

111590004 張意昌 MV_HW4

Approach

[!NOTE]

In this homework, our goal is doing canny edge detection.

There are five steps to complete in this homework.

In this report, I will answer each question and put original images and result for each question.

At the end of report, I will discuss some issue which I found in this homework.

Original Image

[!TIP]

Here is our original pictures.



Step 1 Mark the area you want to segment (output gaussian blur image)

[!IMPORTANT]

In the first step, we need to use gaussian filter.

The formula is:

$$G(x, y) = \frac{1}{2\pi\sigma^2} e^{-(x^2 + y^2)/(2\sigma^2)}$$

σ is the standard deviation (controls the amount of blur).

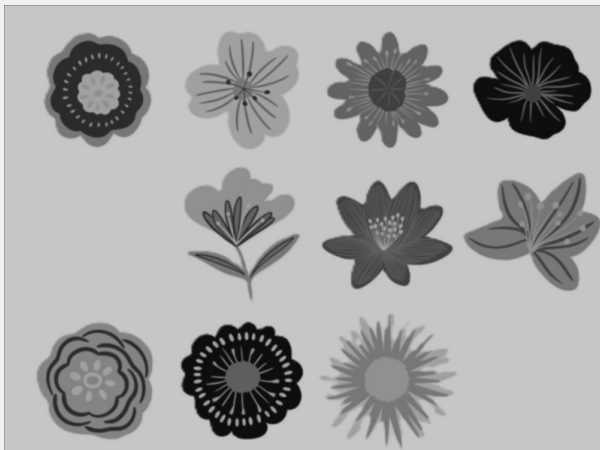
Where σ and kernel size, you need to choose by yourself.

x and y is the distance between the middle point.

I choose $\sigma = 1.0$ and kernel size is 3.

Gaussian Image

[!TIP]



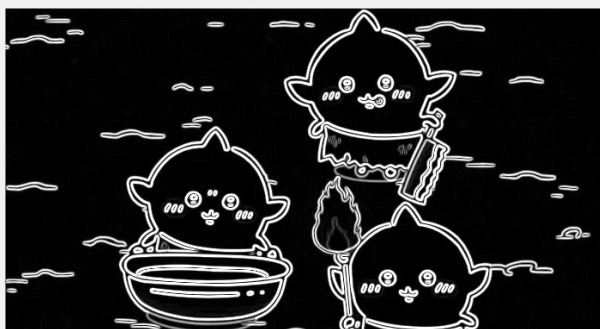
Step 2 Find the intensity gradient of the image (output magnitude G image)

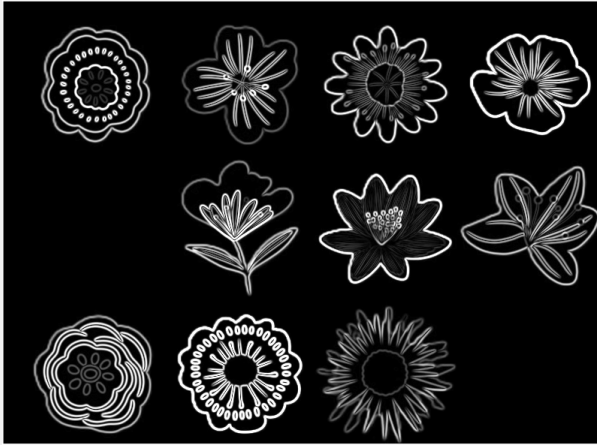
[!IMPORTANT]

In this step, we need to use sobel operation separately x and y.
Where kernel was defined in the homework announcement.
And a θ graph for the slope of gradient.

Magnitude G Image

[!TIP]





Step 3 Non-maximum suppression

[!IMPORTANT]

In this step we need to do non-maximum suppression by θ graph from step 2.

First, we determine the gradient angle and classify it into one of the four nearest directions: 0° , 45° , 90° , or 135° .

Then, if the pixel has a greater value than its neighbors in the gradient direction, it is retained.

Otherwise set it to zero.

Step 4 Double threshold

[!IMPORTANT]

For these step, we need to choose two thresholds.

One is low threshold and the other is high thresholds.

First, calculate the gradient magnitude for all points.

Next, remove zero values since they do not impact the result.

Finally, manually select two values as the thresholds.

Step 5 Edge Tracking by Hysteresis (output edge detection result image)

[!IMPORTANT]

In step 4, we have already chosen two values as thresholds: low and high.

If a pixel's value is lower than the low threshold, it will be ignored.

If the value falls between the low and high thresholds, it will be labeled as a weak edge.

If the value is greater than the high threshold, it will be marked as a strong edge.

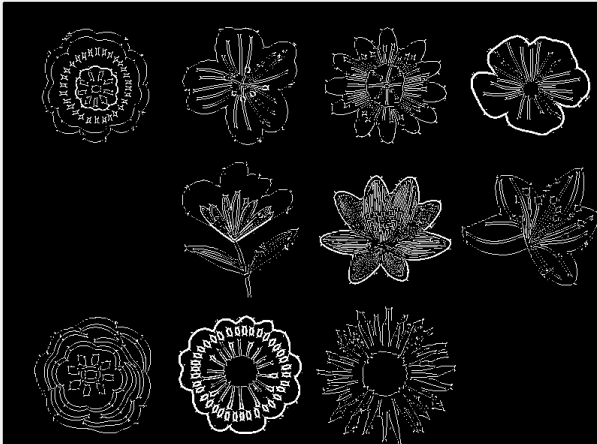
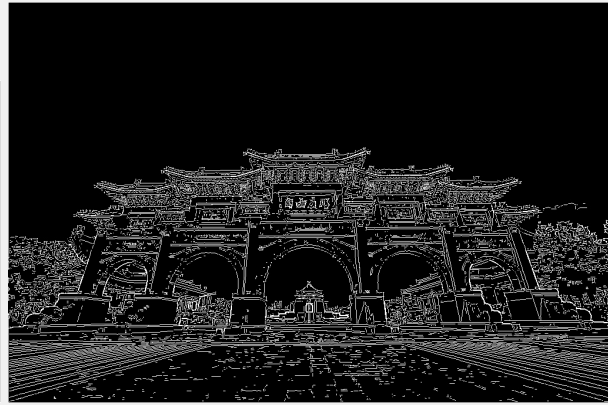
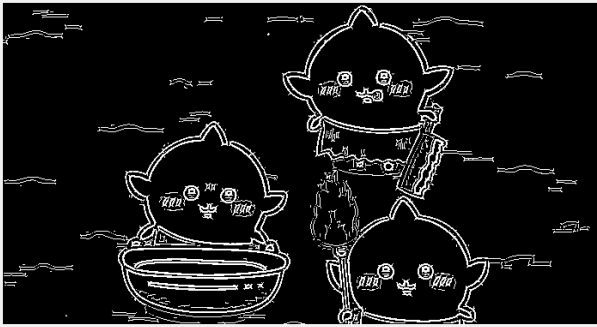
Next, we check each weak edge pixel.

If it has at least one neighboring strong edge, it will be upgraded to a strong edge.

Otherwise, it will be set to zero.

Result Image

[!TIP]



My thought in hw4

[!TIP]

The key points of this homework are selecting the kernel size and σ in Step 1, and determining the thresholds in Step 4.

And since the result is a binary image.

I have convert the test images into grayscale image first and execute these five steps.

One major issue in this homework is performance, as many steps involve nested loops.

This results in longer computation time, since the program is designed to complete all steps before displaying the output.

Therefore, it may take approximately 1 minute to finish running the entire code.