$$

$$a_{ij}(x) = \frac{1}{2} \sigma_i \rho_{ij} \sigma_j x_i x_j, \quad b_i(x) = [-r + \lambda \exp(\mu_{Ji} + \frac{1}{2} \sigma_{Ji}^2) - \lambda] x_i$$

$$g[u] = - \int_{\mathbb{R}^d} (u(xe^z) - u(x)) \nu(dz)$$

$$\sigma_i = 0.5, \rho_{ij} = \delta_{ij} + 0.5(1 - \delta_{ij}), \quad i, j = 1, \dots, d, \quad r = 0.05, \quad \text{time-step} = 0.02$$

Moreover, the parameters of the jumps are

$$\lambda = 1, \mu_{Ji} = 0, \sigma_{Ji} = 0.5, \rho_{Jij} = \delta_{ij} + 0.2(1 - \delta_{ij}), \quad i, j = 1, \dots, d$$

The integral : Gauss-Hermite quadrature

In Merton model, the integral is simply the expected value of the function $h(z) = u(xe^z) - u(x)$ multiplied by the Poisson parameter λ .

- Singular Value Decomposition (SVD) of Σ_J

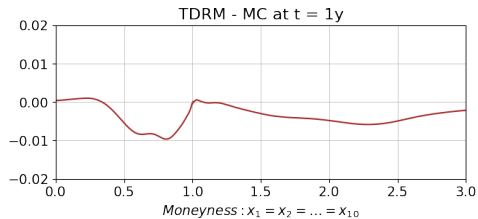
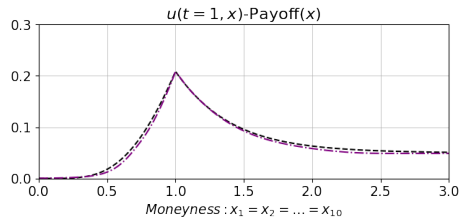
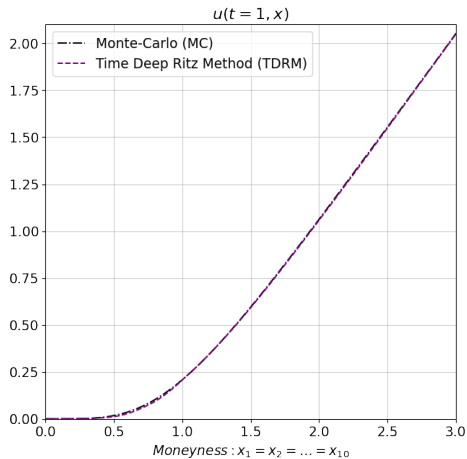
$$\Sigma_J = U\Lambda U^T = U\Lambda^{1/2}\Lambda^{1/2}U^T = VV^T,$$

where $V = U\Lambda^{1/2}$.

- change of variable $Z - \mu = \sqrt{2}VY$

$$\begin{aligned} \int_{\mathbb{R}^d} h(z) \nu(dz) &= \lambda \pi^{-d/2} \int_{\mathbb{R}^d} \exp(y^T y) h(\mu + \sqrt{2}V y) dy \\ &\approx \lambda \pi^{-d/2} \sum_{i \in \Theta_p} h(\mu + \sqrt{2}V y^i) W^i, \end{aligned}$$

10 Assets - Maturity : 1 year



- ▶ We proposed a modified splitting deep Ritz method for option pricing.
- ▶ Our method is capable of accurately approximating the solutions of the partial integro-differential equations (PIDEs) that arise in European basket call options.
- ▶ To evaluate the effectiveness of our method, we compared its results with those obtained using Monte-Carlo simulations.

- ▶ We are working on the multivariate variance Gamma model (infinite jump activity)

Thank you for your attention